



## SDN-Based Approach to Evaluate the Best Controller: Internal Controller NOX and External Controllers POX, ONOS, RYU

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**GJCST-E Classification:** B.4.2



SDN-BASED APPROACH TO EVALUATE THE BEST CONTROLLER INTERNAL CONTROLLER NOX AND EXTERNAL CONTROLLERS POX ONOS RYU

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# SDN-Based Approach to Evaluate the Best Controller: Internal Controller NOX and External Controllers POX, ONOS, RYU

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**Abstract-** Software Defined Networking (SDN) is a rising technique to deal with replace patrimony network (coupled hardware and software program) control and administration by separating the control plane (software program) from the information plane (hardware). It gives adaptability to the engineers by influencing the focal control to plane straightforwardly programmable. Some new difficulties, for example, single purpose of disappointment, may be experienced because of the original control plane. SDN concentrated on flexibility where the security of the system was not essentially considered. It promises to give a potential method to present Quality of Service (QoS) ideas in the present correspondence networks. SDN automatically changes the behavior and functionality of system devices utilizing a single state program. Its immediate OpenFlow is planned by these properties. The affirmation of Quality of Service (QoS) thoughts winds up possible in a versatile and dynamic path with SDN. It gives a couple of favorable circumstances including, organization and framework versatility, improved exercises and tip-top performances. This research work will concentrate on the Quality of Service (QoS) like delay, response time, throughput, and other execution assessing parameters of our proposed arrange design using internal controller, e.g., Network Operating System (NOX) and external controller, e.g., Pythonic Network Operating System (POX), Open Network Operating System (ONOS) and RYU. Regardless of the way that thoughts of QoS, they did not comprehend the correspondence systems with high utilization, diverse quality and acknowledgment costs. It will focus on the outside controller and inner controller execution in the proposed architecture. These perceptions of switch diversity may give SDN application engineer's bits of knowledge while acknowledging QoS ideas in an SDN-based system.

**Keywords:** SDN, QoS, NOX, POX, ONOS, CPU, TCP, OS, BSD, WAN, ODL, FIB, IP, MAC, API, IT, IOT, IOE.

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## I. INTRODUCTION

Software Defined Networking (SDN) is the current worldview of the systems administration which is taken under consideration by stakeholders with a huge concern. The idea works towards significantly decreasing system organization and administration costs. SDN's innovation is a novel method to manage conveyed figuring that encouraged to arrange administration and empowers system setup automatically, keeping in mind the end goal to enhance monitoring and network performance [1]. It is intended to address the way that the static engineering of the conventional network is decentralized and complex while current systems require greater adaptability and simple investigating. SDN recommends incorporating system insight in one system segment by disassociating the sending procedure of network parcels (Data Plane) from the routing procedure (Control plane). The control plane comprises of at least one controller which is the cerebrum of SDN and the entire insight consolidates there. In any case, the knowledge centralization has its particular downsides with regards to security, [2] versatility and elasticity [3] of SDN. Software Defined Networking [4], [5] is a network system that offers a plan to change the impediments of current system frameworks. In the first place, it breaks the vertical coordination by isolating the system's control logic (the control plane) from the hidden switches and routers that forward the activity (the information plane). Second, with the detachment of the control and information planes, arrange switches end up straightforward sending gadgets and the controlling rationale is executed in a sensibly brought together controller (or system working framework), disentangling strategy implementation and network reconfiguration and advancement [6]. It encompasses different sorts of network headway proposed to make more versatile and spry to help the capacity structure and virtual server of the line server ranches. We will without a lot of an understand SDN against standard framework by a prime portrayal; acknowledged inside the groups that we have to pass on a bundle in the standard; it must change its course thing times for finding the ideal way. It is a proficient structure to use better Quality of Service (QoS) which

exhibits to a framework's profitability to achieve most vital transmission limit and oversee other framework execution parts like inactivity, error rate and run time [7]. An SDN controller is an application in SDN that supervises stream control to engage smart frameworks administration. SDN controllers rely upon convention, for instance, OpenFlow, that empower servers to encourage changes where to send Packets.

Network Operating Systems (NOX) is the first OpenFlow controller. It fills in as a system control stage that gives an abnormal state automatic interface for administration and the advancement of system control applications. Its framework reflects the change and sorting out into a product issue. NOX is a bit of the software-defined networking (SDN) biological system. In particular, it's a stage for building system control applications. The main SDN innovation to get acknowledgment is OpenFlow, and NOX is the first creation at Nicira Networks next to each other with OpenFlow — NOX was the primary OpenFlow controller. Nicira gave NOX to the examination group in 2008, and from that point forward, it has been the reason for some and different research extends in the early investigation of the SDN space. Its applications are different kinds of activities on an abnormal state of nonattendance of unfaltering quality in organizing execute fragment, not at all like bring down back of estimation game-plan [8][9] applications. The system working structure does not manage itself; It outfits a programming interface with top state objects, (for instance, plate accumulating volume, CPU preparing power, memory control, etc.) of framework resources, which engages sort out application undertakings to manage secure and down to earth complex assignments on a combination of network [9]. The NOX, in any case, fails in giving the required capacities to QoS-guaranteed Software Defined Networking (SDN) [10] convenience provisioning on transporter review supplier Internet, for example, QoS-cautious virtual network inserting, end-to-end arrange QoS appraisal, and joint efforts among control components for others space network.

Pythonic Network Operating System (POX) [11] is an open source advancement stage for Python-based software-defined networking (SDN) control applications, for example, OpenFlow SDN controllers. The controller gives an effective method to actualize the OpenFlow convention which is the accepted correspondence convention between the controllers and the switches. Utilizing POX controller can run distinctive applications like center point, switch, firewall, and load balancer. TCP dump bundles catch the instruments to see the bundles streaming between POX controller and OpenFlow devices. It uses as a part of SDN network systems since it has a Python dialect interface for research [12]. OpenFlow, when all says in done has pulled in considerable enthusiasm from industry [13] [14]. POX

formally requires Python 2.7 (however quite a bit of it will work fine with Python 2.6) and should keep running under Linux, Mac OS, and Windows. (What's more, pretty much anyplace else - we've run it on Android telephones, under FreeBSD, Haiku, and somewhere else).

Open Network Operating System (ONOS) [15] is the main open source SDN controller for building next-generation SDN/NFV solutions. It gives the control plane to a software-defined network (SDN), overseeing network segments, for example, switches and connections, and running programming projects or modules to give correspondence administrations to end has and neighboring systems. ONOS stages do flaunt being intended to help, like different controllers, different application classifications, for example, control, setup and the executive's applications. Among the applications that are distributed by ON.Lab, some of them are Segment Routing, multi-layer SDN control, topology watcher, way calculation and SDN-IP peering applications.[16][17] ONOS strengthen different types of southbound protocols like OpenFlow, NetConf, and so on., for correspondence with an assortment of net gadgets. ONOS, like different controllers (ex: ODL), utilizes the idea of suppliers — one each for each southbound convention – which conceals convention unpredictability from different segments of the controller stage. These suppliers give all the essential 'depictions' of system components profoundly layer. [18]

RYU Controller is an open; Software Defined Networking (SDN) Controller intended to expand the deftness of the system by making it simple to oversee and adjust how traffic is taken carefully. By and large, the SDN Controller is the brains of the SDN condition, imparting data down to the switches and switches with southbound APIs, and up to the applications and business rationale with northbound APIs. It gives programming segments, with all around characterized application program interfaces (APIs) that make it simple for designers to make new system the executives and control applications. This segmented approach encourages associations to redo arrangements to meet their particular needs; engineers can rapidly and effortlessly adjust existing segments or execute their very own to guarantee the fundamental system can meet the changing requests of their applications. RYU bolsters different conventions for overseeing system gadgets, for example, OpenFlow, NetConf, OF-Config, and so forth. [19]

## II. RELATED WORK

Past work on giving QoS ensures utilizing Open-Flow can be divided into three classifications. To start with, studies about conveying dynamic QoS in an SDN domain [20][21][22]. Second, ponders on switch assorted variety [23] [24] [25] [26].Third, look into on

arranging execution coming about because of QoS with OpenFlow-empowered switches [27], [28].

A portion of the work done in the region of SDN-based, on request provisioning of system assets is concentrated towards computerized, strategy based system provisioning [29] [30], while other focuses towards movement designing crosswise over Wide Area Networks (WANs) [31][32]. Dynamic distribution of system assets additionally requires inside the server farms, and numerous Investigations address this test. For instance, an OpenFlow-based calculation for designation of transfer speed assets between virtual machines in server farms is exhibited in [33], while in [34] the creators depict a stage for incorporated provisioning of a process, stockpiling and system assets in server farms.

Lately, different specialists have been done to break down SDN controllers like NOX, ODL, ONOS, and RYU and so on. Other research paper had found out the beginning consequences of benchmarking through Open-Daylight SDN external Controller with Floodlight controller. The Researcher had assessed throughput, inaction and response time of Open Daylight SDN Controller and Floodlight under various conditions [35]. A related undertaking of particular note is Maestro [36] (made in parallel to NOX), which also charge as a "framework working system." Through NOX controller 4D structures are to control sending (e.g., FIBs in switches),

and in this way their frameworks consolidate to arrange an establishment (e.g., joins, switches/switches). The Rational [37] and Ethane [38] wanders give more broad class of convenience by including a namespace for customers and center points in their framework view and observing the ties between these names and the low-level IP addresses and MAC.

Scientists were Used POX Controller for measuring the Network Programmability [39]. POX is used to examine the Performance parameters including inactivity and throughput, service quality, versatility, delay, response time and security. The exploration of execution and adaptability finish with Clench. Security and service quality test has alter with probe.

### III. DESCRIPTION OF THE PROPOSED ARCHITECTURE

To measure the Quality of Service (QoS) like throughput, response time, delay and other execution evaluating parameters, we made SDN based cloud architecture. In our created engineering, there are nine routers connected with three cloud interfaces. These various routers connect with eight hosts which have an IP address. For measuring QoS shows from hosts to switches, SDN controllers use as existing controllers and external controllers.

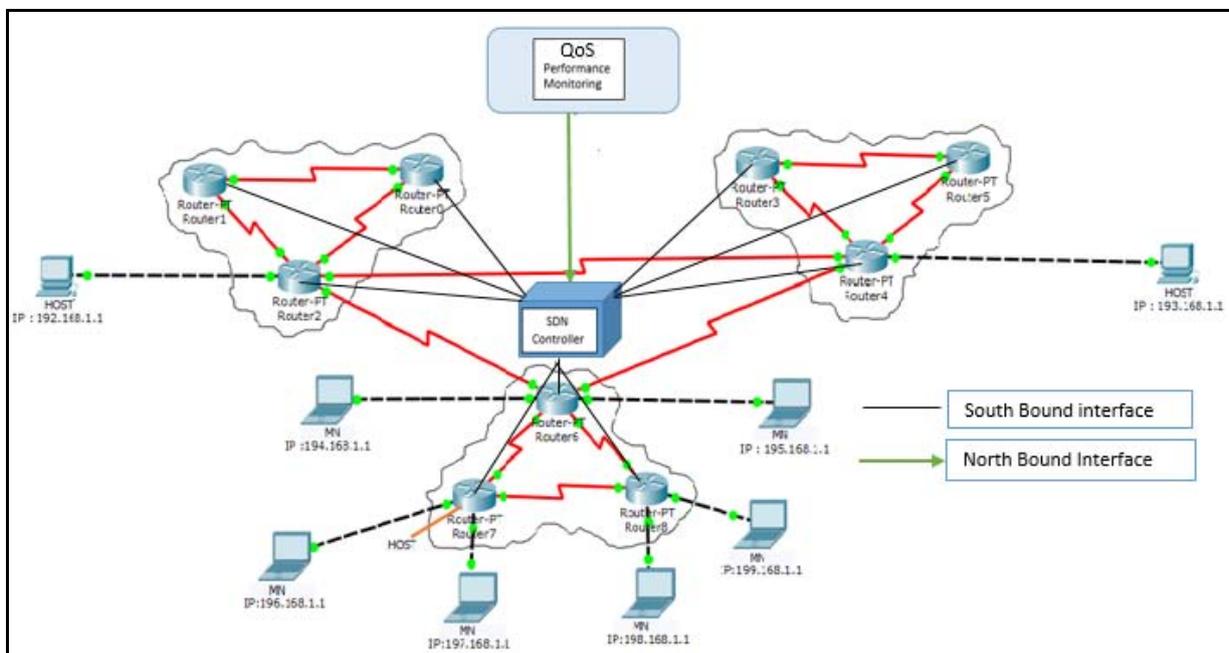


Fig. 1: Proposed\_SDN\_architecture and its real-time loop

#### a) Architectural description based on NOX controller

Network operating system (NOX) empowers administration applications to develop as brought together projects over high state reflections of system assets as an inverse to the dispersed calculations over

low-level locations [40, 41]. The essential parts of a NOX-based system: an arrangement of switches and at least one organize appended servers. The NOX programming (and the administration applications that keep running on NOX) keep running on these servers. IT

includes a few distinctive controller forms (commonly one on each system appended server), and a system sees (this keep in a database running on one of the servers). The arrange see contains the consequences of NOX's system perceptions; applications utilize this state to settle on administration choices. For NOX to control organized the activity, it must control arrange switches; for this reason, we use the switches that help the OpenFlow switch reflection [42].

b) *Architectural description based on POX controller*

POX, which creates in python, is a tip-top, open source OpenFlow controller. An SDN controller developer develops POX in light of Haiku, a trial OpenFlow controller from Stanford University. Huge Switch Networks backs POX as an association that essentially offers answers for business data centers. It offers different features and consultations for controlling an OpenFlow organize. For perfect utilization of benefits, POX relies upon multi-threading and can manage a couple of million new streams for each second. The Westbound python allows the change of custom modules in python and quick interfacing with the middle controller. The modules are stacked by methods for an alternate structure when the POX controller starts. You would along these lines have the capacity to utilize the full handiness of the controller and OpenFlow API and speedily respond to events on the framework, for instance, the ascent of new packages or new streams. The Open Flow datapath despite QoS modules shapes the QoS Flow datapath. This datapath is a consumption space utilize where lines mastermind in the portion space. The QoS module develops a station with the bit through Netlink to relate for both service and bit map. Like this, the POX can instantiated to connect with activity adornment and enqueueing of streams in our proposed engineering.

c) *Architectural description based on ONOS controller*

ONOS was intended to address the issues of administrators wishing to construct bearer level arrangements that use the financial aspects of white box vendor silicon equipment while offering the adaptability to make and send new unique system administrations with disentangled automatic interfaces. It underpins both setup and constant control of the system, disposing of the need to run directing and exchanging control conventions inside the system texture. By moving knowledge into the ONOS cloud controller, advancement empowers, and end-clients can undoubtedly make new system applications without the need to adjust the data-plane frameworks. In ONOS, in contrast to different controllers, disseminated engineering support is one of the plan standards and not an idea in retrospect bolster. It is additionally like five to six of the dispersed models portrayed above in the Distributed SDN Controller Architecture segment. That is, ONOS can be sent as the gathering of controller-

servers that facilitate with one another to accomplish strength, adaptation to non-critical failure, and better load the executives.

d) *Architectural description based on RYU controller*

RYU controller is single-strung substances which execute different functionalities in RYU. Events are messages between them. It sends offbeat occasions to one another. Other than that, there are some RYU-inner occasion sources which are not RYU applications. One of the instances of such occasion sources is Open-stream controller. While an occasion can as of now contain self-assertive python protests, it's debilitated to pass complex items (e.g. unpick capable terms) between RYU. Each RYU controller has a get line for occasions. It has a string for occasion preparing. The RYU controller continues depleting the get line by lining a datapath and calling the proper occasion handler for the occasion's type. Since the occasion handlers bring with regards to the occasion preparing string, it ought to be cautious when blocking. While an occasion handler hinders, no further occasions for the RYU application will process. There are sorts of handlers which are utilized to actualize synchronous between application calls between RYU controller.

#### IV. COMPARISON BETWEEN THE INTERNAL AND EXTERNAL CONTROLLERS ON OUR PROPOSED ARCHITECTURE

a) *NOX controller*

i. *Response Time of NOX controller*

Figure 2 shows the graph of the calculation of Response Time with NOX of Table 1.

*Table 1:* Calculation of Response Time with NOX controller

| Number of Operations | Response Time (NOX) ms |
|----------------------|------------------------|
| 4                    | 0.028                  |
| 8                    | 0.029                  |
| 12                   | 0.030                  |
| 16                   | 0.029                  |
| 20                   | 0.031                  |
| 24                   | 0.032                  |
| 28                   | 0.033                  |
| 32                   | 0.032                  |
| 36                   | 0.033                  |
| 40                   | 0.031                  |
| 44                   | 0.034                  |
| 48                   | 0.033                  |
| 52                   | 0.034                  |
| 56                   | 0.034                  |
| 60                   | 0.035                  |
| 64                   | 0.034                  |

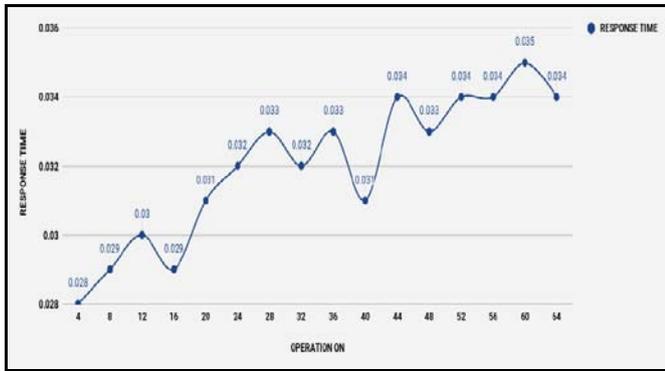


Fig. 2: Response Time of NOX controller

ii. Throughput of NOX controller

Figure 3 shows the graph of the calculation of Throughput with NOX of Table 2.

Table 2: Calculation of Throughput with NOX controller

| Number of Operations | Throughput (NOX) ms |
|----------------------|---------------------|
| 4                    | 0.138               |
| 8                    | 0.156               |
| 12                   | 0.234               |
| 16                   | 0.274               |
| 20                   | 0.279               |
| 24                   | 0.274               |
| 28                   | 0.231               |
| 32                   | 0.234               |
| 36                   | 0.275               |
| 40                   | 0.274               |
| 44                   | 0.187               |
| 48                   | 0.234               |
| 52                   | 0.244               |
| 56                   | 0.217               |
| 60                   | 0.217               |
| 64                   | 0.187               |

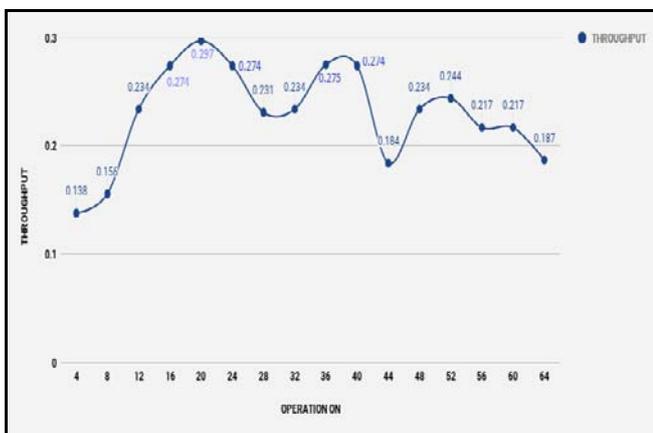


Figure 3: Throughput of NOX controller

b) Pythonic Network Operating System (POX) controller

i. Response Time of POX controller

Figure 4 represents the graph for the calculation of Response Time with POX of Table 3.

Table 3: Calculation of Response Time with POX controller

| Number of Operations | Response Time (POX) ms |
|----------------------|------------------------|
| 4                    | 0.045                  |
| 8                    | 0.041                  |
| 12                   | 0.037                  |
| 16                   | 0.039                  |
| 20                   | 0.039                  |
| 24                   | 0.040                  |
| 28                   | 0.039                  |
| 32                   | 0.038                  |
| 36                   | 0.037                  |
| 40                   | 0.036                  |
| 44                   | 0.036                  |
| 48                   | 0.041                  |
| 52                   | 0.040                  |
| 56                   | 0.044                  |
| 60                   | 0.043                  |
| 64                   | 0.042                  |

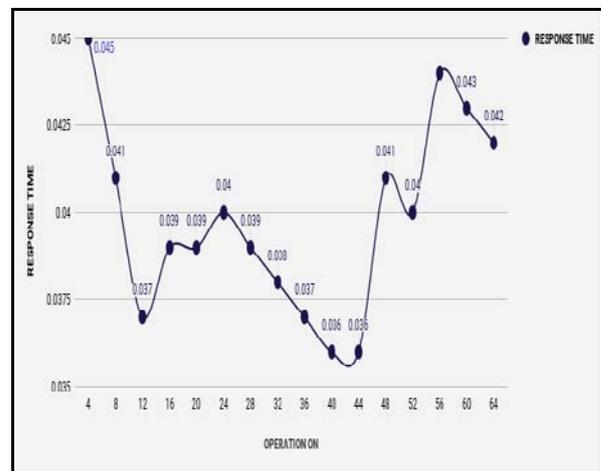


Figure 4: Response Time of POX controller

ii. Throughput of POX controller

Figure 5 shows the graph of the calculation of Throughput with POX of Table 4.

Table 4: Calculation of Throughput with POX controller

| Number of Operations | Throughput (POX) ms |
|----------------------|---------------------|
| 4                    | 0.660               |
| 8                    | 0.751               |
| 12                   | 0.692               |
| 16                   | 0.745               |
| 20                   | 0.649               |
| 24                   | 0.673               |
| 28                   | 0.604               |
| 32                   | 0.589               |
| 36                   | 0.554               |
| 40                   | 0.533               |

|    |       |
|----|-------|
| 44 | 0.510 |
| 48 | 0.502 |
| 52 | 0.476 |
| 56 | 0.462 |
| 60 | 0.442 |
| 64 | 0.420 |

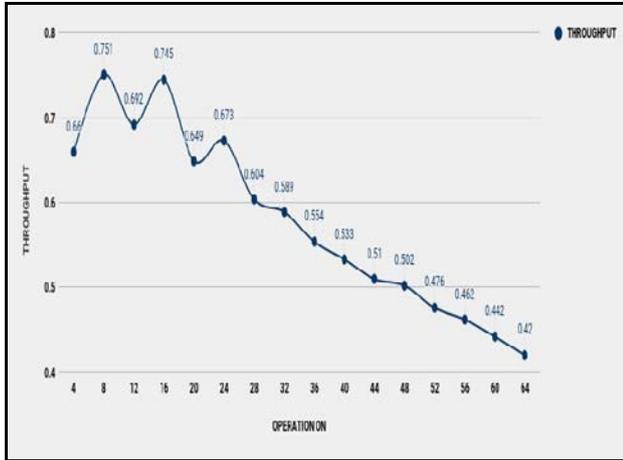


Figure 5: Throughput of POX controller

c) Open Network Operating System (ONOS) controller

i. Response Time of ONOS controller

Figure 6 shows the graph of the calculation of Response Time with ONOS of Table 5.

Table 5: Calculation of Response Time with ONOS controller

| Number of Operations | Response Time (ONOS) ms |
|----------------------|-------------------------|
| 4                    | 0.070                   |
| 8                    | 0.063                   |
| 12                   | 0.060                   |
| 16                   | 0.058                   |
| 20                   | 0.057                   |
| 24                   | 0.056                   |
| 28                   | 0.055                   |
| 32                   | 0.054                   |
| 36                   | 0.053                   |
| 40                   | 0.052                   |
| 44                   | 0.050                   |
| 48                   | 0.049                   |
| 52                   | 0.049                   |
| 56                   | 0.047                   |
| 60                   | 0.047                   |
| 64                   | 0.048                   |

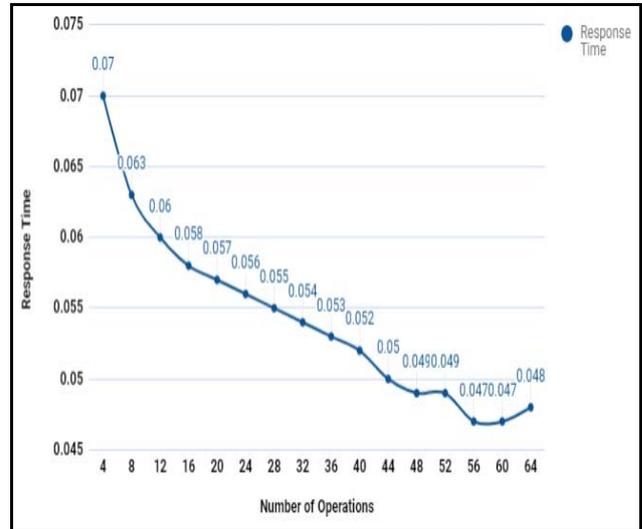


Figure 6: Response Time of ONOS controller

ii. Throughput of ONOS controller

Figure 7 shows the graph of the calculation of Throughput with ONOS of Table 6.

Table 6: Calculation of Throughput with ONOS controller

| Number of Operations | Throughput (ONOS) ms |
|----------------------|----------------------|
| 4                    | 0.634                |
| 8                    | 0.449                |
| 12                   | 0.351                |
| 16                   | 0.303                |
| 20                   | 0.228                |
| 24                   | 0.180                |
| 28                   | 0.161                |
| 32                   | 0.122                |
| 36                   | 0.121                |
| 40                   | 0.118                |
| 44                   | 0.117                |
| 48                   | 0.129                |
| 52                   | 0.116                |
| 56                   | 0.123                |
| 60                   | 0.119                |
| 64                   | 0.127                |

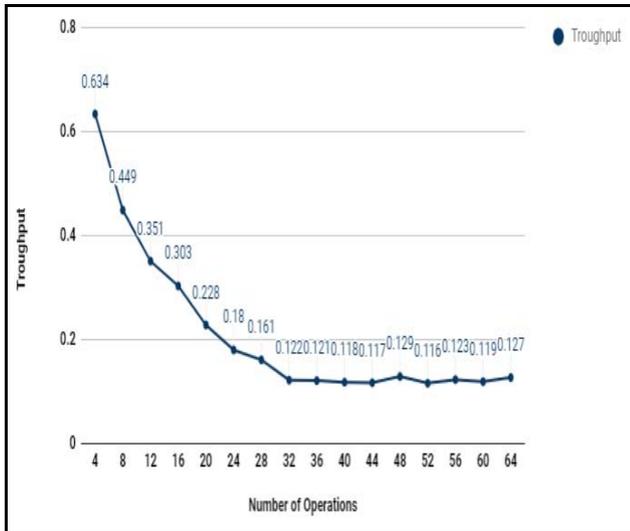


Figure 7: Throughput of ONOS controller

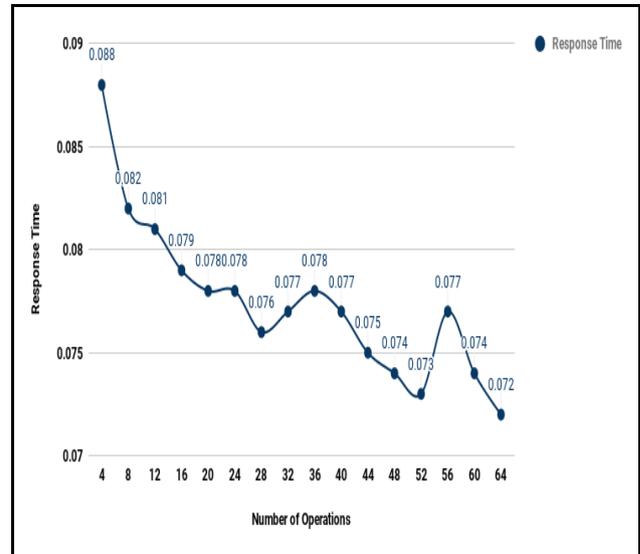


Figure 8: Response Time of RYU controller

d) RYU controller

i. Response Time of RYU controller

Figure 8 shows the graph of the calculation of Response Time with RYU of Table 7.

Table 7: Calculation of Response Time with RYU controller

| Number of Operations | Response Time (RYU) ms |
|----------------------|------------------------|
| 4                    | 0.088                  |
| 8                    | 0.082                  |
| 12                   | 0.081                  |
| 16                   | 0.079                  |
| 20                   | 0.078                  |
| 24                   | 0.078                  |
| 28                   | 0.076                  |
| 32                   | 0.077                  |
| 36                   | 0.078                  |
| 40                   | 0.077                  |
| 44                   | 0.075                  |
| 48                   | 0.074                  |
| 52                   | 0.073                  |
| 56                   | 0.077                  |
| 60                   | 0.074                  |
| 64                   | 0.072                  |

ii. Throughput of RYU controller

Figure 9 shows the graph of the calculation of Throughput with RYU of Table 8.

Table 8: Calculation of Throughput with RYU controller

| Number of Operations | Throughput (RYU) ms |
|----------------------|---------------------|
| 4                    | 1.177               |
| 8                    | 0.652               |
| 12                   | 0.442               |
| 16                   | 0.460               |
| 20                   | 0.251               |
| 24                   | 0.435               |
| 28                   | 0.251               |
| 32                   | 0.215               |
| 36                   | 0.435               |
| 40                   | 0.188               |
| 44                   | 0.262               |
| 48                   | 0.271               |
| 52                   | 0.195               |
| 56                   | 0.276               |
| 60                   | 0.269               |
| 64                   | 0.178               |

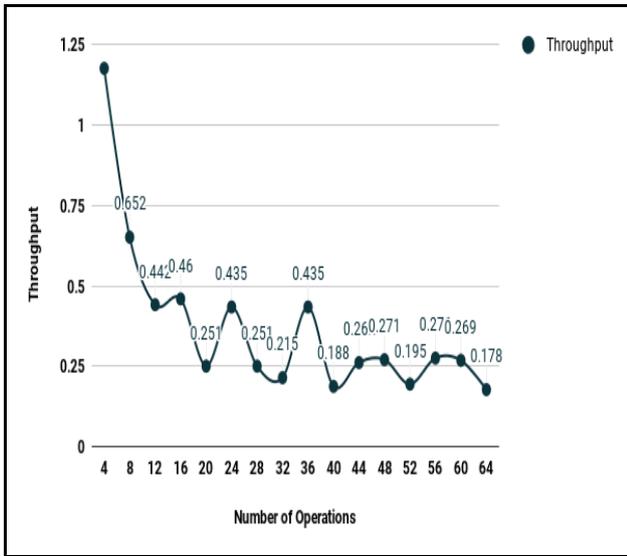


Figure 9: Throughput of RYU controller

### V. PERFORMANCE ANALYSIS EQUATION

We executed 64 operations in our Proposed\_SDN\_architecture. In the comparison of response time and throughput among internal controller Network operating system (NOX) and external controllers Pythonic Network Operating System (POX), Open Network Operating System (ONOS) and RYU.

The performance of response time and throughput in our Proposed\_SDN\_architecture can be calculated against internal and external controllers by the following equation:

Let, Performance (P) = M/N

Where N = Sum of the response time or the throughput of internal controller NOX.

M = Sum of the response time or the throughput of external controllers POX, ONOS, and RYU.

### VI. PERFORMANCE ANALYSIS AMONG INTERNAL CONTROLLER NOX AND EXTERNAL CONTROLLERS POX, ONOS, RYU

#### a) Comparison of Response Time

##### i. Response Time between NOX and POX, NOX and ONOS, NOX and RYU controllers

The performance of response time in our Proposed\_SDN\_architecture can be calculated against internal controller NOX and external controllers POX, ONOS and RYU by the following equation:

#### NOX and POX:

Let, Performance (P) = M/N

Where N = sum of the response time of internal controller NOX

M = sum of the response time of external controller POX

Here, M = 0.637

N = 0.512

So, P = (0.637/0.512) times  
= 1.244 times

#### NOX and ONOS:

Let, Performance (P) = M/N

Where N = sum of the response time of internal controller NOX

M = sum of the response time of external controller ONOS

Here, M = 0.868

N = 0.512

So, P = (0.868/0.512) times  
= 1.695 times

#### NOX and RYU:

Let, Performance (P) = M/N

Where N = sum of the response time of internal controller NOX

M = sum of the response time of external controller RYU

Here, M = 1.239

N = 0.512

So, P = (1.239/0.512) times  
= 2.420 times

##### ii. Throughput between NOX and POX, NOX and ONOS, NOX and RYU controllers

The performance of throughput in our Proposed\_SDN\_architecture can be calculated against internal controller NOX and external controllers POX, ONOS and RYU by the following equation:

#### NOX and POX:

Let, Performance (P) = M/N

Where N = sum of the throughput of internal controller NOX

M = sum of the throughput of external controller POX

Here, M = 9.262

N = 3.655

So, P = (9.262/3.655) times  
= 2.534 times

#### NOX and ONOS:

Let, Performance (P) = M/N

Where N = sum of the throughput of internal controller NOX

M = sum of the throughput of external controller ONOS

Here, M = 3.798

N = 3.655

So, P = (3.798/3.655) times  
= 1.039 times

#### NOX and RYU:

Let, Performance (P) = M/N

Where N = sum of the throughput of internal controller NOX

M = sum of the throughput of external controller RYU

Here,  $M = 5.957$

$N = 3.655$

So,  $P = (5.957/3.655)$  times  
 $= 1.630$  times

## VII. PERFORMANCE ANALYSIS BETWEEN EXTERNAL CONTROLLERS POX, ONOS, RYU

### a) Comparison of Response Time

#### i. Response Time between POX and ONOS, POX and RYU, ONOS and RYU controllers

The performance of response time in our Proposed\_SDN\_architecture can be calculated against external controllers POX, ONOS, and RYU by the following equation:

#### POX and ONOS:

Let, Performance (P) = M/N

Where N = sum of the response time of external controller POX

M = sum of the response time of external controller ONOS

Here,  $M = 0.868$

$N = 0.637$

So,  $P = (0.868/0.637)$  times  
 $= 1.363$  times

#### POX and RYU:

Let, Performance (P) = M/N

Where N = sum of the response time of external controller POX

M = sum of the response time of external controller RYU

Here,  $M = 1.239$

$N = 0.637$

So,  $P = (1.239/0.637)$  times  
 $= 1.945$  times

#### ONOS and RYU:

Let, Performance (P) = M/N

Where N = sum of the response time of external controller ONOS

M = sum of the response time of external controller RYU

Here,  $M = 1.239$

$N = 0.868$

So,  $P = (0.651/0.528)$  times  
 $= 1.427$  times

#### ii. Throughput between POX and ONOS, POX and RYU, ONOS and RYU controllers

The performance of throughput in our Proposed\_SDN\_architecture can be calculated against

external controllers POX, ONOS and RYU by the following equation:

#### POX and ONOS:

Let, Performance (P) = M/N

Where N = sum of the throughput of external controller ONOS

M = sum of the throughput of external controller POX

Here,  $M = 9.262$

$N = 3.798$

So,  $P = (9.262/3.798)$  times  
 $= 2.439$  times

#### POX and RYU:

Let, Performance (P) = M/N

Where N = sum of the throughput of external controller RYU

M = sum of the throughput of external controller POX

Here,  $M = 9.262$

$N = 5.957$

So,  $P = (9.262/5.957)$  times  
 $= 1.555$  times

#### ONOS and RYU:

Let, Performance (P) = M/N

Where N = sum of the throughput of external controller ONOS

M = sum of the throughput of external controller RYU

Here,  $M = 5.957$

$N = 3.798$

So,  $P = (5.957/3.798)$  times  
 $= 1.568$  times

## VIII. RESULT DISCUSSION

In our Proposed\_SDN\_architecture, we executed 64 operations, and we find the better QoS from the architecture through internal and external SDN controller. After measuring performance, we find that internal SDN controller is better than external SDN controller. As a result of comparison between internal controller NOX and external controllers POX, ONOS and RYU, the following results find-

- ❖ The response time of internal controller NOX is **1.244x** higher than the response time of external controller POX.
- ❖ The response time of internal controller NOX is **1.695x** higher than the response time of external controller ONOS.
- ❖ The response time of internal controller NOX is **2.420x** higher than the response time of external controller RYU.
- ❖ So, internal SDN controller **NOX** is better in the performance of response time than other controllers.

- ❖ The throughput of internal controller NOX is **2.534x** better than the throughput of external controller POX.
- ❖ The throughput of internal controller NOX is **1.039x** better than the throughput of external controller ONOS.
- ❖ The throughput of internal controller NOX is **1.630x** better than the throughput of external controller RYU.
- ❖ So, internal SDN controller **NOX** is better in the performance of throughput than other controllers.

As a result of comparison between external controllers POX, ONOS, and RYU, the following results find-

- ❖ The response time of external controller POX is **1.363x** higher than the response time of external controller ONOS.
- ❖ The response time of external controller POX is **1.945x** higher than the response time of external controller RYU.
- ❖ The response time of external controller ONOS is **1.427x** higher than the response time of external controller RYU.
- ❖ So, external SDN controller **POX** is better in the performance of response time than other external controllers.
- ❖ The throughput of external controller ONOS is **2.439x** better than the throughput of external controller POX.
- ❖ The throughput of external controller RYU is **1.555x** better than the throughput of external controller POX.
- ❖ The throughput of external controller ONOS is **1.568x** better than the throughput of external controller RYU.
- ❖ So, external SDN controller **ONOS** is better in the performance of throughput than other external controllers.

## IX. CONCLUSION AND FUTURE WORK

Software-defined networking (SDN) is a design implying to be dynamic, reasonable, cost-effective, and versatile, trying to be appropriate for the high-data transmission, dynamic nature of the present applications. It enables associations to quicken application sending and conveyance, drastically lessening IT costs through strategy empowered work process automation. SDN technology develops cloud models by giving mechanized, on-request application conveyance and versatility at scale. With SDN the item that harps on these controllers settles on the sum decisions and sends this information down to each physical gadget. The central goal of this work is empowering included regard benefits in sort out system. SDN uses to find the security services in different

framework structures. It favors a fundamental and flexible insistence of existing dynamic Quality of Service (QoS) parts in the present correspondence arrange. In the examination of the response time of the proposed architecture, internal controller NOX is superior to external controller POX, ONOS, and RYU. On account of throughput, internal controller NOX is additionally better. Among external controllers, POX is better in the performance of response time, and ONOS is better in the performance of throughput than other external controllers. Using SDN, we will work with Number of Bandwidth Isolation, Queues Impact, QoE Evaluation, and Switch Capacity. We will likewise chip away at stack adjust, security frameworks, remote system, Secure Mobility, Cloud Networking, etc. We will work at IOE or IOT like city automation, industry, home, country etc. through the best Quality of Service (QoS) by adducting our proposed SDN architecture with different controllers.

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