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Controlled Stator Resistance

1107

Highlights

University Grid Network

Renewable Energy System

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Discovering Thoughts, Inventing Future



VOLUME 13 ISSUE 13 VERSIC



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IOT: Detection of Keys, Controlling Machines and Wireless Sensing Via Mesh Networking Through Internet

By Md. Nasimuzzaman Chowdhury , MD. Mahbub Hossain Bhuiyan & Samiul Islam

American International University, Bangladesh

Abstract - Internet of things is getting developed rapidly. Each and every day new devices are getting connected with internet. This stream of IOT brings new experience in our daily life. Connecting our wearable devices, gadgets, keys etc can make our own home a new world to us. Every component of our house can communicate with us through IOT. But connecting each device with internet requires costly devices like Wi-Fi modems, GPRS modems etc. This makes connecting each component with internet quiet expensive. In this paper we have developed a cost effective way of connecting each component with internet with internet quiet expensive. In internet. As most of the household components are stationary and close to each other they can be connected with each other through mesh networking. A central device will receive their information and transmit it to internet. The cheapest way to create a mesh network is to use NRF protocol and a WIFI modem does the rest of the work to upload each and every data of this network to internet. In this project there are several nodes regarding their purpose like sensor nodes to collect temperature, humidity, co2 gas quantity and monitor through internet. Control nodes turn on or off AC, fans, lights of house and detection node to find out keys, sun glasses, and small objects.

Keywords : internet of things (IOT), mesh network, Wi-Fi, home automation, sensor monitor.

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IOT: Detection of Keys, Controlling Machines and Wireless Sensing Via Mesh Networking Through Internet

Md. Nasimuzzaman Chowdhury $^{\alpha}$, MD. Mahbub Hossain Bhuiyan $^{\sigma}$ & Samiul Islam $^{\rho}$

Abstract - Internet of things is getting developed rapidly. Each and every day new devices are getting connected with internet. This stream of IOT brings new experience in our daily life. Connecting our wearable devices, gadgets, keys etc can make our own home a new world to us. Every component of our house can communicate with us through IOT. But connecting each device with internet requires costly devices like Wi-Fi modems, GPRS modems etc. This makes connecting each component with internet guiet expensive. In this paper we have developed a cost effective way of connecting each component with internet quiet expensive. In internet. As most of the household components are stationary and close to each other they can be connected with each other through mesh networking. A central device will receive their information and transmit it to internet. The cheapest way to create a mesh network is to use NRF protocol and a WIFI modem does the rest of the work to upload each and every data of this network to internet. In this project there are several nodes regarding their purpose like sensor nodes to collect temperature, humidity, co2 gas quantity and monitor through internet. Control nodes turn on or off AC, fans, lights of house and detection node to find out keys, sun glasses, and small objects.

Keywords : internet of things (IOT), mesh network, Wi-Fi, home automation, sensor monitor.

I. INTRODUCTION

or centuries researchers are trying to develop home automation systems. But most of the automation system depends on the presence of the user. Some solutions made through voice recognition, some are sound alert systems. Like "A zigbee-based home automation system" by Gill, K. Shuang-Hua Yang; Fang Yao; Xin Lu [1]. But IOT is a breakthrough in the world of home automation. The IOT has the potential to change the entire world into a smarter world. Where automated dictions like when things needs replacing, repairing or recalling can be made easily and efficiently by using IOT. Consequently it would greatly reduce waste, loss and cost of things that

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Author p : Dept. of Electrical & Electronic Engineering, AIUB, American International University, Bangladesh. E-mail : sami.aiub.edu@hotmail.com we cannot monitor properly. Although, the research into the IOT is quiet in its embryonic stage There are also several projects using IOT but the overall cost for each automation is not effective. Researches like An Internet of Things Approach for Managing Smart Services Provided by Wearable Devices [2], The Applications Of WiFi-based Wireless Sensor Network In Internet of Things And Smart Grid [3], Design of Intelligent Internet of Things for Equipment Maintenance [4]. These are controlling limited devices and costly solutions. To reduce the cost of internet connected things this project is implemented. It not only about controlling devices from internet, it also helps to monitor our home from internet, finding little daily needed things through internet. And as in present time internet is available in smart phones, anyone can access internet from anywhere anytime.

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IOT: DETECTION OF KEYS, CONTROLLING MACHINES AND WIRELESS SENSING VIA MESH NETWORKING THROUGH INTERNET

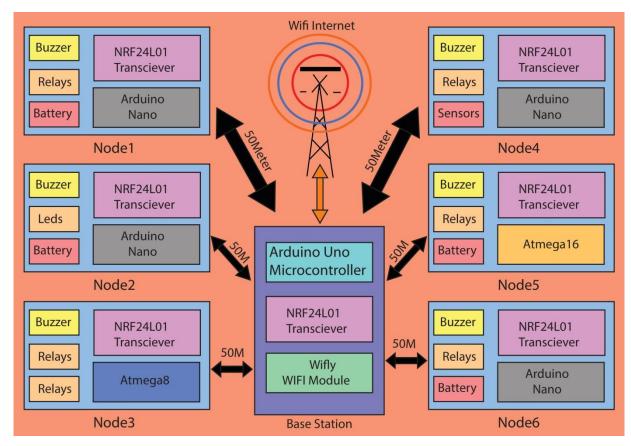


Figure 1 : Main Project Outline

II. MAIN PROJECT OUTLINE

In this project there are several nodes and one base station. Nodes are required to control, collect information and sense devices. Base station is used to transmit these data to internet. With one base station unlimited number of nodes can be connected. The communication between nodes and base station is through radio frequency. But each node has to be within a circle of around 50meter from the base station. Each node can communicate with each other if necessary. If two nodes communicate with each other then the distance between the nodes also have to be 50meter.

But if two nodes do not communicate with each other then they can be placed in any distance while maintaining specific distance from base station. Base station consists of a microcontroller, NRF transceiver, and an R171 wifly module. Nodes are largely categorized into three categories. Firstly controlling nodes (e.g Node 1, 3, 5, 6). Any node consists of relays to control ACs, fans, lights and NRF transceiver falls into this category. Secondly, sensing nodes like node 4 consists of temperature and humidity sensor. In this way this network can be used as wireless sensor network (WSN) also. Last but the most interesting node is called detection node. Lots of time we lost our important things like keys, sun glasses, small bags etc. But we know that these things are somewhere near us. So these nodes contain leds, piezo buzzer and NRF transceiver. Whenever the important little thing is lost an alarm can be generated from internet and leds will start blinking, buzzer will start buzzing.

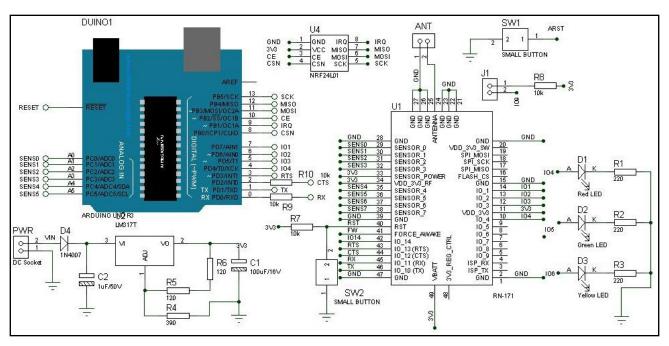


Figure 2 : Main Circuit Diagram

III. MAIN CIRCUIT DESCRIPTION

The heart of the base station is arduino uno microcontroller. The Arduino Uno is a microcontroller board based on the ATmega328. Arduino Uno has serial peripheral communication pins also. With Arduino Uno NRF24L01 rf transceiver is connected. To connect the complete hardware with internet Wifly (Wifi module) has been used. In the simplest configuration the hardware only requires four connections (PWR, TX, RX and GND) to create a wireless data connection. Interface between arduino Uno and NRF transceiver is serial peripheral interface. MISO, MOSI, SCK & SS pins of arduino is connected with the same pins of NRF transceiver. Pin no 8, 9, 10, 11, 12, 13 of arduino uno is connected to 4,8,3,6,7,5 no pins of NRF transceiver. Here arduino is the master and NRF is the slave. NRF runs on 3.3v DC which collects from Vo pin of LM317T. Wifly module communicates through UART. And it also consumes 3.3v dc from Vo pin. For the purpose of UART communication Rx, Tx, RTS & CTS pins of wifly module connected with arduino uno. There are some other GPIO pins of wifly module which is also connected with arduino for different kind of gpio operations. The ability to go into deep sleep mode and automatically scan and associate to an AP when awake makes the RN-171 suitable for roaming applications. The RN-171 also includes a built in HTML client to automatically post serial uart data or sensor data to a web server. Both the device communicates at 9600 baud rate. Rx, Tx, RTS & CTS pins are connected with Tx, Rx, RTS & CTS pins of arduino respectively.

Different nodes consist of different hardware according to their purpose and application. Brain of

node1 is arduino nano. The Arduino Nano is a small, complete board based on the ATmega328. The ATmega168 has 16 KB of flash memory for storing code (of which 2 KB is used for the bootloader); the ATmega328 has 32 KB, (also with 2 KB used for the bootloader). The ATmega168 has 1 KB of SRAM and 512 bytes of EEPROM [7]. It has 14 digital pins, one uart, two external interrupt, 6 PWM channels, 8-channel 10-bit ADC, Master/Slave SPI Serial Interface, Byteoriented 2-wire Serial Interface and Six Sleep Modes. SPI of NANO used to interface with NRF transceiver. In 14 digital I/O pins 14 relays can be connected to control 14 electronics devices like AC, fan, light, door etc. But in this project we used a single relay to control. Another node consists of atmega8 microcontroller. It has similar capabilities like arduino NANO. ADC pins of atmega8 are used to collect data from sensors. Thus this node is called sensing node. In this project temperature & humidity sensor is used in sensing node.

But in available 5 ADC pins different types of sensors can be used. Another node is used to detect devices. That node consists of a microcontroller, leds & buzzer. In any GPIO pin of microcontroller leds, buzzer can be connected. The Circuit diagram of this system consists the following equipments:

a) Arduino Uno Microcontroller :

The Arduino Uno is a microcontroller board based on the ATmega328. It has 14 digital input/output pins (of which 6 can be used as PWM outputs, 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button [5]. It contains everything needed to support the microcontroller; simply need to connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started. It operates at 5V voltage and DC current in I/O pin is 40mA. The DC current in 3.3V pin is 50mA. The figure is given below



Figure 3 : Arduino Uno microcontroller

b) NRF24L01 Transceiver:

The nRF24L01 is a highly integrated, ultra low power (ULP) 2Mbps RF transceiver IC for the 2.4GHz ISM (Industrial, Scientific and Medical) band. With peak RX/TX currents lower than 14mA, a sub μ A power down mode, advanced power management, and a 1.9 to 3.6V supply range [6]. The nRF24L01 integrates a complete 2.4GHz RF transceiver, RF synthesizer, and baseband logic including the Enhanced Shock Burst hardware protocol accelerator supporting a high-speed SPI interface for the application controller.

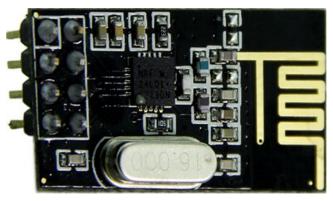


Figure 4 : NRF24L01 Transceiver

c) Wifly Wi-Fi Shield:

It"s a 2.4GHz IEEE 802.11b/g transceiver. High throughput - 921Kbps TX, 500Kbps RX data rate with TCP/IP and WPA2 over UART, up to 2Mbps over SPI slave. The RN-171 module is a standalone complete TCP/IP wireless networking module. [8]

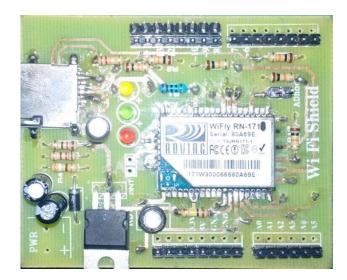


Figure 5 : Wifly Wi-Fi Shield

IV. MAIN TECHNOLOGY USED

Main purpose of this project is to reduce the overall cost to connect devices with internet. Here we used NRF transceiver to create a mesh network and connected the complete network with internet.

A NRF transceiver can communicate with 6 devices at a time as there are 6 different pipe lines each transceiver contains for communication. Each transceiver contains a Rx address and Tx address. But the Rx and Tx address are same. In order to send data to or receive data from the SPI port on the 24L01 the CSN pin on the 24L01 must be high to start out with. Then, bringing the CSN pin low to alert the 24L01 that it is about to receive SPI data. Once transmitted or read all of the bytes that

needed, bringing CSN back high. To execute the R_REGISTER instruction on TX_ADDR register, which will read the contents of the TX address register out of the 24L01 and into micro. The TX_ADDR register is 5 bytes wide and 5-byte addresses is used. First, bringing CSN low and then send the command byte '00010000' to the 24L01. This instructs the 24L01 that needs to read register 0x10, which is the TX_ADDR register. Then five dummy data bytes is sent and the 24L01 will send back to you the contents of the TX_ADDR register. Finally, bringing the CSN pin back high.

The mesh network of nodes is shown below

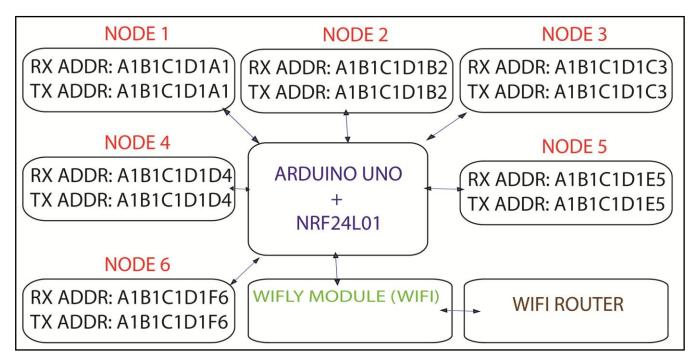


Figure 6 : Mesh networking of 6 nodes with base station

RN171 (Wifly) supports secure Wi-Fi authentication WEP-128, WPA-PSK (TKIP), WPA2-PSK (AES) [8]. To connect with Wi-Fi network WPA-PSK (TKIP) encryption is used.

Connection Security		
2 8 9		
Security type:	WPA-Personal	-
Security type:	THE POINT	

Figure 7: Encryption of wifi network.

For networks using WPA/WPA2 Personal encryption, the SSID and password is needed SSID: Raspberry Password: 04101985

At first the available network need to be searched. As the desired network found it is connected with arduino. Following few lines of codes used to search and connect with Wi-Fi network.

```
byte Networks = WiFi.scanNetworks();
```

char ssid[] = "Raspberry";

char pass[] = "04101985";

```
status = WiFi.begin(ssid, pass);
```

CMD sc5ÖL &æL³fÏ SCAN:Found 1 01,06,-71,03,3104,74:ea:3a:d1:78:24,

Figure 8: Network found to connect internet

Maximum length of 140 characters Tweet can be generated. To generate a tweet through arduino each account need to have a tweeter 'Token'. In this project

Tweeter account name: internetofkeys

Against this tweeter account an unique token is provided from twitter.com.

← → C III 🙆 arduino-tweet.appspot.com/oauth/twitter/callback

Your token is:

1867893906-rz9ZZWJvFCy8o6ciBRevQUqORBLycwGavEuaeKH

```
Figure 9: Token from Twitter
```

These are the few codes to setup twitter account with arduino

char msg[];

Twitter twitter("1867893906-

rz9ZZWJvFCy8o6ciBRevQUqORBLycwGavEuaeKH");

twitter.post(msg)

Here different messages used for different tweet. User can control devices through re-tweeting also.

Year 2013

V. HARDWARE IMPLEMENTATION

The base station is implemented in PCB design and Vero board. The figure is given below

In this node with an Arduino Nano, Led light, buzzer and NRF24I01 protocol is connected. This node PCB device can be connected with any necessary keys that helps to find the keys very quickly.

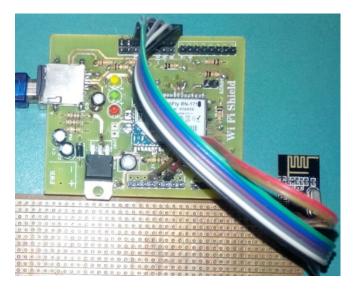


Figure 10. Hardware implementation of base station

There are three nodes implemented in the project. Those are shown bellow.

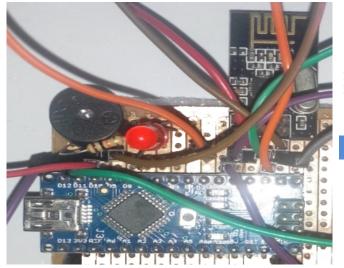


Figure 12 : Detection Node for Key detection

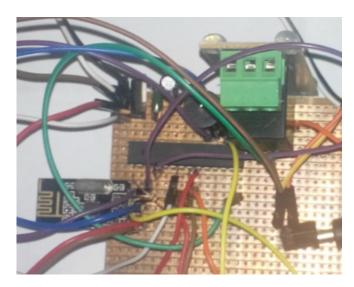


Figure 11: Control Node to control Machines

In this hardware atmega8 is connected with one relay, one buzzer and NRF24I01 transceiver. This node can be connected with machines and machines can be controlled from anywhere in this world through Internet.

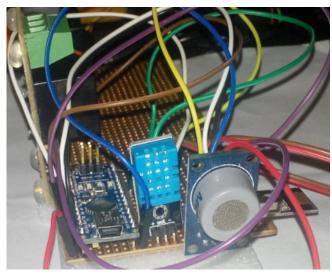


Figure 13: Sensing Node for sensing temperature and humidity

In this node with arduino nano temperature, humidity and gas sensor is connected. With this node device it's possible to sense any places temperature or humidity and the transmitted data can be viewed instantly via internet from anywhere.

VI. OUTPUT RESULTS

All the outputs are shown in the tweeter. Here are some tweets transmitted from user account and retweet from base station. When connection establish base station tweet of connection establishment.

Twe	ets	
	Internet Of Keys @internetofkeys	15 Sep
	WiFi Key Connection Established	
	Expand	

Figure 14 : Connection establishment confirmation

Here user is Md. Nasimuzzaman. So user can select a command to turn on or turn off lights, fans, Ac. This base station will accept tweets from @Md.Nasimuzzaman only.



Md.Nasimuzzaman @chotonmeme Turn off Light1 Expand

Figure 15 : Tweet from the user

If the operation completes successfully the base station execute the operation and re-tweet to user.

0	Internet Of Keys @internetofkeys
	Light1 is turned off
	Expand

Figure 16 : Re-tweet and confirmation of task

The base station also tweet the temperature and humidity after an interval period of time. This time interval is selected by the user. By this node the system can give an update of temperature and humidity of anyplace this system is setup



Internet Of Keys @internetofkeys Temperature: 27 degree & Humidity: 87 percent Expand

Figure 17; Output of Temperature and Humidity Sensor

VII. FURTHER APPLICATION

- a) Complete industry automation.
- b) Wireless Control of any machine via Internet.
- c) Wireless sensor networks.
- d) Official Access & attendance systems.
- e) Patient monitoring systems for doctors.
- f) Internet of keys, moneybags, kids, toys etc.

VIII. Conclusion

For very small distance like 50meter NRF transceiver are reliable but if any movable object go beyond this distance its untraceable. There are other devices like Zigbee can be used for long networking. Here limited number nodes has been used but more than 6nodes are little complex through NRF24I01 transceiver. Overall we can say that through a mesh networking we connect the network with internet and our dream of connecting each component of this world with internet can be achieved very rapidly. It's a perfect present time solution until Wi-Fi modules comes in cheap with IPv6.

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FPGA Controlled Stator Resistance Estimation In IVC of IM using FLC

By B. Mouli Chandra & Dr S. Tara Kalyani

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Keywords : fuzzy logic controller, indirect vector control, induction motor stator resistance estimation, FPGA controller.

GJRE-F Classification : FOR Code: 090699



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FPGA Controlled Stator Resistance Estimation In IVC of IM using FLC

B. Mouli Chandra ^a & Dr S. Tara Kalyani ^o

Abstract - In this paper online estimation of stator resistance in indirect vector control (IVC) of Induction motor (IM) is proposed using fuzzy logic controller (FLC). It is renowned that stator resistance of Induction motor which is sensitive to temperature rise in machine leads to performance deterioration as resistance used in controller is dissimilar from actual stator resistance. Here the effect of change in stator resistance is examined in terms of stator current, rotor flux and torque and corrected using fuzzy logic controller algorithm. The proposed algorithm was tested using MATLAB/SIMULINK software and practically implemented in Field programming Gate array (FPGA) Controller.

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I. INTRODUCTION

he superior performance of separately excited D.C motor in terms of dynamic control had become the work horses for an Industry. Later after development of power electronic converters Induction motors which are rugged in construction replaces the D.C motors even for Adjustable speed applications, i.e., D.C machine like performance was obtained by Induction motor by using vector control, where the three phase stator quantities has been resolved into d-q axes, one resembles torque producing quantities and other flux producing quantity. Therefore the independent control of torque and flux is possible in vector control. However flux position in vector control is essential. There are basically two types of vector control based on how the rotor flux is determined. In direct vector control it is found by direct flux sensors where as in indirect vector control it is found in feed forward manner. However rotor flux which is majorly affected by stator resistance variation which is dependent on temperature rises [40-50%] in machine. In [1] BEMF (Back Electromotive force Detector was proposed, in [2] calculation of flux including stator resistance was accounted, in [3] by treating the rotor speed and stator voltages and currents are the inputs to flux estimator was proposed. In [4] Stator resistance tuning based on error between actual and measured values proposed using full order observer. In [5] Model reference adaptive system (MRAS) based estimation of Rs. In this paper Flux

Author a : Research Scholar in Jawaharlal Nehru Technological University, Hyderabad, India. E-mail : bmoulichandra@yahoo.co.in Author o : Professor of EEE Department in Jawaharlal Technological University, Hyderabad, India. E-mail : tarasunder98@yahoo.co.in estimated from the voltage model is compared with the flux estimated from the current model and error and change in error is given as inputs to the fuzzy controller and the output is taken as change in stator resistance and estimated stator resistance is found by adding the actual resistance.

II. INDUCTION MOTOR MODEL WITH VECTOR CONTROL

Considering the modeling equation of Induction motor in stationary reference frame, the condition for ensuring vector control is

$$\begin{array}{l} \Psi_{dr} = \Psi_{r} \\ \Psi_{qr} = 0 \end{array} \right\}$$
 (1)

The decoupled stator voltages v_{ds} and v_{qs} are given by

$$v_{ds} = R_s i_{ds} + \sigma L_s \frac{di_{ds}}{dt} + \left(\frac{L_m}{L_r}\right) \frac{d\Psi_{r \ ref}}{dt} - \omega_s \sigma L_s i_{qs} \quad (2)$$

$$v_{qs} = R_s i_{qs} + \sigma L_s \frac{di_{qs}}{dt} + \omega_s \left(\left(\frac{L_m}{L_r} \right) \Psi_{r \ ref} + \sigma L_s i_{ds} \right)$$
(3)

$$\omega_{sl} = \left(\frac{L_{miqs\,ref}}{T_r \psi_{r\,ref}}\right) \tag{4}$$

$$\omega_s = \omega_r + \omega_{sl} \tag{5}$$

Where R_s , R_r are stator and rotor resistance values and $Tr = \frac{Lr}{R_r}$ is rotor time constant, ω_{sl} the slip frequency, ω_s and ω_r the stator rotor angular frequency, L_s , L_r , L_m the stator and rotor mutual inductance, p the number of pole pairs, , $\sigma = 1 - \frac{Lm^2}{L_sL_r}$ is the leakage coefficient. From equations (2) and (3)

$$R_s i_{ds} + \sigma L_s \frac{di_{ds}}{dt} = v_{ds} - \left(\frac{L_m}{L_r}\right) \frac{d\Psi_{r\,ref}}{dt} + \omega_s \sigma L_s i_{qs} \tag{6}$$

$$R_{s}i_{qs} + \sigma L_{s}\frac{di_{qs}}{dt} = v_{qs} - \omega_{s}\left(\left(\frac{L_{m}}{L_{r}}\right)\Psi_{r\,ref} + \sigma L_{s}i_{ds}\right)$$
(7)

From equations (6), (7) undoubtedly shows that decoupled rotor fluxes dependent on stator resistance which is assorted during running conditions of motor.

III. EFFECT OF STATOR RESISTANCE

When the Stator resistance is deviated from its actual value during the running conditions of motor, primarily it effect on rotor flux calculation, and motor toque, and stator currents by treating the inductance variation is zero in steady state condition.

IV. STATOR RESISTANCE ESTIMATION USING FUZZY CONTROLLER

It is evident from equations (6) and (7), the rotor flux estimation is affected by stator resistance variation. In order to minimize the error introduced because of stator resistance online stator resistance estimator must be integrated which is implemented by fuzzy logic controller. From the flux estimated by the voltage model equations, the current model equations are given by

$$\frac{d}{dt}\Psi_{dr} = \frac{R_r L_m}{L_r} i_{ds} - \omega_r \Psi_{qr} - \frac{R_r}{L_r} \Psi_{dr}$$
(8)

$$\frac{d}{dt}\psi_{qr} = \frac{R_r L_m}{L_r}i_{qs} - \omega_r\psi_{dr} - \frac{R_r}{L_r}\psi_{qr}$$
(9)

Adapting (6) and (7) equations in (8) and (9) we get reference values of decoupled stator quantities namely ids, ref and iqs, ref from which we can establish reference stator current as shown in Fig.1. ,and this reference current is compared with actual currents in motor and error in currents as well as change in error are inputs to fuzzy controller and output is taken as change in stator resistance. This change in stator resistance is added to the actual value of stator resistance which gives new estimated stator resistance which is further used in voltage model equations.

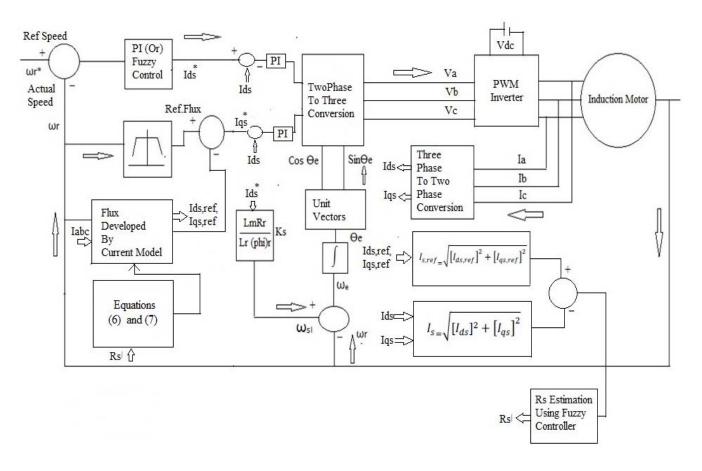


Figure 1 : Indirect Vector Control of Induction motor drive with Stator resistance Estimation

Examining the equation (8) and (9) which also dependent on Rotor resistance which also simultaneously varies with the temperature rise but in this case it with an effort to determine stator resistance variations by assuming rotor resistance effect is constant. An algorithm was developed for stator resistance estimation shown in Fig.2. In the present controller Mandani Fuzzy controller method was used for the estimation of stator resistance. It employs two inputs one is error produced by reference current generated by current model and actual feedback motor currents and the other is change in error produced by same. The rule base acts upon the inputs to produce the given outputs. The linguistic labels are divided into seven groups. They are Negative big, Negative medium, Negative small, Zero, Positive small, Positive medium, Positive big, which are generally expressed as NB,NM,NS,ZE,PS,PM,PB respectively. The rule base mapping of fuzzy inputs to derive require output is shown in table.1. Normally the output obtained produced is fuzzy in nature and has to be transformed into crisp value by using defuzzification method. Here Mean of Maximum method is used at the defuzzification stage.

Table 1 Computation	n of outputs using fuzzy rules	
Table T, Computation		

e/∆e	NB	NM	NS	ZE	PS	PM	PB
NB	NB	NB	NB	NB	NM	NS	ZE
NM	NB	NB	NM	NM	NS	ZE	PS
NS	NB	NM	NB	NB	ZE	PB	PM
ZE	NB	NM	NS	ZE	PB	PM	PB
PS	NM	NB	ZE	PB	PB	PM	PB
PM	NS	ZE	PS	PM	PM	PB	PB
PB	ZE	PS	PM	PB	PB	PB	PB

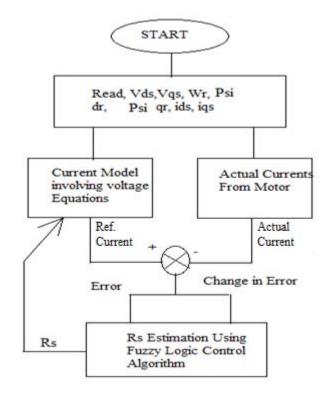


Figure 2 : Stator Resistance Algorithm

V. Simulation and Experimental Analysis

The performance of 1H.P 3-φ Slip ring Induction motor with Indirect Vector control is simulated using MATLAB/Simulink software. After obtaining the satisfactory results, with an effort to analyze the performance of Induction motor with stator resistance variation an additional resistance is added in terms of step manner the response of rotor flux, torque, and steady state stator currents were analyzed. Initial stator resistance 10.6Ω , an additional resistance of 5Ω is added in step manner, the response in torque is decreased to be 32 N-m from 33.075 N-m, and similarly the rotor flux deviates to 1.08T from its actual value of 0.9T, correspondingly the stator current deviated to 2.1A from its rated value of 2.4A. Next the same results were analyzed experimentally using SPATRAN 3A FPGA Controller with the full rated torque of 33.075N-m. In this case to examine the effect of stator resistance variation an additional resistance of 5Ω is added abruptly in series with the star connected stator winding and abrupt changes in rotor flux, motor torgue, and stator currents were experimentally verified and found to be similar to simulated results. Next by implementing Stator resistance algorithm using Fuzzy logic control stator resistance was estimated and adapted to current modeling equations, so estimated stator resistance was found to similar to actual resistance value and thus performance of machine was improved.

Table 2 : Induction motor parameters

3 phase voltage	415V
Rated Current	2.4A
Number of poles	4
Rotor resistance	18.1 Ω
Stator resistance	10.6 Ω
Stator Inductance	0.654H
Rotor Inductance	0.311H
Rated torque	33.075N-m



Figure 3 : Experimental Setup of Indirect Vector control with stator resistance estimation

vi. Results

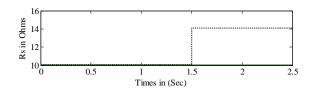
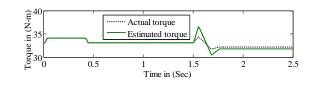
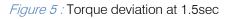


Figure 4 : Change in Stator Resistance at 1.5sec





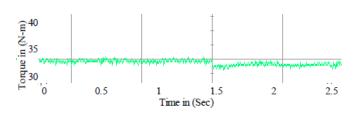


Figure 6 : Torque deviation (Experimental)

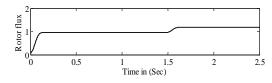


Figure 7 : Rotor Flux deviation at 1.5sec

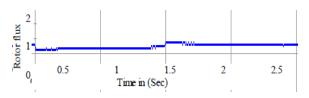


Figure 8 : Rotor Flux deviation at 1.5sec (Experimental)

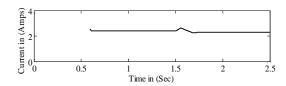


Figure 9 : Deviation in Current at 1.5sec

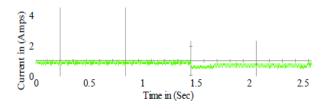


Figure 10 : Deviation in Current at 1.5sec (Experimental)

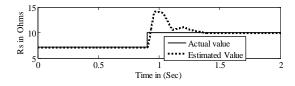


Figure 11: Estimated value converges to actual value adapted at 0.9sec

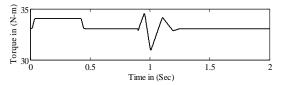


Figure 12 : Torque compensates at 0.9sec

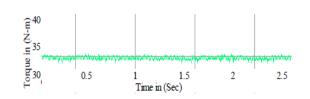


Figure 13 : Torque compensates at 0.9sec(Experiment)

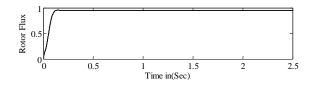


Figure 14 : Flux compensates at 0.9sec

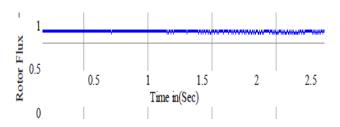


Figure 15 : Flux compensates at 0.9sec (Experimental)

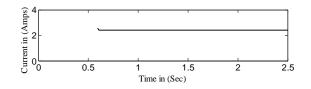


Figure 16 : Stator current compensates at 0.9 sec

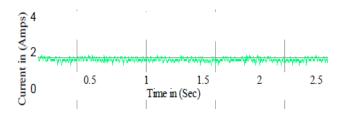


Figure 17 : Stator current compensates (Experiment)

VII. Conclusion

The main drawback of Indirect Vector control technique is stator and rotor resistance variations. In the paper the effect of stator resistance is investigated using MATLAB/Simulink Software as well as experimentally by using FPGA SPATRON 3A controller and also compensated by developing Fuzzy Algorithm.

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BER Analysis of MIMO-OFDM System using Alamouti STBC and MRC Diversity Scheme over Rayleigh Multipath Channel

By Ripan Kumar Roy & Tushar Kanti Roy

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Abstract - This paper represents a bit error rate performance analysis of multiple-input-multiple-output orthogonal frequency division multiplexing (MIMO-OFDM) system with Alamouti Space Time Block Code (STBC) and Maximal Ratio Combining (MRC) diversity scheme over Rayleigh fading channel. Recently, Alamouti STBC has gained much attention as an effective transmit diversity scheme to provide reliable transmission with high peak data rates to increase the capacity of wireless communication system. In this paper, the analysis of Alamouti STBC is used in MIMO-OFDM system to assure transmit diversity and the receive diversity is resolved with MRC diversity technique. For a fixed number of transmit antennas, the performance of Alamouti STBC is analyzed in terms of probability of bit error and diversity gain for a Rayleigh fading channel. At the receiving end, the signals received from multiple paths are weighted and summed in accordance with MRC scheme which provides maximum performance improvement by maximizing the SNR of the MIMO-OFDM system. The simulated results depict that the proposed MIMO-OFDM system concatenated with Alamouti STBC and MRC outperforms conventional SISO-OFDM, MISO-OFDM with Alamouti STBC and SIMO- OFDM with MRC technique in a scattering environment.

Keywords : Alamouti STBC, BPSK modulation, BER, MRC diversity, MIMO, OFDM, Rayleigh channel, SNR.

GJRE-F Classification : FOR Code: 090699

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Ripan Kumar Roy ^a & Tushar Kanti Roy ^o

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Keywords : Alamouti STBC, BPSK modulation, BER, MRC diversity, MIMO, OFDM, Rayleigh channel, SNR.

I. INTRODUCTION

rthogonal frequency division multiplexing (OFDM) is an emerging technique for high data rate wireless communication systems over frequency selective channels and can be considered as one of the most promising techniques for future wireless system. However, it is well known that OFDM-based systems are sensitive to the inter-carrier interference (ICI) generated by a carrier frequency offset (CFO), which degrades the error probability performance for both single-antenna OFDM systems [1]. Moreover, in a multipath fading environment, performances of OFDM system in a wireless channel are severely degraded by random variations in the amplitude of the received signals as well as by the presence of inter-symbolinterference (ISI) and inter-carrier-interference (ICI) which also limit the OFDM system performance. To address

Author o : Assistant Professor, Department of ETE, Rajshahi University of Engineering & Technology (RUET), Rajshahi-6204, Bangladesh. E-mail : roy_kanti@yahoo.com these challenges, a promising combination has been exploited [2], namely, MIMO with OFDM which has already been adopted for present and future broadband communication standards such as LTE or WiMax.

Alamouti coded OFDM is one type of MISO-OFDM system using the Alamouti code proposed by Siavash M .Alamouti in 1998 as a space time block code for transmit diversity which uses two transmit antennas and one receive antenna [3]. A simple space-time coded orthogonal frequency division multiplexing (OFDM) transmitter diversity technique for wireless communications over frequency selective fading channels is presented in [4]. The BER performance of an OFDM system with diversity, in particular Orthogonal Space Time Block Code (OSTBC) systems have been analyzed including a broadband nonlinear power amplifier and closed-form expressions is analyzed in [5]. In [6], a detailed study of diversity coding for MIMO systems including Alamouti's STBC for 2 transmit antennas as well as orthogonal STBC for 3 and 4 transmit antennas was explored.

However, it is well known that MRC as receive diversity provides the maximum performance relative to all other diversity combining schemes by maximizing the SNR at the combiner output. Recently, in the advanced mobile systems, MRC scheme shows the best performance and it tends to be the mostly employed among other diversity schemes [7]. A BER of OFDM with MRC diversity and pulse shaping in Rayleigh fading environments was analyzed in [8].

Although, the performance of Alamouti STBC and maximal ratio combining has been investigated, their performance evaluation and application to OFDM system are not available in the literatures [4, 5, 7, 12]. The works in this paper are as follows: Firstly, the probability of error and hence effective SNR expressions are derived for a multiple-input-multiple-output (MIMO) OFDM system employing the MRC diversity technique as receive diversity and Alamouti Coded OFDM as transmit diversity. Secondly, MATLAB simulations are represented to evaluate the BER with respect to SNR to analyse the MIMO-OFDM system performance applying both Alamouti STBC and MRC diversity over Rayleigh fading channel. Thirdly, a comparison among the SISO, MISO, SIMO and MIMO in OFDM system is made that ensures MIMO-OFDM is the preferable technique for

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present and future broadband communication standards such as Long Term Evolution (LTE) or Worldwide Interoperability for Microwave Access (WiMax).

The rest of the paper is organized as follows: Section II-III represents OFDM system model with MIMO implementation. Section IV gives a simple overview about the Raleigh multipath fading channel. In section V-VI, Alamouti STBC and MRC diversity are discussed in OFDM application. The simulated results are represented and discussed in section VII. At last, a conclusion of the research work is made in section VIII.

II. Ofdm System Model

OFDM is simply defined as a form of multicarrier modulation where the carrier spacing is carefully selected so that each subcarrier is orthogonal to the other subcarriers. The architectures of a typical OFDM transmitter and receiver are shown as an OFDM transceiver in Fig-1. In the transmitting end, the incoming modulated serial bits are converted into parallel streams by using a serial to parallel converter. These parallel bit streams are subjected to Inverse Fast Fourier Transform (IFFT) block for baseband OFDM modulation. To prevent overlapping of the data at the receiver, Cyclic Prefix (CP) is inserted whose duration is one fourth of the total OFDM symbol duration. The modulated data are sent to the channel through a digital-to-analog converter. At the receiver side, firstly the data is received through N linear receivers followed by a linear combiner. This linear combiner is designed in such a way that the output SNR is maximized at each instant of time. Then this data is converted again to the digital domain by passing it through an analog to digital converter. After removing the cyclic prefix, data are again converted into serial to parallel by a serial-toparallel converter. These parallel bit streams are demodulated using Fast Fourier Transform (FFT) to get back the original data by converting parallel bit streams into a serial bit stream.

Denote X_l (*l*=0, *1*, 2,...., *N*-1) as the modulated symbols of the light transmitting subcarrier of OFDM symbol at the transmitter, which are assumed to be independent, zero-mean random variables, with average power σ_x^2 . The complex baseband OFDM signal at output of the IFFT can be written [13] as:

$$X_{n} = \frac{1}{N} \sum_{l=0}^{N-1} X_{l} e^{j\frac{2\pi}{N}nl}$$
(1)

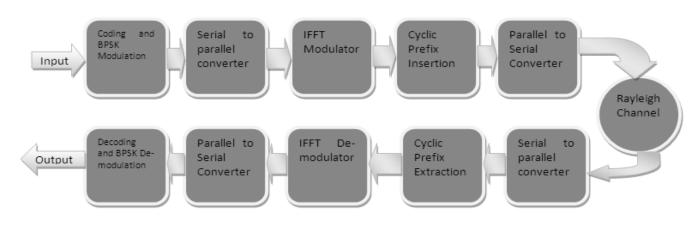
where N is the total number of subcarriers and the OFDM symbol duration is T seconds. At the receiver the received OFDM signal is mixed with local oscillator signal, with the frequency offset deviated from the carrier frequency of the received signal owing to frequency estimation error or Doppler velocity, the received signal is given by [13]:

$$\overline{x_n} = (x \otimes h_n)e^{j\frac{2\pi}{N}n\Delta fT} + z_n$$
(2)

where $h_n e^{j\frac{2\pi}{N}\Delta fT}$ and z_n represent the channel impulse response, the corresponding frequency offset at the sampling instants. Assuming that a cyclic prefix is employed; the receiver has perfect time synchronization. Then the output of the FFT in frequency domain signal on the k^{th} receiving subcarrier becomes [13]:

$$\overline{X_{k}} = \sum_{l=0}^{N-1} X_{l} H_{l} Y_{l-k} + Z_{k}$$

= $X_{k} H_{k} U_{o} + \sum_{l=0, l \neq k}^{N-1} X_{l} H_{l} Y_{l-k} + Z_{k}$ (3)



=

Figure 1 : Block diagram of an OFDM transceiver system over Raleigh multipath channel

The first term of (3) is a desired transmitted data symbol X_{k} . The second term represents the ICI from the

undesired data symbols on other subcarriers in OFDM symbol. H_k is the channel frequency response and Z_k

denotes the frequency domain of z_n . The term Y_{1-k} is the coefficient of *FFT* (*IFFT*), is given by:

$$Y_{l-k} = \frac{1}{N} \sum_{n=0}^{N-1} e^{j\frac{2\pi}{N}n(l-k+\Delta fT)}$$
(4)

When the channel is flat, Y_{l+k} can be considered as a complex weighting function of the transmitted data symbols in frequency domain.

III. MIMO-OFDM SYSTEM

Consider a MIMO-OFDM system as shown in Fig-2 which uses *N* subcarriers with N_{T} antennas at the transmitter and N_{R} antennas at the receiver. We assume independent channel coefficients in the $N_{R} \times N_{T}$ channel matrix, H_{k} for all subcarriers *k*. We assume that the sampled impulse response of the channel is shorter than the cyclic prefix. After removing the cyclic prefix, the channel for the *k*-th subcarrier after the DFT, can then be described as a $N_{R} \times N_{T}$ complex channel matrix, H_{k} . The received vector of the *k*-th subcarrier can be written as

$$R_{K} = H_{k}S_{k} + n_{k} \tag{5}$$

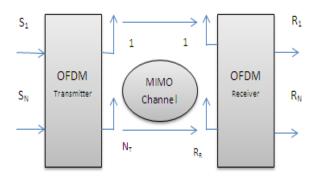


Figure 2 : MIMO-OFDM System Model

Where the channel matrix for the *k-th* subcarrier, ${\cal H}_{\!\scriptscriptstyle k}$ is a $N_{\scriptscriptstyle R} \times N_{\scriptscriptstyle T}$ channel matrix defined by

$$H_{k} = \begin{bmatrix} H_{11}^{k} & H_{12}^{k} & \cdots & H_{1N_{T}}^{k} \\ H_{21}^{k} & H_{22}^{k} & \cdots & H_{2N_{T}}^{k} \\ \vdots & \vdots & \ddots & \vdots \\ H_{N_{R}1}^{k} & H_{N_{R}2}^{k} & \cdots & H_{N_{R}N_{T}}^{k} \end{bmatrix}$$
(6)

The entries, H_{ij}^k , are the (narrow band, flat fading) complex channel gains between the f^h transmit antenna and the i^h receive antenna.

IV. Rayleigh Fading Channel Model

In this investigation, we assume that the channel is flat fading. In simple terms, it means that the

multipath channel has only one tap. Rayleigh channel is modeled with a circularly symmetric complex Gaussian random variable having the following form:

$$h = h_{re} + jh_{im} \tag{7}$$

The real and imaginary parts are zero mean independent and identically distributed Gaussian random variables with mean 0 and variance σ^2 . The probability density function of the magnitude *h* of complex Gaussian random variable has been defined which is expressed [14] as

$$P(h) = \frac{h}{\sigma^2} e^{\frac{-h^2}{2\sigma^2}}$$
(8)

The received signal in a Rayleigh fading channel is of the form,

$$y = hx + n \tag{9}$$

Here *y* is the received symbol and *h* is the complex scaling factor corresponding to Rayleigh multipath channel, *x* is the transmitted symbol and *n* is the Additive White Gaussian Noise (AWGN). The channel is randomly varying in time. It means that each transmitted symbol gets multiplied by a randomly varying complex number *h*. Since *h* is modeled as Rayleigh channel, the real and imaginary parts are Gaussian distributed having mean 0 and variance $\frac{1}{2}$.

V. Alamouti Space Time Coded Ofdm

A single-user Alamouti coded OFDM system with two transmit antennas and one receive antenna is shown in Fig. 3. Two SISO channels from the two transmit antennas to the receive antenna are assumed to be both time- and frequency selective. They both have a maximum channel delay spread that is smaller than the OFDM cyclic prefix (CP) length L.

We assume the OFDM system has N subcarriers, N_A of which are active. The remaining $N_V = N - N_A$ virtual subcarriers are used as frequency guard bands, with $N_V / 2$ virtual carriers on both ends of the spectral band. The bit streams at the transmitter are grouped and mapped into complex symbols. Since we assume the channel delay spread is smaller than the CP length L, after removing the CP at the receiver, it is enough to consider only the two consecutive OFDM symbols which constitute an Alamouti code word.

Assume S_{i} , i = 1, 2 are the two consecutive OFDM symbols which can be written as

$$s_{i} = \left[O_{N_{V}/2 \times 1}^{T} \overline{s}_{i}^{T} O_{N_{V}/2 \times 1}^{T} \right]$$
(10)

where the 0's indicate the guard bands and s_i is the data vector of length $N_A = N - N_V$, which yields of a set of data symbols with power σ_s^2 . During the first OFDM symbol period, s_1 and s_2 are sent from transmit antenna 1 and 2 respectively. Then, $-s_2^*$ and s_1^* are sent from transmit antenna 1 and 2 respectively during the second OFDM symbol period. The IFFT operation converts the frequency-domain signal to a time-domain signal. After the parallel / serial conversion, the CP is added and the overall N + L length vectors are sent from the two transmit antennas simultaneously. At the receiver, after removing the CP, the received signals in

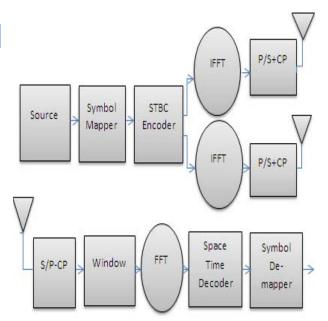


Figure 3 : Alamouti Coded OFDM System Model

two consecutive OFDM symbol periods can be written [9] as

$$y_1^{\circ} = H_{1,1}^{\circ} F^H s_1 + H_{2,1}^{\circ} F^H s_2 + n_1^{\circ}$$
(11)

$$y_{2}^{\circ} = -H_{1,2}^{\circ}F^{H}s_{2}^{*} + H_{2,2}^{\circ}F^{H}s_{1}^{*} + n_{2}^{\circ}$$
(12)

where y_i° is the received $N \times 1$ vector in t^{h} symbol period, $H_{i,j}^{\circ}$ is the time domain $N \times N$ channel matrix between transmit antenna *i* and the receive antenna in symbol period *j* and n_i° is the $N \times 1$ circularly symmetric zero-mean white complex Gaussian random noise. After the serial/parallel conversion, the FFT operation converts the received time-domain signal back to the frequency domain. Before the FFT, a time-domain receiver window is often used to make the frequency-domain channel matrix more banded [10]. In that case, we obtain.

$$y_1 = FWy_1^\circ + FWn_1^\circ \tag{13}$$

$$y_2 = FWy_2^\circ + FWn_2^\circ \tag{14}$$

where W = diag(w) with w the time-domain receiver window. Note that for classical OFDM, we have $W = I_N$. Stacking y_1 and y_2^* in one vector, we obtain.

$$\begin{bmatrix} y_1 \\ y_2^* \end{bmatrix} = \begin{bmatrix} H_{1,1} & H_{2,1} \\ H_{2,2}^* & -H_{1,2}^* \end{bmatrix} \cdot \begin{bmatrix} s_1 \\ s_2 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2^* \end{bmatrix}$$
(15)

In order to allow for low-complexity equalization, we approximate the frequency domain channel matrix $H_{i,i}$ by its banded version

$$\boldsymbol{B}_{i,j} = \boldsymbol{H}_{i,j} \otimes \boldsymbol{\theta}_{Q} \tag{16}$$

where θ_o is the $N \times N$ Toeplitz matrix.

The parameter Q is used to control how many off-diagonal elements should be included to give a good approximation of the banded frequency-domain channel matrix. As shown later, tuning Q allows for a trade-off between equalizer complexity and performance. Usually we take 1 < Q < 5 which is much smaller than the number of subcarriers N.

Rewrite (15) as

$$y = Hs + n \tag{17}$$

where H is a 2×2 block matrix of $N \times N$ approximately banded matrices with band-width parameter Q. Using a specific permutation matrix, we can now turn H into an $N \times N$ approximately banded block matrix of 2×2 matrices with block bandwidth parameter Q. Let us therefore define the permutation matrix $P_{M,N}$ as a $MN \times MN$ matrix. Left multiplying y in (17) with the permutation matrix $P_{2,N}$, we obtain.

$$y_{P} = P_{2,N^{y}} = P_{2,N} H P_{2,N}^{T} P_{2,N^{s}} + P_{2,N^{n}} = H_{PSP} + nP$$
(18)

where $H_P = P_{2,N} H P_{2,N}^T$, and $y_P = P_{2,N^y}$ and $s_P = P_{2,N^y}$ are the permuted received and transmitted

signal, in which the data from the same subcarriers of different transmit antennas are grouped together in s_P and the received data from the same sub- carriers in two

consecutive OFDM symbol periods are grouped together.

VI. Mrc Receiver Diversity

In MRC, the signals received from multiple paths are weighted according to their individual signal

voltage to noise power ratios and then summed. Here, the individual signals must be co-phased before being summed. A simple OFDM system with MRC is shown in Fig-4(a) and 4(b). Maximal ratio combining produces an output SNR equal to the sum of the individual SNRs. Thus, it has the advantage of producing an output with an acceptable SNR even when none of the individual signals are themselves acceptable. The signals at the output of the receivers are linearly combined in MRC to maximize the instantaneous Signal-to-Noise Ratio (SNR). In the assumed system, the complex envelope of the received signal of the *f*th diversity branch, which is defined in [7] by.

$$\overline{s}_{l}(t) = a_{i}e^{j\theta_{i}}\overline{S}(t) + \overline{w}_{l}(t)$$
(19)

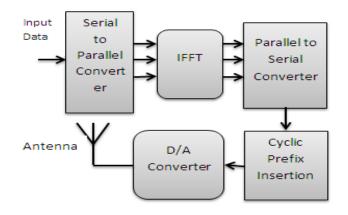
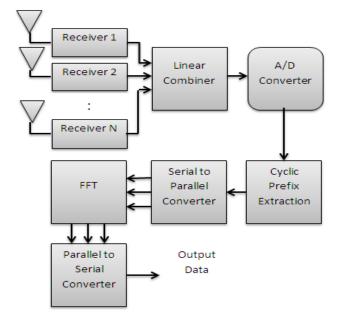
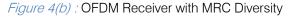


Figure 4(a) : OFDM Transmitter





where $\overline{S}(t)$ denotes the complex envelope of the modulated signal transmitted during the symbol

interval $0 \le t \le T$ for the t^{h} diversity branch, the fading is represented by the multiplicative term $a_i e^{j\theta_i}$ and the additive channel noise is denoted by $w_l(t)$. Now, at the receiver end the maximal-ratio combiner consists of N linear receivers followed by a linear combiner. Using Eq. (20) the corresponding complex envelope of the linear combiner output is defined by [7].

$$\overline{y}(t) = \sum_{i=1}^{N} a_i \overline{x}_i(t)$$
$$= \overline{S}(t) \sum_{i=1}^{N} a_i e^{j\theta_i} + \sum_{i=1}^{N} a_i \overline{w}_i(t)$$
(20)

a) Effective E_{b}/N_{o} with Maximal Ratio Combining

The effective symbol energy to noise ratio is the sum of *N* random variables. Earlier, we noted that in the presence of channel h_i the instantaneous bit energy to noise ratio at t^{th} receive antenna is

$$\gamma_i = \frac{\left|h_i\right|^2 E_b}{N_o} \tag{21}$$

Given that we are equalizing the channel with h^{H} , with the *N* receive antenna case, the effective bit energy to noise ratio is,

$$\gamma = \sum_{i=1}^{N} \frac{\left|h_i\right|^2 E_b}{N_o} \tag{22}$$

b) Error Rate with Maximal Ratio Combining (MRC)

Effective bit energy to noise ratio in N receive antenna case is N times the bit energy to noise ratio for single antenna case. In case of a two-fold diversity scheme, the combining equation is given by:

$$z_k = r_{1k} z_{2k} + r_{2k} z_{2k} \tag{23}$$

where, r_{1k} and r_{2k} represent the instantaneous envelopes of the signals received at each of the diversity branches. The SNR per bit at the output of the maximal ratio combiner can be written as:

$$\gamma = \sum_{k=1}^{N} r_k = \frac{E_b}{N_o} \sum_{k=1}^{N} R_k^2$$
(24)

where,
$$k = R^2 \frac{E_b}{N_a}$$
 is the instantaneous SNR in

the k^{th} diversity branch. The pdf of the output SNR can be written as:

$$f_{\gamma}(\gamma) = \frac{1}{(N-1)!\gamma_c^N} \gamma^{N-1} e^{\frac{-\gamma}{\gamma_c}}$$
(25)

where γ_c is the average SNR per channel. Now the conditional P_e for BPSK must be averaged

over all the possible values of $\boldsymbol{\gamma}$ to obtain the final expression for the probability of error, i.e,

$$P_e = \int_0^\infty P_e(\gamma) f_\gamma(\gamma) d\gamma \tag{26}$$

For large values of N, a closed form expression does exist for this problem given by [11]:

$$P_e \approx \left(\frac{1}{4\gamma_c}\right)^N \frac{(2N-1)!}{(N-1)!N!} \tag{27}$$

From the above equation it can be inferred that the P_e varies as γ_c raises to the N^{th} power. Thus, with MRC, the BER decreases inversely with the N^{th} power of the SNR.

VII. SIMULATED RESULTS

In order to make an investigation of performance analysis of the MIMO-OFDM system with Alamouti Space Time Block Code as the transmit diversity and MRC diversity technique as the receive diversity over a Rayleigh fading channel, we deal with MATLAB simulation using the parameters based on IEEE802.a standard. BPSK modulation was used to determine the BER versus SNR performance of the system. We consider an MIMO-OFDM system with N = 64 subcarriers, CP length L =16 over Rayleigh fading channel.

a) Simulated BER of OFDM without diversity

Here we represent the BER performance of BPSK digital modulation with a simple OFDM system over Rayleigh fading channel. The result involved with this SISO-OFDM system shows the BER performance as a function of the energy per bit to noise ratio. Fig-5 shows the BER Vs SNR curve for the OFDM system with one transmit antenna and one receive antenna (i.e., SISO-OFDM) for a Rayleigh fading environment. However, it is seen from the figure that as the energy per bit to noise ratio increases in the system, a decrement in the bit error rate is encountered.

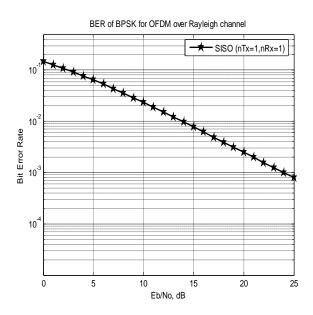


Figure 5 : BER of SISO-OFDM system over Rayleigh Fading Channel

b) Simulated BER Vs SNR of OFDM with Alamouti STBC

Alamouti Space Time Code is a simple Transmit diversity that offers a simple method for achieving spatial diversity with two transmit antennas. Using two transmit antennas and one receive antenna the scheme provides the same diversity order as maximal-ratio combining (MRC) with one transmit antenna, and two receive antennas. The Alamouti STBC as a transmit diversity associated with OFDM system forms a MISO-OFDM system we are calling here so far. The channel experienced by each transmit antenna is independent from the channel experienced by other transmit antennas. For the *I*th transmit antenna, each transmitted symbol gets multiplied by a randomly varying complex number h_i . As the channel under consideration is a Rayleigh channel, the real and imaginary parts of h_i are Gaussian distributed having mean $\mu=0$ and variance $\sigma^2=\frac{1}{2}$. The channel experienced between each transmit to the receive antenna is randomly varying in time. However, the channel is assumed to remain constant over two time slots. The simulated BER versus SNR performance of Alamouti STBC as a transmit diversity involved with OFDM system has been shown in Fig-6 in a multipath

fading channel. It is depicted from the figure that to keep a BER at 10⁻⁴, the SNR gain is 17dB and with BER at 10⁻³, the SNR gain is 12dB. Hence the simulated result shows that the more the bit error rate decreases, the curve moves more downward.

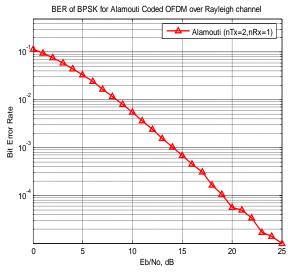


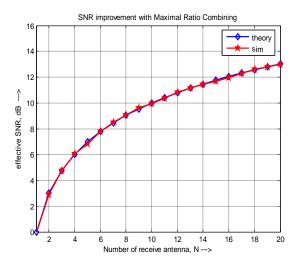
Figure 6 : Simulated BER Vs SNR of OFDM with Alamouti STBC (MISO-OFDM)

c) Simulated Result with MRC Diversity

i. SNR Improvement with MRC Diversity

The effective bit energy to noise ratio in N receiving antennas is N times the bit energy to noise ratio for single antenna case. Actually the gains are same as the improvement in receive diversity for Rayleigh fading environment which are shown in Fig-7(a) for MRC techniques respectively.

This figure shows that the effective SNR gain increases with increasing number of receiving antenna. It also illustrates that the gain increases at a high rate till the number of receiving antenna be eight.





ii. Simulated BER Vs SNR of OFDM with MRC Diversity

Here different antenna configurations such as 1x1, 1x2, 1x4 and 1x6 are used to show the

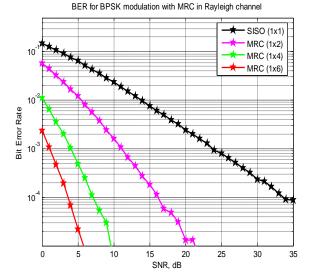


Figure 7(b) : BER for OFDM with MRC (SIMO-OFDM) in Rayleigh Fading Channel

Advantages in terms of BER of 1x6 antenna configuration over other configurations. BER Vs SNR plots for BPSK modulation over Rayleigh fading channel in this SIMO-OFDM system with MRC technique emploving different antenna configurations are presented in Fig-7(b). From these simulated results, it is clear that applying MRC technique in SIMO-OFDM system, the BER keeps on decreasing when the number of receiving antenna is increased. It is depicted in the figure that to maintain BER at 10^{-4} ; SISO(1x1), MRC(1x2), MRC(1x4) and MRC(1x6) configurations should have to keep SNR values at 34dB, 16dB, 7dB and 3.5dB respectively.

d) Simulated BER Vs SNR of OFDM by Alamouti STBC and MRC diversity

In Fig-8, we investigate the performance analysis of MIMO-OFDM system employing both the transmit diversity and receive diversity over a Rayleigh fading channel. In the transmitting end, we incorporate with Alamouti STBC as the transmit diversity with two transmit antenna and one receive antenna. With the help of simulation result, it is pointed out from the figure that the proposed Alamouti STBC gives a BER of 5.5×10^{-2} to obtain the diversity gain of 5dB. In the receiving end, the MRC diversity has been used as the receive diversity with various antenna configurations. Comparing with the Alamouti transmit diversity, the MRC with its 1×2 antenna configuration provides a diversity gain of 5dB at BER of 10⁻² which is 3dB better improvement than the two branch Alamouti STBC. This 3-dB penalty is incurred because each transmit antenna radiates half the energy in order to ensure the same total radiated power as with one transmit antenna. If the BER was drawn against the average SNR per transmit antenna, then the performance curves for the new scheme would

shift 3 dB to the left and overlap with the MRC curves. In the latter case, we examine the performance of the MIMO-OFDM system improved by both the schemes. The Alamouti STBC is confined to two transmit antenna while at the transmitter the number of receiving antenna is increased in accordance with MRC scheme.

BER for MIMO-OFDM with Alamouti & MRC over Rayleigh channel

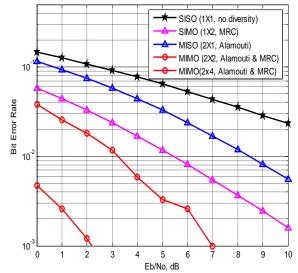


Figure 8 : BER for MIMO-OFDM with Alamouti STBC and MRC Diversity over Rayleigh Fading Channel

However by doing so, the system performance is increased significantly. It is seen from the figure that to obtain a SNR gain of 3dB with the antenna configuration $(1 \times 2, MRC)$ $(2 \times 1, Alamouti)$ of and , $(2 \times 2, \textit{Alamouti \& MRC})$; the BERs are 7×10^{-2} , 3.5×10^{-2} and 1×10^{-2} respectively. This comparison represents that the proposed MIMO-OFDM system concatenated with Alamouti STBC and MRC diversity provides maximum SNR improvement with minimum BER as compared to both MISO-OFDM or SIMO-OFDM with either Alamouti or MRC diversity respectively. The simulation result also shows us that for the antenna configuration of $(2 \times 4, Alamouti \& MRC)$, to obtain the same SNR gain i.e., 3dB; the BER could be at 7×10^{-4} which provides maintained better performance than any other configuration described so before.

VIII. Conclusion

In this paper, the performance of the MIMO-OFDM system has been analyzed with the use of Alamouti STBC and MRC technique as the transmit and receive diversity respectively over a Rayleigh multipath fading channel. The Alamouti STBC is the only STBC that can achieve its full diversity gain without needing to sacrifice its data rate, this property usually gives Alamouti's code a significant advantage over the higherorder STBCs even though they achieve a better errorrate performance. Maximal Ratio Combiner is the optimum combiner for independent Rayleigh fading and AWGN channels. The simulation result represents that the performance of the Alamouti scheme with two transmitters and a single receiver is 3 dB worse than MRC diversity with one transmit and two receive antenna. However, the 3-dB penalty is incurred because the simulations assume that each transmit antenna radiates half the energy in order to ensure the same total radiated power as with one transmit antenna. If each transmit antenna in the new scheme was to radiate the same energy as the single transmit antenna for MRC, however, the performance would be identical. From the simulation result, it is clear that the proposed MIMO-OFDM system concatenated with Alamouti STBC and MRC diversity provides maximum SNR improvement with minimum BER as compared to both MISO-OFDM or SIMO-OFDM system with either Alamouti STBC or MRC scheme respectively.

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Designing Solar and Biogas based Renewable Energy System on University Campus and its Impacts on Energy Cost after Renewable Energy Interconnection on University Campus Grid Network

By Ummay Habiba, Sujan Kumar Talukdar & Md. Rabiul Islam

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Abstract - In Bangladesh power crisis is one of the great problems. The whole of the probable sector is affected by it. The effects of power crisis is destroyed our economic growth. The total development of a country's depends on the power generation. On the other hand when the load shedding is occurred, then the students of the university are basically affected, then they do not attain their lesson attentively and study their lesson attentively. Even they do not able to complete their laboratory works, complete their thesis and their class notes and so on. But, there is a huge opportunity to back up the load shedding using Solar and Biogas energy. This paper presents a design and analysis of Solar based power plant using sunlight and Biogas based plant using Human and Kitchen waste of the University for Load shedding Backup and the cost analysis results that, the system is economically feasible for University campus.

Keywords : solar power, biogas energy, renewable energy, university campus, load-shedding back up, economical system.

GJRE-F Classification : FOR Code: 850599, 850505

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Ummay Habiba[°], Sujan Kumar Talukdar[°] & Md. Rabiul Islam^P

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Keywords : solar power, biogas energy, renewable energy, university campus, load-shedding back up, economical system.

I. INTRODUCTION

Brenewable source of energy [1]. Out of various renewable sources solar, wind, biomass can be effectively used in Bangladesh. Renewable energy practices in Bangladesh are [2]-

- Solar energy
- Biomass energy
- Wind energy
- Hydro power energy

Wind & Hydro power have a limited scope of success in Bangladesh, but could solar & biogas provides a viable solution to our existing energy problems [3].

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Solar power is not new in Bangladesh. Since, 1996 different companies have tried to market solar energy systems to the public [4]. Yet in a technologically backward country like Bangladesh the ides took a fair while to gestate. Solar and biogas energy is a renewable energy without causing pollution to the environment. Grameen Shakti and few other companies are working to provide solar biogas energy to the villages in Bangladesh. The Government of Bangladesh is working to provide more energy to its people to accelerate economic growth, social development and reduce poverty [5]. On one hand, government is working to promote the use of renewable energy technologies. On the other hand, the government works with industry public sector power utilities and private households to increase the use of energy efficient appliance and production processes and promote energy generation. Renewable energy and energy efficiency is a priority area of Bangladeshi-German development co-operation [6].

II. LITERATURE REVIEW

Sun is the richest source of energies like light and heat. Huge amount of energies are available for us to take and make big impact on our electricity requirements [7]. Our sun throws as much amount of energy on earth in one day which is equivalent to the energy requirement for the entire year. Sun surface is about 109 times bigger than surface of the earth [8]. It takes millions of years for energy generated from the center of the sun to reach to the surface of the sun [9]. Our mother earth is about 149.63 * 106 kilometers away from the sun, and light takes about 8 minutes and 31 seconds to reach to the surface of the earth. Light from the sun travels 186,262 miles per second to reach to earth [10] [11]. Energy emitted from the sun which reaches earth is in massive amount and can be extremely dangerous for mankind on earth if direct exposure is made.

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Designing Solar and Biogas based Renewable Energy System on University Campus and its Impacts on ENERGY COST AFTER RENEWABLE ENERGY INTERCONNECTION ON UNIVERSITY CAMPUS GRID NETWORK

a) Solar Energy

Solar electricity is the energy which is extracted by Sun using solar power plants.

i. Photovoltaic or Solar Cell

It is possible to convert solar energy directly into electrical energy by means of silicon wafer photovoltaic cells, also called solar cells, without any intermediate thermodynamic cycle [12]. The solar cell operates operate on the principle of photovoltaic effect, which is a process of generating an EMF as a result of the absorption of ionizing radiation. Thus a solar cell is a transducer, which converts the sun's radiant energy directly into electrical energy.

ii. Storage Device

The electricity produced by the PV modules is stored in batteries for later use when there is no sun [13]. Charge controllers regulate the rate of flow of electricity from the modules to the battery or the loads or to both simultaneously. It keeps the battery from overcharging or overloading thus prolonging its life.

iii. Inverters

The inverter converts the DC electricity produced by the solar modules into alternating current (AC) since most electrical appliances and equipment run on AC electricity [14].

b) Biogas Energy

Biogas originates from bacteria in the process of biodegradation of organic material under anaerobic (without air) conditions [15]. The natural generation of biogas is an important part of the biogeochemical carbon cycle. Methanogens (methane producing bacteria) are the last link in a chain of micro-organisms which degrade organic material and return the decomposition products to the environment. In this process biogas is generated, a source of renewable energy.

i. Hydraulic Retention Time (HRT)

The retention time is the theoretical time that a particle or volume of liquid added to a digester would remain in the digester [16]. It is calculated as the volume of the digester divided by the volume of slurry added per day and it is expressed as days. The solids retention time (SRT) represents the average time that the solids remain in the system. The solids retention time can be determined by dividing the weight of volatile solids in the system by the weight per unit time of volatile solids leaving the system. The hydraulic retention time (HRT) is equal to the solids retention time in completely mixed non-recycled digester systems.

ii. Total Solid (TS)

The amount of solid material without considering the liquid part is termed as Total Solid (TS) [16]. Total solid is the material unit that indicates the production rate of Biogas. The favourable total solid value for smooth fermentation is 8%.

iii. Fresh Discharge

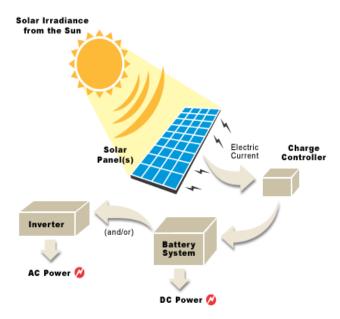
Fresh discharge is the total amount of manure including moisture content directly obtained from the com, chicken, human etc. [16].

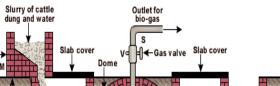
iv. Liquid Part

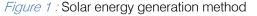
Liquid part is the amount of water to be added with fresh discharge to make the TS value is 8% [16].

Ш Research Methodology

We have designed a biogas plant with respect to human and kitchen waste of four hostel and a dormitory at a university campus and according to area of roof space of a academic building and four hostel, & We are establishing a solar panel which act as an ideal model for reducing load shedding and at the absence of load shedding it will provide electricity at national grid.







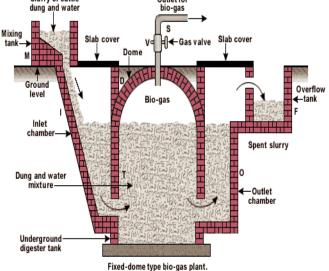


Figure 2 : Biogas based power plant design

The conversion of sunlight into electricity is defined as the solar power. It has done with the help of directly using photovoltaic (PV), or indirectly using concentrated solar power (CSP). CSP use lenses or mirrors and tracking systems to focus a large area of sunlight into a small beam. Photovoltaic Cell converts light into electric current using the photoelectric effect which is the basic principle of solar power generation.

IV. Solar Panel & Biogas Plant

The determination of Solar panel requirements and the composition of Biogas are provided below.

a) Determination of Solar Panel Requirements

For 100 Watt Solar Panel required area is = 7.392 square ft. Consider, Four Student Hostel and One Academic Building where roof space of each hostel is 4000 sq.ft. and Academic Building is 5000 sq.ft. respectively. For 4000 square ft. of every hostel 54.11 KW power can be generated and total panel required in every hostel = 540 pieces. For 5000 sq. ft. of Academic Building 67.64 KW power can be generated and total panel required in every hostel = 670 pieces.

Building Name	Load Emergency KW	Quantity of Light KW	Rating per light (Watt)	Quantity of Fan	Rating of Fan (Watt)
Student hostel 1,2,3,4	22.82	992	23	_	_
Teacher Dormitory	11.60	200	23	100	70
Academic Building	7.615	115	23	71	70
Server	15				

b) Composition of Biogas based Plant

The average composition of biogas is shown in table with respect to percentage 55%-75% biogas is methane gas.

Table 1 : Composition of Biogas

Matter	Percentage (%)
Methane (CH_4)	55-75
Carbon-dioxide (CO ₂)	25-45
Carbon mono-oxide (CO)	0-0.3
Nitrogen (N ₂)	1-5
Hydrogen (H ₂₎	0-3
Hydrogen sulphide (H ₂ S)	0.1-0.5
Oxygen (O ₂)	0.1-0.8

V. CALCULATION OF DIGESTER VOLUME

a) Calculation of Digester Volume for Hostel from Human Waste

Digester volume for student hostel-1:

Let, HRT= 40 day (for temperature 30° C).

We know, From every person 0.5 Kg waste is obtained per day.

Total discharge for human waste = (496×0.5) Kg = 248 Kg.

TS of fresh discharge = $(248 \times 0.2) = 49.6$ Kg.

To make the TS value of 8% for favourable condition we have to mix some additional water with fresh discharge. The required water added can be calculated by the following way. 8 Kg solid equivalent of influent.

49.6 Kg solid equivalent = $\frac{100 \times 49.6}{8}$ Kg = 620 Kg.

Working volume of digester = $Q \times HRT = 620 \times 40 =$ 24.8 m³.

From geometrical assumption,

 $V_{gs} + V_f = 80\%$ of V

or, V =
$$\frac{24.80}{0.80}$$
 = 31 m³

Similarly, For hostel 2, V=31 m³

& For hostel 3, $V = 31 \text{ m}^3$

& For hostel 4, $V = 31 \text{ m}^3$

Parameter of digester volume for hostel 1 from human waste:

Since, $V = 31 \text{ m}^3$

Or, D= 4.10 m

Again, V₃= (3.14×D²×H)/4 = (3.14×4.10²×0.5)/4 = 6.6 m³

Here, H = 0.5m(Calculated).

Then, $f_1 = D/5 = 4.10/5 = 0.82$ m

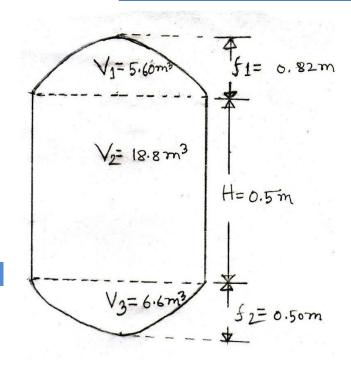
 $f_2 = D/8 = 4.10/8 = 0.50 \text{ m}$

 $V_1 = 0.0827 D^3 = 0.0827 \times 4.10^3 = 5.60 m^3$

 $V_c = 0.05 V = 0.05 \times 31 = 1.55 m^3$

Respectively, we can find these data's for Student Hall-02, 03 & 04.

Designing Solar and Biogas based Renewable Energy System on University Campus and its Impacts on ENERGY COST AFTER RENEWABLE ENERGY INTERCONNECTION ON UNIVERSITY CAMPUS GRID NETWORK





b) Calculation of Digester Volume for Kitchen

Digester volume for kitchen:

Let, HRT = 40 day (for temperature = 30° C).

We know, From every household 0.10 Kg waste is obtained per day.

Total discharge for kitchen waste = 2184×0.10 Kg =218.40 Kg.

TS of fresh discharge = $(218.40 \times 0.52) = 113.568$ Kg.

To make the TS value of 8% for favourable condition, we have to mix some additional water with fresh discharge. The required water to add can be calculated by the following way.

8 Kg solid equivalent of influent.

100×113.568 26.624 Kg solid equivalent = Kg =

1416.60 Kg.

Working volume of digester = $Q \times HRT = 1416.60$ $\times 40 = 56.784 \text{m}^3$.

From geometrical assumption,

 $V_{gs} + V_f = 80\%$ of V

or, 56.784 = 0.8 🗙 V

or, V =
$$\frac{56.784}{0.80}$$
 = 70.98 m3 =71 m3

Parameter of digester volume for Kitchen:

$$V_1 = 13 \cdot 17m^3$$

 $V_2 = 31.98m^3$
 $H = 1.13m$
 $V_3 = 25.85m^3$
 $f_2 = 0.68m$

Since, V=71 m³

D=1.3078 V^(1/3)

Or, D= 5.42 m

Again, $V_3 = (3.14 \times D^2 \times H)/4 = (3.14 \times 5.42^2 \times 1.13)/4 =$ 25.85 m³

Here, H= 1.13m(Calculated).

Then, $f_1 = D/5 = 5.42/5 = 1.08 \text{ m}$

 $f_2 = D/8 = 5.42/8 = 0.68 \text{ m}$

$$V_1 = 0.0827 \text{ D}^3 = 0.0827 \times 5.42^3 = 13.17 \text{ m}^3$$

$$V_c = 0.05 \text{ V} = 3.55 \text{ m}^3$$

c) Calculation of Digester Volume of Teacher's Dormitory

Digester volume for teacher's Dormitory:

Let, HRT = 40 day (for temperature 30° C).

We know, From every person 0.5 Kg waste is obtained per day.

Total discharge for human waste = (200×0.5) Kg = 100 Kg.

TS of fresh discharge = $(100 \times 0.2) = 20$ Kg.

To make the TS value of 8% for favourable condition we have to mix some additional water with fresh discharge. The required water to added can be calculated by the following way.

8 Kg solid equivalent of influent.

6 Kg solid equivalent = $\frac{100 \times 20}{8}$ Kg = 250 Kg.

Working volume of digester = Q \times HRT =250 \times 40= 10.00 m³.

From geometrical assumption,

Vgs + Vf = 80% of V

or, 10.00 = 0.80 X V

or, $V = \frac{10.00}{0.80} = 12 \text{ m}^3$.

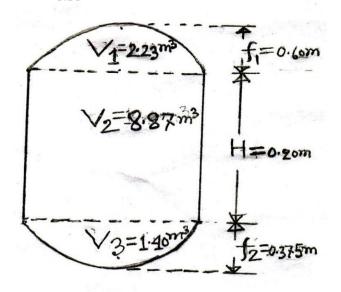


Figure 5 : Design of digester volume of Teachers' Dormitory

d) Parameter of Digester Volume for Teachers Dormitory

Since, V=12.50 m³

Then, D=1.3078 V^(1/3)

Or, D= 3 m

Again,

 $V_3 = (3.14 \times D^2 \times H)/4 = (3.14 \times 3^2 \times 0.20)/4 = 1.40 \text{ m}^3$

Here, H=.20 m(Calculated).

Then, $f_1 = D/5 = 3/5 = 0.60 \text{ m}$

 $f_2 = D/8 = 3/8 = 0.375 \text{ m}$

 $V_1 = 0.0827 D^3 = 0.0827 \times 3^3 = 2.23 m^3$

 $V_c = 0.05 \text{ V} = 0.05 \times 12.50 \text{m}^3 = 0.62 \text{ m}^3$

VI. Electricity Generation Capacity & Load Distributions

The total generation capacity from human waste, kitchen waste and solar energy is given in the table-2 shown in below.

Table 2 : Total Generation Capacity from Human waste, Kitchen Waste, and Solar Energy

Position	Туре	Waste Type	Power (KW)
Student hostel 1,2,3,4	AC	Human	8.54*4 = 34.16
Teachers Dormitory	AC	Human	3.41
Student hostel 1,2,3,4 & Teacher's Dormitory	AC	Kitchen	50.29
Student hostel 1,2,3,4	DC	Solar energy	54*4 = 216
Academic Building	DC	Solar energy	67
		TOTAL	370.86

Table 3 : Identification of Important Loads

Position	Туре	Waste Type	Power (KW)	Volume and Roof space respectively of Biogas and Solar
Student hostel 1,2,3,4	AC	Human	8.54*4 = 34.16	31m of each Digester
Teachers Dormitory	AC	Human	3.41	12m of Digester
Student hostel 1,2,3,4 & Teacher's Dormitory	AC	Kitchen	50.29	71m
Student hostel 1,2,3,4	DC	Solar energy	54*4 = 216	4000 sq. ft. of each Hostel
Academic Building	DC	Solar energy	67	5000 sq. ft.
		TOTAL	370.86	

The important loads are listed as the table-3 as shown. Now, the distributions of the loads are given below:

- *Load-1 :* Teacher's room (60) = 60× (23(Light) +70(Fan)) = 5.58 KW
- Load-2 : Chairman Room (11) = 11× (23(Light) +70(Fan)) = 1.00KW (Approximately)
- Load-3 : Server= 15 KW
- Load-4 : Classroom (22) = 22× (2×23(Light)) = 1KW
- Load-5 : Student Hostel 1,2,3,4 and teacher's dormitory: For student hostel 1,2,3,4 = 992*23 (light) = 22.80 KW. For Teachers dormitory = (200*23(light) + 100*70(fan)) = 11.60 KW, Teachers Dormitory+ Hostel = 11.60+22.80 = 34.40 KW.

2013

Year

The duration of the operation of the loads are shown in the table-4 in below.

Table 4 : Operation time of loads based on priority of loads

Time of Day	00:00 - 06:00	06:00 - 08:00	08:00 – 14:00	14:00 18:0	18:00 - 24:00
Running Load			Load1	Load	Load1
2000				Load	Load2
	Load3	Load3	Load2	Load	Load3
			Load3		
	Load5		Load4	Load	Load5
Total Load (KW)	49.40 KW	15 KW	22.58 KW	22.58 KW	55.98 KW

Load in kw 60 50 40 30 20 22.58 10 49.4 15 22.58 55.98 0 00:00 to 00:06 to 00:08 to 00:14 to 00:18 to 00:06 00:08 00:14 00:18 00:24

Figure 3 : Distribution of Renewable energy

Table 5 : Total demand of load on University campus

Building name	Load in KW	Quantity of light	Rating per light (watt)	Quantity of fan	Rating per fan (watt)
Student hostel 1,2,3,4	92.256	992	23	992	70
Teachers dormitory	11.6	200	23	100	70
Academic building	115.32	1240	23	1240	70
Server	25				

a) Load Distributions

- Load A : Teacher' room (60) =60*(23(light) +70(fan)) =5.58 KW
- Load B : Chairman Room (11) =11*(23(light) +70(fan)) =1.00 KW
- Load C : Server=25KW
- Load D : Classroom (22) = 22*(3*23(light) + 3*70 (fan)) = 7.678KW

VII. Cost Benefit Analysis & Savings

Since, 1 Unit= 1 KWh=5 Taka
From the time duration table:
In time (00:00-06:00) = 49.4×8*5=1482Taka
In time (06:00-08:00) = 15*2*5= 150 Taka
In time (08:00-14:00) = 22.58*6*5=677.40 Taka
In time (14:00-18:00) = 22.58*4*5= 451.60Taka
In time (18:00-24:00) = 55.98*6*5=1679.40 Taka
The total per month savings
=1482*30+150*30+677*30+451.60*30+1679.40*30
= 1, 33,212 Taka.

Load E : Student hostel 1,2,3,4 & teacher's dormitory :

Student hostel 1, 2, 3, 4 = 992*(23(light) +70(fan)) = 92.256 KW

Teacher's dormitory=200*23(light) + 100*70(fan) =11.6 KW

Student hostel 1,2,3,4 + Teacher's dormitory = 92.256+11.6=103.856 KW

Time of day	00:00 - 06:00	06:00- 08:00	08:00- 14:00	14:00 – 18:00	18:00 – 24:00
Running			Load A	Load A	Load A
load			Load B	Load B	Load B
	Load C	Load C	Load C	Load C	Load C
			Load D	Load D	
	Load E				Load E
Total Load (KW)	128.856 KW	25 KW	39.258 KW	9.258 KW	135.436 KW

Table 6 : Time Duration Table

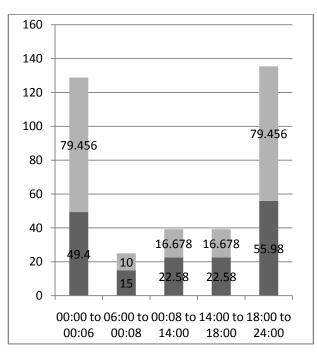


Figure 4 : Distribution of Renewable energy assuming no load-shedding

Time of Day	Load in KW (from renewable energy)	Load in KW (from BPDB)	Total cost (from renewable energy) in Taka	Total cost (from BPDB) in Taka
00:00- 06:00	49.40	79.456	49.40*6*5=1482	79.459*6*5=2383.68
06:00- 08:00	15.00	10.000	15*2*5=150	10*2*5=100
08:00- 14:00	22.58	16.678	22.58*6*5=677.4	16.678*6*5=500.34
14:00- 18:00	22.58	16.678	22.58*4*5=451.6	16.678*4*5=333.56
18:00- 24:00	55.98	79.456	55.98*6*5=1679	79.456*6*5=2383.68
			Total cost= 4440 TK/Day	Total cost= 5701.26 TK/Day

Total cost= 4440 Taka (R.E) + 5701.26 Taka (BPDB) =10141.26 Taka. Total per month cost= 10141.26*30= 304,237.8 Taka.

From renewable energy,

Per month cost= per month saving= 4430*30 = 133,200 Taka.

Assumption of load shedding period: During the load shedding, only the emergency load is connected:

Table 8 : Demand on Load-shedding period

Load shedding period	Demand (KW)
11 am – 12 pm	22.58
03 pm- 04 pm	22.58
07 pm – 09 pm	55.98

During on load shedding, Total per day cost

= (22.56*2*5+55.98*2*5) Taka= 785 Taka. Per month saving = 785*30 Taka = 23568 Taka. During the load shedding time, total saving per month on a University campus = (133200-23568) Taka = 109632 Taka.

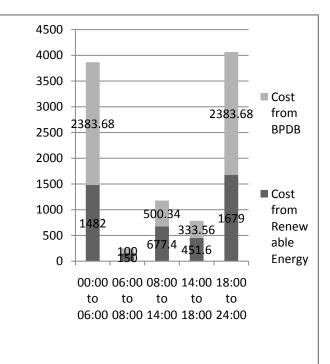


Figure 5 : Cost Analysis Curve

VIII. Conclusion

Bangladesh has a great opportunity to generate biogas and solar based power plant with the help of human waste, kitchen waste and sun shine. This renewable energy sources can be used for generating electricity and removing load shedding problems in Bangladesh. As the load shedding problems may not be removed in near future, this is the best alternative source to generate electricity. Our thesis paper represents the back-up source during load shedding at a University Campus according to biogas and solar based where human waste, kitchen waste and sun-shine is used as new materials. Complete design including system specification has been worked out. To remove load shedding problem, our represented thesis paper can be used as an ideal model for every University Campus in Bangladesh.

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Raspberry Pi Image Processing Based Economical Automated Toll System

By Md. Kawser Jahan Raihan, Mohammad Saifur Rahaman, Mohammad Kaium Sarkar & Sekh Mahfuz

American International University, Bangladesh

Abstract - The highway toll system has already been developed and widely used in many developed countries. But most of them use Radio Frequency ID. In developing countries RFID for each car does not exist. And using RFID is still a costly solution. Some of the developing countries use image processing technique to detect license plate for auto toll system. But the problem is not solved yet due to high price of host device (e.g. computer) to run. Implementation of image processed toll systems are only limited in some places. Keeping these problems in mind we have developed this project where raspberry pi will be used as host. This minicomputer has the ability of image processing and control a complete toll system. A camera will be used to take picture of the vehicle's name plate to sort the toll charge according to vehicles category. Along with multiple automatic tolls taking booth there will be a manual booth with operator also who will handle those vehicles which experience issues with any of the automatic toll taking booth.

Keywords : raspbeery pi, image processing, toll system, electronic toll collection, intelligent transportation system, vehicle identification, vehicle classification.

GJRE-F Classification : FOR Code: 080106, 290903



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Md. Kawser Jahan Raihan ^a, Mohammad Saifur Rahaman ^a, Mohammad Kaium Sarkar ^p & Sekh Mahfuz ^w

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Keywords : raspbeery pi, image processing, toll system, electronic toll collection, intelligent transportation system, vehicle identification, vehicle classification.

I. INTRODUCTION

n developing countries likes Bangladesh the amount of vehicle is increasing rapidly. According to 3rd-EST-Forum Bangladesh Country Paper, annual growth of vehicle is more than 10% and most of them are motor vehicle [1]. So the manual toll system has become a real concern in Bangladesh. Being one of the leading developing countries, Bangladesh is not able to implement automated toll system due to its vast vehicle amount and high cost of implementation on a large scale. At present Bangladesh government has taken steps to digitalize all the vehicles license plate number. So, countries with digitalized license plate numbers can use this project to implement at a negligible cost for automated toll system. There are several countries like china has developed RFID based toll system [2]. There are some researches on developing image processing based toll system like Vehicle Number Recognition System For Automatic Toll Tax Collection by Shoaib Rehman [3] but it's based on computer dependent image processing system. In this system raspberry pi based image processing system depending automated toll system has been proposed. Raspberry Pi will take

Authors α σ ρ ῶ : Dept. of Electrical & Electronic Engineering, AIUB, American International University, Bangladesh. E-mails : kawser.j.raihan@ieee.org, rufias_aiub@hotmail.com, abdul.kaium49@gmail.com, mahfuj.shekh@gmail.com picture through Wifi camera and process the image of license plate. It will connect with database and subtract the toll from user account. When the toll is received the barrier will be moved automatically and after the car has passed the barrier will be placed again automatically.

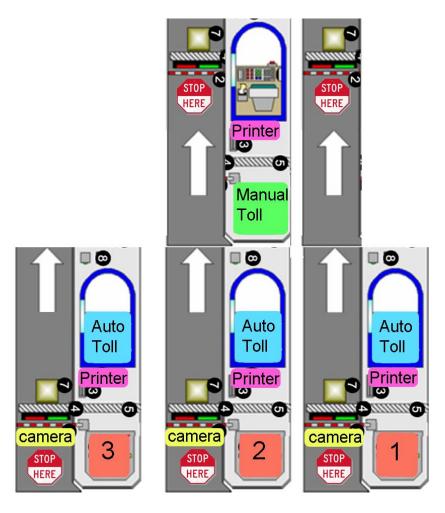


Figure 1 : Complete project outline of Automated toll system

II. Hardware Diagram

There are two types of unit in this system. One is automated toll unit and another is manually toll collecting unit. Both these units are connected internally through RF transceiver. If automated unit face any obstacles like unauthorized vehicle number, insufficient balance etc then the vehicle needs to pay toll through manual system.

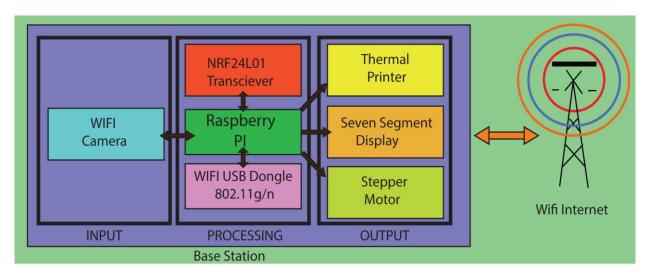


Figure 2 : Automated toll processing unit

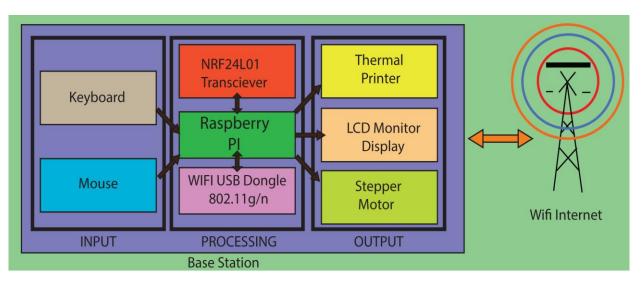
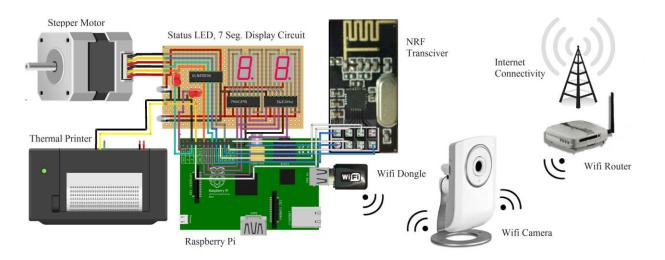


Figure 3 : Manually toll processing Unit

An automated toll processing unit consists of wifi camera to capture the license plate number. In processing there are Raspberry Pi, NRF24L01 transciever & Wifi USB dongle. In output section thermal printer, seven segment display & stepper motor is connected. Raspberry Pi receives the image from wifi camera through wifi network. And through optical character reading algorithm it identifies the license plate number. As the pi is connected with internet it transmits the number to server for matching and subtraction of toll from users account. When successful transaction occurs the stepper motor rotates 90degree clockwise and opens the barrier. Seven segment display starts back counting of 20seconds. Within 20seconds vehicle needs to pass the barrier and after 20s stepper motor again rotates 90degree anti clockwise and close the barrier. Thermal printer prints the toll token and the system is ready for the next vehicle.

If any problem occurs the vehicle is indicated to go to manual terminal for manual toll payment. Manual system also consists of Raspberry Pi, as input here keyboard and mouse is used. Operator will enter the license plate number manually. The toll amount will be entered manually and printer will print the token.

All three auto terminal is connected with manual terminal through NRF24L01 transceiver. If any problem occur auto terminals indicate that to the manual terminal. All the terminals are connected to a tweeter account. They keep updating car number, amount of toll taken or any other issue it faces on tweeter through wifi.





III. Hardware Prototype

Raspberry Pi Model B has 512Mb RAM, 2 USB ports and an Ethernet port. It has a Broadcom BCM2835 system on a chip which includes an ARM1176JZF-S 700 MHz processor, Video Core IV GPU, and an SD card. It has a fast 3D core accessed using the supplied OpenGL ES2.0 and OpenVG libraries. The chip specifically provides HDMI and there is no VGA support. The foundation provides Debian and Arch Linux ARM distributions and also Python as the main programming language, with the support for BBC BASIC, C and Perl.



Figure 5 : Raspberry Pi model B

Thermal printer is a serial printer which is used in several places like credit card machines, bus ticket counters etc. A printer has power, ground, RX & TX.





IV. Circuit Analysis

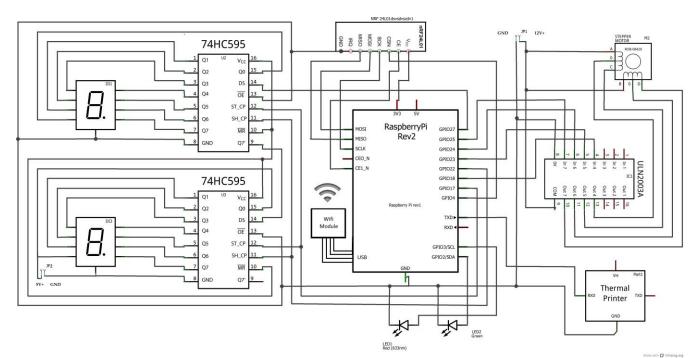


Figure 7: Schematic diagram of auto toll section

Heart of this project is raspberry pi minicomputer. To interface with NRF24I01 raspberry pi has SPI. MISO, MOSI, SCK & SS pins of NRF transceiver is connected with MISO MOSI, SCK & SS pins of raspberry pi. Uart is used to communicate with thermal printer. Rx of raspberry pi is connected with Tx of thermal printer. The tx of thermal printer is not needed. Wifi dongle is connected through USB port. Other parts like seven segment display, stepper motor are controlled through GPIO pins. In manual entry section keyboard and mouse is connected in USB port of raspberry pi. As display 24' tv is used which is connected through a AV cable. The complete system is running on Linux ARC platform.

Two shift register (74HC595) is used to control seven segment displays. The shift register holds what can be thought of as eight memory locations, each of which can be a 1 or a 0.

To set each of these values on or off, we feed in the data using the 'Data' and 'Clock' pins of the chip. The clock pin needs to receive eight pulses, at the time of each pulse, if the data pin is high, then a 1 gets pushed into the shift register, otherwise a 0. When all eight pulses have been received, then enabling the 'Latch' pin copies those eight values to the latch register. This is necessary; otherwise the wrong LEDs would flicker as the data was being loaded into the shift register. The chip also has an OE (output enable) pin, this is used to enable or disable the outputs all at once.

The ULN2003 is a high voltage, high current darlington array containing seven open collector darlington pairs with common emitters. Each channel rated at 500 mA and can withstand peak currents of 600 mA. Suppression diodes are included for inductive load driving and the inputs are pinned opposite the outputs to simplify board layout. 4 GPIO of raspberry pi is needed to drive the stepper motor.

V. Main Technology used

Image processing is the key factor of this project. In this project matlab is used to process the image [4]. In this project template matching algorithm is used. Here is the flow chart.

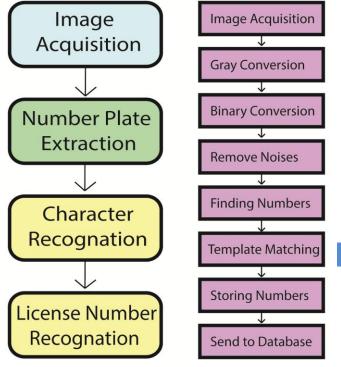


Figure 9 : Algorithm of optical character recognition

At first the front license plate number is captured through webcam and it crops an approximate area where the license plate could exist as the car stand stationary in front of the camera. Matlab code for these operations is

vid = videoinput('winvideo', 1, 'YUY2_640x480');

vid_src = getselectedsource(vid);

vid.ReturnedColorspace = 'rgb';

start(vid)

image=getsnapshot(vid);

imshow(image);

imagen = imcrop(image,[655 1153 560 85]);



Figure 10 : Cropped image of license plate

After converting it to grayscale & then binary image it looks almost same. Then the noise as the high pen is removed from the image.



Figure 11 : binary image removing noise

Through template matching in bangle the letters are saved in English in excel file. Here is the image of the output optical read digits.

	A	В	C
1	license number		
2	232813		
3			
4	1		
-			

Now this license plate number is sent to database for finding its toll amount and subtract the toll amount from users account.

Figure 12: License plate numbers stored in excel

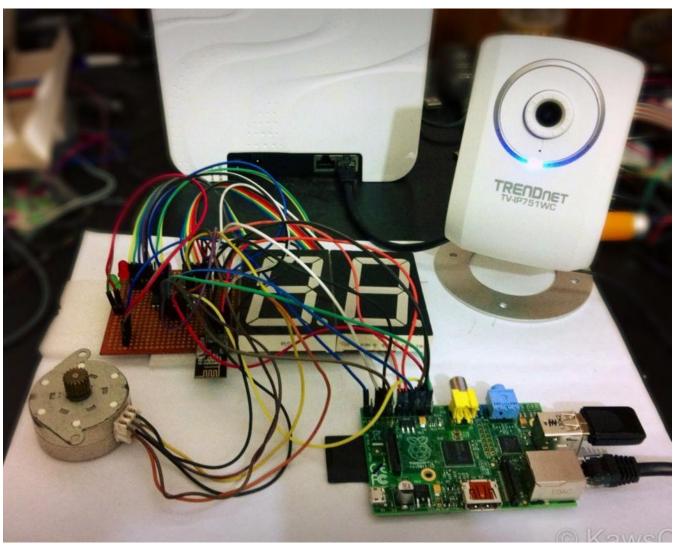


Figure 13 : Hardware implementation of complete toll system.

VI. OUTPUTS & UPDATE OF STATUS

The complete system is connected with internet. Each toll both transmits an update to tweeter. All the errors or users information is stored in data base also. But for repair, hardware faults or user fault each booth sends a tweet to main toll head office tweet account.

First we need to install some required packages, open up a terminal on the Raspberry Pi, install the Python development headers and the ip package manager:

sudo apt-get install python-pip python2.7-dev.

Whenever a vehicle passes the system update its information on tweeter. Image of tweets are shown bellow:-

10s

Tweets



Toll System @TollSystem 232893 license plate number car has cleared the toll. Expand

Figure 14 : Confirmation of payment from Tweeter

VII. FURTHER APPLICATION

- Automated train ticket system.
- Automated bus ticket system.
- Unauthorized vehicle detection system.
- Traffic signal breaking detection system.
- Parking lot automation.

VIII. CONCLUSION

Raspberry pi based image processing is an new and advance technology which can open an era of computer vision. Other gestures and different types of image processing systems can be implemented in raspberry pi which will dramatically reduce the price of the system. But still there are some drawbacks like it has very limited memory which makes it difficult to store data and process database into it [6]. If these obstacles are overcome then it will become a great standalone embedded platform for different solutions.

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(g) Discussion should cover the implications and consequences, not just recapitulating the results; conclusions should be summarizing.

(h) Brief Acknowledgements.

(i) References in the proper form.

Authors should very cautiously consider the preparation of papers to ensure that they communicate efficiently. Papers are much more likely to be accepted, if they are cautiously designed and laid out, contain few or no errors, are summarizing, and be conventional to the approach and instructions. They will in addition, be published with much less delays than those that require much technical and editorial correction.

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21. Arrangement of information: Each section of the main body should start with an opening sentence and there should be a changeover at the end of the section. Give only valid and powerful arguments to your topic. You may also maintain your arguments with records.

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