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Passenger Safety System

Automated Manual Transmission

Highlights

Development of DC Motor

Design and Motion Analysis

Discovering Thoughts, Inventing Future

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Development of DC Motor Controlled Automated Manual Transmission (AMT)

By Mr. M. S. Kumbhar, Dr. Dhananjay Panchagade
& Mr. Kapil Baidya

D. Y. Patil College of Engineering, India

Abstract- Automated Manual Transmission (AMT) has been the best competitive solution to address the problem of increasing fuel prices and to meet the emission norms. Automotive world today mostly uses Automated Manual Transmission (AMT) based on hydraulic actuators. Hydraulic actuators are costly, complex in design, bulky and invite drastic design changes in existing gearbox. AMT system which is low cost and fuel efficient has been developed using DC motor controlled electro mechanical linear actuators. The AMT system consists of three electro-mechanical linear actuators, one for clutch and two for gear shift actuations which are controlled by Transmission control unit (TCU). The wear of synchronizers can be easily taken care by reprogramming the stroke lengths of linear actuators. This system can be retro fitted in vehicle with existing manual gearbox and involve minor design changes. The focus of paper is to introduce the system developed.

Keywords: actuator, AMT, automated manual transmission, transmission.

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Mr. M. S. Kumbhar ^α, Dr. Dhananjay Panchagade ^σ & Mr. Kapil Baidya ^ρ

Abstract- Automated Manual Transmission (AMT) has been the best competitive solution to address the problem of increasing fuel prices and to meet the emission norms. Automotive world today mostly uses Automated Manual Transmission (AMT) based on hydraulic actuators. Hydraulic actuators are costly, complex in design, bulky and invite drastic design changes in existing gearbox. AMT system which is low cost and fuel efficient has been developed using DC motor controlled electro mechanical linear actuators. The AMT system consists of three electro-mechanical linear actuators, one for clutch and two for gear shift actuations which are controlled by Transmission control unit (TCU). The wear of synchronizers can be easily taken care by reprogramming the stroke lengths of linear actuators. This system can be retro fitted in vehicle with existing manual gearbox and involve minor design changes. The focus of paper is to introduce the system developed.

Keywords: actuator, AMT, automated manual transmission, transmission.

I. INTRODUCTION

Today the automobile industry is ruled by two forms of transmission, the Manual Transmission (MT) and the Automatic Transmission (AT). The MT is the most efficient transmission available as it lends itself to providing good fuel economy for the vehicles it is employed in. The MT is relatively easy to manufacture because it has very few parts. Another plus point is that the MT is reliable and easy to maintain. However, the major drawback with the MT is that it is less easy to drive than an AT especially, in congested traffic as it requires the driver to operate the clutch for each gear shift. There has been clear trend in automotive industry in recent years towards increased ride comfort and fuel efficiency keeping cost factor in mind. As the power transmission unit, transmissions play an important role in vehicle performance and fuel economy. There are currently several types of transmissions and associated technologies that offer different priorities in vehicle. Manual transmission (MT) has overall efficiency of 96 percent which is highest in all types. Belt type CVT (Continuously variable Transmission) has overall efficiency of 85 percent. Automatic Transmission has efficiency of 86 percent and Automated manual transmission (AMT) has efficiency par with manual transmission. AMT is essentially a MT with an automated

control system [1]. Combining the fuel efficiency of an MT with the seamless shifting of an AT, this approach shows excellent promise as a compact and cost-effective transmission for future vehicles.

If a transmission could have the benefits of both the MT and AT and the weaknesses of either, this would introduce a new option to the existing market segment. Many researches and studies are directed towards developing AMT. To avoid torque interruption by use of Assist clutch (ACL) by replacing fifth gear synchronizer in gearbox is add-on feature in AMT system [1]. System that allows gear shift in zero seconds was developed, thus eliminating torque interruption during gear shifting [2]. Many researches on AMT Drivetrain modeling and control have also been carried out. In studies devoted to gear shift control [3], considered reduced-order driveline models, clutch and gearbox actuator dynamics have been described by simple models or have been neglected.

Traditionally, the AMT has good fuel economy, inferior performance as compared to the MT. The latter can be optimized by refining control strategy. By automating the MT, a cheap and economic transmission is developed. The aim of this paper is to introduce the concept of DC motor controlled AMT. This paper is split into following sections: First, the objective and feature are discussed. Secondly, the concept and working principle are explained. Then gear shifting strategy is discussed. Finally the system performance is evaluated by discussing simulation based results of DC motor controlled AMT.

II. OBJECTIVE AND FEATURES

The objective of this project was to develop a system that can be retro fitted on vehicle with existing MT. The developed system should be compact, simple to manufacture, low cost and should have efficiency par with MT. The developed DC motor controlled electro-mechanical AMT has many advantages over conventional hydraulic AMT in terms of cost and complexity.

The Low cost AMT has three electro-mechanical linear actuators that are retro fitted on existing MT vehicle. Clutch actuation is done by clutch actuator by modifying existing clutch cable whereas gear select and shift actuation is done by select and shift actuators by modifying existing gear select and shift cables. The actuators are controlled by Transmission control unit

Author α: PG Student, D. Y. Patil College of engineering, Akurdi, Pune.
e-mail: mak.loves@gmail.com

Author σ: Head of Department of Mechanical Engineering, D. Y. Patil College of engineering, Akurdi, Pune.

Author ρ: Assistant General Manager, Tata Motors Ltd.

(TCU). This system helps in reducing torque interruption during gear shifts. Thus a low cost, simple and efficient AMT system has been developed which can be retro fitted on existing MT vehicle.

III. CONCEPT AND WORKING PRINCIPLE

Fig. 1 shows DC motor based AMT system concept which uses a conventional MT, actuators and TCU to automate the process of clutch actuation and

gear shifting. The clutch actuator is connected to clutch lever via clutch cable. Similarly the gear shift and select lever are connected to gear shift and select actuators via shift and select cable respectively. The driver command for gear shift is received by TCU and the corresponding command for actuators are generated after processing all input signals through a gear shifting control strategy.

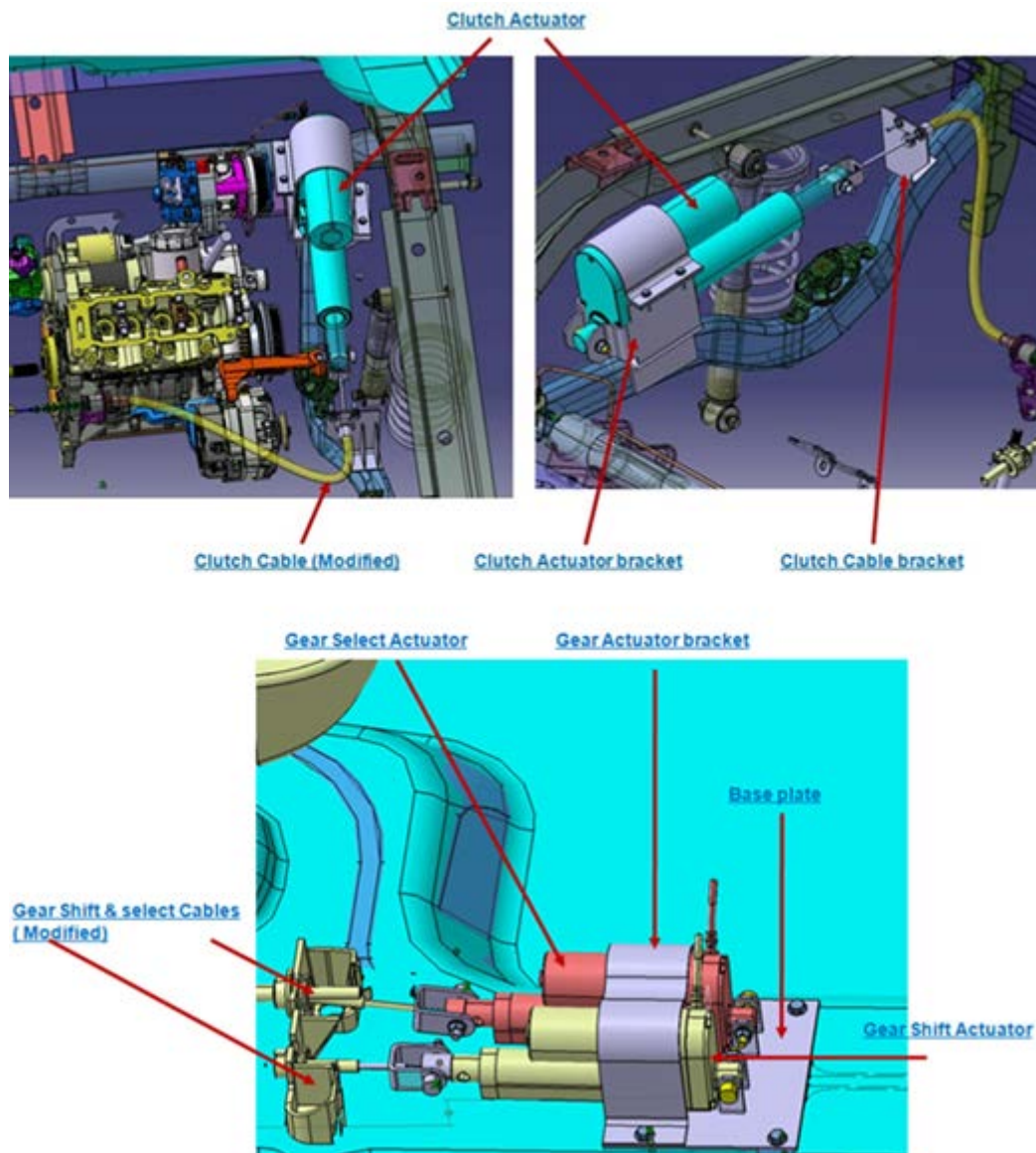


Figure 1 : DC motor controlled AMT system concept

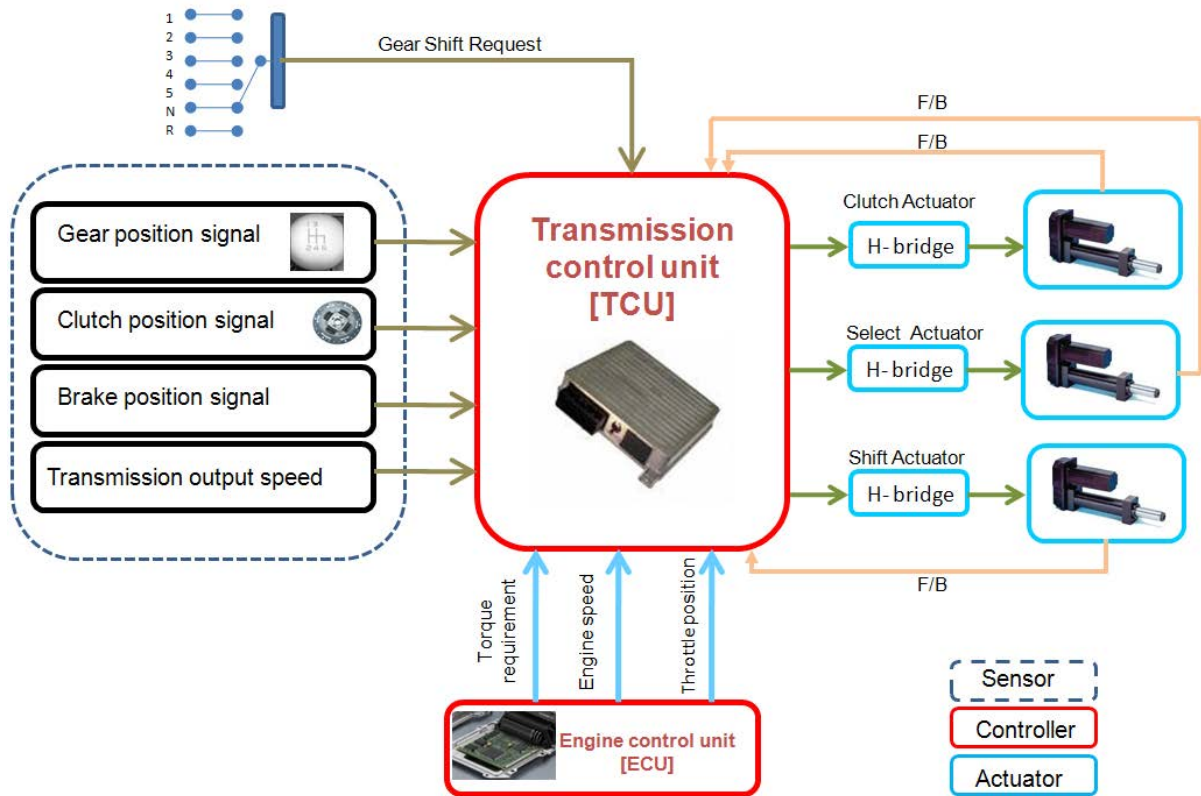


Figure 2 : DC motor controlled AMT system configuration

Fig. 2 shows the system configuration of developed DC motor controlled AMT. It consists of sensors, processors and actuators. The processor, TCU (Transmission Control Unit) gets the input signals from various sensors like gear position sensor, clutch position sensor, brake position sensor, transmission output speed and also vehicle related signals like torque requirement, engine speed and throttle position from ECU (Engine control unit) along with driver shift commands. The TCU has a gear shifting control strategy which on receiving the input signals, generates the output command signals to clutch actuator and gear shifting actuators.

The linear actuators used in our system are DC motor based. For downsizing, weight and cost reduction DC motor based linear actuators are used. DC motor requires H-Bridge circuitry. The H-Bridge circuitry receives the command signal from TCU and controls the linear actuators. The software for microcontroller is developed in such way that it gives PWM signals to the driver IC. The analog feedback signals from actuators are given to the microcontroller in H-Bridge circuitry to analyze and control linear movement of actuator. ADC (Analog to Digital converter) of microcontroller reads this analog value.

Actuators are selected based on force and linear speed required for gear shift operation. The forces were experimentally measured on clutch lever, gear shift

lever and gear select lever and linear speed was finalized from benchmarked standards. Accordingly the linear actuators were selected to suit the purpose.

IV. GEAR SHIFTING STRATEGY

Fig. 3 shows the core of control strategy for gear shifting process. First, control is transferred from the driver to the TCU, entering the torque control phase. The engine is controlled to a torque level corresponding to zero transferred torque in the transmission when the clutch is disengaged by clutch actuator. The gear shift actuator actuates followed by actuation of select gear actuator for rank selection and neutral gear is engaged. Then the speed synchronization phase is entered. Here the engine speed is controlled to track the transmission speed as per new gear desired, and the new gear is engaged after select and shift actuator actuations. Finally, the torque level is transferred back to the level that the driver demands when clutch is engaged with help of clutch actuator. It is important to minimize the total time needed for a gear shift to reduce the torque interruption. The shifting strategy is written such that gear shifting takes place in most efficient zone of engine operating condition.

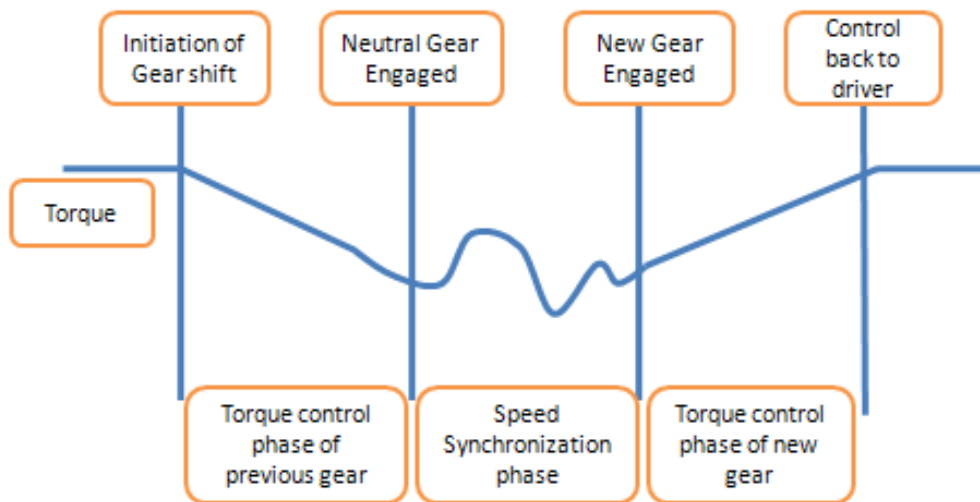


Figure 3 : Phases in Gear Shifting

V. SYSTEM PERFORMANCE

In this section we will summarize our assessment of how well the DC motor controlled AMT achieves the seamless shifting of an AT and the fuel

economy of an MT. Fig. 4 shows the torque interruption in AMT and AT. It can be seen that the total shifting time of AMT is less than MT. So traction loss is less in case of AMT and hence greater efficiency.

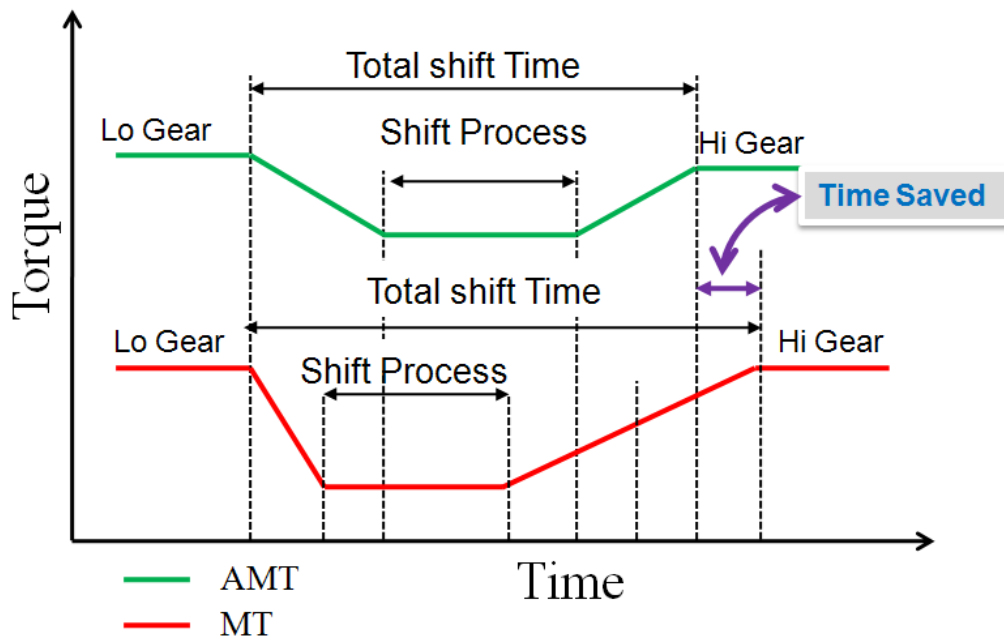


Figure 4 : Torque interruption in AMT and AT

Fig. 5 compares the DC motor controlled AMT with a conventional AT across six different performance measures which are made from the practical data collected on field. It can be seen that the up and down-shifting performance of the DC motor controlled AMT is almost the same as the AT. As there is no slippage from the torque converter that is required by an AT, the fuel efficiency and acceleration response of the DC motor controlled AMT are significantly better. On the other

hand, the torque converter on the AT gives somewhat smoother starts and more power when accelerating as compared to the DC motor controlled AMT unit but we believe based on this overall assessment that the DC motor controlled AMT has excellent potential as a compact and fuel-efficient next-generation transmission that is also affordable. This DC motor controlled unit can be a good alternative for conventional AT unit. Cost is a major factor which can lead to a breakthrough in the

Asian Market with this DC motor controlled AMT serving as the future technology for car manufactures. With minimum modification made to the existing MT unit it is

a highly feasible option in the market in terms of its reliability and easy service.

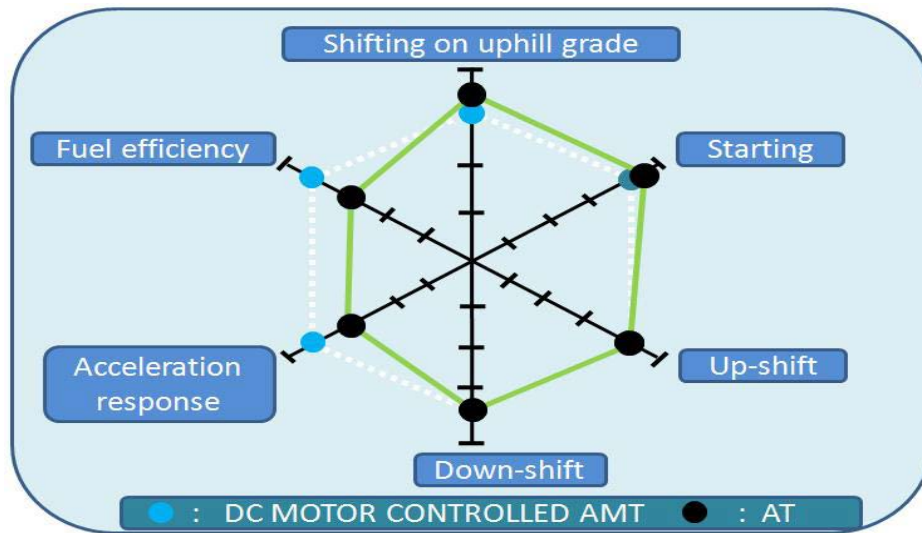


Figure 5 : Performance of Dc motor controlled AMT

A simulation was designed in the ADVISOR (2001) [4], a simulating software tool used in Matlab in order to check Engine performance between MT and our AMT system. Receiving the vehicle speed-time history as input, the simulation works backwards and calculates motion parameters as outputs. The vehicle subsystems in the simulation include engine, clutch, gearbox, differential, wheels, and axles of a default small passenger vehicle with 1400 kg vehicle mass and SI engine. Simulation was carried out on BS-IV Indian drive

cycle (Urban part) with conventional vehicle model and our AMT vehicle model with similar configurations in terms of engine and gear box parameters. Fig. 6 shows the Engine efficiency graph for MT and our AMT for urban part of BS-IV Indian drive cycle. It can be clearly seen that Engine efficiency is high in most part of drive cycle for our AMT as compared to MT for same vehicle thus confirming that in DC motor based AMT optimized gear shifting takes place in most efficient engine efficiency operating zone.

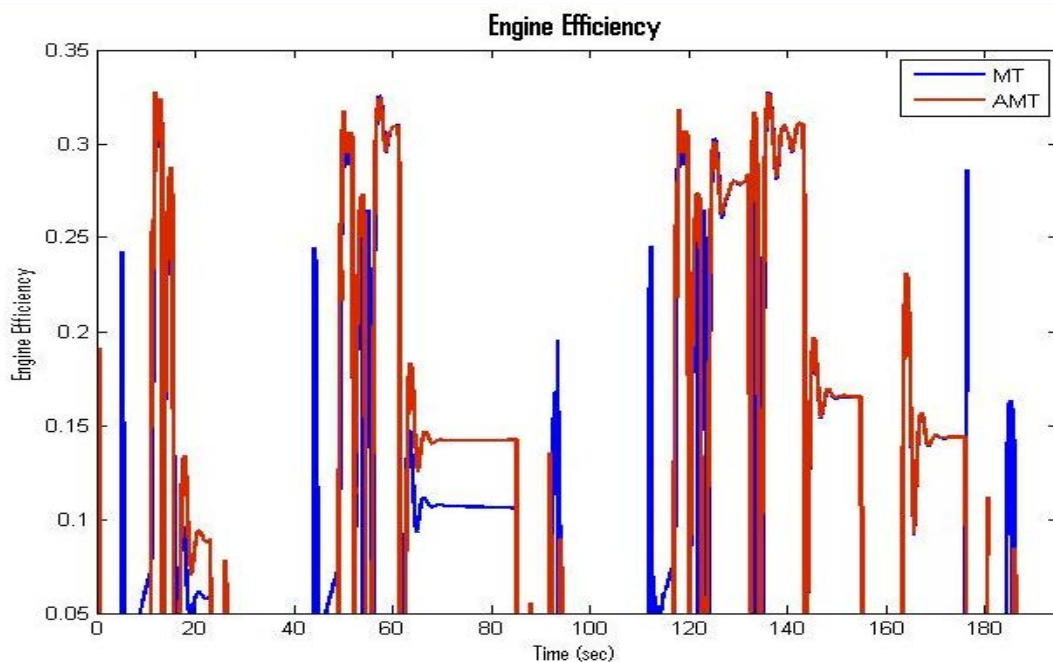


Figure 6 : Engine efficiency profile based on simulation

VI. CONCLUSION

A low cost DC motor controlled AMT concept was developed and performance was evaluated by simulation results. The simulation clearly indicates that DC motor controlled AMT is efficient as compared to MT. Low cost coupled with high efficiency makes the DC motor controlled AMT an extremely appropriate alternative for the conventional AMT. This type of alternative is a much desired and awaited demand of Asian and European Markets. Simplicity in packaging and uncomplicated serviceable design makes this concept a technology for future. This has the potential to become the next big tech revolution in the automobile world.

The Conversion of an Existing MT to DC motor controlled AMT has the Following Benefits

- Automated gear shift in optimum engine efficiency zone with improved shift quality.
- Improved fuel economy compared with torque converter AT.
- Improved acceleration performance and less traction losses.
- Easy to manufacture and is retro fit to install.

Since this concept of AMT system separates the actuator from the gearbox, the actuators can be designed independently and applied to different types of manual transmission with the same capacity. However, non-ideal mechanical connection between the actuator and gearbox brings some technical difficulties, such as cable wear, elasticity and mechanical clearance that need to be overcome.

In conclusion, the low cost DC motor controlled AMT is technically feasible, but there is still a great deal of research to be performed before commercialization.

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Vehicle Anti-Theft and Passenger Safety System

By Sagnik Basu Choudhuri, J. Sam Jeba Kumar, B. Venkatesh
& Rishabh Kumar Pandey

SRM University, India

Abstract- In pursuit of improving the safety of automobile, many companies have invested in developing various systems. Engine Immobiliser is one such innovation. Eventually, the RFID based Engine Immobiliser is becoming prone to getting hacked which compromises the very purpose of the device. Ethical hacker Karsten Nohl of Security Research Labs was able to crack the Hitag 2 car immobiliser algorithm used by Dutch firm NXP Semiconductors in around six hours. The need of the hour is to design an infallible system which enhances the security of the vehicle. We propose a system with a Face Recognition System which replaces the RFID based system. Additionally, a Passive Defense System (PDS) is also implemented that further reduces the chances of vehicle theft. The system also has a Driving Assistant Module (DAM) to help the driver drive in reduced visibility conditions like torrential rainfall, dense fog and the like. Another addition is the alcohol detection which is useful in avoiding drunken driving.

Keywords: engine immobiliser, RFID, encryption, passive defence system, WristAS, Driving While Impaired, ultrasound guidance system.

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Vehicle Anti-Theft and Passenger Safety System

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Keywords: engine immobiliser, RFID, encryption, passive defence system, WristAS, Driving While Impaired, ultrasound guidance system.

I. INTRODUCTION

a) Engine Immobilisers

The present day vehicles have a Radio Frequency Identification Device (RFID) based Engine Immobiliser. An RFID immobiliser is a chip embedded in the top part of an ignition key. This chip sends out an encrypted string of radiofrequency signals, basically a particular number of impulses broadcast on various radio frequencies to create a specific code, when the driver inserts it into the ignition-key slot. Without this code, the car either won't start or won't activate the fuel pump.

Early RFID systems, used 32-bit encryption. That means they sent a code of 32 impulses. With 32 bits in the code, there are billions of possible combinations. In newer schemes, including remote starters that let you start a car with the push of a button, the codes have 40 bits, which increases the possibilities. With so many possible codes, the system seems unbeatable (Julia Layton, 2009).

A report published by the United Nations Office on Drugs and Crime (UNODC) in 2011 highlights the large number of Vehicle Theft cases reported in India.

Author ^α: C- 275 First Floor, Sushant Lok Phase I, Gurgaon, Haryana 122009, India. e-mail: sindhurakshak22@rediffmail.com

Author ^σ: Assistant Professor, Department of Instrumentation and Control engineering, SRM University, Chennai, India. e-mail: jsjebakumar@yahoo.co.in

Author ^ρ ^ω: Undergraduate students, Department of Instrumentation and Control engineering, SRM University, Chennai, India.

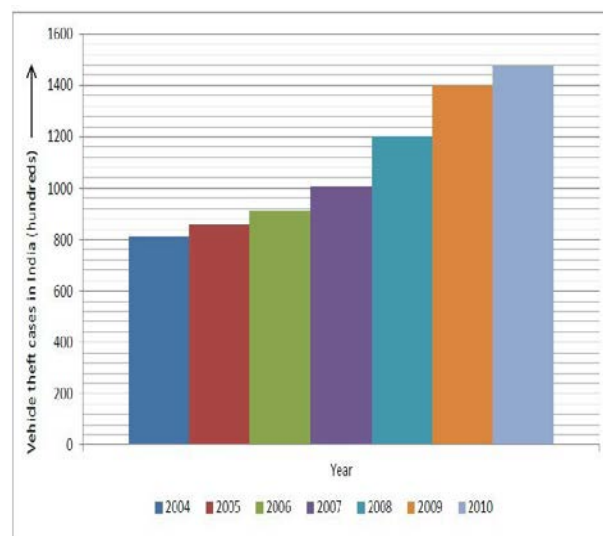


Figure 1 : Number of Vehicle Theft Cases in India

Hence, Fig 1 highlights it is a logical conclusion that the RFID Engine Immobilisers are failing in their basic task of protecting against vehicle theft.

II. IMAGE ACQUISITION & PROCESSING

Our system involves the use of Face Recognition to authenticate if the driver is allowed to run the vehicle. This can be achieved by comparing the driver's face with pre-stored templates of three people who are authorised to run the vehicle. Our system requires a camera, software where we can carry out the desired image processing techniques and finally where we can achieve the Template Matching operation based on the matching of the template and the image obtained from the camera.

The acquired image is fed to NI LabVIEW with the help of Vision Acquisition Software (VAS), which is an additional toolkit to acquire, save and display images. According to National Instruments India (n.d.) one can use NI-IMAQ to acquire images from analog, parallel digital, Camera Link cameras & NI Smart Cameras. It can also be used with NI-IMAQdx with USB3 Vision, GigE Vision, IP (Ethernet) & IEEE 1394 devices.

After selecting the source of the acquisition we have to set the acquisition type. NI Vision Acquisition Software offers a variety of solutions, Single Acquisition with processing; Continuous acquisition with inline processing; Finite acquisition with inline processing; Finite acquisition with post processing. We are using the Single acquisition with processing mode. NI Vision Acquisition Software also gives us an option to alter the

resolution settings of the camera with the option enabling of image logging.

To operate the vehicle in the night, the template match has to be carried out in the dark. The external incident light must have excellent penetration of the skin on the face to perform template matching in the night. Medical studies have shown that near infrared light compared to other bands of light, such as visible light on human skin has strong penetration power and better absorption by haemoglobin so an infrared light supports template matching in the night (Guotian Yang, 2010). According to the research by Yuan and Tang (2011), the 850 nm near infrared light has excellent skin penetration ability, relative to other band infrared light and can be better absorbed by haemoglobin.

After the driver's image is acquired, we perform Image Pre-Processing techniques on it using the NI LabVIEW Vision Development Module (VDM). In the Vision Development Module, we convert the 64 bit image to Gray Scale which is a 8 bit image and reduce the Region Of Interest (ROI) to perform the Template Matching operation.

If the template match between the pre-stored template and the camera's image is successful, the car starts else it does not.

III. STATE MACHINE IMPLEMENTATION

Mathworks India (n.d.) states that a State Machine is a model which a finite set of states and behaviors and how the system transitions from one state to another when certain conditions are true.

The system first checks if all the doors of the vehicle have been latched and the driver has fastened the seat belt as well. If both the above conditions have been met, the State Machine executes the next state else it does not.

After the first state, the State Machine executes the case where the image acquisition process initiates. The driver's image is taken and is compared with the templates already stored in the system. If the template match is successful, the car starts. If the match is not successful in the first attempt the system runs the image acquisition process for an additional ten minutes. However, if the template match is not successful at all, the State Machine executes the Third Party Login.

The Third Party Login is a special case aimed to give temporary access to people who do not have their templates stored in the system yet want to run the vehicle. This system becomes very useful in specific cases like when the technician at the repair centre wants to test the car. The Third Party Login is authenticated using a four letter password which only the owner and his family know. The Third Party Login Password can be entered from a remote location as well. If the password matches the car will start else it does not. The salient feature of this system is that in the Third Party Access

mode, the vehicle runs for a duration of one hour two times a day only. After the expiry of the allowed time, the vehicle automatically comes to a halt.

Further, the system also provides scope for a Passive Defence System (PDS) which comes into effect if the primary defence system, the Face Recognition and Authentication system fails to protect the car. The PDS interacts with the vehicle engine with the help of a redundant Controller Area Network Bus (CAN Bus) which gets activated only when the OTP is generated.

In case a thief steals the car, there is a separate system which generates a unique One Time Password (OTP). The OTP is mailed to the registered mail id of the owner using Simple Mail Transfer Protocol (SMTP), present in NI LabVIEW. The system also switches on a hidden camera when the OTP is generated. The hidden camera will take a set number of images of the thief without his knowledge. The image of the thief is stored in the memory which can be retrieved later and can be handed later to the concerned authorities. The image of the thief can also be sent to the nearest Police Station.

The system enables remote switching of the vehicle's engine off through the NI Data Dashboard App (Version 2.2), which helps us to remotely control the vehicle's engine (National Instruments, 2014). This app enables the owner to feed in the Third Party Access password or the One Time Password

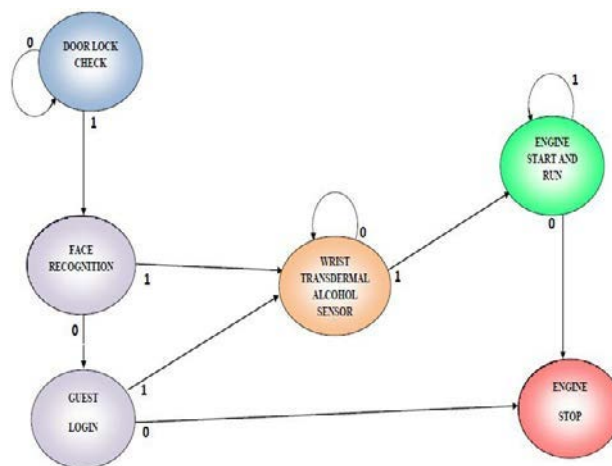


Figure 2 : Implementation of the State Machine

from a remote location. Alternatively, both the passwords can also be entered from an Internet Browser over a secured network.

IV. NEED FOR PASSIVE DEFENCE SYSTEM

When the RFID Engine Immobilisers came into the market everyone considered them to be a fool proof system that will keep vehicle theft in check. RFID based Engine Immobilisers are not safe anymore.

The Passive Defence System (PDS) as highlighted earlier comes into operation only if the Face Recognition and Authentication is breached.

a) Conditions in which we may require the PDS

- The template database is stolen.
- The primary CAN Bus is corrupted.
- Attacks due to Biometric Sensor Overtness (Anthony Delehanty, 2011).

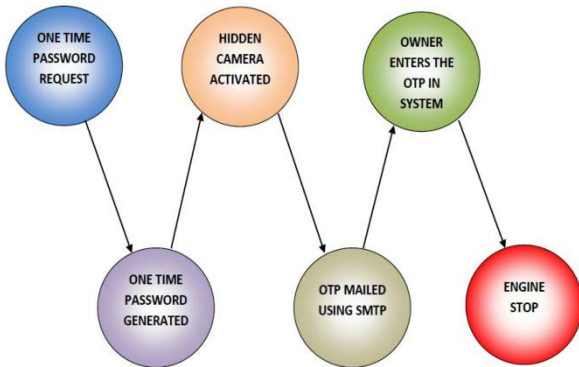


Figure 3 : The Passive Defence System (PDS)

V. ELIMINATING DRIVING WHILE IMPAIRED (DWI)

a) Introduction

Drinking While Impaired (DWI) is a serious offence which not only risks the driver's life but also of others on the road. Steps have to be taken to eliminate this menace. Most of the system available in the market today can detect whether the driver is drunk before starting the vehicle but they fail if the driver drinks while driving. Thus, if the driver drinks while driving, the vehicle does not stop.

In our quest to eliminate the above stated situation we advocate the use of Transdermal Alcohol Sensor (TAS) which tests for alcohol that is excreted through the skin. The two most effective TAS are:

- Secure Continuous Remote Alcohol Monitor (SCRAM)
- Wrist Transdermal Alcohol Sensor (WristAS)

Robertson (2006) *et al.* concluded that after more than 70 years of research and 22 peer-reviewed studies into the science underpinning this new technology, it has been established that ingested alcohol can be measured in perspiration through the process of Transdermal Alcohol Testing.

A research undertaken by Phillips & McAloon (1980) deduced that there was a statistically significant linear relationship between the concentration of ethanol in sweat and the average concentration of ethanol in blood, also called Blood Alcohol Concentration (BAC). Blood Alcohol Concentration is the amount of alcohol per fixed unit of blood.

After evaluating the needs of the system, we have selected the WristAS as the Alcohol sensor. The WristAS uses a constant hydrated platinum electrode maintained at a controlled potential and bathed in

aqueous electrolyte held in a reservoir. In the WristAS, an electrode oxidizes the ethanol and forms acetic acid that diffuses into the reservoir. The current is converted to a digital signal that is averaged and stored at preset time intervals from 30 seconds to 10 minutes. Data can be downloaded to a computer serial port (Marques & McKnight, 2007). We have selected WristAS over SCRAM owing to the following reasons:

- Smaller Size of WristAS as compared to SCRAM.
- Paced drinking with food may not trigger an alert in SCRAM (Marques & McKnight, 2007).
- WristAS continuously scans for the presence of alcohol, while SCRAM does it every half an hour. SCRAM may not be able to protect against Drinking while Driving in all conditions.

b) WristAS Implementation

The WristAS can be interfaced with the car in a multitude of ways. The first method could be pasting an elongated WristAS patch on the steering wheel of the vehicle such that it covers it fully. This method is similar to what the Japanese Automobile giant, Nissan tried in one of its concept car.

The other method could be to connect the WristAS to the Controller Area Network Bus of the vehicle. When the driver wants to drive the vehicle, he has to wear the module. Marques & McKnight (2007) stated that the device has a skin resistance/conductance sensor and a temperature sensor. These sensors, when operative, can aid in determining if a person removed or blocked the device. When in service, data from the device are periodically downloaded to a computer via a serial port interface into the CAN Bus.

The temperature sensor attached to WristAS performs a secondary function as well. It checks if someone is trying to trick the Face Recognition and Authentication by uploading two dimensional images of the people in the stored templates into the system directly. Whenever a driver links up with the WristAS, the temperature sensor gives a high output. The NI LabVIEW reads the sensor values, if there is a high output the vehicle starts else it keeps rescanning the sensor output.

VI. THE DRIVING ASSISTANT MODULE

The Driving Assistant Module (DAM) is essentially a range finder module. The Driving Assistant Module will supplement the driver when he or she is driving by providing information about the surroundings of the vehicle. When the driver knows about the obstacles surrounding of the car, the chances of accidents are bound to reduce. The system will be particularly useful while driving in adverse weather conditions like torrential rainfall, dense fog and conditions of reduced visibility like driving in the night.

In our prototype, we have used an Ultrasound sensor module to detect obstacles in the surrounding of the car. Ultrasound sensors transmit ultrasonic waves from its sensor head and again receive the ultrasonic waves reflected from an object which is the obstacle (SensorCentral.com, n.d.).

By measuring the length of time from the transmission to reception of the sonic wave, it detects the position of the object. The process is shown in Fig. 6.

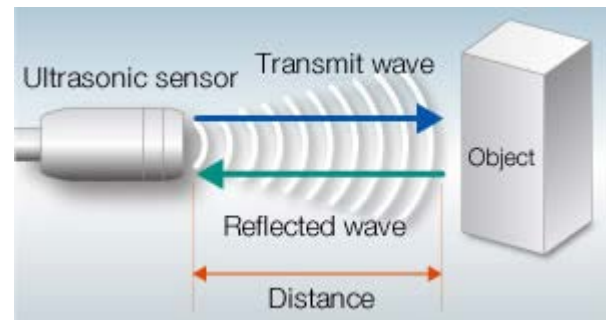


Figure 5 : Basic operation of an Ultrasound Sensor

After the data is retrieved from the sensor, it is fed to the Processing and Arduino Integrated Development Environment (IDE).

Processing is an open source programming language based on Java language and Integrated Development Environment built for the electronic arts, new media art, and visual design communities with the purpose of teaching the fundamentals of computer programming in a visual context, and to serve as the foundation for electronic sketchbooks (Wikipedia, n.d.). The user interface for the Ultrasound Sensor is made using Processing 2 IDE.

Let us consider an example which illustrates the how the distance is calculated using an ultrasound sensor.

The sensor sends an ultrasonic ping at a time t_1 and receives the bouncing ping at a time t_2 .

If we know the speed of sound, the time difference $\Delta t = t_2 - t_1$, can give us an idea of the distance of the object from the Ultrasound sensor.

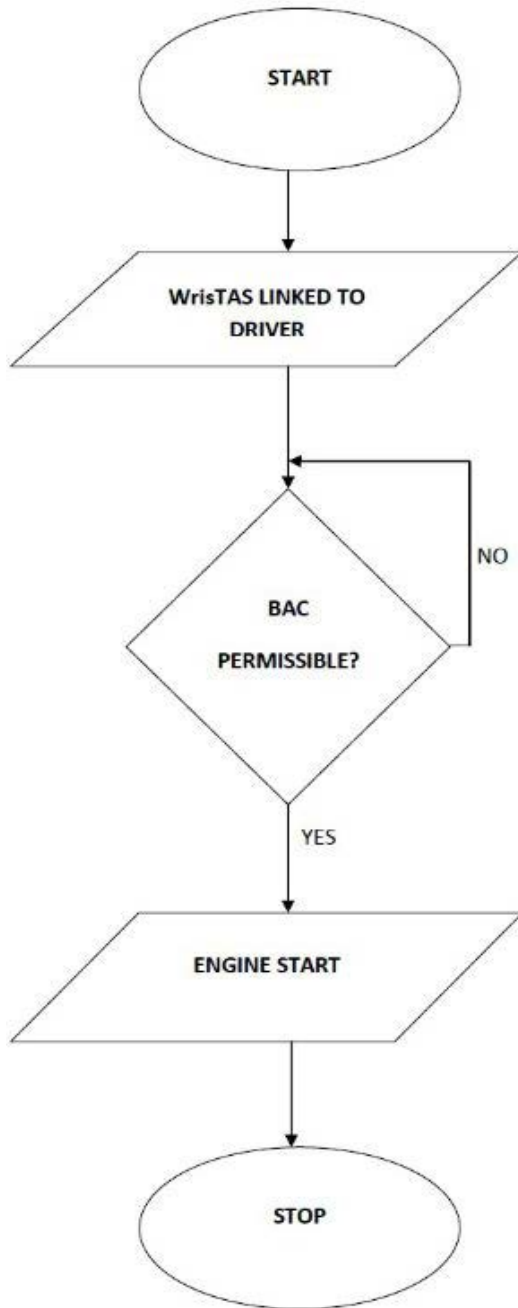


Figure 4 : Flow chart for eliminating Driving While Impaired (DWI)

The temperature sensor attached to WrisTAS performs a secondary function as well. It checks if someone is trying to trick the Face Recognition and Authentication by uploading two dimensional images of the people in the stored templates into the system directly. Whenever a driver links up with the WrisTAS, the temperature sensor gives a high output. The NI LabVIEW reads the sensor values, if there is a high output the vehicle starts else it keeps rescanning the sensor output.

If $\Delta t = 500 \mu s$, we know it took $250 \mu s$ for the ping to hit the object and another $250 \mu s$ for it to come back and strike the receiver.

The approximate speed of sound in dry air is given by the formula:

$$c = 331.3 * \sqrt{(1 + T/273)}$$

Where, c = Speed of sound in dry air

T = Temperature of dry air

At $T = 20^\circ C$, $c = 343.5 \text{ m/s}$

Converting the speed of sound from m/s into $\text{cm}/\mu s$:

$$c = 343.5 * 100 / 10^6$$

At $T = 20^\circ C$, $c = 0.03435 \text{ cm}/\mu s$

Hence, the formula to find the distance, D is

$$D = (\Delta t / 2) * c$$

$$D = 250 * 0.03435 = 8.6 \text{ cm}$$

Thus in this particular case the object is at a distance of 8.6 cm from the Ultrasound Sensor.



Figure 6 : Proposed display of Driver Assistant Module

VII. CONCLUSION

The primary focus was to replace the existing RFID based engine immobiliser with a better and foolproof system which was achieved by implementing Face Recognition as the primary defense mechanism against vehicle theft, using NI LabVIEW and its toolkits. A Third Party Access mode also been developed to help people who do not have their templates stored in the system to run the vehicle for a pre-programmed amount of time. The Passive Defense System (PDS), which includes the OTP generation and its mailing, is also implemented using the State Machine in NI LabVIEW. A Transdermal Alcohol Sensor interface is proposed which adds to the safety of the driver and the surroundings by avoiding Driving in Impaired condition. Apart from these,

an ultrasonic sensor based guidance system is also integrated to the vehicle so as to provide a guidance system to the driver during adverse cases such as heavy fog or poor visibility. All these systems work as a package and offers greater passenger safety while reducing the risk of vehicle theft.

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- Abstract Font size of 9 Bold, "Abstract" word in Italic Bold.
- Main Text: Font size 10 with justified two columns section
- Two Column with Equal Column with of 3.38 and Gaping of .2
- First Character must be three lines Drop capped.
- Paragraph before Spacing of 1 pt and After of 0 pt.
- Line Spacing of 1 pt
- Large Images must be in One Column
- Numbering of First Main Headings (Heading 1) must be in Roman Letters, Capital Letter, and Font Size of 10.
- Numbering of Second Main Headings (Heading 2) must be in Alphabets, Italic, and Font Size of 10.

You can use your own standard format also.

Author Guidelines:

1. General,
2. Ethical Guidelines,
3. Submission of Manuscripts,
4. Manuscript's Category,
5. Structure and Format of Manuscript,
6. After Acceptance.

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All authors should have been credited according to their appropriate contribution in research activity and preparing paper. Contributors who do not match the criteria as authors may be mentioned under Acknowledgement.

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- (c) Up to ten keywords, that precisely identifies the paper's subject, purpose, and focus.
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- (e) Resources and techniques with sufficient complete experimental details (wherever possible by reference) to permit repetition; sources of information must be given and numerical methods must be specified by reference, unless non-standard.
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- One should avoid outdated words.

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Acknowledgements: Please make these as concise as possible.

References

References follow the Harvard scheme of referencing. References in the text should cite the authors' names followed by the time of their publication, unless there are three or more authors when simply the first author's name is quoted followed by et al. unpublished work has to only be cited where necessary, and only in the text. Copies of references in press in other journals have to be supplied with submitted typescripts. It is necessary that all citations and references be carefully checked before submission, as mistakes or omissions will cause delays.

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1. Choosing the topic: In most cases, the topic is searched by the interest of author but it can be also suggested by the guides. You can have several topics and then you can judge that in which topic or subject you are finding yourself most comfortable. This can be done by asking several questions to yourself, like Will I be able to carry our search in this area? Will I find all necessary recourses to accomplish the search? Will I be able to find all information in this field area? If the answer of these types of questions will be "Yes" then you can choose that topic. In most of the cases, you may have to conduct the surveys and have to visit several places because this field is related to Computer Science and Information Technology. Also, you may have to do a lot of work to find all rise and falls regarding the various data of that subject. Sometimes, detailed information plays a vital role, instead of short information.

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27. Refresh your mind after intervals: Try to give rest to your mind by listening to soft music or by sleeping in intervals. This will also improve your memory.

28. Make colleagues: Always try to make colleagues. No matter how sharper or intelligent you are, if you make colleagues you can have several ideas, which will be helpful for your research.

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30. Think and then print: When you will go to print your paper, notice that tables are not be split, headings are not detached from their descriptions, and page sequence is maintained.

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- Write your paper in the form, which is presented in the guidelines using the template.
- Please note the criterion for grading the final paper by peer-reviewers.

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A purpose of organizing a research paper is to let people to interpret your effort selectively. The journal requires the following sections, submitted in the order listed, each section to start on a new page.

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The summary should be two hundred words or less. It should briefly and clearly explain the key findings reported in the manuscript-- must have precise statistics. It should not have abnormal acronyms or abbreviations. It should be logical in itself. Shun citing references at this point.

An abstract is a brief distinct paragraph summary of finished work or work in development. In a minute or less a reviewer can be taught the foundation behind the study, common approach to the problem, relevant results, and significant conclusions or new questions.

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- To the point depiction of the research
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- Shield the model - why did you employ this particular system or method? What is its compensation? You strength remark on its appropriateness from a abstract point of vision as well as point out sensible reasons for using it.
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- Present surroundings information only as desirable in order hold up a situation. The reviewer does not desire to read the whole thing you know about a topic.
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- If use of a definite type of tools.
- Materials may be reported in a part section or else they may be recognized along with your measures.

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- Describe the method entirely
- To be succinct, present methods under headings dedicated to specific dealings or groups of measures
- Simplify - details how procedures were completed not how they were exclusively performed on a particular day.
- If well known procedures were used, account the procedure by name, possibly with reference, and that's all.

Approach:

- It is embarrassed or not possible to use vigorous voice when documenting methods with no using first person, which would focus the reviewer's interest on the researcher rather than the job. As a result when script up the methods most authors use third person passive voice.
- Use standard style in this and in every other part of the paper - avoid familiar lists, and use full sentences.

What to keep away from

- Resources and methods are not a set of information.
- Skip all descriptive information and surroundings - save it for the argument.
- Leave out information that is immaterial to a third party.

Results:

The principle of a results segment is to present and demonstrate your conclusion. Create this part a entirely objective details of the outcome, and save all understanding for the discussion.

The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.



Content

- Sum up your conclusion in text and demonstrate them, if suitable, with figures and tables.
- In manuscript, explain each of your consequences, point the reader to remarks that are most appropriate.
- Present a background, such as by describing the question that was addressed by creation an exacting study.
- Explain results of control experiments and comprise remarks that are not accessible in a prescribed figure or table, if appropriate.
- Examine your data, then prepare the analyzed (transformed) data in the form of a figure (graph), table, or in manuscript form.

What to stay away from

- Do not discuss or infer your outcome, report surroundings information, or try to explain anything.
- Not at all, take in raw data or intermediate calculations in a research manuscript.
- Do not present the similar data more than once.
- Manuscript should complement any figures or tables, not duplicate the identical information.
- Never confuse figures with tables - there is a difference.

Approach

- As forever, use past tense when you submit to your results, and put the whole thing in a reasonable order.
- Put figures and tables, appropriately numbered, in order at the end of the report
- If you desire, you may place your figures and tables properly within the text of your results part.

Figures and tables

- If you put figures and tables at the end of the details, make certain that they are visibly distinguished from any attach appendix materials, such as raw facts
- Despite of position, each figure must be numbered one after the other and complete with subtitle
- In spite of position, each table must be titled, numbered one after the other and complete with heading
- All figure and table must be adequately complete that it could situate on its own, divide from text

Discussion:

The Discussion is expected the trickiest segment to write and describe. A lot of papers submitted for journal are discarded based on problems with the Discussion. There is no head of state for how long a argument should be. Position your understanding of the outcome visibly to lead the reviewer through your conclusions, and then finish the paper with a summing up of the implication of the study. The purpose here is to offer an understanding of your results and hold up for all of your conclusions, using facts from your research and generally accepted information, if suitable. The implication of result should be visibly described. Infer your data in the conversation in suitable depth. This means that when you clarify an observable fact you must explain mechanisms that may account for the observation. If your results vary from your prospect, make clear why that may have happened. If your results agree, then explain the theory that the proof supported. It is never suitable to just state that the data approved with prospect, and let it drop at that.

- Make a decision if each premise is supported, discarded, or if you cannot make a conclusion with assurance. Do not just dismiss a study or part of a study as "uncertain."
- Research papers are not acknowledged if the work is imperfect. Draw what conclusions you can based upon the results that you have, and take care of the study as a finished work
- You may propose future guidelines, such as how the experiment might be personalized to accomplish a new idea.
- Give details all of your remarks as much as possible, focus on mechanisms.
- Make a decision if the tentative design sufficiently addressed the theory, and whether or not it was correctly restricted.
- Try to present substitute explanations if sensible alternatives be present.
- One research will not counter an overall question, so maintain the large picture in mind, where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.

Approach:

- When you refer to information, differentiate data generated by your own studies from available information
- Submit to work done by specific persons (including you) in past tense.
- Submit to generally acknowledged facts and main beliefs in present tense.



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Methods and Procedures	Clear and to the point with well arranged paragraph, precision and accuracy of facts and figures, well organized subheads	Difficult to comprehend with embarrassed text, too much explanation but completed	Incorrect and unorganized structure with hazy meaning
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References	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring



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