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A Numerical Solution for the Coexisting Field of Surface and Internal Solitary Waves

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Keywords: *solitary wave, internal wave, free surface, nonlinear wave equation, numerical solution.*

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A Numerical Solution for the Coexisting Field of Surface and Internal Solitary Waves

Taro Kakinuma^α & Kei Yamashita^σ

Abstract- The numerical solutions for the coexisting fields of surface and internal solitary waves have been obtained, where the set of nonlinear equations based on the variational principle for steady waves are solved using the Newton-Raphson method. The relative phase velocity of surface-mode solitary waves is smaller in the coexisting fields of surface and internal solitary waves than in the cases without the coexistence of internal waves. The relative phase velocity of internal-mode solitary waves is also smaller in the coexisting fields of surface and internal solitary waves than in the cases without surface waves. The interfacial position of an internal-mode internal solitary wave in a coexisting field of surface and internal waves can exceed the critical level determined in the corresponding case without a surface wave. The wave height ratio between internal-mode surface and internal solitary waves is smaller than the corresponding linear shallow water wave solution, and the difference increases, as the relative wave height of internal-mode internal solitary waves is increased.

Keywords: solitary wave, internal wave, free surface, nonlinear wave equation, numerical solution.

I. INTRODUCTION

Surface and internal waves coexist in the ocean with stratification development. The behaviors of waves in such coexisting fields of surface and internal waves show more complicated characteristics than those which exist individually. For instance, the traveling time for a distant tsunami is delayed due to the influence of density stratification in the ocean, according to the theoretical analyses for linear waves^{1), 2)}. Fructus and Grue³⁾ used a pressure field for two-layer fluids sandwiched by two fixed horizontal plates, to obtain the surface waves caused by large-amplitude internal waves. A coexisting field of surface and internal waves can be established even in nearshore zones, where surface long waves have great influence on sediment motion and coastal structures as an external force, and conversely, internal waves may greatly affect the coastal The upper and 1st layer

environment through water salinity and temperature. Surface and internal waves, however, have often been studied individually: especially, the nonlinear characteristics of surface and internal waves have been investigated independently by e.g. Longuet-Higgins and Fenton⁴⁾ and Choi and Camassa⁵⁾. In also the research by Fructus and Grue³⁾ mentioned above, the interaction between surface and internal waves has not been considered.

In the present study, solitary wave solutions for coexistence fields of surface and internal waves have been numerically calculated using the set of nonlinear wave equations based on the variational principle⁶⁾ for two-layer fluids with a free water surface, to examine the characteristics of surface and internal solitary waves, where the phases of both the steady surface and internal solitary waves are assumed to be the same, with a surface mode or an internal mode.

II. FUNDAMENTAL EQUATIONS

The motion in two-layer inviscid and incompressible fluids is assumed to be irrotational. The upper and lower layers are called the first and second layers, respectively, and the fluids in each layer do not mix even in motion. The velocity potential ϕ_i in the i -th layer ($i = 1$ or 2) is expanded into the power series of vertical position z , in the manner similar to that for the derivation process of nonlinear surface wave equations⁷⁾, as

$$\phi_i(\mathbf{x}, z, t) = \sum_{\alpha_i=0}^{N_i-1} [f_{i,\alpha_i}(\mathbf{x}, t) \cdot z^{\alpha_i}], \quad (1)$$

where N_i is the number of terms and $f_{i,\alpha}$ is the weightings of the power series.

By applying the variational principle, the nonlinear surface/internal wave equations⁶⁾ are obtained as follows:

$$\zeta^{\alpha_1} \frac{\partial \zeta}{\partial t} - \eta^{\alpha_1} \frac{\partial \eta}{\partial t} + \frac{1}{\alpha_1 + \beta_1 + 1} \nabla \left[(\zeta^{\alpha_1 + \beta_1 + 1} - \eta^{\alpha_1 + \beta_1 + 1}) \nabla f_{1,\beta_1} \right] - \frac{\alpha_1 \beta_1}{\alpha_1 + \beta_1 - 1} (\zeta^{\alpha_1 + \beta_1 - 1} - \eta^{\alpha_1 + \beta_1 - 1}) f_{1,\beta_1} = 0, \quad (2)$$

$$\zeta^{\beta_1} \frac{\partial f_{1,\beta_1}}{\partial t} + \frac{1}{2} \zeta^{\beta_1 + \gamma_1} \nabla f_{1,\beta_1} \nabla f_{1,\gamma_1} + \frac{1}{2} \beta_1 \gamma_1 \zeta^{\beta_1 + \gamma_1 - 2} f_{1,\beta_1} f_{1,\gamma_1} + g \zeta = 0, \quad (3)$$

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$$\eta^{\beta_1} \frac{\partial f_{1,\beta_1}}{\partial t} + \frac{1}{2} \eta^{\beta_1+\gamma_1} \nabla f_{1,\beta_1} \nabla f_{1,\gamma_1} + \frac{1}{2} \beta_1 \gamma_1 \eta^{\beta_1+\gamma_1-2} f_{1,\beta_1} f_{1,\gamma_1} + g\eta + \frac{p}{\rho_1} = 0, \tag{4}$$

The lower and 2nd layer

$$\eta^{\alpha_2} \frac{\partial \eta}{\partial t} + \frac{1}{\alpha_2 + \beta_2 + 1} \nabla \left[(\eta^{\alpha_2+\beta_2+1} - b^{\alpha_2+\beta_2+1}) \nabla f_{2,\beta_2} \right] - \frac{\alpha_2 \beta_2}{\alpha_2 + \beta_2 - 1} (\eta^{\alpha_2+\beta_2-1} - b^{\alpha_2+\beta_2-1}) f_{2,\beta_2} = 0, \tag{5}$$

$$\eta^{\beta_2} \frac{\partial f_{2,\beta_2}}{\partial t} + \frac{1}{2} \eta^{\beta_2+\gamma_2} \nabla f_{2,\beta_2} \nabla f_{2,\gamma_2} + \frac{1}{2} \beta_2 \gamma_2 \eta^{\beta_2+\gamma_2-2} f_{2,\beta_2} f_{2,\gamma_2} + g\eta + \frac{1}{\rho_2} [p + (\rho_2 - \rho_1)gh_1] = 0, \tag{6}$$

where ζ , η , b , ρ , h_1 , and ρ_i are the water surface displacement, interface displacement, seabed position, pressure at the interface, the upper-layer thickness in still water, and fluid density of the i -th layer, respectively. The fluid density ρ_i is constant in each layer. The horizontal partial differential operator ∇ is $(\partial/\partial x, \partial/\partial y)$, and g is the gravitational acceleration, i.e., $g = 9.8 \text{ m/s}^2$.

It should be noted that the sum rule of product is used for the subscripts α_i , β_i , and γ_i ; for example, β_1 in the first term on the left-hand side of Eq. (3) is the power of ζ .

From Eqs. (4) and (6), p is eliminated to obtain the following equation:

$$\eta^{\beta_2} \frac{\partial f_{2,\beta_2}}{\partial t} + \frac{1}{2} \eta^{\beta_2+\gamma_2} \nabla f_{2,\beta_2} \nabla f_{2,\gamma_2} + \frac{1}{2} \beta_2 \gamma_2 \eta^{\beta_2+\gamma_2-2} f_{2,\beta_2} f_{2,\gamma_2} + \left(1 - \frac{\rho_1}{\rho_2} \right) g(\eta + h_1) - \frac{\rho_1}{\rho_2} \left(\eta^{\beta_1} \frac{\partial f_{1,\beta_1}}{\partial t} + \frac{1}{2} \eta^{\beta_1+\gamma_1} \nabla f_{1,\beta_1} \nabla f_{1,\gamma_1} + \frac{1}{2} \beta_1 \gamma_1 \eta^{\beta_1+\gamma_1-2} f_{1,\beta_1} f_{1,\gamma_1} \right) = 0. \tag{7}$$

In this study, we focus on solitary waves, such that the number of terms for the expanded velocity potential expressed by Eq. (1) is three for both upper and lower layers, i.e., $N_1 = N_2 = N = 3$, based on the accuracy verification⁸⁾ for the surface and internal solitary waves obtained using the fundamental equations.

physical quantities for a steady wave with phase velocity C are evaluated using the Newton-Raphson method. Note that in the resulting equations for steady waves, the physical quantities F are functions of only x , for the time derivative terms are eliminated.

For the discretization in the Newton-Raphson method, the second-order central finite difference is used for spatial differentiation. The computational domain is the region of $1 \leq m \leq M$, where m is grid point number. The grid points of $m = 0$ and $m = M + 1$ are virtual grid points for the central finite difference at the lateral boundaries.

The method to solve the determinant $\mathbf{J}\Delta = \mathbf{D}$, which represents the simultaneous difference equations obtained by the discretization above, is the Gaussian elimination method, with partial pivots of high computational stability, where $\mathbf{J} = \mathbf{J}(m)$ ($m = (1, 2, \dots, M)$) is the Jacobian matrix, and $\Delta = \Delta(m)$ is a column vector composed of the difference ΔF between the numerical solution F at the k th and that at the $(k + 1)$ th iterative calculations for convergence.

The number of elements of the Jacobian matrix \mathbf{J} is $\{(2 + 2N)M\}^2$. For example, if the number of grids in the computational domain is 2,500, the total number of elements is about 400 million, such that it is not efficient to store the Jacobian matrix \mathbf{J} in one array, from the viewpoint of memory capacity. Therefore, considering that the Jacobian matrix \mathbf{J} is a band matrix, we secure only both the elements required to the pivot operation and those of the Jacobian matrix \mathbf{J} corresponding to $\Delta(m) = (\Delta f_{i,\alpha}, \Delta \zeta, \Delta \eta, \Delta f_{2,\alpha})_m$ for one computational grid point, such that the Jacobian matrix \mathbf{J} is composed of $(2 + 2N) \times 4 (2 + 2N) \times M$.

III. CALCULATION METHOD FOR STEADY WAVE SOLUTIONS IN A COEXISTING FIELD OF SURFACE AND INTERNAL SOLITARY WAVES

a) Determinant in the Newton-Raphson method

For the propagation of nonlinear surface/internal waves, the fundamental differential equations, i.e., Eqs. (2), (3), (5), and (7), are transformed to finite difference equations, which are solved using an implicit scheme⁹⁾. In the present study, numerical solutions for surface/internal solitary waves are obtained using the method introduced by Yamashita and Kakinuma⁸⁾, where the Newton-Raphson method is applied to solve the fundamental equations for steady waves in a coexisting fields of surface and internal waves. We substitute the advection equation $\partial F/\partial t = -C \partial F/\partial x$ into the time derivative terms of Eqs. (2), (3), (5), and (7), and then solve the resulting nonlinear wave equations for steady waves traveling in the direction of the x -axis, where C is the phase velocity of the waves, and the physical quantity F is the water surface displacement ζ , the interface displacement η , and the weightings of the expanded velocity potential $f_{i,\alpha}$. In this method, an arbitrary phase velocity C is given, and these unknown

Consequently, the number of elements has been reduced to around 640,000, and the calculation efficiency could be improved significantly.

b) *Initial values in the Newton-Raphson method*

The initial values in the Newton-Raphson method are the surface and interface profiles, as well as the velocity potential, obtained through the KdV theory for small amplitude solitary waves. In two-layer fluids, there are two types of solitary waves with different

restoring forces: solitary waves with a surface-wave mode due to gravity, as sketched in Fig. 1, and solitary waves with an internal-wave mode owing to the effective gravity between the two layers, as illustrated in Fig. 2. For the former, the initial values in the Newton-Raphson method are the KdV solutions for a one-layer fluid, and for the latter, those are the KdV solutions for two-layer fluids, the upper surface of which contacts with a fixed horizontal plate.

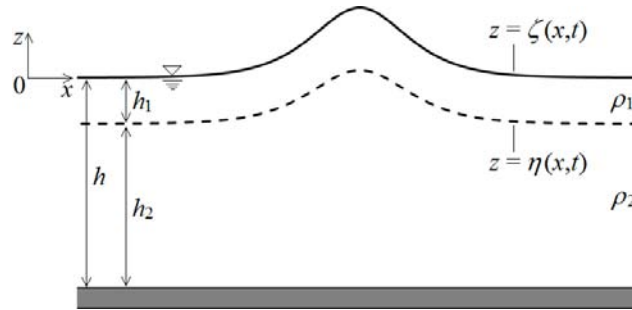


Fig. 1: Schematic for surface-mode surface and internal solitary waves in two-layer fluids with free water surface.

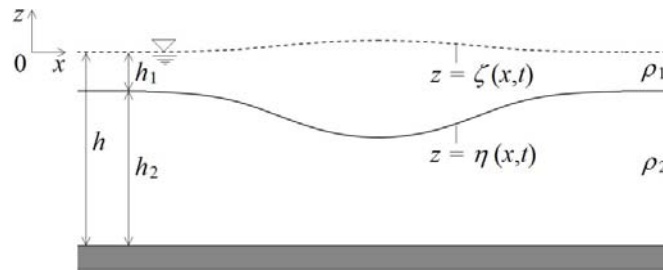


Fig. 2: Schematic for internal-mode surface and internal solitary waves in two-layer fluids with free water surface.

c) *Lateral boundary conditions for approximating solitary waves in the finite domain*

Solitary waves have the property that the horizontal gradient dF/dx of the physical quantity asymptotically approaches zero at a distance in the horizontal direction. In the numerical calculation, however, the target domain is a finite region, such that the property should be described using boundary conditions. First, as a boundary condition of the calculation using the central finite difference, we assumed $dF/dx = 0$ for the physical quantities F at the virtual grid points, i.e., $m = 0$ and $m = M + 1$, and then the calculation diverged immediately. Second, although we extrapolated the physical quantities F at the virtual grid points $m = 0$ and $M + 1$ using the first- or second-order approximation, the calculation also diverged. These calculation results indicate that the water surface displacement ζ near the boundaries oscillates without asymptotically approaching zero toward the boundary, which means that in order to obtain stable solutions, it is necessary to suppress such oscillation and express that dF/dx approaches zero toward the boundaries. Finally, we adopted $F_0 = F_1$ and $F_{M+1} = F_M$, which means that the gradient of physical quantities in the virtual regions adjacent to the boundaries is assumed to be zero,

although it does not mean $dF/dx = 0$ at the boundaries. For example, dF/dx at the boundary $m = 1$ is expressed as $(F_2 - F_1) / 2\Delta x$, which has the same sign as dF/dx at the position $m \approx 1.5$, and the absolute value is 1/2 of dF/dx at the position $m \approx 1.5$, such that the oscillation due to sign reversal around the boundaries is suppressed, and the property of solitary waves, where dF/dx approaches zero toward the boundary, is approximately expressed.

IV. SURFACE-MODE SOLITARY WAVES

The illustration in Fig. 1 is our schematic for surface and internal solitary waves with a surface-wave mode, where the still water depth $h = h_1 + h_2$ is uniform, and the thickness of the upper layer h_1 is $0.2h$ in still water. By applying the final method described above, we obtain numerical solutions for surface-mode solitary waves, where the phases of both surface-mode surface and internal solitary waves are assumed to be the same as shown in Fig. 1.

The density ratio of the lower and upper layers, ρ_2/ρ_1 , is 1.02, which is close to the density ratio of seawater and freshwater. The total length of the calculation domain, L , is $100.0h$, and the grid width in the x direction, Δx , is $0.05h$.

Shown in Fig. 3 are the numerical results for the water surface profiles of the surface-mode surface solitary waves, where the horizontal and vertical axes indicate horizontal distance from the position of the wave-profile peak and the ratio of surface displacement from the still water level to still water depth h . The ratio of the wave height of the surface solitary waves to still

water depth, a_s/h , is 0.1, 0.3, and 0.5. Comparing the water surface profiles of the surface solitary waves for the one-layer fluid indicated by the black solid lines and those for the two-layer fluids drawn with the red broken lines, a significant difference is not observed between the two, although the latter is slightly sharpened.

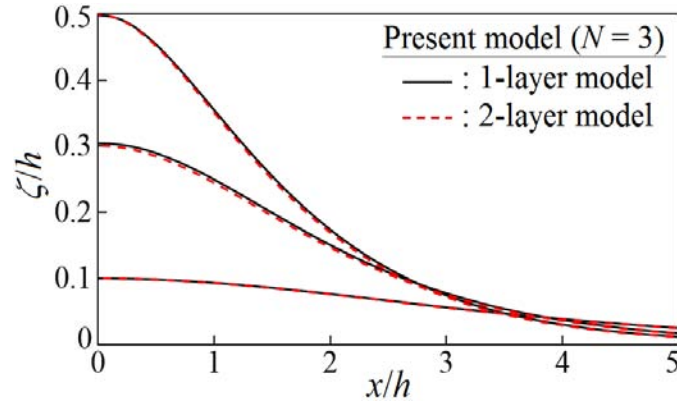


Fig. 3: Surface profiles for the surface-mode surface solitary waves, where the ratio of wave height to still water depth $a_s/h = 0.1, 0.3, \text{ and } 0.5$; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

Figure 4 shows the relationship between the relative representative wavelength of surface-mode surface solitary waves, λ_s/h , and the ratio of wave height to still water depth, a_s/h , where the red solid line shows the numerical solution for the two-layer fluids, and the black solid and broken lines show the numerical solution

and the KdV solution for the one-layer fluid, respectively. The representative wavelength λ_s of surface solitary waves is defined by

$$\lambda_s = \int_{-L/2}^{L/2} \zeta dx / a_s \tag{8}$$

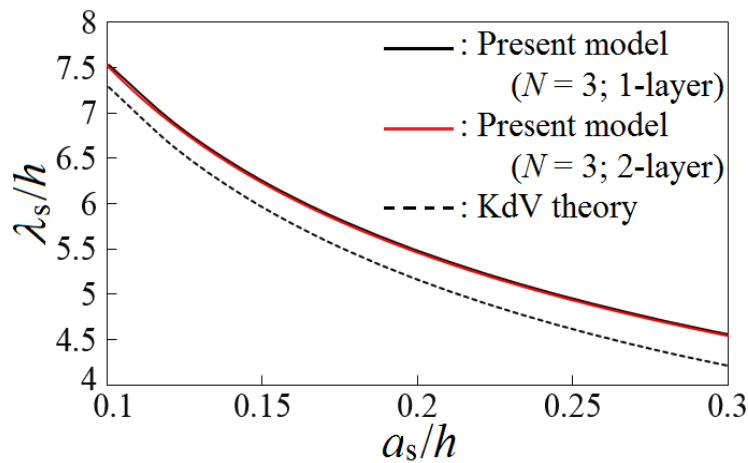


Fig. 4: Relationship between the relative representative wavelength of surface-mode surface solitary waves, λ_s/h , and the ratio of wave height to still water depth, a_s/h , where λ_s is defined by Eq. (8); $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

Fig. 4 indicates that the relative representative wavelength decreases, as the ratio of wave height to still water depth, a_s/h , is increased. Although the representative wavelength for the two-layer fluids is slightly shorter than that for the one-layer fluid, there is almost no difference between the two. The representative wavelength from the KdV theory for the one-layer fluid is shorter than those through the numerical calculation for the one-layer fluid and the two-

layer fluids, for the wavelength by the KdV theory decreases as the wave height is increased, satisfying the assumption that $O(a_s/h) = O((h/\lambda_s)^2)$. Conversely, in the derivation process of the set of fundamental equations⁶⁾, no assumptions are made regarding both the ratio of wave height to water depth and the ratio of water depth to wavelength, when the number of the expansion terms for velocity potential, N , is infinity.



Figure 5 shows the relationship between the relative phase velocity $C/C_{s,0}$ and the ratio of wave height to still water depth, a_s/h , for the surface-mode surface solitary waves, where $C_{s,0} = \sqrt{gh}$ is the phase velocity of linear shallow water waves for a one-layer fluid. In Fig. 5, the red solid line shows the numerical solution for the two-layer fluids, and the black solid and broken lines indicate the numerical solution and the KdV solution, respectively, for the one-layer fluid. The relative phase velocity $C/C_{s,0}$ through the numerical calculation

is smaller than the KdV solution, and the numerical solution of $C/C_{s,0}$ is smaller for the two-layer fluids than for the one-layer fluid. The difference $\Delta(C/C_{s,0})$ between the numerical solution for the one-layer fluid and that for the two-layer fluids is 2.0×10^{-3} , 1.8×10^{-3} , 1.4×10^{-3} , and 6.0×10^{-5} , when $a_s/h = 0.1, 0.3, 0.5,$ and $0.6,$ respectively, where $\Delta(C/C_{s,0})$ decreases as a_s/h is increased.

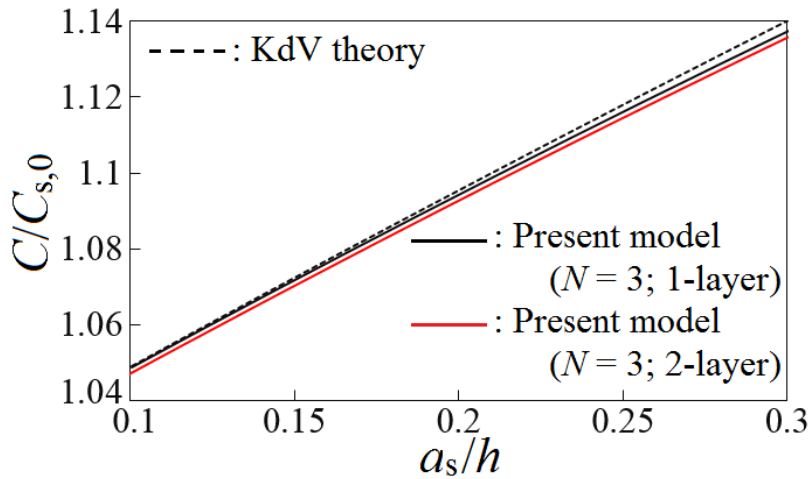


Fig. 5: Relationship between the relative phase velocity $C/C_{s,0}$ and the ratio of wave height to still water depth, a_s/h , for the surface-mode surface solitary wave, where $C_{s,0} = \sqrt{gh}$ is the phase velocity of linear shallow water waves for a one-layer fluid; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

Shown in Fig. 6 is the ratio of the wave height a_i of surface-mode internal solitary waves to the wave height a_s of surface-mode surface solitary waves, for the two-layer fluids. Although the numerical solution of a_i/a_s is close to 0.8, which is the value through the linear

theoretical solution for small-amplitude surface solitary waves, the difference between the value of a_i/a_s through the numerical calculation and that from the linear theory increases, a_s/h is increased.

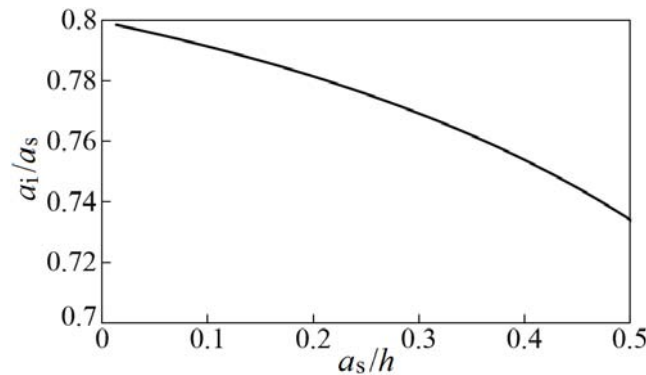


Fig. 6: Relationship between the wave height ratio a_i/a_s and the ratio of wave height to still water depth, a_s/h , where a_i and a_s are the wave height of surface-mode internal and surface solitary waves, respectively; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

In the following cases, the density ratio of lower and upper layers, ρ_2/ρ_1 , is 1.20. In the numerical calculation, the total length of the calculation domain, L , is $50.0h$, and the grid width in the x direction, Δx , is $0.02h$. Figure 7 shows the numerical results for the water surface profiles of surface-mode surface solitary waves,

where the ratio of the wave height of surface solitary waves to still water depth, a_s/h , is 0.5. The distance between the front and back surfaces of the wave profile at each height of the surface-mode surface solitary wave is shorter in the coexisting field of surface and internal waves than in the case without internal waves.

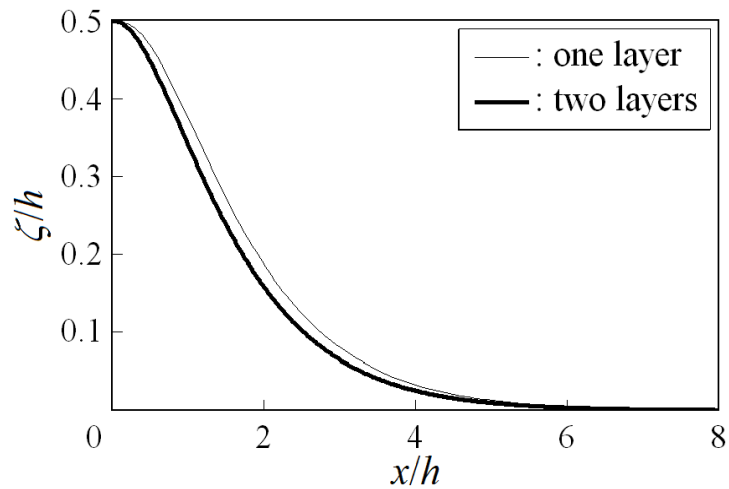


Fig. 7: Surface profiles of surface-mode surface solitary waves, where the ratio of the wave height of surface solitary waves to still water depth, a_s/h , is 0.5; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.20$.

Figure 8 indicates the relationship between the relative representative wavelength of surface-mode surface solitary waves, λ_s/h , and the ratio of their wave height to water depth, a_s/h , where the thick and thin lines show the numerical solutions for the two-layer fluids and

for the one-layer fluid, respectively. The representative wavelength λ_s is defined by Eq. (8). The relative representative wavelength decreases, as the ratio of wave height to still water depth, a_s/h , is increased, as in the case shown in Fig. 4.

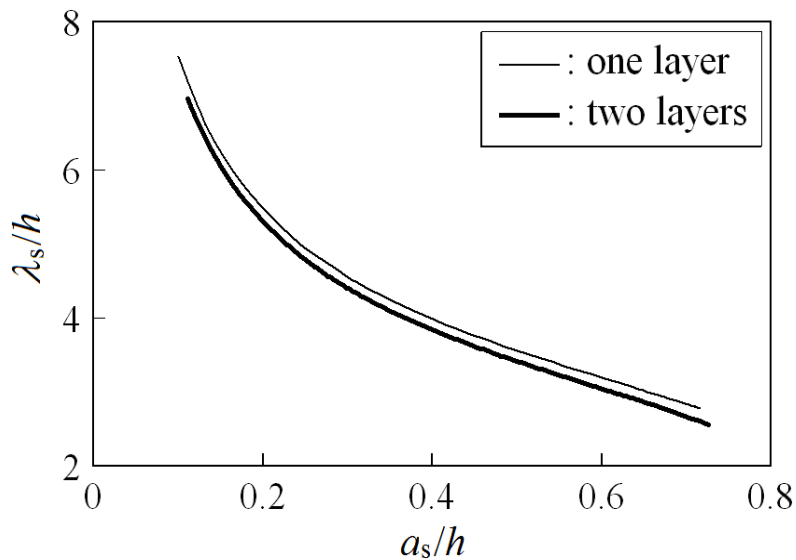


Fig. 8: Relationship between the relative representative wavelength of surface-mode surface solitary waves, λ_s/h , and the ratio of their wave height to water depth, a_s/h , where λ_s is defined by Eq. (8); $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.20$.

Figure 9 shows the relationship between the relative phase velocity $C/C_{s,0}$ and the ratio of wave height to water depth, a_s/h , for surface-mode surface solitary waves, where $C_{s,0} = \sqrt{gh}$ is the phase velocity of linear shallow water waves for a one-layer fluid. The numerical solution for relative phase velocity $C/C_{s,0}$ is smaller for the two-layer fluids than for the one-layer fluid, which is the same as in the case shown in Fig. 5.

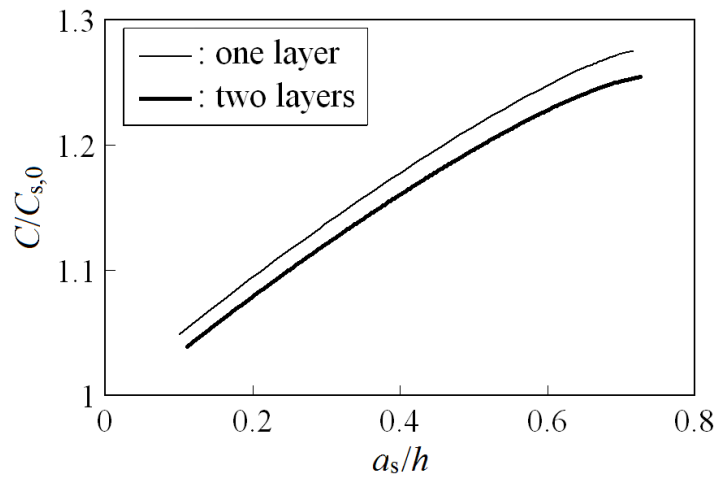


Fig. 9: Relationship between the relative phase velocity $C/C_{s,0}$ and the ratio of wave height to water depth, a_s/h , for surface-mode surface solitary waves, where $C_{s,0} = \sqrt{gh}$ is the phase velocity of linear shallow water waves for a one-layer fluid; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.20$.

Shown in Fig. 10 is the ratio of the wave height a_i of surface-mode internal solitary waves to the wave height a_s of surface-mode surface solitary waves, for the two-layer fluids. The surface-mode wave height ratio

a_i/a_s decreases, as the relative wave height of surface-mode surface solitary waves, a_s/h , is increased, as in the case shown in Fig. 6.

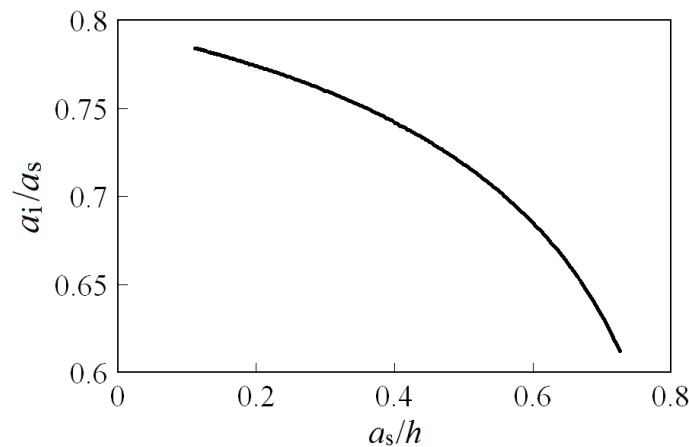


Fig. 10: Relationship between the wave height ratio a_i/a_s and the ratio of wave height to still water depth, a_s/h , where a_i and a_s are the wave height of surface-mode internal and surface solitary waves, respectively; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.20$.

V. INTERNAL-MODE SOLITARY WAVES

Illustrated in Fig. 2 are internal-mode surface and internal solitary waves, where the still water depth h is uniform, and the thickness of the upper layer h_1 is $0.2h$ in still water. By applying the same method, the numerical solutions for internal-mode solitary waves are obtained, where the phases of both internal-mode surface and internal solitary waves are assumed to be the same as shown in Fig. 2. The total length of the calculation domain, L , is $25.0h$, and the grid width in the x direction, Δx , is $0.005h$. First, the density ratio of the lower and upper layers, ρ_2/ρ_1 , is 1.02.

The numerical solutions for the interface profiles of internal-mode internal solitary waves are shown in Fig. 11. The red lines indicate the interface profiles for the

coexisting field of both surface and internal solitary waves, where the ratio of wave height to upper-layer thickness in still water, a_i/h_1 , is 0.15, 0.5, and 1.0, as well as 1.493, which is the maximum value obtained by numerical calculation. On the other hand, the black line shows the numerical solution for the interface profile of the internal solitary wave with the obtained maximum wave height, where the upper surface is in contact with a fixed horizontal plate. In the absence of a free water surface, the downward convex interface of stable internal waves cannot appear below the height of $(z_c + h_1)/h_1 = -1.488$, which is called the critical level¹⁰. Figure 11, however, indicates that $(\eta_{\min} + h_1)/h_1 = -1.493$, such that the interfacial minimum position η_{\min} can exceed the critical level, when the free water surface coexists.

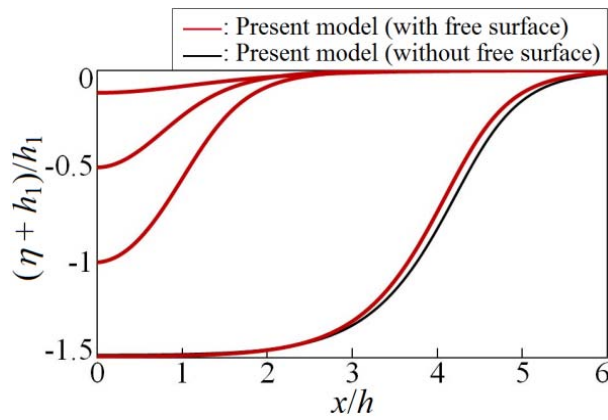


Fig. 11: Interface profiles of internal-mode internal solitary waves, where $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$. The red lines indicate the interface profiles for the coexisting fields of both surface and internal solitary waves, where the ratio of wave height to upper-layer thickness in still water, a_i/h_1 , is 0.15, 0.5, and 1.0, as well as 1.493, which is the maximum value obtained by numerical calculation. The black line shows the numerical solution for the interface profile of the internal solitary wave with the obtained maximum wave height, where the upper surface is in contact with a fixed horizontal plate.

Figure 12 shows the relative representative wavelength λ_i/h_1 for internal-mode internal solitary waves, where the red solid line shows the numerical solution for the coexisting field of surface and internal waves, and the black solid and broken lines show the numerical solution and the KdV solution, respectively,

when the upper surface is in contact with the fixed horizontal plate. The representative wavelength λ_i is defined by

$$\lambda_i = \int_{-L/2}^{L/2} |\eta + h_1| dx / a_i . \tag{9}$$

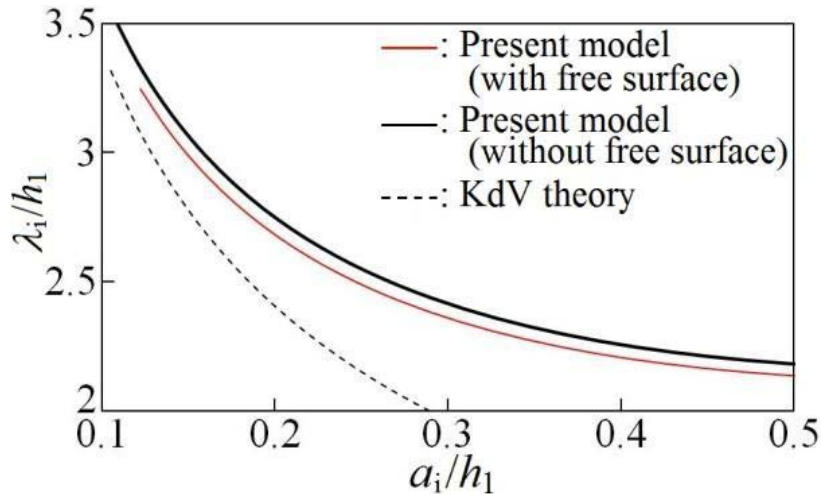


Fig. 12: Relationship between the relative representative wavelength λ_i/h_1 and the ratio of wave height to upper layer thickness in still water, a_i/h_1 , for internal-mode internal solitary waves, where the representative wavelength λ_i is defined by Eq. (9); $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

As shown in Fig. 12, the numerical solution for the representative wavelength of internal-mode solitary waves in the coexistence field of surface and internal waves is shorter than that for the case without the coexistence of surface waves. These numerical solutions are larger than the corresponding KdV solution, which is similar to surface-mode surface solitary waves shown in Fig. 4.

Figure 13 shows the relative phase velocity $C_i/C_{i,0}$ of internal-mode solitary waves, where

$C_{i,0} = \sqrt{(\rho_2 - \rho_1)gh_1h_2 / (\rho_2h_1 + \rho_1h_2)}$ is the phase velocity of linear internal shallow water waves without the coexistence of surface waves. As indicated in Fig. 13, the relative phase velocity $C_i/C_{i,0}$ decreases in the coexistence field of surface and internal waves than in the case without the coexistence of surface waves, where the difference between the two decreases as a_i/h_1 is increased, as for the case of surface-mode solitary waves shown in Fig. 5.

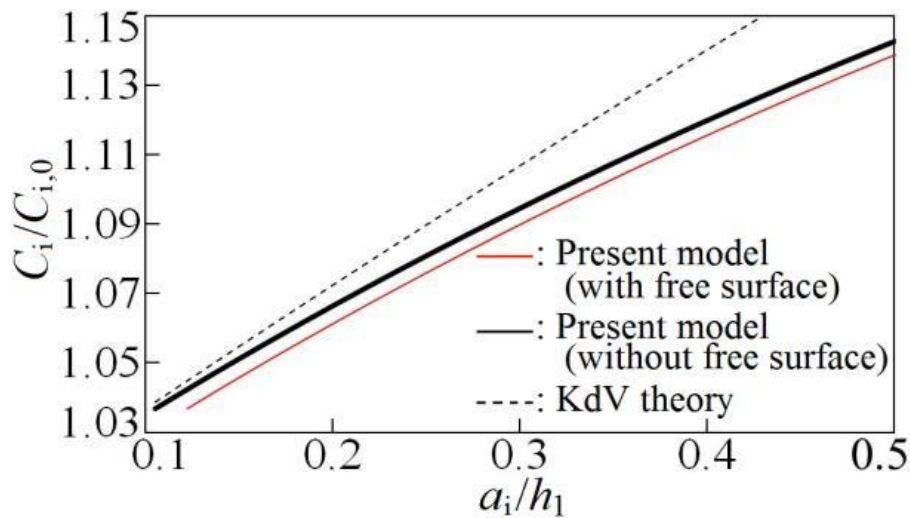


Fig. 13: Relationship between the relative phase velocity $C_i/C_{i,0}$ and the ratio of wave height to upper-layer thickness in still water, a_i/h_1 , for internal-mode internal solitary waves, where $C_{i,0}$ is the phase velocity of linear internal shallow water waves without the coexistence of surface waves; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

Shown in Fig. 14 is the ratio of wave height of internal-mode surface solitary waves to that of internal-mode internal solitary waves, a_s/a_i . The wave height ratio a_s/a_i decreases, as the ratio a_i/h_1 is increased. Conversely, the wave height ratio a_s/a_i from the linear

shallow water wave theory for the coexisting field of surface and internal waves does not depend on the ratio a_i/h_1 , for $a_s/a_i = (1 - \rho_1/\rho_2) h_2/h = 0.016$.

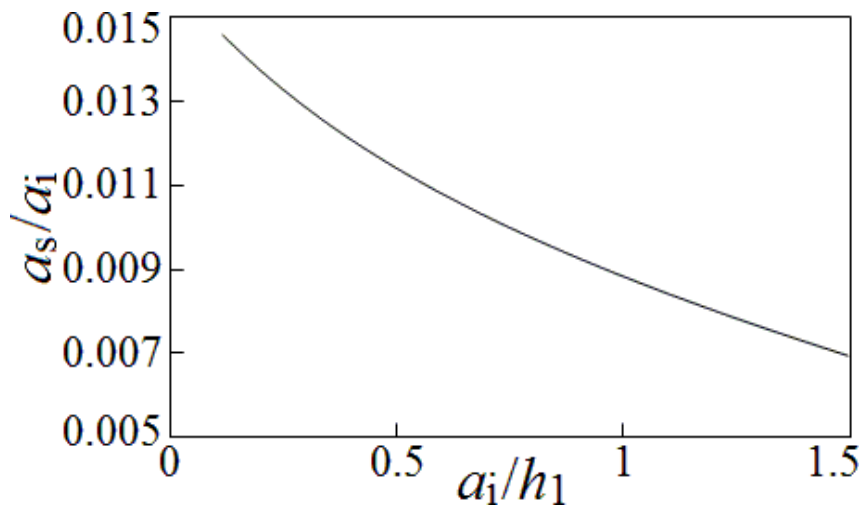


Fig. 14: Relationship between the wave height ratio a_s/a_i and the ratio of wave height to the upper layer thickness in still water, a_i/h_1 , where a_s and a_i are the wave height of internal-mode surface and internal solitary waves, respectively; $h_2/h_1 = 4.0$ and $\rho_2/\rho_1 = 1.02$.

Second, we compare the numerical solutions for two cases, where the density ratio of the lower and upper layers, ρ_2/ρ_1 , is 1.02 and 1.20. Figure 15 shows the relative representative wavelength λ_i/h_1 for internal-mode internal solitary waves, where λ_i is defined by Eq. (9). As shown in Fig. 15, although the representative wavelength λ_i of internal-mode internal solitary waves in the coexisting field of surface and internal waves is larger in the case where $\rho_2/\rho_1 = 1.02$ than in the case where $\rho_2/\rho_1 = 1.20$, when a_i/h_1 is relatively small, the opposite is true, when a_i/h_1 is relatively large.

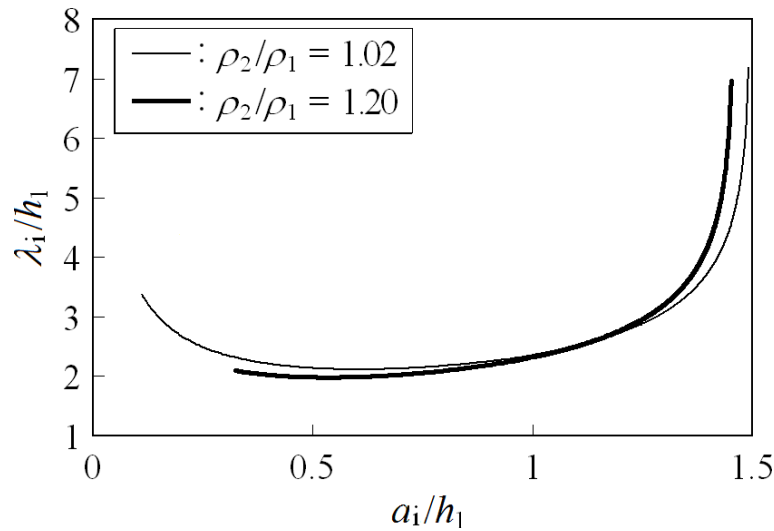


Fig. 15: Relationship between the relative representative wavelength λ_i/h_1 and the ratio of wave height to upper layer thickness in still water, a_i/h_1 , for internal-mode internal solitary waves, where the representative wavelength λ_i is defined by Eq. (9), and $h_2/h_1 = 4.0$.

Figure 16 shows the relative phase velocity $C_i/C_{i,0}$ of internal-mode solitary waves, where $C_{i,0} = \sqrt{(\rho_2 - \rho_1)gh_1h_2 / (\rho_2h_1 + \rho_1h_2)}$ is the phase velocity of linear internal shallow water waves without the

coexistence of surface waves. The relative phase velocity $C_i/C_{i,0}$ is larger when $\rho_2/\rho_1 = 1.02$ than when $\rho_2/\rho_1 = 1.20$.

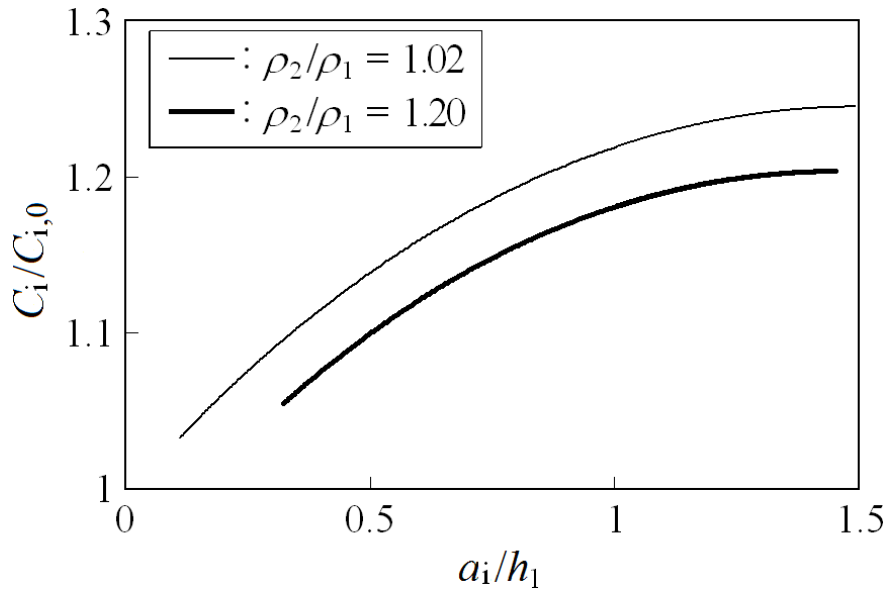


Fig. 16: Relationship between the relative phase velocity $C_i/C_{i,0}$ and the ratio of wave height to upper-layer thickness in still water, a_i/h_1 , for internal-mode internal solitary waves, where $C_{i,0}$ is the phase velocity of linear internal shallow water waves without the coexistence of surface waves, and $h_2/h_1 = 4.0$.

Shown in Fig. 17 are the ratios of wave height, a_s/a_i , where a_s and a_i are the wave height of internal-mode surface and internal solitary waves, respectively. The wave height ratio a_s/a_i is larger when $\rho_2/\rho_1 = 1.20$ than when $\rho_2/\rho_1 = 1.02$. The numerical solutions for wave height ratio a_s/a_i decrease, as the relative wave height a_i/h_1 is increased, although that through the linear shallow water wave theory for the coexisting field of surface and internal waves does not depend on the

relative wave height a_i/h_1 , for $a_s/a_i = [(\rho_2/\rho_1) - 1] / [(\rho_2/\rho_1)/(h_2/h_1) + 1]$, such that $a_s/a_i \approx 0.154$ when $\rho_2/\rho_1 = 1.20$, and $a_s/a_i \approx 0.016$ when $\rho_2/\rho_1 = 1.02$.

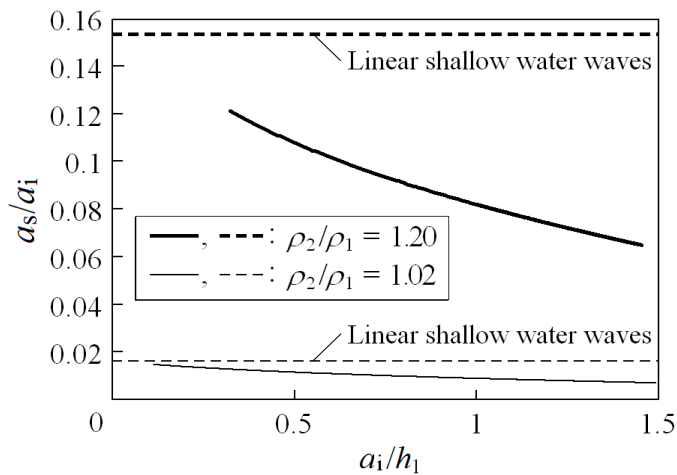


Fig. 17: Relationship between wave height ratio a_s/a_i and relative wave height a_i/h_1 , where a_s and a_i are the wave height of internal-mode surface and internal solitary waves, respectively, and $h_2/h_1 = 4.0$.

VI. CONCLUSIONS

The numerical solutions for the solitary waves in the coexisting fields of surface and internal waves were obtained for the two-layer fluids with a free water surface, where the phases of both the steady surface and internal solitary waves were assumed to be the same, with a surface mode or an internal mode. The set of nonlinear equations based on the variational principle for steady waves were solved using the Newton-Raphson method.

The relative phase velocity of surface-mode solitary waves was smaller in the coexisting fields of surface and internal waves than in the cases without the coexistence of internal waves. The difference in the relative phase velocity between the two decreased, as the relative wave height of surface-mode surface solitary waves was increased.

The relative phase velocity of internal-mode solitary waves was also smaller in the coexisting fields of surface and internal waves than in the cases without the coexistence of surface waves. The difference in the relative phase velocity between the two decreased, as the relative wave height of internal-mode internal solitary waves was increased.

The interfacial position of the internal-mode internal solitary waves in the coexisting fields of surface and internal waves exceeded the critical level determined in the cases without the coexistence of surface waves.

The wave height ratio between internal-mode surface and internal solitary waves was smaller than the corresponding linear shallow water wave solution, and the difference increased, as the relative wave height of internal-mode internal solitary waves was increased.

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