GLOBAL JOURNAL

OF RESEARCHES IN ENGINEERING: I

Numerical Methods

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VOLUME 24

ISSUE 1

VERSION 1.0



GLOBAL JOURNAL OF RESEARCHES IN ENGINEERING: I NUMERICAL METHODS

GLOBAL JOURNAL OF RESEARCHES IN ENGINEERING: I NUMERICAL METHODS

Volume 24 Issue 1 (Ver. 1.0)

OPEN ASSOCIATION OF RESEARCH SOCIETY

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Global Journal of Researches in Engineering: I Numerical Methods

Volume 24 Issue 1 Version 1.0 Year 2024

Type: Double Blind Peer Reviewed International Research Journal

Publisher: Global Journals

Online ISSN: 2249-4596 & Print ISSN: 0975-5861

Science, Technology and Society: Challenges and Possibilities for STEM in Engineering Courses

By Felicien Gonçalves Vásquez, Nataliana de Souza Paiva & Ana Cláudia Ribeiro de Souza

Universidade do Estado do Amazonas

Abstract- Ingês: The study of Science, Technology and Society (STS) is quite embracing and relevant to today's society. In this article, we intend to approach the issue and reflect on the interaction that exists between the three areas and education, as well as the relationship with Science, Technology, Engineering and Mathematics (STEM). For that, a qualitative research was carried out from a narrative review about the subject in books, articles and works presented in event annals highlighting STS in the context of education, the challenges faced in relation to the STEM approach and the possibilities of integration between science, technology and society in engineering courses. The results indicate that there are challenges such as lack of adequate training for teachers, lack of didactic resources and resistance to change on the part of some educators and managers, as well as that the STS approach in education and STEM in the training of engineers makes it possible to develop professional skills and competencies focused on sustainability, innovation and a fairer and more humane society.

Keywords: STS, STEM, Engineering Education.

GJRE-I Classification: LCC: T65



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Science, Technology and Society: Challenges and Possibilities for STEM in Engineering Courses

Ciência, Tecnologia e Sociedade: Desafios e possibilidades para o STEM nos cursos de Engenharia do Amazonas

Felicien Gonçalves Vásquez a, Nataliana de Souza Paiva & Ana Cláudia Ribeiro de Souza P

Resumo- O estudo do tema Ciência, Tecnologia e Sociedade (CTS) é bastante abrangente e relevante para a sociedade atual. Neste artigo, pretende-se abordar a temática e refletir a respeito da interação que existe entre as três áreas e a educação, como também, a relação com a Ciência, Tecnologia, Engenharia e Matemática (STEM). Para tanto, foi realizada uma pesquisa qualitativa a partir de uma revisão narrativa sobre o tema em livros, artigos e trabalhos apresentados em anais de eventos destacando a CTS no contexto da educação, os desafios enfrentados em relação à abordagem STEM e as possibilidades de integração entre ciência, tecnologia e sociedade nos cursos de Engenharia. Os resultados apontam a falta de formação adequada dos professores, falta de recursos didáticos e resistência à mudança por parte de alguns educadores e gestores, como também que a abordagem CTS na educação e no STEM na formação de engenheiros possibilita desenvolver habilidades e competências profissionais voltadas à sustentabilidade, inovação e uma sociedade mais justa e humanitária.

Palavras-chave: CTS, STEM, Ensino de Engenharia.

Abstract- Ingês: The study of Science, Technology and Society (STS) is quite embracing and relevant to today's society. In this article, we intend to approach the issue and reflect on the interaction that exists between the three areas and education, as well as the relationship with Science, Technology, Engineering and Mathematics (STEM). For that, a qualitative research was carried out from a narrative review about the subject in books, articles and works presented in event annals highlighting STS in the context of education, the challenges faced in relation to the STEM approach and the possibilities of integration between science, technology and society in engineering courses. The results indicate that there are challenges such as lack of adequate training for teachers, lack

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of didactic resources and resistance to change on the part of some educators and managers, as well as that the STS approach in education and STEM in the training of engineers makes it possible to develop professional skills and competencies focused on sustainability, innovation and a fairer and more humane society.

Keywords: STS, STEM, Engineering Education.

I. Introdução

busca humana pelo entendimento das leis da natureza remonta à antiguidade, quando os gregos e egípcios realizavam estudos e observações para entender os fenômenos naturais – conhecimentos esses que foram se acumulando e dando origem ao que entendemos hoje como ciência. Ao longo dos séculos, a ciência vem evoluindo e se desenvolvendo em diferentes culturas e sociedades, sendo influenciada por diversas correntes filosóficas e contextos sociais complexos.

O estudo do tema Ciência, Tecnologia e Sociedade (CTS) é bastante abrangente, indo além do que se discute neste artigo. Temos como objetivo revisitar uma reflexão a respeito não só da interação que existe entre essas três áreas e a educação, mas também a relação com Ciência, Tecnologia, Engenharia e Matemática (STEM).

A discussão a respeito do papel do STEM, em particular nos cursos de Engenharia, se dá pela possibilidade que essa abordagem traz para o desenvolvimento não só de habilidades profissionais dos estudantes, como também pela busca em formar indivíduos cada vez mais comprometidos com o meio ambiente e com uma sociedade mais justa e humana.

No contexto amazônico, especificamente no Amazonas, torna-se estruturante pensar nas questões sociais, ambientais, éticas, políticas e suas conexões com os povos do campo, das águas e das florestas que aqui habitam e se relacionam com: o Polo Industrial de Manaus (PIM) nos segmentos eletroeletrônico, duas rodas, naval, mecânico, metalúrgico e termoplástico, entre outros (Brasil, 2017); a extração de minerais que vem fazendo parte da economia do estado (Hauradou e Amaral, 2019); e a bioeconomia gerada do

desdobramento das ciências básicas, aplicadas e áreas tecnológicas (informática, robótica e controle de processos) (Willerding, et al, 2020).

Diante dos impactos que as questões econômicas podem causar na sociedade e no meio ambiente, a engenheira dialoga com estes cenários locais e globais, tonando-se campo fértil para integração de CTS e STEM, numa perspectiva de ensino crítico e reflexivo sobre ciência e tecnologia, possibilitando uma capacidade de resposta rápida as inovações e soluções tecnológicas.

Apesar de importante, a abordagem STEM nas instituições de ensino superior enfrenta desafios aos quais podemos elencar como sendo a sua implementação, a mudança na cultura educacional, falta de formação pedagógica dos professores, ausência de recursos didáticos adequados e a necessidade de uma abordagem interdisciplinar e aplicada. Dessa forma, para torná-la possível é necessário que as instituições de ensino superior estejam preparadas para enfrentá-los, investindo em recursos e formação adequada de seu corpo docente.

Neste estudo discutimos quais os desafios e as possibilidades para o STEM nos cursos de engenharia, com foco na temática CTS? Para isso, realizamos uma revisão narrativa sobre o tema em livros, artigos e trabalhos apresentados em anais de evento, a fim de discutir alguns apontamentos sobre a abordagem Ciência, Tecnologia e Sociedade (CTS) na educação e o STEM na formação de engenheiros relacionado com CTS, de maneira que possam contribuir para a formação de profissionais críticos e reflexivos.

II. Abordagem Ciência, Tecnologia e Sociedade (cts) na Educação

Quando questionados quanto ao conceito de tecnologia, logo nos vem à mente, aparelhos eletrônicos, de informática e comunicação, pois estamos acostumados a nos referir à tecnologia como equipamentos e aparelhos. Estes são considerados exemplos de tecnologia, assim como um simples lápis ou um caderno também o são, pois, a tecnologia não é representada apenas pelo produto final, mas pelo conjunto de saberes necessários desde a sua concepção, execução e à utilização do produto ou serviços (Veraszto et al, 2008; Oliveira, 2008).

A tecnologia, então, surge da capacidade do homem em expandir seus conhecimentos, facilitar seu trabalho, tornar a vida mais agradável a partir das dificuldades encontradas e com criação de sistemas, instrumentos (artefatos, processos ambientes), capazes de suprir suas necessidades históricas pessoais e coletivas, garantindo sua sobrevivência em qualquer ambiente com diferentes formas, usos e aplicações (Kenski, 2007; Veraszto et al, 2008; Araújo e Sá, 2021).

Na antiguidade, a tecnologia estava voltada para o comércio, transporte de água, para uma economia predominantemente doméstica, mais tarde virou força propulsora da expansão social para o crescimento das cidades pelo desenvolvimento da tecnologia do transporte e hoje como em outros momentos da história da humanidade o monopólio das armas e do poderio militar, do emprego de imagens, assim como também as tecnologias digitais (Elias, 1994).

A temática que envolve a tecnologia, continua alvo de preocupação e exige reflexões, por ser um dos principais problemas teóricos e práticos da atualidade, abordados nos mais diversos campos de estudo,

Da Engenharia à Sociologia da Ciência, da História à Biotecnologia, da Antropologia aos Estudos Sociais da Ciência, da Física/Química/Matemática à Pedagogia/Psicologia/Economia, passando pelas Ciências da Computação, ecoam questões que envolvem a condição tecnológica. Não só! O tema não se restringe ao universo acadêmico e um observador mais estimulado não terá dificuldade de encontrar nas transmissões televisivas, nos jornais, nos mercados, nas praças, nos diálogos do cotidiano, elementos teóricos problematizadores da referida temática (Silva, 2007, p.116).

Nessa perspectiva, na busca incessante pelo bem-estar humano, surge o conflito entre a manutenção dessa situação e o risco à sobrevivência devido à exploração excessiva, destruição dos recursos naturais e até mesmo da degradação humana, pois se tornou acessório da tecnologia, sendo substituído até mesmo das relações afetivas e morais constituindo-se como fenômeno de alienação (Oliveira, 2008).

A abordagem CTS tem como um de seus objetivos a compreensão da ciência e da tecnologia como atividades humanas, socialmente situadas e culturalmente mediadas – que superará a visão ingênua e idealizada da ciência e da tecnologia como atividades neutras, objetivas e desinteressadas, propondo uma reflexão crítica sobre as implicações sociais, políticas, econômicas e ambientais em nossa sociedade (Bazzo, 2018).

Apesar de haver muitas iniciativas e produções bibliográficas em CTS, ainda há desafios a serem enfrentados - como a falta de formação adequada dos professores para trabalhar com CTS e a dificuldade em integrar essa abordagem ao currículo escolar. Além disso, Bazzo (2018) aponta haver uma tendência em reduzir a abordagem CTS a um conjunto de técnicas ou atividades pontuais, sem considerar sua dimensão crítica e reflexiva.

A visão desta dificuldade de CTS chegar até a escola sempre me acometeu desde que comecei a trabalhar com a relação ciência, tecnologia e sociedade. [...] Essa dificuldade se acentuou nesses últimos anos porque pela 'febre' das publicações em revistas 'indexadas' muitos autores se despreocuparam em chegar até os

professores que estavam na lida diária da construção de conhecimento (Bazzo, 2018, p.262).

Mesmo promissora, ainda há muito o que ser feito para consolidar a abordagem CTS na educação brasileira. O autor destaca haver muitas iniciativas e produções bibliográficas na área, bem como a criação de grupos de pesquisa e redes colaborativas. Isso porque, o ensino de ciências no Brasil ainda é marcado por uma visão tecnicista e descontextualizada da ciência, que não considera as dimensões sociais, culturais e políticas envolvidas na produção do conhecimento científico (Bazzo, 2018).

É necessário avançar na consolidação da abordagem CTS na educação brasileira, buscando superar os desafios mencionados. Ele também ressalta a importância de se manter uma perspectiva crítica e reflexiva sobre a ciência e a tecnologia, buscando desmistificar esses temas promover е desenvolvimento tecnológico mais humano (Bazzo, 2018).

Nesse processo civilizatório é importante entender as concepções dos processos sociais, a economia, a política, a tecnologia, a cultura ao que tange a mudança de conduta e sentimentos humanos em outras direções. Muito embora essa mudança não tenha sido "racionalmente" planejada, não quer dizer que tão pouco foi aleatória, foi pela ação integrada do homem (ações coletivas são mais fortes para o processo civilizador).

De acordo com N. Elias (1994, p. 199) "a transformação da existência social na totalidade é a condição básica para civilizar-se a conduta", mas apesar disso costuma-se mensurar o grau de civilização pela estrutura social a qual pertencem, geralmente julgando-se civilizados aqueles inseridos numa cultura digital.

A aplicação da ciência e tecnologia trouxeram implicações na organização do trabalho e das empresas e, consequentemente, nas profissões e na maneira como ocorre o processo de formação destes no contexto educacional. Desta forma, os avanços tecnológicos. em especial na informação comunicação, impactam na formação de professores, nos processos de ensino e aprendizagem, nos currículos e nas políticas educacionais de CTS, ou seja, na forma de conceber a educação (Peña; Alves; Peppe, 2003).

Na busca por uma sociedade mais justa e igualitária, a educação tecnológica é uma possibilidade de emancipação do cidadão, quando visa formar cidadãos críticos e reflexivos para o mundo, por conhecimentos técnicos das ferramentas necessárias para o trabalho, para contribuir na construção de uma sociedade mais humana (Durães, 2009).

Desta forma, Gonçalves e Azevedo (2021), ressalta que a "Educação Tecnológica busca não somente formar um nível ou grau, mas sim uma formação que consiga proporcionar aos indivíduos um olhar crítico e reflexivo para as questões do mundo". Ou seja, deve-se incentivá-los a pensar de forma crítica e analítica sobre o papel da tecnologia em nossa sociedade e refletir sobre as implicações éticas, sociais, ambientais e econômicas do uso da tecnologia, tais como o impacto da tecnologia na privacidade, segurança, saúde, emprego, relações sociais, entre outras.

Para Harari (2018), compreender o impacto da tecnologia na sociedade, reforça a ideia de que a educação tecnológica deve incluir uma formação mais ampla, que vá além das habilidades técnicas e profissionais, buscando desenvolver um pensamento crítico e reflexivo das implicações que a tecnologia pode trazer para a sociedade.

O autor argumenta que a tecnologia está rapidamente a sociedade, mudando oportunidades e desafios, dessa forma, o ensino tecnológico pode ajudar a preparar os estudantes para lidar com essas mudanças, capacitando-os a adaptarse a novas tecnologias e contextos (Harari, 2018).

Não podemos deixar de descrever a relação entre a Educação Tecnológica com o STEM, o qual é uma abordagem interdisciplinar para o ensino que integra essas quatro áreas de conhecimento, e é amplamente reconhecido como uma forma de preparar os estudantes para as demandas do mercado de trabalho atual, valorizando habilidades em tecnologia e "permitem desenvolver a ciência. Além disso, observação, o questionamento e a resolução de problemas no processo de ensino e aprendizagem" (Bacich; Moran, 2018).

Bazzo, Pereira e Bazzo (2014) apontam três alternativas para a inserção do enfoque CTS no currículo de Engenharia, a) inserção de temas sobre CTS nos conteúdos; b) inserção de disciplinas específicas de CTS, c) organização de um currículo no qual todas as disciplinas tenham enfoque CTS (descritas pelos autores como a abordagem ideal) e na formação didático-pedagógica que apontam para um olhar reflexivo na abordagem STEM.

III. STEM NA FORMAÇÃO DE ENGENHEIROS E A RELAÇÃO COM CTS

Os estudos sobre STEM emergem nos Estados Unidos a partir da corrida espacial de 1950 e 1960 engenheiros, cientistas e matemáticos ajudaram a enviar os primeiros objetos ao espaço, em 1970 e 1980 o EUA tornou-se líder global de educação científica e os computadores passaram cada vez mais parte da vida das pessoas. Nos anos de 1990, ciências, matemática. engenharia e tecnologia, SMET, foi utilizado pela National Science Foundation (NSF), orientaram políticas de currículo integrado, avaliações externas e em larga escala, levando para as escolas a alfabetização

científica, fortalecendo sobretudo a economia competitiva usando como fundamento a tecnologia e engenharia (Pugliese, 2020; Hardoim e Santos, 2021).

Nos anos 2000, a palavra do acrônico STEM aparece na literatura perdurando até os dias atuais, contudo só em 2008 passou a chamar-se STEAM, que para alguns aparece como estímulo à criativade e estética e para outros como forma de evitar a preeminência da Ciência e da Tecnologia em relação aos demais (Pugliese, 2021). Em 2010 o termo STEM tornou-se popular, mas referia-se as quatro áreas do conhecento de forma distinta, de lá para cá em 2024 podemos perceber que no contexto educacional brasileiro há movimentos de integrar essas áreas numa abordagem de aprendizagem integrada e interdisiclinar (Gamboa et al., 2020; Hardoim e Santos, 2021).

Internacionalmente existem muitas críticas à educação STEM, por estar relacionada a movimentos de políticas educacionais globalizantes para atender sobretudo ao mercado de trabalho competitivo e impulsionar ao crescimento econômico, com algumas ações voltadas as mudanças nos currículos, entregas de pacotes metodológicos de ensino, materiais (kits de maker) e espaços, principalmente no ensino médio (Pugliese, 2020b).

Embora seja importante preparar estudantes para as demandas do mundo do trabalho atual e futuro, é importante que carreiras relacionadas à ciência, tecnologia, engenharia e matemática suscitam uma educação ampla, humanizada e equilibrada para a vida profissional.

Para Bacich e Holanda (2020) as palavras do acrônico STEM, nome utilizado neste estudo, ganham sentido quando relacionados a aprendizagem ativa e integrativa. Para a Ciência estão os conhecimentos científicos e a experimentação que levam à reflexão e modelagem de diferentes fenômenos; a Tecnologia para obtenção de informação, análise, uso de programação para soluções de problemas; a Engenharia para estudantes realizam o planejamento, o design e a construção de objetos para solucionar algo para compreensão de um fenônemo ou conceito científico; a Arte, como forma transversal da arteeducação na proposta de inovação, criatividade, pensamento crítico, comunicação, integração; e a Matemática empregada para medir, calcular, projetar soluções, ajudar nas análises dos dados obtidos e desta forma integrar a educação científica e tecnológica. (Bacich; Holanda, 2020)

Na abordagem STEM são considerados relevantes os conhecimentos das áreas STEM pelo menos ao nível de compreensão conceitual, poisajuda o professor a apreender e desenvolver o conhecimento pedagógico no ensino STEM. Esse diálogo entre conheicmento e ensino possibilita estudantes a desenvolvem sua capacidade de realizar investigações, resolver problemas da vida cotidiana, trabalharem

colaborativamente e desenvolverem sua capacidade de criação, que são balizares na formação do engenheiro e do papel da CTS (Kutlu, Bakirci e Kara, 2022; Tekin e Şan, 2023).

Em consonância com Bazzo e Costa (2019) é questão de engenharia pensar o uso dos recursos naturais, as questões climáticas, os impactos na distribuição de renda na sociedade, refletindo o papel CTS na formação de engenheiros e na formação dos professores de engenharia para uma toma de consciência crítica, criativa, resolutiva, ética e humanista.

Desta forma, esta abordagem é vista cada vez mais como caminho possível aos cursos de Engenharia, à medida que as questões ambientais e sociais das quais estamos vivendo e que colocam em risco a segurança global. Logo a demanda por habilidades STEM articuladas à CTS está se tornando exasperada devido ao cenário econômico, social, ambiental e político enfrentados por muitos países.

No Brasil, a Resolução Nº 2, de 24 de abril de 2019, estabelece as novas Diretrizes Curriculares Nacionais (DCN) para a formação em engenharia. Essas diretrizes propõem uma nova proposta de formação do egresso, baseado em competências e habilidades, em contraposição ao modelo tradicional focado apenas no conteúdo, trazendo os fundamentos científicos e tecnológicos, projeto e análise de sistemas, produtos e processos, comunicação, trabalho em equipe e liderança, autoaprendizagem e educação continuada (DCN Nº 2, 2019).

Além disso, as DCN enfatizam a importância da integração do estudante às demandas sociais por meio da curricularização da extensão. Conforme Vásquez, Paiva e Souza (2022), isso é relevante porque a engenharia é uma das profissões responsáveis pelas transformações no planeta e precisa considerar a responsabilidade social e a qualidade de vida humana, considerando os possíveis impactos ambientais e sociais.

Em 2015 a Organização das Nações Unidas - ONU adotou a Agenda 30 com os 17 objetivos para o desenvolvimento sustentável para assegurar um futuro melhor, onde engenheiros são chamados a desempenhar papel essencial para que essas metas sejam atingidas não só através da criação de tecnologias ambientalmente amigáveis, mas também com aplicações de soluções ambientalmente sustentáveis, diretamente relacionada à redução da pobreza, ao desenvolvimento de infraestrutura, de promoção da saúde e da educação (Vásquez; Paiva; Souza, 2022, p. 2).

Nesse contexto, é urgente olhar para a formação dos estudantes de engenharia, que devem ser capazes de pesquisar, adaptar e utilizar tecnologias inovadoras e empreendedoras, assim como reconhecer as exigências do mercado e resolver problemas de engenharia com perspectivas multidisciplinares,

transdisciplinares e com foco na redução da pobreza e dos impactos ambientais. Habilidades essas que inclusive já são mencionadas no Art 3º da DCNs do CNE/CES nº 02/2019.

Os estudantes de curso de engenharia na abordagem STEM com enfoque CTS problematizam, constroem perguntas, identificam conhecimentos científicos necessários para a solução, são estimulados à autodisciplina, tem oportunidade de errar, autoconfiança e ao professor o papel mediador que permita ao estudante construir seus próprios projetos (Pugliese, 2020; Gamboa et al., 2020).

Kelley e Knowles (2016) pontuam o problema de desinteresse que os estudantes geralmente apresentam em relação às ciências e matemática quando aprendem de maneira isolada e desarticulada, acabando por perder as conexões entre os conceitos e o mundo real, que acaba contribuindo para que muitas instituições de ensino procurem formas de manter o interesse e a motivação dos alunos em relação à abordagem STEM.

Assim como a CTS, a abordagem STEM surgi como alternativa de pensar em uma educação mais contextualizada e interdisciplinar, que considere as implicações sociais, políticas e ambientais da ciência e da tecnologia. Ambas as abordagens pretendem formar cidadãos críticos e conscientes, capazes de compreender e intervir nos processos de produção, difusão do conhecimento científico e tecnológico.

Reforçando esse ideia, para Pugliese (2020) é fundamental refletir que quem trabalha com a abordagem STEM, a reconheça como um processo dialógico, não se tem uma receita pronta, mas aponta uma uma possiblidade de encontrar os seus próprios caminhos para promover as experiências.

Enquanto o STEM se concentra principalmente nas áreas do conhecimento de ciências, tecnologia, engenharia e matemática, a abordagem CTS amplia essa perspectiva para incluir outras áreas do conhecimento, como as ciências humanas e sociais. Faz-se necessário uma interdisciplinaridade efetiva entre os campos do saber para formar seres humanos mais críticos e preocupados com o coletivo (Bordin; Bazzo, 2017).

A educação STEM pode desenvolver nos estudantes a compreensão da base social e institucional da credibilidade científico-tecnológica, como estimular e habilitar os estudantes a aprender ciências a partir de seus próprios interesses. Os principais percalços enfrentados no STEM se voltam para um ensino centrado no docente, na aprendizagem mecânica de conteúdos, na falta de integração entre componentes curriculares (Moreira, 2018).

O STEM ancorado numa abordagem CTS otimiza e enfatiza a reflexão crítica sobre as implicações sociais da ciência e da tecnologia em nossa sociedade como na Figura 1.



Fonte: Produção dos próprios autores. 2024.

Figura 1: Relação STEM e CTS

É preciso que as escolas de engenharia pensem em soluções sustentáveis, criativas e inovadoras, ao pressupor a integração de conhecimentos que possibilite ao estudante se preparar para desafios como cidadão crítico, colaborativo, produtivo para a vida e o mercado de trabalho, integrando diferentes áreas do conhecimento e

resolutivo diante dos problemas diários, ultrapassando os modelos tradicionais de ensino e suas relações didático-pedagógicas.

Podemos dizer que do ponto de vista da educação, na relação engenharia e vida, serão necessárias outras concepções epistemológicas de ciência e tecnologia, romper com a perspectiva de

ensino instrumental, investimento na formação continuada em questões didático-pedagógicas e mobilizar os saberes docentes dos engenheiros a partir de formações de professores priorizadas por suas instituições (Bordin; Bazzo, 2017).

No STEM, o foco significativo de trabalho está na ressignificação da prática pedagógica do corpo docente, apoiando-se na mudança da apresentação baseada em palestras para a prática baseada em evidências, pela investigação (Stainset al., 2018).

É importante ressaltar que estar que professores engenheiros que participam de processos formativos didático-pedagógicos, tem possibilidade de trabalhar melhor as atividades de aprendizagem, escolher seu material significativo, definir a melhor metodologia de ensino para sua realidade, redimensionar o papel da avaliação da aprendizagem, entre outros elementos conseguem articular sua atividade de ensino ao STEM articulado a CTS na engenharia (Rüütmann, 2023).

Moreira (2018, p.224) apresenta algumas estratégias de ensino para disciplinas de STEM, com a utilização de atividades práticas e experimentais, o uso de tecnologias educacionais, a integração de componentes curriculares STEM, a promoção da criatividade e do pensamento crítico, com participação em atividades contextualizadas com a vida cotidiana dos estudantes. Além disso, é importante que os professores tenham um profundo conhecimento do seu

componente de ensino articulado com práticas pedagógicas inovadoras.

Corroborando neste sentido de práticas pedagógicas ressaltamos Tardif (2014), ao dizer que a pedagogia na sala de aula é feita de negociações, pois "ensinar é fazer escolhas constantemente, em plena interação com os alunos", (Tardif, 2014, p. 132). Logo no ensino de engenharia que abordagem STEM de enfoque CTS propiciam situações e respostas únicas para cada local e realidade trabalhada.

O ensino STEM na abordagem CTS, emergem condições basilares focada em pensamento crítico, questionamentos, problemas da vida real, contextualizado, de natureza multidisciplinar, interdisciplinar, envolvido com a inovação, resolução de problemas, trabalho colaborativo, desenvolvimento da capacidade de observação e comunicação. (Thibaut et al., 2018).

Outro ponto relevante nesta discussão está voltado para o currículo, no STEM está geralmente centrado em projetos de engenharia, que pode ajudar a desenvolver o conhecimento dos estudantes por meio da aplicação prática do conteúdo (Fan; Yu e Lin, 2021). Os autores exploram as etapas importantes na aplicação do conhecimento de conteúdo ao processo da elaboração de um projeto de engenharia, propondo uma estrutura para implementar um currículo STEM focado tanto na engenharia, quanto no projeto, conforme figura 2.



Fonte: adaptado de Fan; Yu; Lin (2021, p. 1528).

Figura 2: Estrutura para implementar um currículo STEM focado em engenharia

No caso de um currículo STEM, geralmente as seguintes características são consideradas: um histórico do mundo real; conteúdo de integração e aplicação de ciência, tecnologia, engenharia e matemática; atividades baseadas em investigação,

problema ou projeto; um ambiente que inspira os alunos a se tornarem aprendizes ativos; e cultivo de habilidades de pensamento de alto nível em estudantes (Bayer Corporation, 2010; Hudson, English e Dawes, 2014; Roehrig, Moore, Wang e Park, 2012 apud Fan et al, 2021, p.1525).

Fan et al (2021) também define as principais etapas utilizadas na aplicação do conhecimento STEM no processo de construção de um projeto de engenharia, tais como: identificar um problema ou necessidade; definir os requisitos do projeto; gerar soluções conceituais; avaliar e selecionar uma solução; desenvolver um modelo ou protótipo da solução selecionada assim como testar e avaliar a solução. Essas etapas são descritas como fundamentais para a implementação de um currículo STEM centrado em um projeto de engenharia.

IV. Considerações Finais

Hoje, quer na Amazônia como em todo o mundo, as questões ambientais, sociais e econômicas nos levam a refletir a formação técnica e humanista do papel do engenheiro na sociedade e o uso da tecnologia. Contribuindo com essa discussão, o STEM se apresenta como possiblidade, quando crítico e reflexivo, de pensar um ensino pautado em situações reais que levam o futuro profissional engenheiro a refletir as possíveis consequências de suas tomadas de decisões frente a sociedade, a natureza e ecossistema.

Diante deste cenário, este estudo apresenta os desafios enfrentados pelos cursos de Engenharia em relação ao STEM, apontando a falta de formação adequada dos professores para trabalhar com CTS e a dificuldade em integrar essa abordagem ao currículo. Além disso, foi apontada uma tendência em reduzir a abordagem CTS a um conjunto de técnicas ou atividades pontuais, sem considerar sua dimensão crítica e reflexiva.

Neste contexto, é de fundamental importância relacionar a educação STEM à CTS, pois esta interconexão pode ajudar os estudantes a entenderem como essas áreas estão interconectadas e como elas se aplicam no mundo real, o que é um dos objetivos da CTS.

É fundamental refletir que quem trabalha com a abordagem STEM no ensino de engenharia com enfoque CTS, reconheça o processo dialógico, sem receita pronta ou uma metodologia a ser seguida, mas aponta possiblidades de encontrar seus próprios caminhos para promover suas experiências.

Dessa forma, entendemos com este estudo que a abordagem integrada pode ajudar a desenvolver, quer em docentes e discentes, habilidades importantes, como resolução de problemas com um pensamento crítico e colaborativo, contribuindo para a formação de indivíduos comprometidos com o meio ambiente e com uma sociedade mais justa e humana. E o âmbito das Engenharias é sensível a está construção. Portanto, destacamos ser de fundamental importância que os cursos de Engenharia incluam essa abordagem em seus currículos e que os professores sejam capacitados para trabalhar com ela.

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Global Journal of Researches in Engineering: I Numerical Methods

Volume 24 Issue 1 Version 1.0 Year 2024

Type: Double Blind Peer Reviewed International Research Journal

Publisher: Global Journals

Online ISSN: 2249-4596 & Print ISSN: 0975-5861

Application of Differentialintegral Functions

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GJRE-I Classification: ACM: (G.1), (G.2), (G.4), (F.1)



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Application of Differentialintegral Functions

Alexey S. Dorokhov ^α, Solomashkin Alexey Alekseevich ^σ, Vyacheslav A. Denisov ^ρ & Kataev Yuri Vladimirovich ^ω

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Research Results: As a result of the research, it is shown how the Laplace transform and Borel's theorem are used to calculate differentialintegral functions. It is shown how to use these functions to carry out differentiation and integration. It is presented how fractional derivatives and fractional integrals should be obtained. Dependencies for their calculation are obtained. Examples of their application for such functions as $\cos(x)$, $\exp(x)$ and loudness curves in music, Fletcher-Manson or Robinson-Dadson curves are shown.

Conclusions: Studies show the possibility of a wide application of differentialintegration functions in modern scientific research. These functions can be used both in office and in specialized programs where calculations of fractional derivatives and fractional integrals are needed.

Keywords: differentialintegral functions, derivative, fractional derivative, integral, fractional integral.

I. Introduction

n modern sciences, such as mathematics, physics, astronomy, economics and other sciences, there is little use of differential functions in calculations, because with the help of fractional derivatives and integrals, very few physical, natural, social and other processes are described that use not only the first and second derivatives, single and double integrals, but fractional derivatives and fractional integrals. So in classical mechanics, the first derivative is used as velocity, the second as acceleration, and the third as a jerk. A one-time integral is used to calculate the area under the curve, the mass of an inhomogeneous body, a two-time integral is used to calculate the volume of a cylindrical beam, a three-time integral is used to calculate the volume of the body.

They can be found in the equations of mathematical physics, where, in particular, generalized functions and convolutional operations on them are used, and in spectral analysis, and in operational calculus based on integral Fourier and Laplace transformations, and in many other methods where differentiation and integration of functions are used.

The basis of all these concepts is the derivative and integral 1 . Two mathematical operations that are "opposite" to each other, like addition and subtraction, multiplication and division. Two "reciprocal" functions like sin(x) and arcsin(x), x^2 and \sqrt{x} , e^x and ln(x). Two mathematical operations that logically complement each other, the derivative of the integral does not change the integrable function, as does the integral of the derivative, leaves it unchanged.

Let us recall the symbols on graphs and in computer programs. Like any mathematical operation, they have their symbols (designations) on a piece of paper, like ordinary symbols on a computer screen. So, differentiation is denoted as y' or d/dx, and integration is $\int y(x)dx$. In this case, a one – time integral is denoted as $\int y(x)dx$, and a two - time integral is $\int \int y(x)z(t)dxdt$. With the derivative, the situation is more complicated, it has two designations:

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¹ And also, definitions of derivatives/integrals based on such concepts as the Riemann-Liouville, Grunwald-Letnikov and Weyl differentialintegrals.

y' and d/dx. Figure 1 shows (as one of the options) the currently existing designations of differentials and integrals, widely used in the literature.

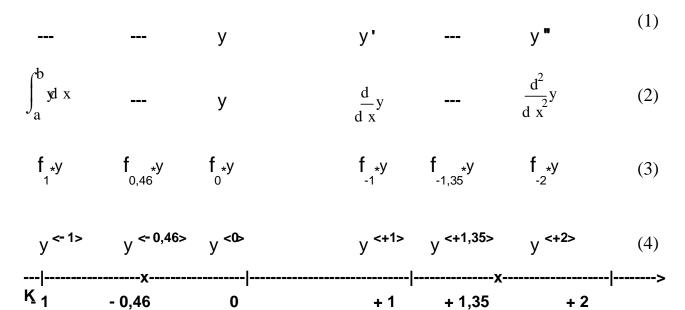


Figure 1: Notation of integrals and derivatives

As can be seen from Figure 1, all the variety of these notations has one property common to all: they try to reflect in various ways, either with the help of numbers or graphically, the order of derivatives or the multiplicity of the integral.

In order to unify the record of derivatives and integrals, consider them relative to a certain numerical axis "K" (Figure 2), where the value of the parameter k corresponds to the multiplicity of the integral or the order of the derivative. So, in this scenario of notation, k = -1 corresponds to the designation of a single integral $\int y(x)dx$ from the 2nd line and the designation of the same integral f_1 *y from the 3rd row, and for k = 1- we have the designation of the first derivative y' from the 1st row and the designation of the same first derivative d /dx from the 2nd row.

The third line contains the notation of differentials and integrals based on convolutional operations of generalized functions: $y^{(k)} = f_{-k} * y$, where k > 0, a value unequal to an integer is called a fractional derivative of order k. An expression of the form: $y_{(k)} = f_k * y$ is called a primitive of order k, i.e. an integral of multiplicity k [1].

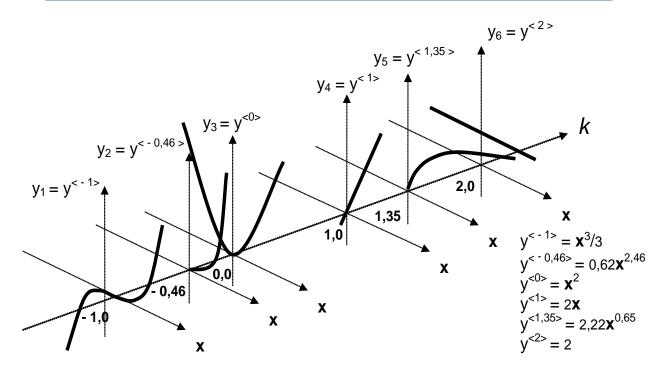


Figure 2: Notation of derivatives and integrals for a parabolay(x) = x^2

At the same time, all derivatives, including fractional ones, having a negative index, are located on the numerical axis on the right, and all integrals with a positive index - on the contrary, on the left. It was possible to arrange the designations differently, change the plus to minus, but the essence would not change at the same time. There are many types of symbols, binding to the numeric axis requires clarification.

To bring these notations in line with the numerical axis "K", the 4th line contains universal notations for derivatives of any order and integrals of any multiplicity, using angle brackets.

The angle brackets denote the order of the derivative or the multiplicity of the integral, for example, $y^{<0>}$ y(x) is the function under study, and $y^{<-7>} = \int y(x) dx$ is its integral, multiplicity 1. So $y^{<2>} = d^2/dx^2 = y''$ is the second derivative, and y <-0,46> is the integral, multiplicity 0,46. For example, a certain derivative of the order of 1,35 is denoted as $y^{<1,35>}$. In other words, if there is a positive number in the angle brackets, it means it is some kind of derivative, and if it is negative, it means it is an integral. And it is easy to read, and it is located correctly on the numeric axis: negative values of the k index are on the left, and positive values are on the right. This form of writing integrals and derivatives is very convenient, for example, for their designation on graphs or diagrams.

Figure 2 shows an example of the notation of derivatives and integrals for the parabola $y(x) = x^2$.

In addition to notation on graphs, this method can be used for programmers writing programs in various programming languages, for example,

```
int main () {
float y, u, z;
int n3;
z = y(4) < 1.5 > 
u=n3 < -0.25 >;
```

where $y^{<1,5>}$ is the derivative of the function y(4) of order 1,5 and $n3^{<-0.25>}$ is the integral of multiplicity 0,25 of the function n3.

In Figure 2, the integral of multiplicity -0.46 and the derivative of the order of 1,35 are shown for x > 0.

It should be borne in mind that when calculating a derivative of a "high" order, say, 123 orders – v <123>. previously it was necessary to perform 122 differentiation operations beforehand. This is due to the fact that the definition of the derivative/integral implies an increase in the order of the derivative/integral by only 1. It is impossible, using the existing definition of the derivative, to immediately calculate a high-order derivative from it. Only with the

help of sequential multiple calculations can the order of the derivative be increased to the desired value. The same applies to integration.

II. Materials and Methods

This method of calculating derivatives reduces the efficiency of using the differentiation operation, for example, in series expansions, because it requires calculating derivatives of a "high" order, and this is time-consuming and involves calculation errors. Therefore, in such calculations, only the first few terms of the decomposition are taken, and the rest are discarded, which increases the calculation error.

As for calculating integrals, especially multiplicities greater than 2, this is an even more difficult task. Thus, the lack of a simple, reliable and accurate method of differentiation and/or integration significantly hinders computational progress in mathematics.

The same problem is observed in physics. Many laws of mathematical physics, most often appearing in simple, accessible calculations, are based on the use, mainly, of the 1st, maximum 2nd derivative (for example, current i = dq / dt, force $F = m \cdot d^2x/dt^2$) and a single integral, for example, voltage across the capacitor $u(t) = 1 / C \cdot \int i(t)dt$.

It is very rare in everyday physics or mathematics to find a 3rd derivative or a 3-fold integral. This does not happen often. One of the ways to use a 3-fold integral is the Ostrogradsky-Gauss integral to calculate the volume of a body if the surface bounding this body is known.

And if you look more broadly, then neither in physics nor in mathematics have the everyday laws of the universe using fractional derivatives and integrals been discovered so far, because their calculation is fraught with great difficulties [1]. At the same time, it is possible that all the diversity of the world exists exactly there, in a fractional dimension, which can be described and studied, precisely with the help of fractional (analog), and not integer (discrete) integrals and differentials.

Take, for example, the mechanism of describing multidimensional structures, for example, multidimensional space. Our 3-dimensional space and one-dimensional time are described by discrete (integer) coordinate values, in this case one and three. At the same time, the question of the existence of a space having, not 3, but, say, 2,345 coordinates is of great scientific and practical interest. In other words, the structure of a special "fractional" space, no longer two-dimensional, is a plane (because to describe the plane, you need 2 coordinates, and we have more – 2,345), but also not a three-dimensional volume (where 3 coordinates are needed), i.e. something average between the plane and the volume. It is very difficult to imagine such a structure. In nature, such a space does not seem to exist.

It is even more difficult to determine the velocity or acceleration in such a space, i.e. to describe the kinematics of the motion of bodies. If it is possible to define the force in such a space (or to use the already existing classical method of specifying forces), then we can count on success in creating the dynamics of such structures, i.e., in other words, to create the mechanics of multidimensional space. At the same time, our classical 3-dimensional mechanics will turn out to be a special case of a more general mechanics – the mechanics of multidimensional spaces. This can be said about other physical laws of the universe.

And whether our idea of the world will change with the emergence of a new, more general, idea of space. So far we don't know much about this, because our concepts are tied to a three-dimensional dimensional space, and all the diversity of the world "lies" in a multidimensional "fractional" world that has not been studied at all.

A number of legitimate questions arise:

- What kind of space is "located", say, between a plane (2-dimensional space) and a volume (3-dimensional), i.e. a substance with the dimension of space R, where 2 < R < 3?
- What kind of physical quantity, which is between speed and acceleration between y <1> and y <2> from the move, i.e. a physical quantity, defined, for example, the fractional derivative of y <1,23>, the order of 1,23 (not 1 or 2)?
- Whether Newton's laws are applicable to the so-called fractional space?
- How will the definition of force in fractional space change (if it changes)?
- Will it be possible to apply the classical laws of mechanics to fractional space, or will it be necessary to create a new, more general, mechanics of the macro and microcosm?
- Will the interaction between space and time change if we "replace" the classical concept of space with a fractional one?
- Will there be changes in Einstein's theory of relativity and will the concepts of "gravitational, electromagnetic and other interactions" and much, much more remain the same?

Answers to these and other questions can be obtained if you have a convenient apparatus for calculating derivatives/integrals of any order/multiplicity, including fractional ones. In other words, it is necessary to create such

a calculation algorithm, simple and convenient, especially for novice researchers, where instead of calculating integrals/differentials, it would be possible to use the usual substitution of numbers, in which the desired order or multiplicity could be set without performing calculations, but simply substitute the desired parameter into the desired formula and get a ready derivative/integral without their calculations, i.e. immediately. Such a tool, which could be called, for example, functions - SL(x, k), would greatly simplify the process of calculating derivatives and integrals and significantly expand the boundaries of our knowledge.

First, we introduce the concepts of a differential integral function based on the definition of a differential integral. The differential integral function SL(x, k) is an ordinary function of several arguments, where, separated by commas, its arguments (in this case one -x) and the parameter k, the order of future derivatives and/or the multiplicity of integrals are indicated².

For example, for a parabola $y(x) = x^2$, such a differential function SL(x, k) will have the form³.

$$SL(x,k) := 2 \cdot \frac{x^{2-k}}{\Gamma(3-k)}$$
 (1)

where, x is the argument of the function.

k is a parameter that specifies the order of the derivative or the multiplicity of the integral.

This is the differential integral function of a parabola, the usual function of 2 arguments, argument x and parameter k. It represents a whole set of integrals and derivatives of any order and multiplicity⁴ (the main, mother function). How to use it? You need to set the parameter k and get the desired derivative or integral.

For example, for a parabola, we substitute k = 0 into it. Then, for k = 0y $(x, k) = x^2$, $(\Gamma(3 - k) = 2)^5$ the function (parabola) does not change. When k = 1y (x, k) = 2x and the parabola is transformed into its 1st derivative $y^{<1>}$. When k = -1 y $(x, k) = x^3/3$ and the function becomes its one-time integral $-y^{<-1>}$, and for k = -2 y $(x, k) = x^3/3$ $x^4/12$ - double - $y^{<-2>}$. No calculations, just substitution.

Fractional derivatives and integrals are of particular interest, because there is no simple and reliable way to calculate them, except for the method indicated above [2]. In this case, the method of obtaining is the same. To calculate them, it is enough to substitute the necessary value of the derivative instead of the parameter k, for example, k = 0.123 and the parabola becomes its derivative of the order 0.123 - y < 0.123 >:

$$SL(x,k) := 2 \cdot \frac{x^{2-0,123}}{\Gamma(3-0,123)} \ float, 3 \to 1,12$$
 (2)

If it is necessary to obtain an integral of multiplicity 3,45 - y < 3,45 > 1, it is enough to substitute k = -3,45 into the differential function (1) and the parabola becomes its integral of multiplicity 3,45 - y <-3,45>:

$$SL(x,k) := 2 \cdot \frac{x^{2+3,45}}{\Gamma(3+3,45)} float, 3 \rightarrow 7,6060^{-3} x^{5,4}$$
 (3)

This method of calculating fractional derivatives is no different from the method of obtaining integer (discrete) derivatives - the same substitution. There is no difference between an integer or fractional derivative/integral. Simple substitution to get a given result.

Consider another example: y(x) = sin(x). For a sine wave, the differential integral function SL(x,k) will have the following form:

$$SL(x,k) := \sin\left(x + k \cdot \frac{\pi}{2}\right) \tag{4}$$

This is a sine wave whose phase shift depends on the order of its derivative/multiplicity of its integral. At k = 10, the sine wave does not change, at k = 1, and becomes cos(x), i.e. its the first derivative is $y^{<1>}$, and at k = -1 it becomes $-\cos(x)$, i.e. its integral is $y^{<-1>}$. At -1 < k < 1, the function occupies an intermediate position between cos(x) and cos(x), including sin(x) at k = 0.

The differential integral function for the sine wave (4) is a graphical representation of the differential integral function, namely, the parameter k represents a part of the right angle for unit orts. At k = 1, the function SL(x, 1)becomes the 1st derivative, such a unit ort is perpendicular to the abscissa axis, and at k = var it is a fractional derivative of k order and the angle k (in values from 0 to 1 or in % of 90 degrees) it is only a part of the right angle.

For the exponent $y(x) = e^x$, the differential integral function SL(x, k) does not depend on k and all its derivatives and integrals are equal to each other and equal to the exponent itself.

² Here SL(x, k) is another form of writing a power differential function, different from writing the formy<k>.

³ Here and further calculations are performed in the MathCad program, so it uses a dot in its formulas instead of a comma.

⁴ As the latter, there may be the differentialintegral functions themselves. In this case, the parameter k can also be a complex value.

 $^{^{5}}$ G(x) - gamma function.

These examples can be summarized in Table 1, where its derivatives and integrals are given for some elementary functions.

		and integrals

y<-1>	y<-0.5>	y<0>	y ^{<0.5>}	y<1.5>	SL (x, k)
$\frac{\Gamma(n+1) x^{n+1}}{\Gamma(n+2)}$	$\frac{\Gamma (n+1) x^{n+0,5}}{\Gamma (n+1,5)}$	X ⁿ	$\frac{\Gamma (n+1) x^{n-0,5}}{\Gamma (n+0,5)}$	$\frac{\Gamma (n+1) x^{n-1,5}}{\Gamma (n-0,5)}$	$\frac{\Gamma(n+1) x^{n-k}}{\Gamma(n+1-k)}$
x ³ /3	0,601x ^{2.5}	x ²	1,504x ^{1.5}	2,256x ^{0.5}	<u>2 х^{2-к}</u> Г (3- <i>k</i>)
e ^x	e ^x	e ^x	e ^x	e ^x	e ^x
sin(x-π/2)	sin(x-0,5.π/2)	sin(x)	sin(x+0,5.π/2)	sin(x+1,5.π/2)	$\sin (x+k\pi/2)$

Differential functions can be a function of 2 or more arguments, for example, SL (x, y, k), where (x) and (y) are two arguments of the same function: $SL(x, y, k_x, k_y) = 2 \cdot k_y + (x - y) \cdot k_x$, and k_x and k_y - are still a parameter. In addition, any continuous elementary function can be used as a parameter, including the same differential integral function, for example:

$$(x, y, k1, k2) := x^{\sin\left(y \cdot k1 + \frac{\pi}{2}k2\right)}$$
(5)

Of particular interest is the differential integral function, in which the parameter k is a complex number s, s = 1 $a+i\cdot b$, although in general, the parameter k can be any function of a real or complex argument.

III. RESEARCH RESULTS

To obtain the differential integral function, we recall the Laplace integral transformation and Borel's theorem. The integral Laplace transform has the form

$$L[f(t)] = F(s) = \int_0^\infty f(t)e^{-st}dt \equiv [f(t) \cdot e^{-st}dt]^{<-1>_{0 < t < \infty}}$$
(6)

where s = a + i * b is a complex quantity. Here f(t) is the original function, and F(s) is its Laplace image. This is a direct conversion of the original into an image. The inverse Laplace transform

$$f(t) := \frac{1}{2\pi i} \cdot \int_{\sigma - i \cdot \infty}^{\sigma + i \cdot \infty} e^{st} F(s) ds \equiv [e^{st} \cdot F(s) \cdot ds]^{\langle -1 \rangle_{\sigma - i \cdot \infty} \langle \sigma + i \cdot \infty}$$
 (7)

it is necessary to find the original of the function by its image.

Let's consider one of the main properties of this transformation – the differentiation of the original function.

Let L[f(t)] = F(s). Let's find $L[f(t)^{<1>}]$, where $f(t)^{<1>}$ is the 1st derivative, and $L[f(t)^{<1>}]$ is its image.

$$L[f(t)^{<1>}] = [f(t)^{<1>} \cdot e^{-st} dt]^{<-1>_{0 < t < \infty}} = e^{-st} \cdot f(t)_{0 < t < \infty} + s \cdot [f(t) \cdot e^{st} dt]^{<-1>_{0 < t < \infty}}$$
(8)

If for $t \rightarrow \infty$ the function f(t) increases no faster than $M * e^{at}$, then $e^{-st} * f(t) \rightarrow 0$ for $t \rightarrow \infty$ and is equal to f(0), and

$$L[f(t)^{<1>}] = s * F(s) - f(0)$$
 (9)

For f(0) = 0

$$L[f(t)^{<1>}] = s * F(s)$$

$$\tag{10}$$

and the differentiation of the original function corresponds to the multiplication of the image of the function by s. Let's consider another important property – the integration of the original.

If $g(t) = [f(\tau)d\tau]^{<-1>}_{0<\tau< t}$ then under zero initial conditions $g(t)^{<1>} = f(t)$ and

$$L[g(t)^{<1>}] = L[f(t)] = s * L[g(t)] = s * L[[f(\tau) d\tau]^{<-1>} |_{0 < \tau < t}]$$
(11)

Since L[f(t)] = F(s), then

$$L\left[\left[f\left(\tau\right)^{\star}d\tau\right]^{<1}\right]_{0<\tau< t} = F(s)/s \tag{12}$$

that is, the integration of the function corresponds to the division of the image F (s) by s.

Taking into account expressions (14) and (16), we can conclude that the operations of differentiation/integration of the original can be replaced by algebraic actions (multiplication/division by s) on their images [3]. Thanks to this replacement, this method has found the widest application in integral and differential calculus [4].

However, the case is of particular interest when the function is represented as

$$L[f(t)] = F(s)/(s^{-k})$$
(13)

that is, the image is divided by (s-k). In this case, depending on k, we get fractional derivatives/integrals. For k > 0, fractional derivatives of the order k are formed, and for k < 0, fractional integrals of the same multiplicity are formed.

$$L[f(t)] = \frac{F(s)}{s^{-k}} = 1/(\Gamma(-k))$$
 (14)

$$SL(x, k) = L[f(t)]$$
(15)

These expressions (18) and (19) define fractional derivatives/integrals of order k, and are the differential functions of the desired function f(t). Examples of these functions are shown in Table 1.

Let's consider some examples of the use of differential integral functions in solving approximation problems. Suppose must be approximated by a power series $p_{\mathcal{A}} cos(x)$ in a neighborhood of the point x0, the function cos(x), and choose the polynomial coefficients $a_0...a_5$ so as to minimize the mean square error of approximation of this polynomial are:

$$\cos(x) = a_0 + a_1 \cdot x + a_2 \cdot x^2 + a_3 \cdot x^3 + a_4 \cdot x^4 + a_5 \cdot x^5$$
 (16)

and at the selected point is known for its derivatives and differentials, as an integer and the fraction.

To do this, we fulfill the approximation conditions according to which the value of the polynomial $\cos(x)$ and its fractional derivatives (for simplicity of calculation, only six (5) derivatives are used⁶. To increase the accuracy, you can use more, for example, several dozen derivatives, the computer allows it. Instead of derivatives, its integrals can also be used in the same way) in the vicinity of a given point x0, from the domain of the polynomial definition, should equal the corresponding values of the desired function $\cos(x)$ and its fractional derivatives (and integrals). 2 points are selected as points -x = 3 and x = 15.

The fractional derivatives/integrals for the elements of the polynomial are defined as

$$SL(x,n,k) := \frac{\Gamma(n+1) \cdot x^{n-k}}{\Gamma(n+1-k)}$$
(17)

where x -is the matrix of diagnostic information;

n - is the exponent of the polynomial;

k- is a parameter that sets the multiplicity of the integral or the order of derivatives.

Further, solving a linear algebraic equation of the form:

$$a = A1^{-1} \cdot B1$$
 (18)

we obtain the solution of this equation in the form of the desired coefficients $a_0...a_5$ (Application A Figure A.1).

The solution was made in the MathCad program, the calculation listing is given for the point x = 3 and additionally for x = 15.

Another example. In addition to the approximation at a point, using the differential integral functions, it is possible to approximate on a given segment. Examples of this approximation are given below.

Let it be necessary to approximate, for simplicity, the known functions $\cos(x)$ and the exponent $\exp(x)$, as well as $\cos(x)$ on the plot 4 < x < 6, as well as volume curves, according to the type of Fleicher-Manson or Robinson-Dadson curves. For ease of calculation, we approximate 6 points for 2 $\cos(x)$ functions, 4 (four) points for the exponent $\exp(x)$ and 23 for volume curves.

For a sine wave, the desired points will be of two types. In the first case, these are the points -5, -4, -2, 1, 3, 5. In the second case, this is -5, -3, -1, 1, 3, 5.

We will approximate the sinusoid with a polynomial (17).

Exponent – exponent.

⁶ To approximate in this case, it is to decompose into a power series using differential integral functions in the vicinity of the point x_0 , bearing in mind that these points are the values of the function $f(x) = \cos(x)$.

For the first case, for points -5, -4, -2, 1, 3, 5 the initial data obtained by formula (17) will have the following form.

$$A2 := \begin{pmatrix} 1 & -5 & 25 & -125 & 625 & -3125 \\ 1 & -4 & 16 & -64 & 256 & -1024 \\ 1 & -2 & 4 & -8 & 16 & -32 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 3 & 9 & 27 & 81 & 243 \\ 1 & 5 & 25 & 125 & 625 & 3125 \end{pmatrix} \qquad B2 := \begin{pmatrix} \cos(-5) \\ \cos(-4) \\ \cos(-2) \\ \cos(1) \\ \cos(3) \\ \cos(5) \end{pmatrix} \qquad b2 := A2^{-1} \cdot B2 \quad b2 = \begin{pmatrix} 0.615 \\ 0.207 \\ -0.257 \\ -0.036 \\ 9.731 \times 10^{-3} \\ 1.117 \times 10^{-3} \end{pmatrix}$$

As a result of calculating the series rjad_cos (x), we get the values of cos (x).

$$rjad_1\cos(x) := b2_0 + b2_1 + b2_2 \cdot x^2 + b2_3 \cdot x^3 + b2_4 \cdot x^4 + b2_5 \cdot x^5$$
 (19)

The graphs of these two functions cos (x) and rjad 1 cos(x) and some values of these graphs are shown in Figure 3.

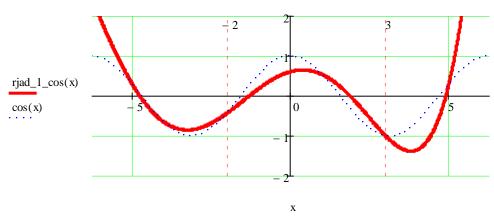


Figure 3: Values of the functions-rjad 1 cos (x) and cos (x)

$$rjad_1\cos(-5) = 0.284$$

 $\cos(-5) = 0.284$

$$rjad_1\cos(-2) = -0.416$$

 $\cos(-2) = -0.416$

$$rjad_1\cos(3) = -0.99$$

 $\cos(3) = -0.99$

$$rjad_1\cos(-4) = -0.654$$

 $\cos(-4) = -0.284$

$$rjad_1\cos(-1) = 0.54$$

 $\cos(-1) = 0.54$

$$rjad_1\cos(5) = 0.284$$

 $\cos(5) = 0.284$

For another cosine, for the values -5, -3, -1, 1, 3, 5 the initial data obtained by the formula (17) will have the following form:

$$A3 := \begin{pmatrix} \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_0, -\mathbf{n}_5, 0 \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_1, -\mathbf{n}_5, 0 \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_2, -\mathbf{n}_5, 0 \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_3, -\mathbf{n}_5, 0 \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_4, -\mathbf{n}_5, 0 \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_0, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_5, 0 \end{pmatrix} \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_5, 0 \end{pmatrix} \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_5, 0 \end{pmatrix} \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_5, 0 \end{pmatrix} \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_2, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_3, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_4, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_5, 0 \end{pmatrix} \end{pmatrix} \end{pmatrix} \\ & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{n}_1, 0 \end{pmatrix} & \mathrm{SL} \begin{pmatrix} \mathbf{x}_5, -\mathbf{$$

$$B3 := \begin{pmatrix} \cos(-5) \\ \cos(-3) \\ \cos(-1) \\ \cos(1) \\ \cos(3) \\ \cos(5) \end{pmatrix} \quad -x := \begin{pmatrix} -5 \\ -3 \\ -1 \\ 1 \\ 3 \\ 5 \end{pmatrix} \qquad d = A3^{-1} B3$$

$$rjad_2\cos(x) := d_0 + d_1x + d_2x^2 + d_3x^3 + d_4x^4 + d_5x^5$$
 (20)

The graphs of these two functions cos (x) and rjad_2_cos(x) and some values of these graphs are shown in Figure 4.

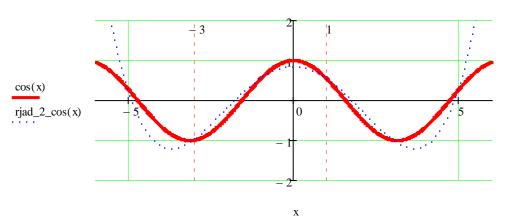


Figure 4: Values of the functions - rjad 2 cos (x) and cos (x)

$$rjad_2_\cos(-5) = 0.284$$
 $rjad_2_\cos(1) = 0.54$ $\cos(-5) = 0.284$ $\cos(1) = 0.54$ $\cos(1) = 0.54$ $rjad_2_\cos(-3) = -0.99$ $\cos(-3) = -0.99$ $\cos(3) = -0.99$ $rjad_2_\cos(-1) = 0.54$ $rjad_2_\cos(5) = 0.284$ $\cos(-1) = 0.54$ $\cos(5) = 0.284$

If we look at the same graphs in other coordinates, we can say that at these points the graphs coincide with their values, and at other points they do not, and they differ significantly.

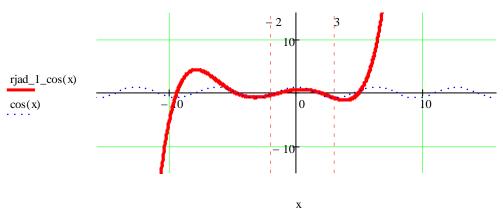


Figure 5: Values of the functions-rjad 1 cos (x) and cos (x)

The values of these two functions- $rjad_1\cos(x)$ and $\cos(x)$ in other coordinate systems coincide only in this section in $\pm 2\pi$, and for other values of the argument they differ greatly.

Figure 6 shows the values of these two functions rjad_2_cos(x) and cos (x).

In the given figure shows that the values of these two functions $r_jad_2\cos(x)$ and $\cos(x)$ in different coordinate systems coincide only in this region of \pm 6, and for other values of the argument vary greatly.

This suggests that approximation by differential integral functions is possible both at a point and at a certain area. The approximation error is minimal and can be reduced by increasing the number of terms of the polynomial.

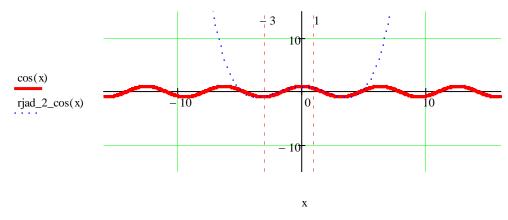


Figure 6: Values of the functions-rjad 2 cos (x) and cos (x)

(21)

The exponent can be approximated by the exponent itself. An example is shown below in Figure 7.

$$A1 := \begin{pmatrix} 1^{0} & 1^{1} & 1^{2} & 1^{3} \\ 2^{0} & 2^{1} & 2^{2} & 2^{3} \\ 7^{0} & 7^{1} & 7^{2} & 7^{3} \\ 10^{0} & 10^{1} & 10^{2} & 10^{3} \end{pmatrix} \qquad B1 := \begin{pmatrix} e^{1} \\ e^{2} \\ e^{7} \\ e^{10} \end{pmatrix} \qquad a := A1^{-1} \cdot B1 \qquad a = \begin{pmatrix} -1.19 \times 10^{3} \\ 1.966 \times 10^{3} \\ -863.71 \\ 89.924 \end{pmatrix}$$

$$k \coloneqq \begin{pmatrix} 1 & 2 & 7 & 10 \end{pmatrix}^{T}$$

$$e^{k} = \begin{pmatrix} 2.718 \\ 7.389 \\ 1.097 \times 10^{3} \end{pmatrix}$$

$$rjad_\exp(x) := a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

$$rjad_\exp(1) = 2.718 \qquad e^1 = 2.718$$

$$rjad_\exp(2) = 7.389 \qquad e^2 = 7.389$$

$$rjad_\exp(7) = 1.097 \times 10^3 \qquad e^7 = 1.097 \times 10^3$$

$$rjad_\exp(10) = 2.203 \times 10^4 \qquad e^{10} = 2.203 \times 10^4$$

Figure 7 shows the values of these two functions - rjad exp(x) and exp(x).

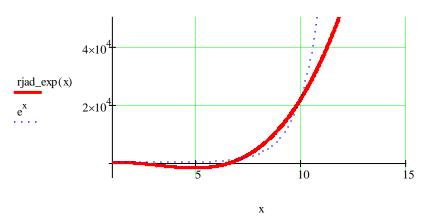


Figure 7: Values of the functions - rjad exp (x) and exp (x)

The graph of the cos(x) function on the section from x = 4 to x = 6 and the initial data are shown below in Figure 8.

$$k_1 \coloneqq 1 + 1 \cdot 10^{-6}$$

$$SL(x,k,n) \coloneqq \frac{x^{n-k} \cdot \Gamma(n+1)}{\Gamma(n-k+1)}$$
 The set point - μ
$$\mu \coloneqq 5$$

$$A1 := \begin{pmatrix} 1 & \mu & \mu^2 & \mu^3 & \mu^4 & \mu^5 \\ \frac{\mu^{-0.25} \cdot \Gamma(1)}{\Gamma(1-0.25)} & \frac{\mu^{1-0.25}}{\Gamma(2-0.25)} & \frac{2 \cdot \mu^{2-0.25}}{\Gamma(3-0.25)} & \frac{6 \cdot \mu^{3-0.25}}{\Gamma(4-0.25)} & \frac{120 \cdot \mu^{5-0.25}}{\Gamma(5-0.25)} \\ \frac{\mu^{-0.5} \cdot \Gamma(1)}{\Gamma(1-0.5)} & \frac{\mu^{1-0.5}}{\Gamma(2-0.5)} & \frac{2 \cdot \mu^{2-0.5}}{\Gamma(3-0.5)} & \frac{6 \cdot \mu^{3-0.5}}{\Gamma(4-0.5)} & \frac{24 \cdot \mu^{4-0.5}}{\Gamma(5-0.5)} & \frac{120 \cdot \mu^{5-0.5}}{\Gamma(6-0.5)} \\ \frac{\mu^{-0.5} \cdot \Gamma(1)}{\Gamma(1-0.5)} & \frac{\mu^{1-0.5}}{\Gamma(2-0.5)} & \frac{2 \cdot \mu^{2-0.5}}{\Gamma(3-0.5)} & \frac{6 \cdot \mu^{3-0.5}}{\Gamma(4-0.5)} & \frac{24 \cdot \mu^{4-0.5}}{\Gamma(5-0.5)} & \frac{120 \cdot \mu^{5-0.5}}{\Gamma(6-0.5)} \\ \frac{\mu^{-0.75} \cdot \Gamma(1)}{\Gamma(1-0.75)} & \frac{\mu^{1-0.75}}{\Gamma(2-0.75)} & \frac{2 \cdot \mu^{2-0.75}}{\Gamma(3-0.75)} & \frac{6 \cdot \mu^{3-0.75}}{\Gamma(4-0.75)} & \frac{24 \cdot \mu^{4-0.75}}{\Gamma(5-0.75)} & \frac{120 \cdot \mu^{5-0.75}}{\Gamma(6-0.75)} \\ \frac{\mu^{-k_{-1}} \cdot \Gamma(1)}{\Gamma(1-k_{-1})} & \frac{\mu^{1-1}}{\Gamma(2-1)} & \frac{2 \cdot \mu^{2-1}}{\Gamma(3-1)} & \frac{6 \cdot \mu^{3-1}}{\Gamma(4-1)} & \frac{24 \cdot \mu^{4-1}}{\Gamma(5-1)} & \frac{120 \cdot \mu^{5-1}}{\Gamma(6-1)} \\ \frac{\mu^{-1.25} \cdot \Gamma(1)}{\Gamma(1-1.25)} & \frac{\mu^{1-1.25}}{\Gamma(2-1.25)} & \frac{2 \cdot \mu^{2-1.25}}{\Gamma(3-1.25)} & \frac{6 \cdot \mu^{3-1.25}}{\Gamma(4-1.25)} & \frac{24 \cdot \mu^{4-1.25}}{\Gamma(5-1.25)} & \frac{120 \cdot \mu^{5-1.25}}{\Gamma(6-1.25)} \end{pmatrix}$$

$$B1 := \begin{pmatrix} \cos\left(\mu + 0.00 \cdot \frac{\pi}{2}\right) & \alpha = A1^{-1} B1 \\ \cos\left(\mu + 0.25 \cdot \frac{\pi}{2}\right) \\ \cos\left(\mu + 0.50 \cdot \frac{\pi}{2}\right) \\ \cos\left(\mu + 0.75 \cdot \frac{\pi}{2}\right) \\ \cos\left(\mu + 1.00 \cdot \frac{\pi}{2}\right) \\ \cos\left(\mu + 1.25 \cdot \frac{\pi}{2}\right) \end{pmatrix}$$

$$-\cos(x) := a_0 + a_1 \cdot x + a_2 \cdot x^2 + a_3 \cdot x^3 + a_4 \cdot x^4 + a_5 \cdot x^5$$
(22)

 $\cos(5) = 2,836622 \cdot 10^{-1}$ $\cos(5) = 2.836622 \cdot 10^{-1}$

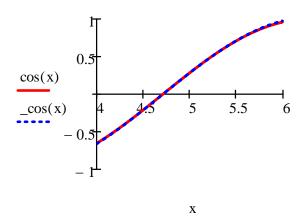


Figure 8: Values of the functions - cos(x) and cos (x)

Additionally, the application of differential integration functions in music, curves of equal loudness, for example, Fletcher-Manson curves or Robinson-Dudson curves, Figure 9, is presented.

10 17 22 23 6 11 16 18 19 20 21 1.104 1.25.10 200 250 400 500 630 800 1.103 1.25.103 2.5·10³ 3.15·10³ 4.103 5·10³ 8-103 40 100 160 315 1.6-103 2.103 6.3·10³ 20 63 KRG= 9.43 9.21 2.996 3.689 4.143 4.605 5.075 5.298 5.521 5.753 5.991 6.215 6.446 6.685 6.908 7.131 7.378 7.601 7.824 8.055 8.294 8.517 8.748 8.987 105.3 82.9 91.7 85. 119 98.4 92.5 87.8 84.3 81.7 80.9 80.2 79.7 80 82.5 83.7 80.6 77.9 77.1 78.3 86.8 91.4 81.6

$$SL(x,n,k) \coloneqq \frac{x^{n-k} \cdot \Gamma(n+1)}{\Gamma(n-k+1)} \qquad \qquad \begin{array}{c} i \coloneqq 0..23 \\ j \coloneqq 0..23 \\ k \coloneqq 0 \end{array} \qquad 0,2,7,11,12,14,16,17,19,21,22,23$$

$$\mathbf{n} := \begin{pmatrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \\ 10 \\ 11 \end{pmatrix} \qquad \begin{pmatrix} 2.996 \\ 4.143 \\ 5.753 \\ 6.685 \\ 7.378 \\ 7.824 \\ 8.055 \\ 8 \\ 9 \\ 10 \\ 11 \end{pmatrix} \qquad \mathbf{n} := \begin{pmatrix} 119 \\ 98.4 \\ 82.9 \\ 79.7 \\ 80 \\ 83.7 \\ 77.9 \\ 80 \\ 83.7 \\ 77.9 \\ 77.1 \\ 81.6 \\ 91.4 \\ 9.21 \\ 9.433 \end{pmatrix} \qquad \mathbf{n} := \begin{pmatrix} 119 \\ 98.4 \\ 82.9 \\ 79.7 \\ 80 \\ 83.7 \\ 77.9 \\ 77.1 \\ 81.6 \\ 91.4 \\ 91.7 \\ 85.4 \end{pmatrix}$$

$$B := \begin{pmatrix} 119 \\ 98.4 \\ 82.9 \\ 79.7 \\ 80 \\ 83.7 \\ 77.9 \\ 77.1 \\ 81.6 \\ 91.4 \\ 91.7 \\ 85.4 \\ \end{pmatrix}$$

$$rjad(x) := a_0 + a_1 \cdot x + a_2 \cdot x^2 + a_3 \cdot x^3 + a_4 \cdot x^4 + a_5 \cdot x^5 + a_6 \cdot x^6 + a_7 \cdot x^7 + a_8 \cdot x^8 + a_9 \cdot x^9 + a_{10} \cdot x^{10} + a_{11} \cdot x^{11}$$
(23)

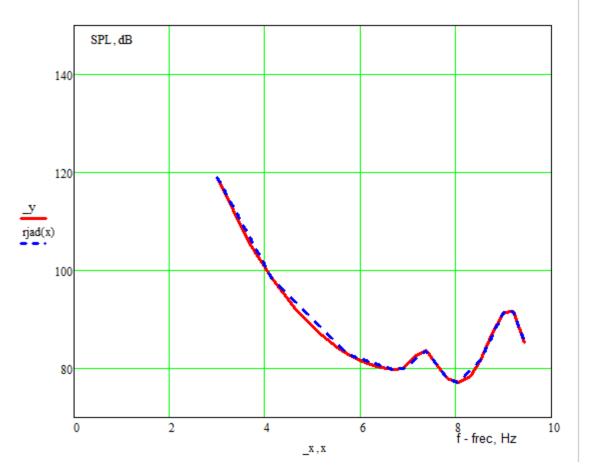


Figure 9: Curves of equal loudness y, dB and a curve approximating them rjad(x), Hertz

From the materials presented in the figures, it can be seen that for a given number of points, the approximation is satisfactory.

IV. Conclusions

Differential integral functions, this is the Riemann-Liouville differential integral, written in a convenient form, as a function of two variables⁷: the usual argument x and the parameter k, which sets the multiplicity of the integral or the order of the derivative. These functions allow you to calculate the desired integral or derivative by substituting the parameter k into the established formula. The formula does not change, only one parameter changes. Classical tables of integrals and differentials are not required. Only tables of pre-prepared formulas of differential functions are used, which can be represented in simple calculations in the form of icons, and in the form of SL (x, k) functions in computer programs written in programming languages such as VBasic, C++, Excel, MathCad, Python, etc.

These differential integral functions are of great practical importance, for example, they allow us to approximate a certain given function in the vicinity of the desired point (by the type of decomposition into a Taylor, Maclaurin, Fourier series or Z transformation) or on a segment. At the same time, the conditions of equality of not only the function itself, but also the selected derivatives and differentials, integer and fractional, are observed at the desired approximation points themselves.

Examples of approximation of some elementary functions are shown, for example, using a standard polynomial. It is also possible to approximate trigonometric, power functions and their combinations.

To simplify working with differential integral functions, they can be represented in two forms: for a graphic image-as a function with angle brackets, and for writing in the program text-as a function SL(x, k) of two or more arguments (Application B).

⁷ There may be other parameters, for example, integration limits, constants, etc.

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APPLICATION A

Figure A.1: Decomposition of the function $\cos(x)$ into a series $\cos(x)$ in the vicinity of two different points $\mu = 3$ and $\mu = 15$

 $\cos(3) = -9.899925 \times 10^{-1}$

The system consists of the polynomial $\cos(x)$ and its six fractional derivatives ki, with a maximum multiplicity of 1.25. The order of the derivatives of *k* changes after 0.25.

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Application B

Differential integral functions of SL().

The text of the VBasic program for calculating the differential functions of SL() is given below.

The text of the program in VBasic for calculating the differential functions of SL ().

Option Explicit

Dim n, k As Double Dim in_n, in_k As Double Dim Message1, Title1, Default, MyValue Dim Message2, Title2 Dim MathcadObj Dim MCWSheet

Private Sub Form_Load () Form1.Enabled = True Form1.Cls

Form1.Visible = False Form1.Appearance = 0 Form1.WindowState = 2

Call nk End Sub

Private Sub nk ()

Message1 = "Enter the degree <n> for the power function y = x n "

Title1= "Default n =2"

Default= "2"

MyValue = InputBox (Message1, Title1, Default)

n = CDbl (MyValue)

l ------

Message 2 = ```Enter K. If K < 0, then it is an integral of multiplicity K, and if K > 0, then it is a derivative of order K

k = InputBox (Message2, Title1, Default)

Call Gam End Sub

Private Sub Gam()

'Setting a custom function

Set MathcadObj = OLE1.object

Set MCWSheet = MathcadObj.Worksheet

 $in_n = n$ $in_k = k$

Call MathcadObj.setcomplex("in_n", n, 0)

Call MathcadObj.setcomplex("in k", k, 0)

'Recalculating results in MathCad and getting a custom SLFunctions function

Call MathcadObj.Recalculate

'End of the program

Dim Msg, Style, Title, Response

Msg = "Continue? Yes"

Style = vbYesNo + vbCritical + vbDefaultButton2

Title = "The program has finished working. Viewing the result"

Response = MsgBox (Msg, Style, Title)

If Response = 6 Then Form1.Enabled = False

Set MathcadObj = Nothing

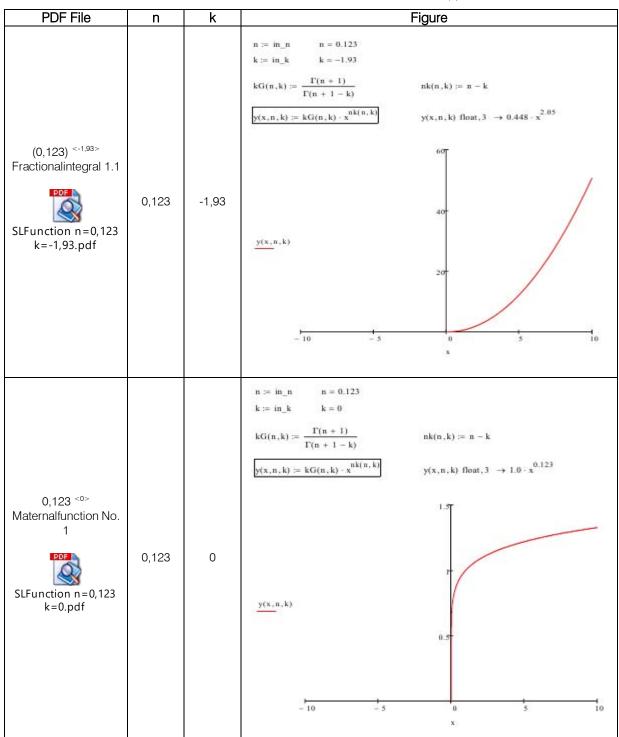
Set MCWSheet = Nothing

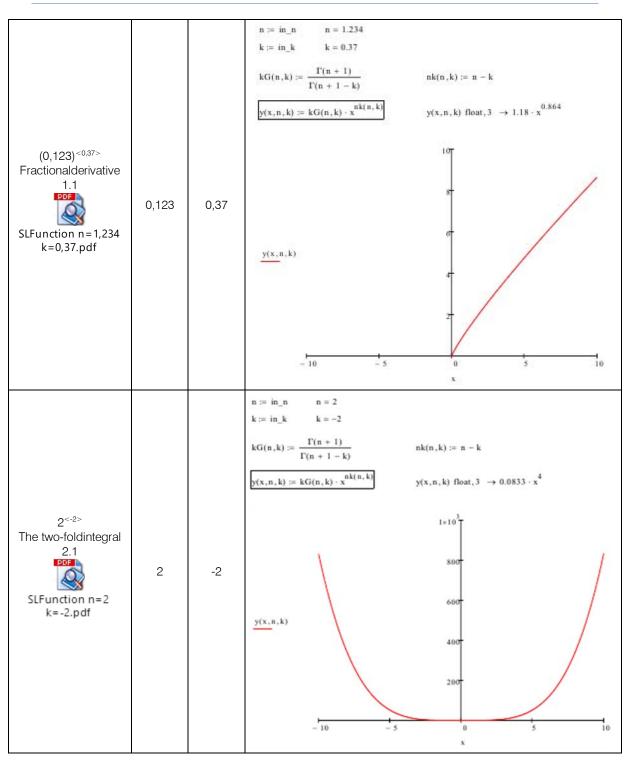
End

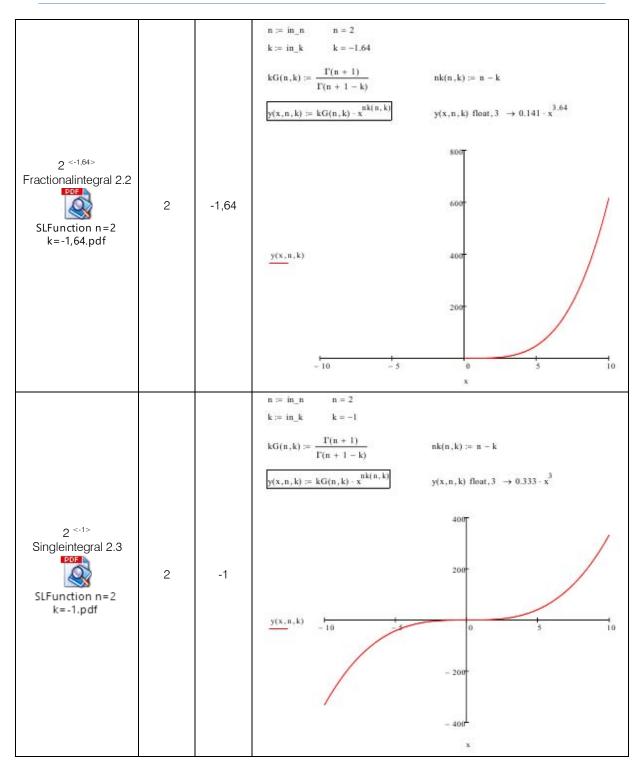
End Sub

Below, as an example, is a table (Table 1) with the results of calculating the differential functions on VBasic, where n is the exponent of the power function, and k is the parameter of the differential function. For k < 0 it is a fractional integral, k = 0 is the parent function, and for k > 0 it is a fractional derivative.

Table B.1: Values of functions $x^{0,123}$, x^2 , $x^{12,3}$ and sin(x)







2 <0> Maternal functionNo.2 SLFunction n=2 k=0.pdf	2	0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
2 <1> The firstderivative 2.1 SLFunction n=2 k=1.pdf	2	1	$\begin{array}{c} n := in_n & n = 2 \\ k := in_k & k = 1 \\ kG(n,k) := \frac{\Gamma(n+1)}{\Gamma(n+1-k)} & nk(n,k) := n-k \\ \hline \\ y(x,n,k) := kG(n,k) \cdot x^{nk(n,k)} & y(x,n,k) \text{ float, } 3 \to 2.0 \cdot x \\ \hline \\ \frac{20}{10} & 10 \\ \hline \\ -10 & -5 \\ \hline \end{array}$

			$\begin{array}{ll} n:=in_n & n=2 \\ k:=in_k & k=1.75 \\ \\ kG(n,k):=\frac{\Gamma(n+1)}{\Gamma(n+1-k)} & nk(n,k):=n-k \\ \\ \hline y(x,n,k):=kG(n,k)\cdot x^{nk(n,k)} & y(x,n,k) \ \text{float}, 3 \ \rightarrow 2.21 \cdot x^{0.25} \end{array}$
2 <1,75> Fractionalderivative 2.2 SLFunction n=2 k=1,75.pdf	2	1,75	y(x,n,k) 2 -10 -5 0 5 10
2 <2> The secondderivative 2.3 SLFunction n=2 k=2.pdf	2	2	$n := in_n \qquad n = 2 \\ k := in_k \qquad k = 2$ $kG(n,k) := \frac{\Gamma(n+1)}{\Gamma(n+1-k)} \qquad nk(n,k) := n-k$ $y(x,n,k) := kG(n,k) \cdot x^{nk(n,k)} \qquad y(x,n,k) \text{ float, } 3 \rightarrow 2.0$ 2.002 2.002 2.007 1.999

(12,34)<-0.45> Fractionalintegral 3.1 SL Fun 12,34 -0,45.xmcd	12,34	-0,45	Введите показатель степенной функции < n > $n := \frac{12.34}{12.34}$ Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 k := $\frac{-0.45}{-0.45}$ Дифферинтегральная Функция Y равна $y(x,n,k) := \frac{\Gamma(n+1)}{\Gamma(n+1-k)} \cdot x^{n-k}$ $y(x,n,k)$ float, $3 \to 0.315 \cdot x^{12.8}$ Вид этой функции представлен на графике
12,34 ^{<0>} Maternal functionNo.3 SL Fun 12,34 0.xmcd	12,34	0	Введите показатель степенной функции < n > $n := 12.34$ Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 k := 0 Дифферинтегральная Функция Y равна $y(x,n,k) := \frac{\Gamma(n+1)}{\Gamma(n+1-k)} x^{n-k}$ $y(x,n,k)$ float, $3 \to 1.0 \cdot x^{12.3}$ Вид этой функции представлен на графике

 1×10^{1}

5×10

2

6 4

y(x,n,k)

(12,34)<1.75> Fractionalderivative 3.1 SL Fun 12,34 1,75.xmcd	12,34	1,75	Введите показатель степенной функции < n > $n := \frac{12,34}{12,34}$ Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 k := $\frac{1.75}{1.75}$ Дифферинтегральная Функция Y равна $y(x,n,k) := \frac{\Gamma(n+1)}{\Gamma(n+1-k)} \cdot x^{n-k}$ $y(x,n,k)$ float, $3 \to 76.9 \cdot x^{10.6}$ Вид этой функции представлен на графике
sin(x)<-1.64> Fractionalintegral 4.1 Final State of the		-1,64	Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 $k := \frac{1.64}{1.64}$ Дифферинтегральная Функция Y равна $y(x,k) := \sin\left(x + k \cdot \frac{\pi}{2}\right)$ $y(x,k) \text{ float}, 3 \rightarrow \sin(x - 2.58)$ Вид этой функции представлен на графике

sin(x) <0> Maternal function No.4 sin x 0.pdf	0	Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 $ k := \boxed{0} $ Дифферинтегральная Функция Y равна $ y(x,k) := \sin \left(x + k \cdot \frac{\pi}{2} \right) $ $ y(x,k) \text{ float}, 3 \to \sin(x) $ Вид этой функции представлен на графике
sin(x) <1,75> Fractionalderivative 4.1 sin x 1,75.pdf	1,75	Введите порядок производной или интеграла < k > Для производной k > 0 для интеграла k < 0 $ k := \frac{1,75}{1,75} $ Дифферинтегральная Функция Y равна $ y(x,k) := \sin\left(x + k \cdot \frac{\pi}{2}\right) $ $ y(x,k) \text{ float, 3} \rightarrow \sin(x + 2.75) $ Вид этой функции представлен на графике



Global Journal of Researches in Engineering: I Numerical Methods

Volume 24 Issue 1 Version 1.0 Year 2024

Type: Double Blind Peer Reviewed International Research Journal

Publisher: Global Journals

Online ISSN: 2249-4596 & Print ISSN: 0975-5861

Investigating the Effects of Physical Parameters on First and Second Reflected Waves in Air-Saturated Porous Media under Low-Frequency Ultrasound Excitation

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Abstract- This simulation study investigates the impact of a 20% variation in physical parameters, including porosity, tortuosity, viscous and thermal characteristic lengths, and two newly introduced viscous and thermal shape factor parameters, on reflected waves at the first and second interfaces in air-saturated porous media under low-frequency ultrasound excitation. The acoustic behavior of air-saturated porous media is modeled using the equivalent fluid theory and the Johnson-Allard model, refined by Sadouki [Phys. Fluids 33, (2021)]. Our results demonstrate that a 20% variation in certain physical parameters significantly affects the reflected waves at the first and second interfaces in the low-frequency domain of ultrasound. This study enhances our understanding of the underlying mechanisms governing acoustic wave propagation in air-saturated porous media, which is valuable for optimizing ultrasound-based techniques in a range of applications, such as nondestructive testing, medical imaging, and noise pollution control in buildings, aircraft, automobile industry, and civil engineering sectors.

Keywords: air-saturated porous media, ultrasound, physical parameters, reflected waves, simulation study, equivalent fluid theory, Johnson-Allard model.

GJRE-I Classification: LCC: TA705



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I. Introduction

orous materials have a rich history that dates back to ancient times, and they continue to be of great importance in modern chemistry and materials science [1]. These materials exhibit unique properties that make them valuable across a wide range of applications, including biomedical, building and construction, aerospace, and environmental domains. Their diverse classifications, such as fibrous, granular agglomerates, polymeric, and construction materials, contribute to their widespread use in our daily lives.

In recent years, there has been a growing interest in the use of porous materials due to their versatility and unique properties. For example, in the biomedical field [2], porous materials have shown tremendous potential for drug delivery and tissue engineering. The porous structure of these materials

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allows for controlled drug release and promotes cell growth, making them ideal candidates for advanced medical applications. In the building and construction industry [3], porous materials are commonly used for insulation and soundproofing. Their ability to absorb sound waves through viscous friction and thermal exchanges makes them an excellent choice for reducing noise pollution. Similarly, in the aerospace industry[4], porous materials are used for thermal insulation and noise reduction.

The physical and mechanical parameters used to characterize the properties of porous materials include geometric tortuosity, viscous and thermal characteristic lengths [5-8], Young's modulus of elasticity, and Poisson's ratio. In the field of acoustics, porous materials are widely used to reduce noise pollution by absorbing a part of the sound waves through viscous friction and thermal exchanges [4]. Previous studies have been conducted to investigate the influence of physical parameters describing porous media on the transmitted signal in the low-frequency ultrasound regime [9-11]. However, there is a need for a more comprehensive numerical simulation study to determine the effect of physical parameters on the lowfrequency ultrasonic signal reflected by the first and second interfaces of the medium.

In this study, we address this gap by investigating the impact of a 20% variation in physical parameters, including porosity, tortuosity, viscous and thermal characteristic lengths, and two newly introduced viscous and thermal shape factor parameters, on the reflected waves at the first and second interfaces in airsaturated porous media in the low-frequency domain of ultrasound. The acoustic behavior of air-saturated porous media is modeled using the equivalent fluid theory and the Johnson-Allard model refined by Sadouki [12]. This study enhances our understanding of the underlying mechanisms governing acoustic wave propagation in porous media, providing valuable insights for optimizing ultrasound-based techniques in a range of applications, such as nondestructive testing, medical imaging, and noise pollution control in buildings, aircraft, automobile industries, and civil engineering.

II. Model

Acoustic propagation in porous materials is a complex phenomenon that involves the interaction of sound waves with fluid and solid components of the porous medium. When considering air-saturated porous materials with immobile solid skeletons, propagation is confined to the fluid, and this behavior is typically modeled using the equivalent fluid model [5,6], which is a particular case of Biot theory [13-15]. The two frequency response factors, the dynamic tortuosity of the medium $\alpha(\omega)$ and the dynamic compressibility of air in the porous material $\beta(\omega)$, are used to account for structure-fluid interactions. The dynamic tortuosity is provided by Johnson et al [5,6], while the dynamic compressibility is given by Allard [7]. In the frequency domain, these factors are multiplied by the density and compressibility of the fluid.

At extremely low and high frequencies, the equations governing the acoustic behavior of the fluid simplify and the parameters involved are different. In the high-frequency range [7], this simplification occurs when the viscous and thermal skin thicknesses $\delta(\omega)$ =

 $\sqrt{\frac{2\eta}{
ho_0\omega}}$ and $\delta'(\omega)=\sqrt{\frac{2\eta}{p_r\rho_0\omega}}$ are smaller than the pore radius r. (Here, the density of the saturating fluid is represented by $\rho 0$, the viscosity by η , the pulse frequency by ω , and the Prandtl number by Pr). In the low-frequency range of the ultrasonic domain, the dynamic tortuosity and compressibility are given by [12]:

$$\alpha(\omega) = \alpha_{\infty} \left(1 + \frac{\delta(\omega)}{\Lambda} \left(\frac{2}{j} \right)^{\frac{1}{2}} + \xi \left(\frac{\delta(\omega)}{\Lambda} \right)^{2} \left(\frac{2}{j} \right) + \cdots \right)$$
 (1)

$$\beta(\omega) = 1 + (\gamma - 1) \left(\frac{\delta'(\omega)}{\Lambda'} \left(\frac{2}{j} \right)^{1/2} + (\xi' - 1) \left(\frac{\delta'(\omega)}{\Lambda'} \right)^2 \left(\frac{2}{j} \right) + \dots \right)$$
 (2)

where, $j = \sqrt{-1}$ and γ is the adiabatic constant.

The relevant physical parameters of the models are the high-frequency limit of the tortuosity α_{∞} , the viscous and thermal characteristic lengths Λ and Λ' , respectively, and the dimensionless parameter ξ introduced by Sadouki [12], which is a shape factor related to the correction of the viscous skin depth of the air layer near the tube surface where the velocity distribution is significantly perturbed by the viscous forces generated by the stationary frame in the lowfrequency ultrasonic regime. ξ' is the associated thermal counterpart.

Consider a homogeneous porous material that occupies the region $0 \le x \le L$. A sound pulse normally strikes the medium, generating an acoustic pressure field p(x,t) and an acoustic velocity field $v(x,\omega)$ within the material (Fig. 1). These fields satisfy the Euler equation and the constitutive equation along the x-axis:

$$\rho_0 \alpha(\omega) j \omega \ v(x, \omega) = \frac{\partial p(x, \omega)}{\partial x}, \qquad \frac{\beta(\omega)}{K_a} j \omega \ p(x, \omega) = \frac{\partial v(x, \omega)}{\partial x},$$
(3)

Here, K_a is the compressibility modulus of the fluid.

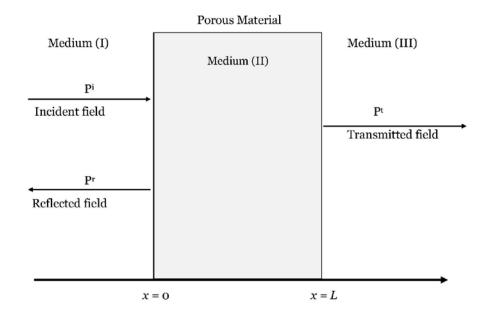


Figure 1: Problem geometry

The continuity of the pressure and velocity fields at the medium boundary gives the reflection coefficient of the porous material [17]:

$$R = \frac{(1-\tilde{Z}^2)\sinh(j\tilde{k}L)}{2\tilde{Z}\cos h(j\tilde{k}L) + (1+\tilde{Z}^2)\sinh(j\tilde{k}L)}$$
(4)

Where $\tilde{Z} = \frac{1}{\phi} \sqrt{\frac{\alpha(\omega)}{\beta(\omega)}}$ is the normalized characteristic impedance of the material, ϕ is the porosity, and $\tilde{k}=\omega\sqrt{\frac{\rho_0\alpha(\omega)\beta(\omega)}{\kappa_a}}$ is the wave number of the acoustic wave in the porous medium. The incident and reflected fields p^i and p^r_{sim} are related in the frequency domain by the reflection coefficient R:

$$p_{sim}^{r}(x,\omega) = R p^{i}(x,\omega)$$
 (5)

In the time domain, the reflected signal $p_{sim}^{r}(x,t)$ is obtained by taking the inverse Fourier transform of Eq. (5):

$$P^{t}(x,t) = \mathcal{F}^{-1}\left(R P^{i}(x,\omega)\right) \tag{6}$$

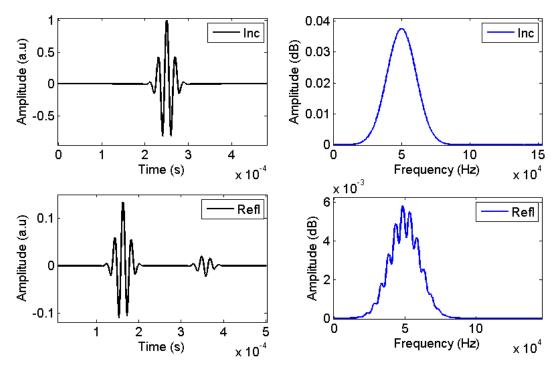


Figure 2: The incident and reflected signals of a monolayer porous medium constructed in frequency via expression (5) and in time via Eq. (6)

The simulated incident and reflected signals of a single-layer porous medium are shown in Fig. 2, and were obtained by expression (5) in the frequency domain and equation (6) in the time domain. The characteristic parameters of the porous medium are as follows: L = 3.0 cm, ϕ = 0.85, α_{∞} = 1.2, Λ = 300 μm , Λ'/Λ = 3, ξ = 10, and ξ/ξ' = 2. These signals were generated using the Gauss function in Matlab with center frequencies of 50 kHz and 120 kHz. In the time domain, two successive reflections on the first and second interface can be clearly observed, as shown in black color below in Figure 2.

III. SIMULATION STUDY

To investigate the influence of physical parameters, such as porosity, tortuosity, viscous and thermal characteristic lengths, and newly introduced shape factors on the reflected waves, a parameter analysis was performed. Specifically, each parameter was varied while holding the others constant, and the impact on the first and second reflected waves in the time domain, as indicated by equation (6), was observed. By systematically varying each parameter and analyzing its effect on the reflected waves, we can better understand the individual contributions of these physical factors to the overall acoustic behavior of the porous material.

a) Effect of Porosity ϕ on the Reflected Signal

Figure 3 shows the impact of varying the porosity (ϕ) on the amplitude of the first and second reflected waves through a rigid porous medium, while keeping the other parameters fixed at $\alpha_{\infty}=1.2$, $\Lambda=300$ μ m, $\Lambda'/\Lambda=3$, $\xi=10$, and $\xi/\xi'=2$. The porosity ϕ varies from +20% to -20% of its initial value ($\phi=0.85$). Table 1 presents the variation ratio of the reflection coefficient compared to a $\pm20\%$ variation of each parameter.

According to Table 1, a significant influence of porosity on the reflected signal is observed at frequencies of 50 kHz and 120 kHz. When the porosity increases by +20%, the modulus of the first and second reflected signals decrease by -66.84% and -65.06%, respectively. Conversely, when the porosity decreases by -20%, the amplitude of the 1st and 2nd reflected signals increases by +80.26% and +71.32% respectively. Moreover, the sensitivity of the porosity \$\phi\$ increases with frequency, as also shown in Table 1.

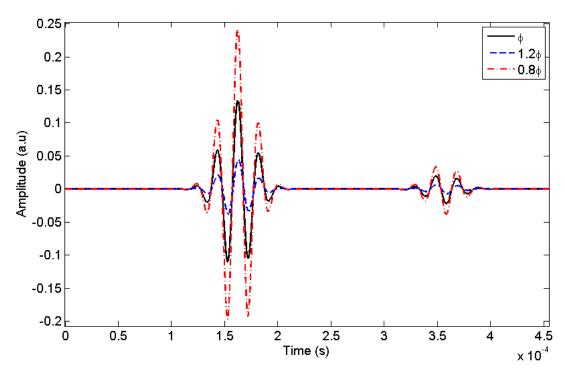


Figure 3: Sensitivity of porosity ϕ on the 1st and 2nd reflected signals at 50 kHz

b) Effect of Tortuosity $\pmb{\alpha}_{\!\scriptscriptstyle \infty}$ on the Reflected Signal

Figure 4 illustrates the sensitivity of tortuosity $\alpha_{\scriptscriptstyle \infty}$ on the 1st and 2nd reflected waves, for an excitation pulse of frequency 50 kHz. When the initial tortuosity value is increased by +20%, the amplitude of the 1st and 2nd reflected waves increases by +33.16% and 10.82%, respectively. Conversely, a decrease of -20% in

tortuosity results in a decrease in the amplitude of the 1st and 2nd reflected waves by -40.98% and -27.47%, respectively. Notably, the impact of tortuosity is more pronounced on the 1st reflected signal than on the 2nd. Additionally, the sensitivity of tortuosity to the reflected signal increases with frequency, as detailed in Table 1.

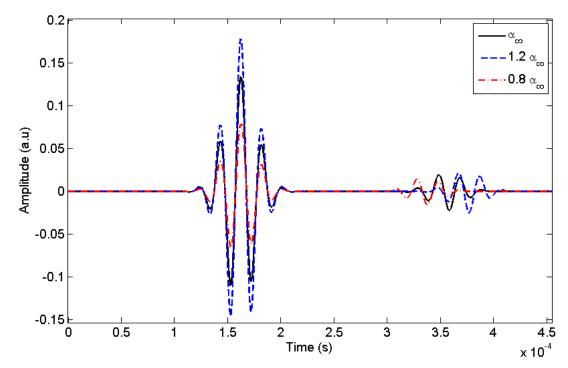


Figure 4: Sensitivity of Tortuosity α_{∞} on the 1st and 2nd Reflected Waves

) Effect of Viscous Characteristic Length 1 on the Reflected Waves

The impact of varying the viscous characteristic length on the 1st and 2nd reflected waves at high frequency is shown in Figure 5. With an excitation frequency of 50 kHz, a +20% change in Λ results in a -1.07% decrease in the amplitude of the first reflected wave and a 42.76% increase in the amplitude of the

second reflected signal. Furthermore, as the frequency increases, the sensitivity of the viscous characteristic length decreases for the 1st reflected wave and increases for the 2nd reflected wave. Therefore, we can conclude that the viscous characteristic length has a relatively small influence on the 1st reflected wave at high frequency but a high sensitivity on the 2nd reflected wave.

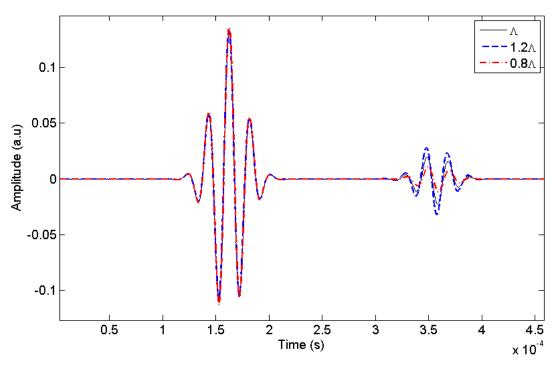


Figure 5: The sensitivity of the viscous characteristic length on the 1st and 2nd reflected waves at a frequency of 50 kHz

d) Effect of Thermal Characteristic Length A on the 1st and 2nd Reflected Waves

The sensitivity of the thermal characteristic length Λ' on the two reflected waves at low ultrasonic frequency is shown in Figure 5 for a variation from +20% to -20% of its initial value. From Figure 6, we can see that for a frequency of 50 kHz, there is very little influence of the thermal characteristic length on the 1st reflected signal. An increase of +20% in Λ' results in a 0.17% increase in the modulus of the 1st reflected signal, while a variation of -20% results in a -0.26% decrease in the amplitude of the 1st reflected signal. However, the second reflected wave is more sensitive than the first. For a variation of +20% of Λ' , the amplitude of the 2nd reflected wave increases by 3.29%. Moreover, according to Table 1, we observe that the sensitivity of the thermal characteristic length slightly decreases with frequency for the first reflection, while it increases for the second reflected wave.

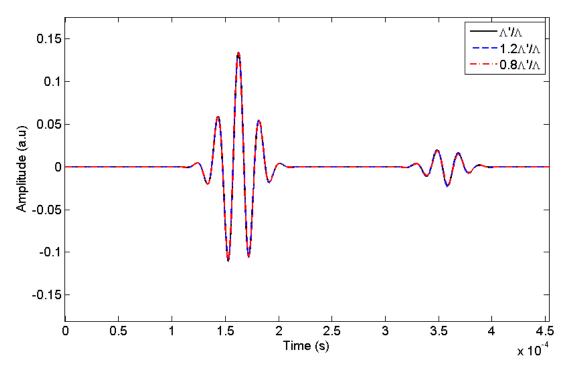


Figure 6: The sensitivity of the thermal characteristic length on the 1st and 2nd reflected waves for a frequency of 50 kHz

e) Effect of Viscous Shape Factor ξ on the Reflected Signal

The sensitivity of the shape factor ξ on the 1st and 2nd reflected waves in the Low-Frequency Ultrasound regime is presented in Figure 7. According to this figure, a -20% variation of ξ results in a regression of -0.26% and -4.89% in the amplitude of the 1st and 2nd reflected waves, respectively. For a variation of +20% of ξ , we observe a growth of +0.17% and 3.29% in the amplitude of the 1st and 2nd reflected waves. It can be concluded that the shape factor ξ has a weak influence on the first reflected wave but a strong sensitivity on the second wave in the low-frequency range of ultrasound. Moreover, the variation decreases for the first reflected wave and increases for the second wave as the frequency increases.

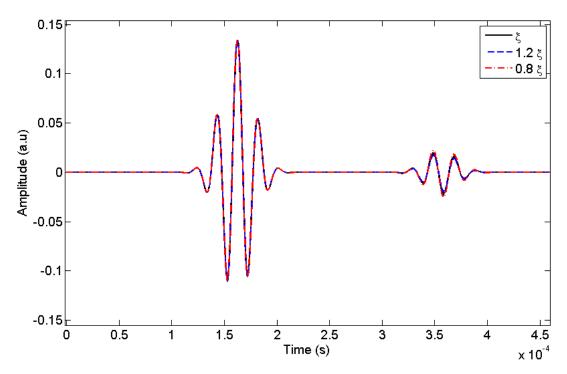


Figure 7: Sensitivity of the shape factor ξ on the 1st and 2nd reflected waves in the low-frequency ultrasound regime Effect of Thermal Shape Factor & on the Reflected Signal

To investigate the impact of varying the thermal shape factor ξ' on the 1st and 2nd high-frequency reflected waves, Figure 8 is presented. At an excitation frequency of 50 kHz, a +20% variation in ξ/ξ' results in a +0.10% increase and a -1.91% attenuation in the amplitude of the 1st and 2nd reflected waves, respectively. This parameter exhibits a weak influence on the 1st reflected wave but a more significant effect on the 2nd reflected wave in the low-frequency ultrasound regime. Table 1 summarizes the effects of porosity, tortuosity, viscous and thermal characteristic lengths, as well as the two shape factors on the 1st and 2nd reflected waves in the low-frequency regime of ultrasound (50-120 kHz).

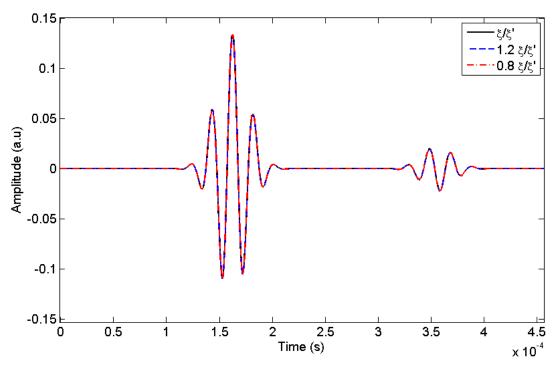


Figure 8: Sensitivity of thermal shape factor ξ on the 1st and 2nd high-frequency reflected waves at an excitation frequency of 50 kHz

Based on the results presented in Table 1 and Figures 3-8, we can classify the sensitivity of each parameter on the reflected signal in the order of decreasing influence as presented in Table 2.

Table 1: Relative variation of the reflection coefficient $\frac{\Delta R}{R}$ % corresponding to a variation of \pm 20% of each physical parameter

		$\frac{\Delta R}{R}$ %			
		1st reflec	ted wave	2nd reflec	cted wave
Parameters	Variations	50 kHz	120 kHz	50 kHz	120 kHz
Dorocity to	+20%	-66.84	-68.88	-65.06	-67.66
Porosity φ	-20%	80.26	82.30	71.32	74.12
Tortugoity a	+20%	33.16	34.02	10.82	5.82
Tortuosity α _∞	-20%	-40.98	-42.10	-27.47	-24.77
Viscous characteristic length	+20%	-1.07	-0.61	42.76	58.54
Λ (μm)	-20%	1.77	0.93	-44.86	-52.95
Ratio thermal-viscous	+20%	0.17	0.11	3.29	4.63
characteristic lengths (Λ'/Λ)	-20%	-0.26	-0.16	-4.89	-6.57
Viscous shape factor ξ	+20%	0.10	0.19	-11.91	-12.16
Tiboodo dilapo labior y	-20%	-0.97	-0.18	13.56	13.88
Ratio viscous-thermal shape	+20%	0.16	0.25	0.35	0.34
factors ξ/ξ'	-20%	-0.25	-0.38	-0.52	-0.51

Table 2: Classification of the sensitivity of each parameter on the 1st and 2nd reflected signal

Parameters	ф	α^{∞}	Λ	ξ	Λ'	ξ'
Influence on the 1st reflected signal	+++	++	+	~	~~	~~~
Influence on the 2nd reflected signal	+++	+	++	+	~	~~

+: Considerable

~: Weak

IV. Conclusion

In conclusion, this study investigated the influence of physical parameters on the reflected wave at the 1st and 2nd interface of rigid porous media in the low-frequency ultrasound regime. The results show that porosity and tortuosity are the most influential parameters affecting the two reflected signals. This influence varies proportionally with the frequency and inversely with the porosity for both the 1st and 2nd reflected waves. For the 1st reflected wave, the influence varies proportionally with the tortuosity and frequency, while for the 2nd reflected wave; it varies proportionally with the tortuosity and inversely with the frequency. However, the impact of porosity and tortuosity on the 1st reflected wave is greater than on the 2nd reflected wave. Moreover, the viscous characteristic length has a small effect on the 1st reflected wave but a substantial influence on the 2nd reflected wave, exceeding the impact of tortuosity. On the other hand, the shape factor has a minor impact on the 1st reflected wave and a significant sensitivity on the 2nd reflection. Concerning the thermal parameters, the thermal characteristic length and the thermal shape factor have a negligible impact on the 1st reflected wave, while the sensitivity of the thermal characteristic length on the 2nd reflected wave is considerable.

The study's strength is that it analyzed the two reflected waves separately and independently, which allows us to treat each wave individually. These results could have important implications for the design and optimization of ultrasound-based techniques in various applications such as medical imaging, non-destructive testing, and materials characterization. However, further research may be necessary to investigate the effect of these parameters in other frequency ranges and porous medium structures.

ACKNOWLEDGMENT

This work was funded by The General Directorate of Scientific Research and Technological Development (DGRSDT) under grant number PRFU: B00L02UN440120200001, Algeria.

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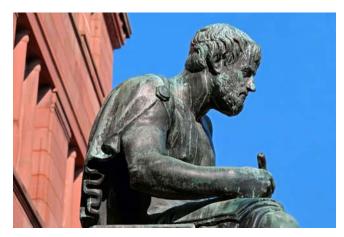
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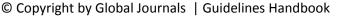
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- **23. Upon conclusion:** Once you have concluded your research, the next most important step is to present your findings. Presentation is extremely important as it is the definite medium though which your research is going to be in print for the rest of the crowd. Care should be taken to categorize your thoughts well and present them in a logical and neat manner. A good quality research paper format is essential because it serves to highlight your research paper and bring to light all necessary aspects of your research.

INFORMAL GUIDELINES OF RESEARCH PAPER WRITING

Key points to remember:

- Submit all work in its final form.
- Write your paper in the form which is presented in the guidelines using the template.
- Please note the criteria peer reviewers will use for grading the final paper.

Final points:

One purpose of organizing a research paper is to let people interpret your efforts selectively. The journal requires the following sections, submitted in the order listed, with each section starting on a new page:

The introduction: This will be compiled from reference matter and reflect the design processes or outline of basis that directed you to make a study. As you carry out the process of study, the method and process section will be constructed like that. The results segment will show related statistics in nearly sequential order and direct reviewers to similar intellectual paths throughout the data that you gathered to carry out your study.

The discussion section:

This will provide understanding of the data and projections as to the implications of the results. The use of good quality references throughout the paper will give the effort trustworthiness by representing an alertness to prior workings.

Writing a research paper is not an easy job, no matter how trouble-free the actual research or concept. Practice, excellent preparation, and controlled record-keeping are the only means to make straightforward progression.

General style:

Specific editorial column necessities for compliance of a manuscript will always take over from directions in these general guidelines.

To make a paper clear: Adhere to recommended page limits.

Mistakes to avoid:

- Insertion of a title at the foot of a page with subsequent text on the next page.
- Separating a table, chart, or figure—confine each to a single page.
- Submitting a manuscript with pages out of sequence.
- In every section of your document, use standard writing style, including articles ("a" and "the").
- Keep paying attention to the topic of the paper.



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- Use paragraphs to split each significant point (excluding the abstract).
- Align the primary line of each section.
- Present your points in sound order.
- Use present tense to report well-accepted matters.
- Use past tense to describe specific results.
- Do not use familiar wording; don't address the reviewer directly. Don't use slang or superlatives.
- Avoid use of extra pictures—include only those figures essential to presenting results.

Title page:

Choose a revealing title. It should be short and include the name(s) and address(es) of all authors. It should not have acronyms or abbreviations or exceed two printed lines.

Abstract: This summary should be two hundred words or less. It should clearly and briefly explain the key findings reported in the manuscript and must have precise statistics. It should not have acronyms or abbreviations. It should be logical in itself. Do not cite references at this point.

An abstract is a brief, distinct paragraph summary of finished work or work in development. In a minute or less, a reviewer can be taught the foundation behind the study, common approaches to the problem, relevant results, and significant conclusions or new questions.

Write your summary when your paper is completed because how can you write the summary of anything which is not yet written? Wealth of terminology is very essential in abstract. Use comprehensive sentences, and do not sacrifice readability for brevity; you can maintain it succinctly by phrasing sentences so that they provide more than a lone rationale. The author can at this moment go straight to shortening the outcome. Sum up the study with the subsequent elements in any summary. Try to limit the initial two items to no more than one line each.

Reason for writing the article—theory, overall issue, purpose.

- Fundamental goal.
- To-the-point depiction of the research.
- Consequences, including definite statistics—if the consequences are quantitative in nature, account for this; results of any numerical analysis should be reported. Significant conclusions or questions that emerge from the research.

Approach:

- Single section and succinct.
- o An outline of the job done is always written in past tense.
- o Concentrate on shortening results—limit background information to a verdict or two.
- Exact spelling, clarity of sentences and phrases, and appropriate reporting of quantities (proper units, important statistics) are just as significant in an abstract as they are anywhere else.

Introduction:

The introduction should "introduce" the manuscript. The reviewer should be presented with sufficient background information to be capable of comprehending and calculating the purpose of your study without having to refer to other works. The basis for the study should be offered. Give the most important references, but avoid making a comprehensive appraisal of the topic. Describe the problem visibly. If the problem is not acknowledged in a logical, reasonable way, the reviewer will give no attention to your results. Speak in common terms about techniques used to explain the problem, if needed, but do not present any particulars about the protocols here.

The following approach can create a valuable beginning:

- o Explain the value (significance) of the study.
- O Defend the model—why did you employ this particular system or method? What is its compensation? Remark upon its appropriateness from an abstract point of view as well as pointing out sensible reasons for using it.
- o Present a justification. State your particular theory(-ies) or aim(s), and describe the logic that led you to choose them.
- o Briefly explain the study's tentative purpose and how it meets the declared objectives.



Approach:

Use past tense except for when referring to recognized facts. After all, the manuscript will be submitted after the entire job is done. Sort out your thoughts; manufacture one key point for every section. If you make the four points listed above, you will need at least four paragraphs. Present surrounding information only when it is necessary to support a situation. The reviewer does not desire to read everything you know about a topic. Shape the theory specifically—do not take a broad view.

As always, give awareness to spelling, simplicity, and correctness of sentences and phrases.

Procedures (methods and materials):

This part is supposed to be the easiest to carve if you have good skills. A soundly written procedures segment allows a capable scientist to replicate your results. Present precise information about your supplies. The suppliers and clarity of reagents can be helpful bits of information. Present methods in sequential order, but linked methodologies can be grouped as a segment. Be concise when relating the protocols. Attempt to give the least amount of information that would permit another capable scientist to replicate your outcome, but be cautious that vital information is integrated. The use of subheadings is suggested and ought to be synchronized with the results section.

When a technique is used that has been well-described in another section, mention the specific item describing the way, but draw the basic principle while stating the situation. The purpose is to show all particular resources and broad procedures so that another person may use some or all of the methods in one more study or referee the scientific value of your work. It is not to be a step-by-step report of the whole thing you did, nor is a methods section a set of orders.

Materials:

Materials may be reported in part of a section or else they may be recognized along with your measures.

Methods:

- Report the method and not the particulars of each process that engaged the same methodology.
- Describe the method entirely.
- o To be succinct, present methods under headings dedicated to specific dealings or groups of measures.
- o Simplify—detail how procedures were completed, not how they were performed on a particular day.
- o If well-known procedures were used, account for the procedure by name, possibly with a reference, and that's all.

Approach:

It is embarrassing to use vigorous voice when documenting methods without using first person, which would focus the reviewer's interest on the researcher rather than the job. As a result, when writing up the methods, most authors use third person passive voice.

Use standard style in this and every other part of the paper—avoid familiar lists, and use full sentences.

What to keep away from:

- o Resources and methods are not a set of information.
- Skip all descriptive information and surroundings—save it for the argument.
- Leave out information that is immaterial to a third party.

Results:

The principle of a results segment is to present and demonstrate your conclusion. Create this part as entirely objective details of the outcome, and save all understanding for the discussion.

The page length of this segment is set by the sum and types of data to be reported. Use statistics and tables, if suitable, to present consequences most efficiently.

You must clearly differentiate material which would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matters should not be submitted at all except if requested by the instructor.



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Content:

- Sum up your conclusions in text and demonstrate them, if suitable, with figures and tables.
- o In the manuscript, explain each of your consequences, and point the reader to remarks that are most appropriate.
- o Present a background, such as by describing the question that was addressed by creation of an exacting study.
- Explain results of control experiments and give remarks that are not accessible in a prescribed figure or table, if appropriate.
- Examine your data, then prepare the analyzed (transformed) data in the form of a figure (graph), table, or manuscript.

What to stay away from:

- Do not discuss or infer your outcome, report surrounding information, or try to explain anything.
- Do not include raw data or intermediate calculations in a research manuscript.
- Do not present similar data more than once.
- o A manuscript should complement any figures or tables, not duplicate information.
- Never confuse figures with tables—there is a difference.

Approach:

As always, use past tense when you submit your results, and put the whole thing in a reasonable order.

Put figures and tables, appropriately numbered, in order at the end of the report.

If you desire, you may place your figures and tables properly within the text of your results section.

Figures and tables:

If you put figures and tables at the end of some details, make certain that they are visibly distinguished from any attached appendix materials, such as raw facts. Whatever the position, each table must be titled, numbered one after the other, and include a heading. All figures and tables must be divided from the text.

Discussion:

The discussion is expected to be the trickiest segment to write. A lot of papers submitted to the journal are discarded based on problems with the discussion. There is no rule for how long an argument should be.

Position your understanding of the outcome visibly to lead the reviewer through your conclusions, and then finish the paper with a summing up of the implications of the study. The purpose here is to offer an understanding of your results and support all of your conclusions, using facts from your research and generally accepted information, if suitable. The implication of results should be fully described.

Infer your data in the conversation in suitable depth. This means that when you clarify an observable fact, you must explain mechanisms that may account for the observation. If your results vary from your prospect, make clear why that may have happened. If your results agree, then explain the theory that the proof supported. It is never suitable to just state that the data approved the prospect, and let it drop at that. Make a decision as to whether each premise is supported or discarded or if you cannot make a conclusion with assurance. Do not just dismiss a study or part of a study as "uncertain."

Research papers are not acknowledged if the work is imperfect. Draw what conclusions you can based upon the results that you have, and take care of the study as a finished work.

- You may propose future guidelines, such as how an experiment might be personalized to accomplish a new idea.
- o Give details of all of your remarks as much as possible, focusing on mechanisms.
- Make a decision as to whether the tentative design sufficiently addressed the theory and whether or not it was correctly restricted. Try to present substitute explanations if they are sensible alternatives.
- One piece of research will not counter an overall question, so maintain the large picture in mind. Where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.



Approach:

When you refer to information, differentiate data generated by your own studies from other available information. Present work done by specific persons (including you) in past tense.

Describe generally acknowledged facts and main beliefs in present tense.

THE ADMINISTRATION RULES

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CRITERION FOR GRADING A RESEARCH PAPER (COMPILATION) BY GLOBAL JOURNALS

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Topics	Grades		
	A-B	C-D	E-F
Abstract	Clear and concise with appropriate content, Correct format. 200 words or below	Unclear summary and no specific data, Incorrect form Above 200 words	No specific data with ambiguous information Above 250 words
Introduction	Containing all background details with clear goal and appropriate details, flow specification, no grammar and spelling mistake, well organized sentence and paragraph, reference cited	Unclear and confusing data, appropriate format, grammar and spelling errors with unorganized matter	Out of place depth and content, hazy format
Methods and Procedures	Clear and to the point with well arranged paragraph, precision and accuracy of facts and figures, well organized subheads	Difficult to comprehend with embarrassed text, too much explanation but completed	Incorrect and unorganized structure with hazy meaning
Result	Well organized, Clear and specific, Correct units with precision, correct data, well structuring of paragraph, no grammar and spelling mistake	Complete and embarrassed text, difficult to comprehend	Irregular format with wrong facts and figures
Discussion	Well organized, meaningful specification, sound conclusion, logical and concise explanation, highly structured paragraph reference cited	Wordy, unclear conclusion, spurious	Conclusion is not cited, unorganized, difficult to comprehend
References	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring



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