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## An Efficient Class of Ratio-Cum-Dual to Product Estimator of Finite Population Mean in Sample Surveys

By Sanjib Choudhury & Bhupendra Kumar Singh

North Eastern Regional Institute of Science and Technology

*Abstract* - We consider a class of ratio-cum-dual to product estimator for estimating a finite population mean of the study variate. The bias and mean square error of the proposed estimator have been obtained. The asymptotically optimum estimator (AOE) in this class has also been identified along with its approximate bias and mean square error. Theoretical and empirical studies have been done to demonstrate the superiority of the proposed estimator over the other estimators.

*Keywords* : Finite population mean; ratio-cum-dual to product estimator; Bias; Mean square error; Efficiency.

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## AN EFFICIENT CLASS OF RATIO-CUM-DUAL TO PRODUCT ESTIMATOR OF FINITE POPULATION MEAN IN SAMPLE SURVEYS

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 $N_{\rm otes}$ 

# An Efficient Class of Ratio-Cum-Dual to Product Estimator of Finite Population Mean in Sample Surveys

Sanjib Choudhury<sup>a</sup> & Bhupendra Kumar Singh<sup>o</sup>

*Abstract* - We consider a class of ratio-cum-dual to product estimator for estimating a finite population mean of the study variate. The bias and mean square error of the proposed estimator have been obtained. The asymptotically optimum estimator (AOE) in this class has also been identified along with its approximate bias and mean square error. Theoretical and empirical studies have been done to demonstrate the superiority of the proposed estimator over the other estimators.

Keywords : Finite population mean; ratio-cum-dual to product estimator; Bias; Mean square error; Efficiency.

#### I. INTRODUCTION

In sample surveys, auxiliary information is used at both selections as well as estimation stages to improve the efficiency of the estimators. The use of auxiliary information at the estimation stage appears to have started with the work of Cochran (1940). When the correlation between study variate and auxiliary variate is positive (high), the ratio method of estimation is used for estimating the population mean. The ratio method is most effective if  $\rho C_y/C_x > 1/2$ , where  $C_y$ ,  $C_x$  and  $\rho$  are coefficient of variation of y, coefficient of variation of x and correlation coefficient between y and xrespectively. On the other hand, if the correlation is negative, the product method of estimation is used and this is most effective if  $\rho C_y/C_x < -1/2$ , suggested by Murthy (1964). Srivenkataramana (1980) first proposed dual to ratio estimator and Bandyopadhyay (1980) proposed dual to product estimator. Singh and Tailor (2005), Singh and Espejo (2003), Tailor and Sharma (2009) worked on ratio-cum-product estimators. Sharma and Tailor (2010), Choudhury and Singh (2012) worked on ratio, dual to ratio and dual to product estimators to estimate the study variable. These motivated authors to propose a new ratio-cum-dual to product estimators for estimating the population mean.

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Consider a finite population  $U = (u_1, u_2, ..., u_N)$  of size N units. Let y and x denotes the study and auxiliary variates respectively. A sample of size n (n < N) is drawn using simple random sampling without replacement (SRSWOR) to estimate the population mean  $\overline{Y} = (1/N) \sum_{i=1}^{N} y_i$  of the study variate y. Let the sample mean  $(\overline{x}, \overline{y})$  are the unbiased estimator of  $(\overline{X}, \overline{Y})$  based on n observations.

The usual ratio and product estimators for  $\overline{Y}$  are

 $\overline{y}_R = \overline{y} \left( \overline{X} / \overline{x} \right)$ 

and

 $\overline{y}_P = \overline{y}(\overline{x}/\overline{X})$  respectively,

Notes

when

re 
$$\overline{y} = (1/n) \sum_{i=1}^{n} y_i$$
 and  $\overline{x} = (1/n) \sum_{i=1}^{n} x_i$ .

Let  $x_i^* = (1+g)\overline{X} - gx_i$ , i = 1, 2, ..., N, where g = n/(N-n).

Then clearly  $\overline{x}^* = (1+g)\overline{X} - g\overline{x}$  is also unbiased estimator for  $\overline{X}$  and  $Corr(\overline{y}, \overline{x}^*) = -\rho$ .

Using the transformation  $x_i^* = (1+g)\overline{X} - gx_i$ , Srivenkataramana (1980) obtained dual to ratio estimator as

$$\overline{y}_R^* = \overline{y}\left(\overline{x}^*/\overline{X}\right)$$

and Bandyopadhyay (1980) obtained dual to product estimator as

$$\overline{y}_P^* = \overline{y} \left( \overline{X} / \overline{x}^* \right).$$

In this paper, we have proposed a class of ratio-cum-dual to product type estimator for estimating population mean  $\overline{Y}$ . Numerical illustrations are given in the support of the present study.

#### II. The Proposed Estimator

For estimating population mean  $\overline{Y}$ , we propose an estimator as

$$\overline{y}_{RdP} = \overline{y} \left[ \alpha \left( \frac{\overline{X}}{\overline{x}} \right) + (1 - \alpha) \left( \frac{\overline{X}}{\overline{x}^*} \right) \right]$$
(1)

where  $\alpha$  is a suitably chosen scalar.

To obtain the bias and mean square error (MSE) of  $\overline{y}_{RdP}$  to a first degree of approximation, we write

$$e_0 = \left(\overline{y} - \overline{Y}\right) / \overline{Y} \text{ and } e_1 = \left(\overline{x} - \overline{X}\right) / \overline{X}$$

Such that

$$E(e_{0}) = E(e_{1}) = 0, \quad E(e_{0}^{2}) = \frac{1-f}{n}C_{y}^{2},$$

$$E(e_{1}^{2}) = \frac{1-f}{n}C_{x}^{2}, \quad E(e_{0}e_{1}) = \frac{1-f}{n}CC_{x}^{2},$$
(2)

 $N_{otes}$ 

where f = n/N is the sampling fraction,  $C_y^2 = S_y^2/\overline{Y}^2$ ,  $C_x^2 = S_x^2/\overline{X}^2$ ,  $C = \rho C_y/C_x$ and defined as  $\rho = S_{xy}/S_xS_y$ ,  $S_x^2 = \frac{1}{N-1}\sum_{i=1}^N (x_i - \overline{X})^2$ ,  $S_y^2 = \frac{1}{N-1}\sum_{i=1}^N (y_i - \overline{Y})^2$  and  $S_{xy} = \frac{1}{N-1}\sum_{i=1}^N (y_i - \overline{Y})(x_i - \overline{X})$ .

Expressing  $\overline{y}_{RdP}$  in terms of e's, we obtain

$$\overline{y}_{RdP} = \overline{Y}(1+e_0)\left\{\alpha(1+e_1)^{-1}+(1-\alpha)(1-ge_1)^{-1}\right\}.$$

We now assume that  $|e_1| < 1$  and  $|ge_1| < 1$ , so that we may expand  $(1+e_1)^{-1}$  and  $(1-ge_1)^{-1}$  as a series in powers of  $e_1$  and  $ge_1$  respectively. Expanding, multiplying out and retaining terms of e's to the second degree, we obtain

$$\overline{y}_{RdP} - \overline{Y} \cong \overline{Y} \Big[ e_0 + g \left( e_1 + e_0 e_1 + g e_1^2 \right) + \alpha \left( 1 + g \right) \Big\{ -e_1^2 + \left( 1 - g \right) e_1 - e_0 e_1 \Big\} \Big]$$
(3)

Taking the expectation of both sides in equation (3) and using the results of equation (2) we get the bias of  $\overline{y}_{RdP}$  as

$$B\left(\overline{y}_{RdP}\right) = \frac{1-f}{n} \overline{Y} C_x^2 \left[ \left\{ g^2 - \alpha \left( g^2 - 1 \right) \right\} + C \left\{ g - \alpha \left( g + 1 \right) \right\} \right]$$
(4)

The bias,  $B(\overline{y}_{RdP})$  in (4) is 'zero' if  $\alpha = \frac{g(C+g)}{(1+g)(1-g-C)}$ . Thus the estimator  $\overline{y}_{RdP}$ 

with  $\alpha = \frac{g(C+g)}{(1+g)(1-g-C)}$  is almost unbiased.

Squaring and taking expectations of both the sides of equation (3) and using the results of equation (2), we obtain the MSE of  $\overline{y}_{RdP}$  to the first degree of approximation as

$$M\left(\overline{y}_{RdP}\right) = \frac{1-f}{n}\overline{Y}^{2}\left[C_{y}^{2}+C_{x}^{2}\left\{g-\alpha\left(1+g\right)\right\}\left\{2C+g-\alpha\left(1+g\right)\right\}\right\}$$
(5)

which is minimized when

$$\alpha = \frac{1}{1+g} (g+C) = \alpha_{opt.} \text{(say)}$$
(6)

Substituting equation (6) in equation (1) yield the 'asymptotically optimum estimator' (AOE) as

$$\overline{y}_{RdP}^{opt.} = \overline{y} \left[ \left( \frac{g+C}{1+g} \right) \frac{\overline{X}}{\overline{x}} + \left( \frac{1-C}{1+g} \right) \frac{\overline{X}}{\overline{x}^*} \right]$$
Note:

Thus the resulting bias and MSE of  $\overline{y}_{PdP}^{opt.}$  respectively as

$$B\left(\overline{y}_{RdP}^{opt.}\right) = \frac{1-f}{n} \overline{Y} C_x^2 \left(1-C\right) \left(g+C\right)$$
(7)

and

$$M\left(\overline{y}_{RdP}^{opt.}\right) = \frac{1-f}{n} \overline{Y}^2 C_y^2 \left(1-\rho^2\right)$$
(8)

which is the same as the MSE of the linear regression estimator  $\overline{y}_{reg.} = \overline{y} + b_{yx} \left(\overline{X} - \overline{x}\right)$ , where  $b_{yx}$  is the sample regression coefficient of y on x.

From equation (7), we note that the bias of AOE  $\overline{y}_{RdP}^{opt.}$  is 'zero' if

either C = 1 or C = -g.

#### Remark 2.1.

To the first degree of approximation, the proposed strategy  $\overline{y}_{RdP}$  under optimality condition (6), is equal to linear regression estimator.

#### Remark 2.2.

For  $\alpha = 1$ , the estimator  $\overline{y}_{RdP}$  in equation (1) boils down to the usual ratio estimator  $\overline{y}_{R}$ . The bias and MSE of  $\overline{y}_{R}$  can be obtained by putting  $\alpha = 1$  in equations (4) and (5) respectively as

$$B\left(\overline{y}_{R}\right) = \frac{1-f}{n} \overline{Y} C_{x}^{2} \left(1-C\right)$$
$$M\left(\overline{y}_{R}\right) = \frac{1-f}{n} \overline{Y}^{2} \left\{C_{y}^{2} + C_{x}^{2} \left(1-2C\right)\right\}$$
(9)

#### Remark 2.3.

For  $\alpha = 0$ , the estimator  $\overline{y}_{RdP}$  in equation (1) boils down to the dual to product estimator  $\overline{y}_{p}^{*}$ , proposed by Bandyopadhyay (1980). The bias and MSE of  $\overline{y}_{p}^{*}$  can be obtained by putting  $\alpha = 0$  in equations (4) and (5) respectively as

$$B\left(\overline{y}_{p}^{*}\right) = \frac{1-f}{n}\overline{Y}C_{x}^{2}g\left(g+C\right)$$

and

Notes

$$M\left(\overline{y}_{p}^{*}\right) = \frac{1-f}{n}\overline{Y}^{2}\left\{C_{y}^{2} + gC_{x}^{2}\left(g+2C\right)\right\}$$
(10)

Thus, we see that this study provides unified treatment towards the properties of different estimators.

#### III. EFFICIENCY COMPARISONS

#### a) Comparison of $\overline{y}_{RdP}$

In this section, firstly, we compare MSE of conventional estimators  $\overline{y}$ ,  $\overline{y}_R$  and  $\overline{y}_P$  with MSE of proposed estimator  $\overline{y}_{RdP}$ .

The MSE of sample mean  $\overline{y}$  under SRSWOR sampling scheme is given by

$$M\left(\overline{y}\right) = \frac{1-f}{n}\overline{Y}^2 C_y^2.$$
<sup>(11)</sup>

From equations (5) and (11), it is found that the proposed estimator  $\overline{y}_{RdP}$  is more efficient than  $\overline{y}$  if

$$\left\{-g+\alpha\left(1+g\right)\right\}\left\{2C+g-\alpha\left(1+g\right)\right\}>0$$

This condition holds if

either 
$$\frac{g}{1+g} > \alpha$$
 and  $\frac{1}{1+g} (2C+g) < \alpha$ ,  
or  $\frac{g}{1+g} < \alpha$  and  $\frac{1}{1+g} (2C+g) > \alpha$ .

Therefore, the range of  $\alpha$  for which the proposed estimator  $\overline{y}_{_{RdP}}$  is more efficient than  $\overline{y}$  is

$$\left[\min\left\{\frac{g}{1+g}, \frac{1}{1+g}(2C+g)\right\}, \max\left\{\frac{g}{1+g}, \frac{1}{1+g}(2C+g)\right\}\right].$$

From equations (5) and (9), we note that the estimator  $\overline{y}_{RdP}$  has smaller MSE than that of the usual ratio estimator  $\overline{y}_{R}$  if

$$\left\{1+g-\alpha\left(1+g\right)\right\}\left\{1-2C-g+\alpha\left(1+g\right)\right\}>0$$

This condition holds if

either 
$$1 > \alpha$$
 and  $\frac{1}{1+g} (2C+g-1) < \alpha$ ,  
or  $1 < \alpha$  and  $\frac{1}{1+g} (2C+g-1) > \alpha$ .

Therefore, the range of  $\alpha$  for which the proposed estimator  $\overline{y}_{RdP}$  is better than  $\overline{y}_{R}$  is

 $\left[\min\left\{1, \frac{1}{1+g}(2C+g-1)\right\}, \max\left\{1, \frac{1}{1+g}(2C+g-1)\right\}\right].$ 

To compare the usual product estimator  $\overline{y}_p$ , we write the bias and MSE of  $\overline{y}_p$  to the first degree of approximation respectively as

$$B\left(\overline{y}_{P}\right) = \frac{1-f}{n} \overline{Y} C C_{x}^{2}$$

$$M\left(\overline{y}_{P}\right) = \frac{1-f}{n} \overline{Y}^{2} \left\{ C_{y}^{2} + C_{x}^{2} \left(1+2C\right) \right\}$$
(12)

Notes

We note from equations (5) and (12) that the estimator  $\overline{y}_{RdP}$  will dominate over usual product estimator  $\overline{y}_{P}$  if

$$\left\{-(g-1)+\alpha(g+1)\right\}\left\{(2C+1+g)-\alpha(g+1)\right\}>0$$

This condition holds if

either 
$$\frac{g-1}{1+g} > \alpha$$
 and  $1 + \frac{2C}{1+g} < \alpha$   
or  $\frac{g-1}{1+g} < \alpha$  and  $1 + \frac{2C}{1+g} > \alpha$ .

Hence, the range of  $\alpha$  in which the proposed estimator  $\overline{y}_{PdP}$  is better than  $\overline{y}_{P}$  is

$$\left\{\min\left(\frac{g-1}{1+g}, 1+\frac{2C}{1+g}\right), \max\left(\frac{g-1}{1+g}, 1+\frac{2C}{1+g}\right)\right\}.$$

Secondly, comparing the MSE between the proposed estimator and dual to ratio estimator  $\overline{y}_{R}^{*}$ , proposed by Srivenkataramana (1980).

The bias and MSE of  $\overline{y}_{R}^{*}$  to the first degree of approximation respectively as

$$B\left(\overline{y}_{R}^{*}\right) = -\overline{Y}\frac{1-f}{n}gCC_{x}^{2}$$

and

Notes

$$M\left(\overline{y}_{R}^{*}\right) = \frac{1-f}{n}\overline{Y}^{2}\left\{C_{y}^{2} + gC_{x}^{2}\left(g-2C\right)\right\}.$$
(13)

From equations (5) and (13), it is found that the proposed estimator  $\overline{y}_{RdP}$  will dominate over Srivenkataramana (1980) estimator  $\overline{y}_{R}^{*}$  if

$$\left\{2g-\alpha\left(g+1\right)\right\}\left\{-2C+\alpha\left(g+1\right)\right\}>0$$

This condition exist if

either 
$$\frac{2g}{1+g} > \alpha$$
 and  $\frac{2C}{1+g} < \alpha$ ,  
or  $\frac{2g}{1+g} < \alpha$  and  $\frac{2C}{1+g} > \alpha$ .

Therefore, the range of  $\alpha$  in which the proposed estimator  $\overline{y}_{RdP}$  is more efficient than dual to ratio estimator  $\overline{y}_{R}^{*}$  is

$$\left\{\min\left(\frac{2g}{1+g}, \frac{2C}{1+g}\right), \max\left(\frac{2g}{1+g}, \frac{2C}{1+g}\right)\right\}.$$

Lastly, we compare MSE of the proposed estimator  $\overline{y}_{RdP}$  with dual to product estimator  $\overline{y}_{p}^{*}$ .

We note from equations (5) and (10) that

$$M\left(\overline{y}_{p}^{*}\right) > M\left(\overline{y}_{RdP}\right) \text{ if}$$
$$\alpha\left(1+g\right)\left\{2C+2g-\alpha\left(1+g\right)\right\} > 0$$

This condition exist if

either 
$$0 < \alpha < \frac{2}{1+g} (C+g)$$
,  
or  $\frac{2}{1+g} (C+g) < \alpha < 0$ .

Therefore, the range of  $\alpha$  in which the proposed estimator  $\overline{y}_{RdP}$  is more efficient than dual to product estimator  $\overline{y}_{P}^{*}$  is

$$\left[\min\left\{\frac{2(C+g)}{1+g}, 0\right\}, \max\left\{\frac{2(C+g)}{1+g}, 0\right\}\right]$$

Thus, it seems from the above results that the proposed estimator  $\overline{y}_{RdP}$  may be made better than other estimators by making a suitable choice of the value of  $\alpha$  within the respective ranges.

#### b) Comparison of 'AOE' of $\overline{y}_{RdP}^{opt.}$

1

From equations (8)-(13), it is found that the 'AOE'  $\overline{y}_{RdP}^{opt.}$  is more efficient than the other existing estimators like  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$  and  $\overline{y}_P^*$ . Since

Notes

$$M\left(\overline{y}\right) - M\left(\overline{y}_{RdP}^{opt.}\right) = \frac{1-f}{n}\overline{Y}^2\rho^2 C_y^2 > 0.$$

$$M\left(\overline{y}_{R}\right)-M\left(\overline{y}_{RdP}^{opt.}\right)=\frac{1-f}{n}\overline{Y}^{2}C_{x}^{2}\left(1-C\right)^{2}>0.$$

$$M\left(\overline{y}_{P}\right)-M\left(\overline{y}_{RdP}^{opt.}\right)=\frac{1-f}{n}\overline{Y}^{2}C_{x}^{2}\left(1+C\right)^{2}>0.$$

$$M\left(\overline{y}_{R}^{*}\right)-M\left(\overline{y}_{RdP}^{opt.}\right)=\frac{1-f}{n}\overline{Y}^{2}C_{x}^{2}\left(C-g\right)^{2}>0.$$

$$M\left(\overline{y}_{p}^{*}\right)-M\left(\overline{y}_{RdP}^{opt.}\right)=\frac{1-f}{n}\overline{Y}^{2}C_{x}^{2}\left(C+g\right)^{2}>0.$$

Hence, we conclude that the proposed estimator  $\overline{y}_{RdP}$  is the best (in the sense of having optimum MSE).

#### IV. NUMERICAL ILLUSTRATIONS

To examine the merits of the constructed estimator over its competitors numerically, we consider eight sets of data. The source of the population, the nature of the variates y and x and the values of the various parameters are listed in Table 1.

To reflect the gain in the efficiency of the proposed estimator  $\overline{y}_{RdP}$  over the estimators  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$  and  $\overline{y}_P^*$ , the effective ranges along with the optimum value of  $\alpha$  are presented in Table 2 with respect to the population data sets.

The percent relative efficiencies (PREs) of the different estimators with respect to usual unbiased estimator  $\overline{y}$  computed by the formula

$$PRE(E, \overline{y}) = \frac{M(\overline{y})}{M(E)} \times 100$$

where

$$E = \overline{y}, \ \overline{y}_R, \ \overline{y}_P, \ \overline{y}_R^*, \ \overline{y}_P^* \text{ and } \overline{y}_{RdP} \text{ or } \overline{y}_{RdH}^{opt}$$

and are presented in Table 3.

Popu- lation	Source	Study variate v	Auxiliary variate x	Ν	n	ρ	C <sub>y</sub>	$C_x$	$\overline{Y}$
1	Steel and Torrie (1960)	Log of leaf burn in secs	Chlorine percentage	30	6	-0.4996	0.7001	0.7493	0.6860
2	Pandey and Dubey (1988)			20	8	-0.9199	0.3552	0.3943	19.55
3	Kadilar and Cingi (2006) pp. 1054	Level of apple production	Number of apple trees	106	20	0.82	4.18	2.02	15.37
4	Sukhatme and Sukhatme (1970)	Number of villages in the circles.	A circle consisting more than five villages	89	12	0.766	0.604	2.1901	3.36
5	Maddala (1977)	Consump- tion per capita.	Deflated prices of veal	30	6	-0.6823	0.2278	0.0986	7.6375
6	Murthy (1967)	Output	Fixed capital	80	20	0.9413	0.3542	0.7507	51.8264
7	Murthy (1967)	Output	Number of workers	80	20	0.9150	0.3542	0.9484	51.8264
8	Kadilar and Cingi (2006) pp. 78			106	20	0.86	5.22	2.1	2212.59

 $N_{\rm otes}$ 

*Table 1 :* Description of the populations

Table 2 : Effective ranges and optimum value of  $\alpha$  of  $\overline{y}_{RdP}$ .

lation	Ranges of $\alpha$ in which the proposed estimator $\overline{y}_{RdP}$ is better than						
Popu	$\overline{y}$	$\overline{y}_R$	$\overline{y}_P$	$\overline{\mathcal{Y}}_{R}^{*}$	$\overline{y}_{P}^{*}$	$lpha_{opt.}$	
1	(-0.55,0.20)	(-1.35, 1.00)	(-0.60, 0.25)	(-0.75, 0.40)	(-0.35, 0.00)	-0.1734	
2	(-0.59, 0.40)	(-1.19, 1.00)	(-0.20, 0.01)	(-0.99, 0.80)	(-0.19, 0.00)	-0.0972	
3	(0.19, 2.94)	(1.00, 2.13)	(-0.62, 3.75)	(0.38, 2.75)	(0.00, 3.13)	1.5654	
4	(0.13, 0.50)	(-0.36, 1.00)	(-0.73, 1.37)	(0.27, 0.37)	(0.00, 0.64)	0.3176	
5	(-2.32, 0.20)	(-3.12, 1.00)	(-1.52, -0.60)	(-2.52, 0.40)	(-2.12, 0.00)	-1.0611	
6	(0.25, 0.92)	(0.17, 1.00)	(-0.50, 1.67)	(0.50, 0.67)	(0.00, 1.17)	0.5831	
7	(0.25, 0.76)	(0.01, 1.00)	(-0.50, 1.51)	(0.50, 0.51)	(0.00, 1.01)	0.5063	
8	(0.19, 3.66)	(1.00, 2.85)	(_0.62, 4.47)	(0.38, 3.47)	(0.00, 3.85)	1.9231	

Population	$\overline{y}$	$\overline{\mathcal{Y}}_R$	$\overline{\mathcal{Y}}_P$	$\overline{\mathcal{Y}}_{R}^{*}$	$\overline{\mathcal{Y}}_P^*$	$\overline{y}_{RdP}$ or $\overline{y}_{RdP}^{opt.}$
1	100.00	Ť	Ť	Ť	124.34	133.26
2	100.00	t	526.50	t	537.23	650.26
3	100.00	226.76	Ť	120.73	ť	305.25
4	100.00	Ť	Ť	220.46	Ť	241.99
5	100.00	Ť	167.59	Ť	115.73	187.10
6	100.00	Ť	Ť	591.38	Ť	877.54
7	100.00	Ť	Ť	612.44	Ť	614.34
8	100.00	212.82	Ť	117.95	Ť	384.02

Notes

*Table 3*: Percentage relative efficiency of  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$ ,  $\overline{y}_P^*$  and  $\overline{y}_{RdP}$  or  $\overline{y}_{RdP}^{opt.}$  with respect to  $\overline{y}$ .

*†Relative efficiency less than 100%.* 

#### V. Conclusion

Table 2 provides the wide ranges along with the optimum value of  $\alpha$  for which the proposed estimators  $\overline{y}_{RdP}$  or  $\overline{y}_{RdP}^{opt}$  are more efficient than all other estimators considered in this paper. It is also observed from Table 2 that there is a scope for choosing  $\alpha$  to obtain better estimators than  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$  and  $\overline{y}_P^*$ .

Table 3 shows that there is a substantial gain in efficiency by using proposed estimator  $\overline{y}_{RdP}$  (or  $\overline{y}_{RdP}^{opt.}$ ) over  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$  and  $\overline{y}_P^*$ . This shows that even if the scalar  $\alpha$  deviates from its optimum value  $(\alpha_{opt.})$ , the suggested estimator  $\overline{y}_{RdP}$  will yield better estimates then  $\overline{y}$ ,  $\overline{y}_R$ ,  $\overline{y}_P$ ,  $\overline{y}_R^*$  and  $\overline{y}_P^*$ . Thus it is preferred to use the proposed estimators  $\overline{y}_{RdP}$  or  $\overline{y}_{RdP}^{opt.}$  in practice.

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Notes



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## Proof of 'J is a Radical Class' Using Amitsur Theorem By Raju Chowdhury, Dewan Ferdous Wahid & Md. Anowar Hossain

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*Abstract* - The aim of this paper is to study radical class of rings, right quasi-regular rings and finally, to prove that J, the class of all right quasi-regular rings is a radical class. Amitsur gives a theorem of radical class for the sufficient condition that a class of rings would be a radical class. This paper represents, the proof of, J is a radical class using the theorem of radical class given by Amitsur.

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# PRODE OF J IS A RADICAL CLASSUSING AMITSUR THEOREM

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# R<sub>ef.</sub> Proof of '*J* is a Radical Class' Using Amitsur Theorem

Raju Chowdhury<sup>a</sup>, Dewan Ferdous Wahid<sup>a</sup> & Md. Anowar Hossain<sup>a</sup>

*Abstract* - The aim of this paper is to study radical class of rings, right quasi-regular rings and finally, to prove that *J*, the class of all right quasi-regular rings is a radical class. Amitsur gives a theorem of radical class for the sufficient condition that a class of rings would be a radical class. This paper represents, the proof of, *J* is a radical class using the theorem of radical class given by Amitsur.

Keywords : Ring, Ideal, Radical Class, Right quasi-regular ring.

#### I. INTRODUCTION

The concept of a radical was introduced by J. H. M. Wedderburn [10] in 1908, for the determination of structures of algebras and later on various radicals have been proposed by Artin [14], Baer [11], Jacobson [9], Brown-McCoy [12], Levitzki [7] etc. for the study of rings in the forties. The general theory of radicals was initiated by Kurosh [6] (1953) and Amitsur [1] in the early fifties. Andrunakievic [4], Sulinski [15], Divinsky [8] and many others have followed up the works of Kurosh and Amitsur.

Radical properties based on the notion of nilpotence do not seem to yield fruitful results for rings without chain conditions. The notion of quasi-regularity was introduced by Perlis [16]. In 1945, Jacobson [9] used it and the significant "chainless" results were obtained.

In this paper, the general ring theory covering elementary definition of rings and its ideals, homomorphism, theorem related to homomorphism and some definitions related to radical class has been discussed in preliminaries. Also, we will introduce radical class of rings and some theorems related to radical class. Amitsur gives a theorem of radical class, which works as a sufficient condition of a class of rings that would be a radical class. We will know about this theorem and also right quasi-regular ring, right quasi-regular right ideal and some lemmas related to right quasi regular rings. Finally, we will prove that J, the class of all right quasi-regular rings is a radical class. It has already been proved by using the definition of radical class. But, here we will prove this using Amitsur theorem of radical class. Year 2012

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#### II. Preliminaries

#### 2.1. Definition

A **ring** is an ordered triple  $(R, +, \cdot)$  such that R is a nonempty set and + and  $\cdot$  are two binary operations on R satisfying the following axioms:

- a) R is an additive abelian group. i.e.
- i)  $a + b \in R$  for all  $a, b \in R$  [ closure law ]
- ii) (a + b) + c = a + (b + c) for all  $a, b, c \in R$ . [associative law]

iii) there exists an element  $0 \in R$  such that a + 0 = 0 + a = a, for all  $a \in R$ . [identity law]

- iv) for every non-zero element  $a \in R$  there exists an element  $-a \in R$  such that a + (-a) = (-a)
- +a = 0. [inverse law]
- v) a + b = b + a for all  $a, b \in R$ . [commutative law]
- b)  $(R, \cdot)$  is a semi group. i.e.
- i)  $a \cdot b \in R$  for all  $a, b \in R$ . [closure law]
- ii)  $(a \cdot b) \cdot c = a \cdot (b \cdot c)$  for all  $a, b, c \in R$  [associative law]
- c) Distributive laws are true in R. i.e. for all  $a, b, c \in R$ ,
- i)  $a \cdot (b+c) = a \cdot b + a \cdot c$

ii)  $(a+b) \cdot c = a \cdot c + b \cdot c$ 

#### Example

i) (  $\mathbb{Z}$ , +,·), ( $\mathbb{Q}$ , +,·), ( $\mathbb{R}$ , +,·), ( $\mathbb{C}$ , +,·) are rings.

ii) The residue class of modulo 6,

 $\mathbb{Z}_6 = \{\overline{0}, \overline{1}, \overline{2}, \overline{3}, \overline{4}, \overline{5}\}$  is a ring.

iii) [x], the set of all polynomials in x with real coefficients, is a ring.

#### 2.2. Definition

A non-empty subset I of a ring R is called a *left (right) ideal* of R if

i) I is an additive subgroup of R

ii)  $\forall r \in R$  and  $\forall i \in I, ri \in I, (ir \in I)$ .

#### 2.3. Definition

A non-empty subset I of a ring R is called an *ideal* of R if I is both a left ideal and a right ideal of R. For a commutative ring all left and right ideals are ideals.

#### Example:

1. 2  $\mathbb{Z}$  is an ideal of  $\mathbb{Z}$ .

2. The set of integers  $\mathbb{Z}$  is only a subring but not an ideal of the ring of rational numbers  $\mathbb{Q}$ . As  $3 \in \mathbb{Z}$ ,  $\frac{2}{5} \in \mathbb{Q}$  but  $3 \cdot \frac{2}{5} = \frac{6}{5} \notin \mathbb{Z}$ .

#### 2.4. Definition

Let R be a ring and I be an ideal of R then the *quotient ring* or *factor ring*  $\frac{K}{I}$  is the set {  $r + I : r \in R$  }, where addition and multiplication of two elements  $r_1 + I$ ,  $r_2 + I \in \frac{R}{I}$  are given by

i) 
$$(r_1 + I) + (r_2 + I) = (r_1 + r_2) + I$$
  
ii)  $(r_1 + I)(r_2 + I) = r_1r_2 + I$ .

Example:

 $\frac{\mathbb{Z}}{2\mathbb{Z}}$  is a quotient ring.

#### 2.5. Definition

Let  $(R, +, \cdot)$  and  $(R', +, \cdot)$  be two rings. A mapping  $f: R \to R'$  is called a ring **homomorphism** if  $\forall a, b \in R$ 

*i)* f(a + b) = f(a) + f(b) and *ii)* f(ab) = f(a) f(b).

#### 2.5.1. Theorem

 $N_{otes}$ 

Every factor ring of a ring is the homomorphic image of that ring.

**Proof:** Let R be a ring and I be an ideal of R, then we have to show that  $\frac{R}{I}$  is a homomorphic image of R. Let us define a map  $f: R \to \frac{R}{I}$  by f(r) = r + I for all  $r \in R$ . We need to show that f is a onto homomorphism.

Clearly f is well defined.

Now  $f(r_1 + r_2) = (r_1 + r_2) + I = (r_1 + I) + (r_2 + I) = f(r_1) + f(r_2)$ and  $f(r_1r_2) = r_1r_2 + I = (r_1 + I) (r_2 + I) = f(r_1) f(r_2)$ . Thus f is a homomorphism.

Let  $r + I \in \frac{R}{I}$  where  $r \in R$ . Then by definition, f(r) = r + I i.e. r + I = f(r). This implies that every element of  $\frac{R}{I}$  is the image of some element in R. Thus f is onto. Hence the theorem is proved.

#### 2.6. Definition

A ring R is said to have the **ascending chain condition** (A.C.C.) on left (right) ideals, if every ascending sequence of left (right) ideals  $L_1 \subseteq L_2 \subseteq L_3 \subseteq \ldots \subseteq L_n \subseteq \ldots$ , terminates after a finite number of steps, i.e. there exists a positive integer n such that  $L_n = L_{n+1} = \ldots$ .

#### 2.7. Definition

A ring R is said to have the *descending chain condition (D.C.C.)* on left (right) ideals, if every descending sequence of left (right) ideals  $R \supseteq L_1 \supseteq L_2 \supseteq L_3 \supseteq \dots \supseteq L_n$  $\supseteq$ ....., terminates after a finite number of steps, i.e. there exists a positive integer n such that  $L_n = L_{n+1} = \dots$ .

#### III. RADICAL CLASS OF RINGS

#### 3.1. Definition

Let  $\mathfrak{R}$  be a nonempty class of rings with a certain property. A ring A is said to be an  $\mathfrak{R}$ -ring if  $A \in \mathfrak{R}$ .

#### Example:

Let  $\mathfrak{R}$  be the class of all nilpotent ring and A be an idempotent ring. Then A is not nilpotent ring and hence  $A \notin \mathfrak{R}$ . Therefore A is not an  $\mathfrak{R}$ -ring.

#### 3.2. Definition

An ideal I of a ring A is said to be an  $\mathfrak{R}$ -ideal if I is an  $\mathfrak{R}$ -ring. i.e.  $I \in \mathfrak{R}$ .

#### Example:

Let  $\mathfrak{R}$  be the class of all nilpotent ring and I be an ideal of a nilpotent ring A. Then  $I \in \mathfrak{R}$ . Therefore I is an  $\mathfrak{R}$ -ideal.

#### 3.3. Definition

A ring A is said to be  $\Re$ -semi-simple if A has no non-zero  $\Re$ -ideal.

#### 3.4. Definition

Let  $\mathfrak{R}$  be a non-empty class of rings with a certain property. Then  $\mathfrak{R}$  is said to be a *radical property* or *radical class* if the following conditions are hold:

- A)  $\mathfrak{R}$  is homomorphically closed. i.e. every homomorphic image of an  $\mathfrak{R}$ -ring A is an  $\mathfrak{R}$ -ring. i.e. if  $A \in \mathfrak{R}$  and  $I \triangleleft A$ , then  $\frac{A}{I} \in \mathfrak{R}$ .
- B) Every ring  $A \in \Re$  contains a non-zero  $\Re$ -ideal R(A) which contains every other  $\Re$ -ideals of A.

C)  $\frac{A}{R(A)}$  has no non-zero  $\Re$ -ideal. i.e.  $\frac{A}{R(A)}$  is  $\Re$ -is semi-simple.

A radical class is simply called a radical.

#### 3.5. Definition

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Let  $\mathfrak{R}$  be a radical class. The  $\mathfrak{R}$ -ideal R(A) of a ring A is called the  $\mathfrak{R}$ -radical of the ring A.

#### 3.6. Definition

Let  $\mathfrak{R}$ -be a radical class. Then a ring A is said to be an  $\mathfrak{R}$ -radical ring if R(A) = A, where R(A) is the radical of A.

#### 3.7. Definition

Let  $\mathfrak{R}$  be a radical class. Then a ring A is said to be an  $\mathfrak{R}$ -semi-simple ring if R(A) = 0, where R(A) is the radical of A.

0 is the only ring which is both an  $\Re$ -radical ring and an  $\Re$ -semi-simple ring.

#### 3.7.1. Theorem [8]

Let  $\mathfrak R$  be a non-empty class  $\mathfrak R$  of rings. Then  $\mathfrak R$  is said to be a radical class if and only if

A)  $\mathfrak{R}$  is homomorphically closed.

D) If every non-zero homomorphic image of a ring A contains a non-zero  $\mathfrak{R}$ -ideal, then A is in  $\mathfrak{R}$ . i.e.  $\forall I \triangleleft A$ , if  $\frac{A}{I} \supset \frac{B}{I} \in \mathfrak{R}$  then  $A \in \mathfrak{R}$ , where  $B \triangleleft A$ .

This theorem is known as Kurosh's Theorem.

#### 3.7.2.1. Lemma (Zorn's Lemma)

Let A be a nonempty partially ordered set in which every totally ordered subset has an upper bound in A. Then A contains at least one maximal element.

#### 3.7.2. Theorem (Amitsur) [3]

Let  $\mathfrak{R}$  be a nonempty class of rings. Then  $\mathfrak{R}$  is a radical class if and only if

A')  $\Re$  is homomorphically closed.

B') For any ring A and an ideal I of A if both I and  $\frac{A}{I}$  is in  $\Re$ , then  $A \in \Re$ . i.e.  $\Re$  is closed under extension.

C') If  $I_1 \subseteq I_2 \subseteq I_3 \subseteq \dots$ , is an ascending chain of  $\Re$ -ideals of a ring A, then  $\bigcup_{\alpha} I_{\alpha}$  is an  $\Re$ -ideal.

#### IV. RIGHT QUASI-REGULAR RINGS

#### 4.1. Definition

Let R be a ring and  $x \in R$ . Then x is called **right quasi-regular** if there exists an

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element  $y \in R$  such that x + y + xy = 0.

We often write x + y + xy by xoy. When xoy = 0 then the element y is called **right** quasi-inverse of x.

4.2. Definition

A ring R is said to be *right quasi-regular* if every element in R is right quasi-regular.

4.2.1. Lemma

If R is a ring with 1, then (1+x) has right inverse (1+y) iff x is right quasi-regular. **Proof:** Let us consider a ring with unity element 1. Let (1+y) be the right inverse

of (1 + x). Then we have,

$$(1 + x) (1 + y) = 1$$

 $\Rightarrow 1 + y + x + xy = 1$ 

 $\Rightarrow x + y + xy = 0$ 

 $\Rightarrow x$  is right quasi-regular.

Conversely, let x be right quasi-regular. Then there is a right quasi-inverse y such that x + y + xy = 0

 $\Rightarrow 1 + y + x + xy = 1$ 

 $\Rightarrow 1(1+y) + x(1+y) = 1$ 

 $\Rightarrow (1 + x) (1 + y) = 1$ 

i.e. (1 + y) is right inverse of (1 + x).

4.2.2. Lemma

Let R be a ring. Then for any element x in R, x is a right quasi-regular if and only if  $\{r + xr\} = R, \forall r \in R$ .

**Proof:** Let R be a ring and  $x \in R$ . Consider  $\{r + xr\}$ , the set of all elements r + xr,  $\forall r \in R$ . Then  $\{r + xr\}$  is clearly a right ideal of R. Now suppose that  $\{r + xr\} = R$ . We are to show that x is right quasi-regular. Since  $\{r + xr\} = R$ , then x = r + xr for some r in R. This implies that x + (-r) + x(-r) = 0. This implies that x is right quasi-regular for some  $r \in R$ .

Conversely, suppose that x is right quasi-regular element of R. We have to show that  $R = \{r + xr\}$ . Since x is right quasi-regular then  $\exists$  an element  $y \in R$  such that  $x + y + xy = 0 \Rightarrow x = (-y) + x (-y) \in \{r + xr\}$ . Then  $xr \in \{r + xr\}$  and therefore  $r \in \{r + xr\}$  for every  $r \in R$ . Hence  $\{r + xr\} = R$ .

#### 4.3. Definition

Let R be a ring and I be a right ideal of R. Then I is called a right quasi-regular right ideal if every element of I is right quasi-regular.

#### 4.3.1. Lemma/8/

If x is right quasi-regular and if y belongs to a right quasi-regular right ideal I, then x + y is right quasi-regular.

**Proof:** Since x is right quasi-regular, then there exists an element x' such that, x + x' + xx' = 0. Now, consider the element y + yx'. Then y + yx' is in I and thus is right quasi-regular. Let z be the right quasi-inverse of y + yx' then, (y + yx') + z + (y + yx')z = 0.

R<sub>ef.</sub>

Now we will show that x' + z + x'z is a right quasi-inverse of x + y. Therefore, (x + y) + (x' + z + x'z) + (x + y)(x' + z + x'z)= x + y + x' + z + x'z + xx' + xz + xx'z + yx' + yz + yx'z= (x + x' + xx') + (y + yx') + z + (y + yx')z + (x + x' + xx')z= 0

Hence x + y is right quasi-regular.

#### 4.3.2. Lemma

The sum of two right quasi-regular right ideals of a ring is also a right quasi-regular right ideal.

**Proof:** Let  $I_1$  and  $I_2$  be two right quasi-regular right ideals of a ring R. We have to show that  $I_1 + I_2$  is also a right quasi-regular right ideal of R. Let  $p \in I_1 + I_2$  then p = x + y for some  $x \in I_1$  and  $y \in I_2$ . Since x is right quasi-regular and  $y \in I_2$  then we have x + y is also right quasi-regular (by Lemma 4.3.1). i.e. p is right quasi-regular.

Hence every element of  $I_1 + I_2$  is right quasi-regular.

Hence  $I_1 + I_2$  is right quasi-regular right ideal of R.

#### 4.3.3. Lemma

The sum of any finite number of right quasi-regular right ideals of a ring is again a right quasi-regular right ideal.

**Proof:** Let  $I_1, I_2, ..., I_n$  are right quasi-regular right ideals of a ring R. We have to show that  $I_1 + I_2 + ... + I_n$  is right quasi-regular right ideal. We shall prove this by the method of induction on n.

If n = 1 then the proof is obvious. Now suppose n = 2, then,  $I_1 + I_2$  is right quasiregular right ideal (by Lemma 4.3.1).

Now, let  $I = I_1 + I_2 + \dots + I_{n-1}$  a right quasi-regular right ideal of R. We show that  $I + I_n$  is right quasi-regular right ideal of R.

Let  $p \in I + I_n$  then p = x' + y' for some  $x' \in I$  and  $y' \in I_n$ . Then x' is right quasiregular and y' belongs to a right quasi-regular right ideal  $I_n$ . Therefore x' + y' is right quasi-regular (by Lemma 4.3.1). Hence  $I + I_n$  is right quasi-regular right ideal. i.e.  $I_1 + I_2$ +.....+  $I_{n-1} + I_n$  is a right quasi-regular right ideal of R.

#### 4.3.4. Lemma

Sum (Union) of all right quasi-regular right ideals of a ring R is a right quasi-regular right ideal of R.

#### 4.3.5. Lemma/8/

J(R), the sum of all right quasi-regular right ideals of a ring R is a two sided ideal of R.

**Proof:** Let x be any element in J(R) and r any element of R. We have to show that rx is in J(R) i.e. J(R) is a left ideal. We know that J(R) is a right quasi-regular right ideal. Hence  $xr \in J(R)$  is a right quasi-regular. Then there exists an element w such that

```
xr + w + xrw = 0. \text{ Then}
rx + (-rx - rwx) + rx(-rx - rwx)
= rx - rx - rwx - rx \cdot rx - rx \cdot rwx
= -r(w + xr + xrw)x
= -r \cdot 0 \cdot x
= 0
```

Therefore, *rx* is right quasi-regular.

Next consider the right ideal generated by rx. This is the set of all rxi + rxs, where i is an integer and s is in R. The element xi + xs is in J(R) and, as above, r(xi + xs) is right quasi-regular. Therefore,  $\{rxi + rxs\}$  is a right quasi-regular right ideal. It is thus in J(R) and then, in particular, rx is in J(R). Therefore J(R) is a two-sided ideal of R.

#### 4.3.6. Lemma

Every homomorphic image of a right quasi-regular ring R is right quasi-regular.

**Proof:** Let R be a right quasi-regular ring and I be any ideal of R, then we have to

show that  $\frac{R}{I}$  is right quasi-regular. Let  $x \in \frac{R}{I}$  then x = r + I for some  $r \in R$ .

Since R is right quasi-regular, then r is right quasi-regular. Then there exists an element  $r' \in R$  such that r + r' + rr' = 0.

```
Now (r + I) + (r' + I) + (r + I)(r' + I) = r + r' + I + rr' + I
= r + r' + rr' + I
= 0 + I
```

= I

 $N_{otes}$ 

But *I* is the zero element of  $\frac{R}{I}$ . Therefore r' + I is right quasi-inverse of r + I. Hence r + I is right quasi-regular i.e. *x* is right quasi-regular. Therefore  $\frac{R}{I}$  is right quasi-regular.

#### 4.3.7. Lemma

Let R be a ring and I be an ideal of R. If I and  $\frac{R}{I}$  are right quasi-regular then R is right quasi-regular.

**Proof:** Since  $\frac{R}{I}$  is right quasi-regular, then for every  $x \in \frac{R}{I}$ , there exists  $y \in \frac{R}{I}$  such that

 $\begin{aligned} (x+I) + (y+I) + (x+I)(y+I) &= I \\ \Rightarrow x+I+y+I+xy+I &= I \\ \Rightarrow x+y+xy+I &= I \end{aligned}$ 

 $\Rightarrow x + y + xy \in I$ 

Since I is right quasi-regular then there exists  $w \in I$  such that

x + y + xy + w + (x + y + xy)w = 0

 $\Rightarrow x + y + xy + w + xw + yw + xyw = 0$ 

 $\Rightarrow x + (y + w + yw) + x(y + w + yw) = 0$ 

This implies that y + w + yw is a right quasi-inverse of x and thus x is a right quasi-regular. Hence R is right quasi-regular.

#### V. Conclusions

From the above discussions, we can prove the following theorem.

5.1. Theorem

The class of all right quasi-regular rings is a radical class.

**Proof:** Let J be the class of all right quasi-regular rings. We shall prove this using Amitsur theorem.

By Lemma 4.3.6, A') holds. i.e. J is homomorphically closed.

By Lemma 4.3.7, B') holds. i.e. J is closed under extension.

To prove C'), let  $I_1 \subseteq I_2 \subseteq I_3 \subseteq \ldots$  be an ascending chain of right quasi-regular right ideals of a ring R. We have to show that  $\bigcup_{\alpha} I_{\alpha}$  is right quasi-regular. Let  $x \in \bigcup_{\alpha} I_{\alpha}$ then  $x \in I_{\alpha}$  for some  $\alpha$ . Since each  $I_{\alpha}$  is right quasi-regular right ideal then  $\exists$  an element x'such that x + x' + xx' = 0. i.e. x is right quasi-regular. Hence every element of  $\bigcup_{\alpha} I_{\alpha}$  is right quasi-regular. i.e.  $\bigcup_{\alpha} I_{\alpha}$  is right quasi-regular. Hence J is a radical class.

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## Positive Solutions for Systems of Three-Point Nonlinear Boundary Value Problems on Time Scales

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*Abstract* - Values of are determined for which there exist positive solutions of the system of dynamic equations,  $u^{\Delta\Delta}(t) + \lambda p(t)f(v(\sigma(t))) = 0$ ,  $v^{\Delta\Delta}(t) + \lambda q(t)g(u(\sigma(t))) = 0$ , for  $t \in [a,b]_{\mathbb{T}}$  Satisfying the three - point boundary conditions,  $\alpha u(a) - \beta u^{\Delta}(a) = 0$ ,  $u(\sigma^2(b)) - \delta u(\eta) = 0$ ,  $\alpha v(a) - \beta v^{\Delta}(a) = 0$ ,  $v(\sigma^2(b)) - \delta v(\eta) = 0$ , where  $\mathbb{T}$  is a time scales. A Guo-Krasnosel'skii fixed point theorem is applied.

Keywords : Time scales, three-point boundary value problems, dynamic equations, system of equations, positive solution, eigenvalue problem.

GJSFR-F Classification : MSC 2010: 34B15, 39B10, 34B18

## POSITIVE SOLUTIONS FOR SYSTEMS OF THREE-POINT NONLINEAR BOUNDARY VALUE PROBLEMS ON TIME SCALES

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Notes

# Positive Solutions for Systems of Three-Point Nonlinear Boundary Value Problems on Time Scales

#### A Kameswara Rao $^{\alpha}$ & S. Nageswara Rao $^{\sigma}$

Abstract - Values of  $\lambda$  are determined for which there exist positive solutions of the system of dynamic equations,  $u^{\Delta\Delta}(t) + \lambda p(t)f(v(\sigma(t))) = 0$ ,  $v^{\Delta\Delta}(t) + \lambda q(t)g(u(\sigma(t))) = 0$ , for  $t \in [a,b]_{\mathbb{T}}$  Satisfying the three - point boundary conditions,  $\alpha u(a) - \beta u^{\Delta}(a) = 0$ ,  $u(\sigma^2(b)) - \delta u(\eta) = 0$ ,  $\alpha v(a) - \beta v^{\Delta}(a) = 0$ ,  $v(\sigma^2(b)) - \delta v(\eta) = 0$ , where  $\mathbb{T}$  is a time scales. A Guo-Krasnosel'skii fixed point theorem is applied. *Keywords : Time scales, three-point boundary value problems, dynamic equations, system of equations, positive solution, eigenvalue problem.* 

#### I. INTRODUCTION

Let  $\mathbb{T}$  be a time scale with  $a, \sigma^2(b) \in \mathbb{T}$ . Given an interval J of  $\mathbb{R}$ , we will use the interval notation

$$J_{\mathbb{T}} = J \cap \mathbb{T}.$$

We are concerned with determining intervals of the parameter  $\lambda$  (eigenvalues) for which there exist positive solutions for the system of dynamic equations,

$$u^{\Delta\Delta}(t) + \lambda p(t)f(v(\sigma(t))) = 0, \quad t \in [a,b]_{\mathbb{T}},$$
  
$$v^{\Delta\Delta}(t) + \lambda q(t)g(u(\sigma(t))) = 0, \quad t \in [a,b]_{\mathbb{T}},$$
  
(1.1)

satisfying the boundary conditions

$$\alpha u(a) - \beta u^{\Delta}(a) = 0, \quad u(\sigma^2(b)) - \delta u(\eta) = 0,$$
  

$$\alpha v(a) - \beta v^{\Delta}(a) = 0, \quad v(\sigma^2(b)) - \delta v(\eta) = 0,$$
(1.2)

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where  $\alpha, \beta \geq 0, \alpha + \beta \geq 0, \lambda \geq 0, 0 < \delta < 1, \eta \in [a, \sigma^2(b)]$ , and

- (A1)  $f, g \in C([0, \infty), [0, \infty)),$
- (A2)  $p, q \in C([a, \sigma(b)]_{\mathbb{T}}, [0, \infty))$ , and each does not vanish identically on any closed subinterval of  $[a, \sigma(b)]_{\mathbb{T}}$ ,

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$$f_0 := \lim_{x \to 0^+} \frac{f(x)}{x}, \quad g_0 := \lim_{x \to 0^+} \frac{g(x)}{x}$$
$$f_\infty := \lim_{x \to \infty} \frac{f(x)}{x}, \quad g_\infty := \lim_{x \to \infty} \frac{g(x)}{x}$$

exist as positive real numbers.

On a larger scale, there has been a great deal of activity in studying positive solutions of boundary value problems for ordinary differential equations. Interest in such solutions is high from a theoretical sense [9, 10, 12, 15] and as applications for which only positive solutions are meaningful. These considerations are caste primarily for scalar problems, but good attention has been given to boundary value problems for systems of differential equations [13, 14, 19, 21, 22].

The main tool in this paper is an application of the Guo-Krasnoselskii fixed point theorem for operators leaving a Banach space cone invariant [10]. A Green's function plays a fundamental role in defining an appropriate operator on a suitable cone.

#### Some Preliminaries П.

In this section, we state some preliminary lemmas and the well-known Guo-Krasnosel'skii fixed point theorem.

Let G(t, s) be the Green's function for the boundary value problem

$$-y^{\Delta\Delta}(t) = 0, \qquad (2.1)$$

$$\alpha y(a) - \beta y^{\Delta}(a) = 0, \qquad y(\sigma^2(b)) - \delta y(\eta) = 0, \qquad (2.2)$$

which is given by

$$G(t,s) = \frac{1}{d} \begin{cases} G_1(t,s) : & a \le s \le \eta \\ G_2(t,s) : & \eta \le \sigma(s) \le \sigma^2(b) \end{cases}$$

where

$$G_1(t,s) = \begin{cases} \left[\beta + \alpha(\sigma(s) - a)\right] \left[\sigma^2(b) - \delta\eta - t(1 - \delta)\right], & \sigma(s) \le t\\ \left[\beta + \alpha(t - a)\right] \left[\sigma^2(b) - \delta\eta - \sigma(s)(1 - \delta)\right], & t \le s \end{cases}$$

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$$G_2(t,s) = \begin{cases} \left[\beta + \alpha(\sigma(s) - a)\right](\sigma^2(b) - t) + (t - \sigma(s))(\eta + \beta - \alpha a)\delta, & \sigma(s) \le t\\ \left[\beta + \alpha(t - a)\right](\sigma^2(b) - \sigma(s)), & t \le s \end{cases}$$

and

$$d := \beta(1-\delta) + \alpha(\sigma^2(b) - a - \delta(\eta - a)).$$

**Lemma 2.1** For  $h(t) \in C[a, \sigma^2(b)]_{\mathbb{T}}$ , the BVP

$$-y^{\Delta\Delta}(t) = h(t), \quad t \in [a, b]_{\mathbb{T}}, \tag{2.3}$$

$$\alpha y(a) - \beta y^{\Delta}(a) = 0, \quad y(\sigma^2(b)) - \delta y(\eta) = 0, \tag{2.4}$$

has a unique solution

$$y(t) = \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))h(s)\Delta s$$
$$-\frac{\delta(\beta + \alpha(t-a))}{d} \int_{a}^{\eta} (\eta - \sigma(s))h(s)\Delta s - \int_{a}^{t} (t - \sigma(s))h(s)\Delta s.$$
(2.5)

From (2.5) obviously we have that

$$y(t) \le \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))h(s)\Delta s, \qquad (2.6)$$

and

$$y(\eta) \ge \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^2(b) - \sigma(s))h(s)\Delta s.$$
 (2.7)

**Lemma 2.2** Let  $0 < \delta < 1$ . If  $h(t) \in C[a, \sigma^2(b)]_{\mathbb{T}}$ , and  $h \ge 0$ , then the unique solution y of the problem (2.3), (2.4) satisfies

 $y(t) \ge 0, \quad t \in (a, \sigma^2(b))_{\mathbb{T}}.$ 

*Proof:* From the fact that  $y^{\Delta\Delta}(t) = -h(t) \leq 0$ , we know that the graph of y(t) is concave down on  $[a, \sigma^2(b)]_{\mathbb{T}}$  and  $y^{\Delta}(t)$  is monotone decreasing. Thus  $y^{\Delta}(t) \leq y^{\Delta}(a) = \frac{\alpha}{\beta}y(a)$ , where  $\beta \neq 0$ .

Case 1. If y(a) < 0, then  $y^{\Delta}(t) < 0$  for  $[a, \sigma^2(b)]_{\mathbb{T}}$ . Thus y is a monotone decreasing function, that is  $y(t) \ge y(\sigma^2(b))$ .

1. If  $y(\sigma^2(b)) \ge 0$ , then y(t) > 0. So this contradicts the assertion y(t) is a monotone decreasing function.

2. If  $y(\sigma^2(b)) < 0$ , then we have that

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$$y(\eta) = \frac{1}{\delta}y(\sigma^2(b)) < 0,$$
$$y(\sigma^2(b)) = \delta y(\eta) \ge y(\eta),$$

which contradicts the assertion that y(t) is monotone decreasing.

Case 2. If  $y(a) \ge 0$ , then  $y^{\Delta}(a) \ge 0$ . So y(t) is a monotone increasing on  $[a, a + \epsilon]$ .

1. If  $y(\sigma^2(b)) \ge 0$ , then  $y(t) \ge 0$  on  $[a, \sigma^2(b)]_{\mathbb{T}}$ .

2. If  $y(\sigma^2(b)) < 0$ , then we have that

$$y(\eta) = \frac{1}{\delta}y(\sigma^2(b)) < 0,$$
$$y(\sigma^2(b)) = \delta y(\eta) \ge y(\eta)$$

which contradicts the assertion that the graph of y(t) is concave down on  $(a, \sigma^2(b))_{\mathbb{T}}$ .

If  $\beta = 0$ , from the boundary conditions we obtain y(a) = 0.

1. If  $y(\sigma^2(b)) \ge 0$ , then the concavity of y implies that  $y(t) \ge 0$  for  $t \in [a, \sigma^2(b)]_{\mathbb{T}}$ .

2. If  $y(\sigma^2(b)) < 0$ , then

$$y(\eta) = \frac{1}{\delta}y(\sigma^2(b)) < 0,$$
$$y(\sigma^2(b)) = \delta y(\eta) \ge y(\eta).$$

This contradicts with the concavity of y.

**Lemma 2.3** If  $y^{\Delta\Delta}(t) \leq 0$ , then  $\frac{y(\sigma^2(b))}{\sigma^2(b)} \leq \frac{y(t)}{t} \leq \frac{y(\eta)}{\eta}$  for all  $t \in [\eta, \sigma^2(b)]_{\mathbb{T}}$ .

*Proof:* Let  $h(t) := y(t) - \frac{t}{\sigma^2(b)-a}y(\sigma^2(b))$ . Thus, we have  $h(\eta) > 0$  and  $h(\sigma^2(b)) = 0$ . Since  $h^{\Delta\Delta}(t) \leq 0$  then  $h(t) \geq 0$  on  $[\eta, \sigma^2(b)]_{\mathbb{T}}$ . So  $\frac{y(\sigma^2(b))}{\sigma^2(b)} \leq \frac{y(t)}{t}$ . For the function h(t), since  $h(\eta) > 0$ ,  $h(\sigma^2(b)) = 0$  and  $h^{\Delta\Delta}(t) \leq 0$  then the function h(t) is decreasing on  $[\eta, \sigma^2(b)]_{\mathbb{T}}$ . So  $\frac{y(t)}{t} \leq \frac{y(\eta)}{\eta}$  for all  $t \in [\eta, \sigma^2(b)]_{\mathbb{T}}$ .

**Lemma 2.4** Let  $0 < \delta < 1$ . If  $h(t) \in C[a, \sigma^2(b)]_{\mathbb{T}}$ , and  $h \ge 0$ , then the unique solution y of the problem (2.3), (2.4) satisfies

$$\inf_{t \in [\eta, \sigma^2(b)]_{\mathbb{T}}} y(t) \ge \gamma \|y\|,$$

where

$$\gamma := \min\left\{\frac{\delta(\sigma^2(b) - \eta)}{\sigma^2(b) - \delta\eta - a(1 - \delta)}, \frac{\delta\eta}{\sigma^2(b)}\right\}.$$

Notes
*Proof:* By the second boundary condition we know that  $y(\eta) \ge y(\sigma^2(b))$ . Pick  $t_0 \in (a, \sigma^2(b))_{\mathbb{T}}$  such that  $y(t_0) = ||y||$ . If  $t_0 < \eta < \sigma^2(b)$ , then

$$\min_{t \in [\eta, \sigma^2(b)]} y(t) = y(\sigma^2(b)),$$

and

Ref.

[17] M. A. Krasnosel'skii, *Positive Solutions of Operator Equations*, P. Noordhoff Ltd, Groningen, The Netherlands (1964).

$$\frac{y(\sigma^2(b)) - y(\eta)}{\sigma^2(b) - \eta} \le \frac{y(\eta) - y(t_0)}{\eta - t_0}$$

Therefore

$$\min_{t \in [\eta, \sigma^2(b)]_{\mathbb{T}}} y(t) \ge \frac{\delta(\sigma^2(b) - \eta)}{\sigma^2(b) - \delta\eta - a(1 - \delta)} \|y\|$$

If  $\eta \leq t_0 < \sigma^2(b)$ , again we have  $y(\sigma^2(b)) = \min_{t \in [\eta, \sigma^2(b)]_{\mathbb{T}}} y(t)$ . From Lemma 2.3, we have  $\frac{y(\eta)}{\eta} \geq \frac{y(t_0)}{t_0}$ . Combining with the boundary condition  $\delta y(\eta) = y(\sigma^2(b))$ , we conclude that

$$\frac{y(\sigma^{2}(b))}{\delta\eta} \ge \frac{y(t_{0})}{t_{0}} \ge \frac{y(t_{0})}{\sigma^{2}(b)} = \frac{\|y\|}{\sigma^{2}(b)}$$

This is

$$\min_{t \in [\eta, \sigma^2(b)]_{\mathbb{T}}} y(t) \ge \frac{\delta \eta}{\sigma^2(b)} \|y\|_{\mathbb{T}}$$

We note that a pair (u(t), v(t)) is a solution of the eigenvalue problem (1.1), (1.2) if, and only if,

$$u(t) = \lambda \int_{a}^{\sigma(b)} G(t,s)p(s)f\left(\lambda \int_{a}^{\sigma(b)} G(\sigma(s),r)q(r)g(u(\sigma(r)))\Delta r\right)\Delta s, \ a \le t \le \sigma^{2}(b)$$

where

$$v(t) = \lambda \int_{a}^{\sigma(b)} G(t,s)q(s)g(u(\sigma(s)))\Delta s, \quad a \le t \le \sigma^2(b).$$

Values of  $\lambda$  for which there are positive solutions (positive with respect to a cone) of (1.1), (1.2) will be determined via applications of the following fixed point-theorem [17].

**Theorem 2.5** (*Krasnosel'skii*) Let  $\mathcal{B}$  be a Banach space, and let  $\mathcal{P} \subset \mathcal{B}$  be a cone in  $\mathcal{B}$ . Assume  $\Omega_1$  and  $\Omega_2$  are open subsets of  $\mathcal{B}$  with  $0 \in \Omega_1 \subset \overline{\Omega}_1 \subset \Omega_2$ , and let

$$T: \mathcal{P} \cap (\overline{\Omega}_2 \backslash \Omega_1) \to \mathcal{P}$$

be a completely continuous operator such that, either

(i)  $||Tu|| \le ||u||, u \in \mathcal{P} \cap \partial \Omega_1$ , and  $||Tu|| \ge ||u||, u \in \mathcal{P} \cap \partial \Omega_2$ , or

(ii)  $||Tu|| \ge ||u||, u \in \mathcal{P} \cap \partial \Omega_1$ , and  $||Tu|| \le ||u||, u \in \mathcal{P} \cap \partial \Omega_2$ .

Then, T has a fixed point in  $\mathcal{P} \cap (\overline{\Omega}_2 \setminus \Omega_1)$ .

#### III. POSITIVE SOLUTIONS IN A CONE

In this section, we apply Theorem 2.5 to obtain solutions in a cone (i.e., positive solutions) of (1.1), (1.2).

For our construction, let  $\mathcal{B} = \{x : [a, \sigma^2(b)]_{\mathbb{T}} \to \mathbb{R}\}$  with supremum norm  $||x|| = \sup\{|x(t)|: t \in [a, \sigma^2(b)]_{\mathbb{T}}\}$  and define a cone  $\mathcal{P} \subset \mathcal{B}$  by

$$\mathcal{P} = \bigg\{ x \in \mathcal{B} \mid x(t) \ge 0 \text{ on } [a, \sigma^2(b)]_{\mathbb{T}}, \text{ and } \min_{t \in [\eta, \sigma^2(b)]_{\mathbb{T}}} x(t) \ge \gamma \|x\| \bigg\}.$$

For our first result, define positive numbers  $L_1$  and  $L_2$  by

$$L_{1} := \max\left\{ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)\Delta s f_{\infty} \right]^{-1}, \\ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))q(s)\Delta s g_{\infty} \right]^{-1} \right\},$$

and

$$L_2 := \min\left\{ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))p(s)\Delta s f_0 \right]^{-1} \right\}$$
$$\left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))q(s)\Delta s g_0 \right]^{-1} \right\}.$$

**Theorem 3.1** Assume that conditions (A1) - (A3) are satisfied. Then, for each  $\lambda$  satisfying

$$L_1 < \lambda < L_2, \tag{3.1}$$

there exists a pair (u, v) satisfying (1.1), (1.2) such that u(x) > 0 and v(x) > 0 on  $(a, \sigma^2(b))_{\mathbb{T}}$ .

*Proof:* Let  $\lambda$  be as in (3.1). And let  $\epsilon > 0$  be chosen such that

$$\max\left\{\left[\gamma\frac{\beta+\alpha(\eta-a)}{d}\int_{\eta}^{\sigma(b)}(\sigma^{2}(b)-\sigma(s))p(s)\Delta s(f_{\infty}-\epsilon)\right]^{-1},\right.$$

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$$\left[\gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^2(b) - \sigma(s))q(s)\Delta s(g_{\infty} - \epsilon)\right]^{-1} \right\} \le \lambda,$$

and

Notes

$$\lambda \leq \min\left\{ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))p(s)\Delta s(f_0 + \epsilon) \right]^{-1}, \\ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))q(s)\Delta s(g_0 + \epsilon) \right]^{-1} \right\},$$

Define an integral operator  $T: \mathcal{P} \to \mathcal{B}$  by

$$Tu(t) := \lambda \int_{a}^{\sigma(b)} G(t,s)p(s)f\left(\lambda \int_{a}^{\sigma(b)} G(\sigma(s),r)q(r)g(u(\sigma(r)))\Delta r\right)\Delta s, \ u \in \mathcal{P}.$$
(3.2)

We seek suitable fixed points of T in the cone  $\mathcal{P}$ .

By Lemma 2.4,  $T\mathcal{P} \subset \mathcal{P}$ . In addition, standard arguments show that T is completely continuous.

Now, from the definitions of  $f_0$  and  $g_0$ , there exists  $H_1 > 0$  such that

$$f(x) \le (f_0 + \epsilon)x$$
 and  $g(x) \le (g_0 + \epsilon)x$ ,  $0 < x \le H_1$ .

Let  $u \in \mathcal{P}$  with  $||u|| = H_1$ . We first have from (2.6) and choice of  $\epsilon$ ,

$$\begin{split} \lambda \int_{a}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r \\ &\leq \lambda \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r \\ &\leq \lambda \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)(g_{0} + \epsilon)u(r)\Delta r \\ &\leq \lambda \frac{\beta + \alpha(\sigma^{2}(b) - a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)\Delta r(g_{0} + \epsilon) \|u\| \\ &\leq \|u\| \\ &= H_{1}. \end{split}$$

As a consequence, we next have from (2.6) and choice of  $\epsilon$ ,

$$Tu(t) = \lambda \int_{a}^{\sigma(b)} G(t,s)p(s)f\left(\lambda \int_{a}^{\sigma(b)} G(\sigma(s),r)q(r)g(u(\sigma(r)))\Delta r\right)\Delta s$$

$$\leq \lambda \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)$$

$$f\left(\lambda \int_{a}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r\right)\Delta s$$

$$\leq \lambda \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)$$

$$(f_{0} + \epsilon)\lambda \int_{a}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r\Delta s$$

$$\leq \lambda \frac{\beta + \alpha(\sigma^{2}(b) - a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)(f_{0} + \epsilon)H_{1}\Delta s$$

$$\leq H_{1}$$

$$= \|u\|.$$

So,  $||Tu|| \le ||u||$ . If we set

$$\Omega_1 = \{ x \in \mathcal{B} : \|x\| < H_1 \},\$$

then

$$||Tu|| \le ||u||, \text{ for } u \in \mathcal{P} \cap \partial \Omega_1.$$
 (3.3)

Notes

Next, from the definitions of  $f_{\infty}$  and  $g_{\infty}$ , there exists  $\overline{H}_2 > 0$  such that

$$f(x) \ge (f_{\infty} - \epsilon)x$$
 and  $g(x) \ge (g_{\infty} - \epsilon)x$ ,  $x \ge \overline{H}_2$ .

Let

$$H_2 = \max\left\{2H_1, \frac{\overline{H}_2}{\gamma}\right\}.$$

Let  $u \in \mathcal{P}$  and  $||u|| = H_2$ . Then,

$$\min_{t \in [\eta, \sigma^2(b)]} u(t) \ge \gamma \|u\| \ge \overline{H}_2.$$

Consequently, from (2.7) and choice of  $\epsilon$ ,

$$\lambda \int_{a}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r$$
  

$$\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r$$
  

$$\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)(g_{\infty} - \epsilon)u(r)\Delta r$$

$$\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^2(b) - \sigma(r))q(r)(g_{\infty} - \epsilon)\Delta r\gamma ||u|$$
  
$$\geq ||u||$$
  
$$= H_2.$$

And so, we have from (2.7) and choice of  $\epsilon$ ,

 $\mathbf{N}_{\mathrm{otes}}$ 

$$Tu(\eta) \ge \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)$$

$$f\left(\lambda \int_{\eta}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r\right)\Delta s$$

$$\ge \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)$$

$$(f_{\infty} - \epsilon)\lambda \int_{\eta}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r\Delta s$$

$$\ge \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)(f_{\infty} - \epsilon)H_{2}\Delta s$$

$$\ge \lambda \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)(f_{\infty} - \epsilon)H_{2}\Delta s$$

$$\ge H_{2}$$

$$= ||u||.$$

Hence,  $||Tu|| \ge ||u||$ . So, if we set

$$\Omega_2 = \{ x \in \mathcal{B} : \|x\| < H_2 \},\$$

then

$$||Tu|| \ge ||u||, \text{ for } u \in \mathcal{P} \cap \partial \Omega_2.$$
 (3.4)

Applying Theorem 2.5 to (3.3) and (3.4), we obtain that T has a fixed point  $u \in \mathcal{P} \cap (\overline{\Omega}_2 \setminus \Omega_1)$ . As such, and with v being defined by

$$v(t) = \lambda \int_a^{\sigma(b)} G(t,s)q(s)g(u(\sigma(s)))\Delta s,$$

the pair (u, v) is a desired solution of (1.1), (1.2) for the given  $\lambda$ . The proof is complete.

Prior to our next result, we define positive numbers  $L_3$  and  $L_4$  by

$$L_3 := \max\left\{ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^2(b) - \sigma(s)) p(s) \Delta s f_0 \right]^{-1}, \\ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^2(b) - \sigma(s)) q(s) \Delta s g_0 \right]^{-1} \right\},$$

and

$$L_4 := \min\left\{ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))p(s)\Delta s f_\infty \right]^{-1}, \\ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))q(s)\Delta s g_\infty \right]^{-1} \right\}.$$

**Theorem 3.2** Assume that conditions (A1) - (A4) are satisfied. Then, for each  $\lambda$  satisfying

$$L_3 < \lambda < L_4, \tag{3.5}$$

there exists a pair (u, v) satisfying (1.1), (1.2) such that u(x) > 0 and v(x) > 0 on  $(a, \sigma^2(b))_{\mathbb{T}}$ .

*Proof:* Let  $\lambda$  be as in (3.5). And let  $\epsilon > 0$  be chosen such that

$$\max\left\{ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s)) p(s) \Delta s(f_{0} - \epsilon) \right]^{-1}, \\ \left[ \gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s)) q(s) \Delta s(g_{0} - \epsilon) \right]^{-1} \right\} \leq \lambda,$$

and

$$A \le \min\left\{ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))p(s)\Delta s(f_\infty + \epsilon) \right]^{-1} \\ \left[ \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(s))q(s)\Delta s(g_\infty + \epsilon) \right]^{-1} \right\}.$$

Let T be the cone preserving, completely continuous operator that was defined by (3.2).

From the definitions of  $f_0$  and  $g_0$ , there exists  $H_3 > 0$  such that

$$f(x) \ge (f_0 - \epsilon)x$$
 and  $g(x) \ge (g_0 - \epsilon)x$ ,  $0 < x \le H_3$ .

Also, from the definition of  $g_0$  it follows that g(0) = 0 and so there exists  $0 < H_3 < \overline{H}_3$  such that

$$\lambda g(x) \le \frac{\overline{H}_3}{\frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma(b)} (\sigma^2(b) - \sigma(r)) q(r) \Delta r}, \quad 0 \le x \le H_3.$$

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Choose  $u \in \mathcal{P}$  with  $||u|| = H_3$ . Then

$$\begin{split} \lambda \int_{a}^{\sigma(b)} G(\sigma(s), r)q(r)g(u(\sigma(r)))\Delta r \\ &\leq \lambda \frac{\beta + \alpha(t-a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r \\ &\leq \lambda \frac{\beta + \alpha(\sigma^{2}(b) - a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r \\ &\leq \frac{\frac{\beta + \alpha(\sigma^{2}(b) - a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)\overline{H}_{3}\Delta r}{\frac{\beta + \alpha(\sigma^{2}(b) - a)}{d} \int_{a}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))q(s)\Delta s} \\ &\leq \overline{H}_{3}. \end{split}$$

 $N_{\mathrm{otes}}$ 

Then, by 
$$(2.7)$$

$$\begin{split} Tu(\eta) &\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s) \\ &\qquad f\left(\lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r\right)\Delta s \\ &\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s) \\ &\qquad (f_{0} - \epsilon)\lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r\Delta s \\ &\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s) \\ &\qquad (f_{0} - \epsilon)\lambda\gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(r))q(r)(g_{0} - \epsilon))||u||\Delta r\Delta s \\ &\geq \lambda \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)(f_{0} - \epsilon)||u||\Delta s \\ &\geq \lambda\gamma \frac{\beta + \alpha(\eta - a)}{d} \int_{\eta}^{\sigma(b)} (\sigma^{2}(b) - \sigma(s))p(s)(f_{0} - \epsilon)||u||\Delta s \\ &\geq \|u\|. \end{split}$$

So,  $||Tu|| \ge ||u||$ . If we put

$$\Omega_3 = \{ x \in \mathcal{B} : \|x\| < H_3 \},\$$

then

$$||Tu|| \ge ||u||, \text{ for } u \in \mathcal{P} \cap \partial\Omega_3.$$
 (3.6)

Next, by definitions of  $f_{\infty}$  and  $g_{\infty}$ , there exists  $\overline{H}_4$  such that

 $f(x) \le (f_{\infty} + \epsilon)x$  and  $g(x) \le (g_{\infty} + \epsilon)x$ ,  $x \ge \overline{H}_4$ 

Clearly, since  $g_{\infty}$  is assumed to be a positive real number, it follows that g is unbounded at  $\infty$ , and so, there exists  $\widetilde{H}_4 > \max\{2H_3, \overline{H}_4\}$  such that  $g(x) \leq g(\widetilde{H}_4)$ , for  $0 < x \leq \widetilde{H}_4$ .

Set

$$f^*(t) = \sup_{a \le s \le t} f(s), \quad g^*(t) = \sup_{a \le s \le t} g(s), \text{ for } t \ge 0.$$

Clearly  $f^*$  and  $g^*$  are nondecreasing real valued functions for which it holds

$$\lim_{x \to \infty} \frac{f_i^*(x)}{x} = f_{\infty}, \quad \lim_{x \to \infty} \frac{g_i^*(x)}{x} = g_{\infty}.$$

Hence, there exists  $H_4$  such that  $f^*(x) \leq f^*(H_4), g^*(x) \leq g^*(H_4)$ , for  $0 < x \leq H_4$ .

Choosing  $u \in \mathcal{P}$  with  $||u|| = H_4$ , we have

$$\begin{split} Tu(t) &\leq \lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))q(r)g(u(\sigma(r)))\Delta r\right)\Delta s \\ &\leq \lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))q(r)g^*(u(\sigma(r)))\Delta r\right)\Delta s \\ &\leq \lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))q(r)g^*(H_4)\Delta r\right)\Delta s \\ &\leq \lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(r))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^{\sigma^{(b)}} (\sigma^2(b) - \sigma(s))p(s) \\ &\qquad f^* \left(\lambda \frac{\beta + \alpha(\sigma$$

$$\leq \lambda \frac{\beta + \alpha(\sigma^2(b) - a)}{d} \int_a^\sigma (\sigma^2(b) - \sigma(s)) p(s)(f_\infty + \epsilon) H_4 \Delta s$$
  
$$\leq H_4$$
  
$$= \|u\|,$$

and so  $||Tu|| \leq ||u||$ . For this case, if we let

$$\Omega_4 = \{ x \in \mathcal{B} : ||x|| < H_4 \},\$$

then

Notes

$$||Tu|| \le ||u||, \text{ for } u \in \mathcal{P} \cap \partial\Omega_4.$$
 (3.7)

Application of part (*ii*) of Theorem 2.5 yields a fixed point u of T belonging to  $\mathcal{P} \cap (\overline{\Omega}_4 \setminus \Omega_3)$ , which in turn yields a pair (u, v) satisfying (1.1), (1.2) for the chosen value of  $\lambda$ . The proof is complete.

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## Application of Laplace Transform

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*Abstract* - The present discounted value equation in finance has a broad range of uses and may be applied to various areas of finance including corporate finance, banking finance and investment finance etc. The basic premise of present discounted value is the time value money .Not many analytic solutions exist for present discounted value problems but by using Laplace transform we can deduce some of the closed form solutions quite easily. In this note we show how present discounted value in finance related to Laplace transforms. Also we discus on the present value rules for the elementary functions and the general properties of the Laplace transform. And we will focus on the application of time derivative property using Laplace transforms to each present value rule.

*Keywords : Present discounted value, cash flow, perpetuity, Time derivative, Laplace transform. GJSFR-F Classification : MSC 2010: 44A10* 

## APPLICATION OF LAPLACE TRANSFORM

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## Notes

## Application of Laplace Transform

Dr. N. A. Patil<sup>a</sup> & Vijaya N. Patil<sup>a</sup>

*Abstract* - The present discounted value equation in finance has a broad range of uses and may be applied to various areas of finance including corporate finance, banking finance and investment finance etc. The basic premise of present discounted value is the time value money .Not many analytic solutions exist for present discounted value problems but by using Laplace transform we can deduce some of the closed form solutions quite easily. In this note we show how present discounted value in finance related to Laplace transforms. Also we discus on the present value rules for the elementary functions and the general properties of the Laplace transform. And we will focus on the application of time derivative property using Laplace transforms to each present value rule.

Keywords : Present discounted value, cash flow, perpetuity, Time derivative, Laplace transform.

#### I. INTRODUCTION

During the past few decades, methods based on integral transforms, in particular, the Laplace transforms, are being increasingly employed in mathematics, physics, mechanics and other engineering sciences. Laplace transforms have a wide variety of applications in the solution of differential, integral and difference equations. It is much less used in financial engineering. One reason is technical: not many people know that all that they need to do is to make simple calculations in the Laplace domain.

The outline of this note is as follows –

In section 1 we show the relation between present discounted value and Laplace transforms.

In section 2 we identified the present value rules for each of the cash flow.

In section 3 we discussed the general properties of Laplace transforms with present value rules.

In section 4 we show the application of time derivative property to each of the present value rules.

#### II. Relation Between Present Value and Laplace Transform

The Present value of a series of payments given by,

$$\left(PV\right)_{t} = \sum_{t=1}^{T} \frac{C(t)}{\left(1+r\right)^{t}}$$
(1)

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Where,  $(PV)_t = Present$  discounted value at time t

C(t) = Cash flowr = rate of discount

t = Period

Here we assume the Present value with continuous compounding .It is the current value of a stream of cash flows. In other words, it is the amount that we would be willing to pay today in order to receive a cash flow or a series of them in the future. Now by using an exponential series we can write equation (1) as,

$$\left(PV\right)_{t} = \sum_{t=1}^{T} e^{-rt} C(t)$$
<sup>(2)</sup>

In the limiting case replacing summation to an integral, equation (2) can be written as

$$\left(PV\right)_{\mathbf{r}} = \int_{0}^{T} e^{-rt} C(t) dt$$
(3)

Again here T is some finite quantity. So if we consider as  $T \to \infty$ , equation (3) will becomes

$$\left(PV\right)_{r} = \int_{0}^{\infty} e^{-rt} C(t) dt$$
(4)

This equation is the exact replica of Laplace transform in mathematics.

$$(PV)_{r} = L[C(t)]$$
<sup>(5)</sup>

Therefore,

#### III. LAPLACE TRANSFORMS AND PRESENT VALUE RULES FOR SOME CASH FLOWS

Using Present value equation: Consider the case of constant cash payment K made at the end of each year at interest rate r as shown in the following time line,

Here the cash flow is continuous forever Therefore the Present value is given by an infinite geometric series:

Dividing both sides by (1+r) we get,

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Subtracting equation (7) from (6) we get,

$$PV - \frac{PV}{1+r} = \frac{K}{1+r}$$

On solving we get the Present value of perpetuity.

Using Laplace transform equation: If the cash flow is constant say K then the Present discounted value of a stream at interest rate r is given by,

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$$L[K] = K \int_{0}^{\infty} e^{-rt} dt = \frac{K}{r}$$

This is the same formula as above.

For example: An insurance company has just launched a security that will pay Rs.200 indefinitely, starting the first payment next year. How much should this security be worth today if the appropriate return is 10%? We solve this example by using the time line,

$$PV = \frac{K}{r} = \frac{200}{0.10} = Rs.2000$$

Using Present value equation: Consider the payments in perpetuity increases at a certain growth rate g as shown on the time line:

The Present value of a growing perpetuity can be written as the following infinite series-

Multiplying both sides by  $\frac{(1+g)}{(1+r)}$ . Hence we get,

$$PV\frac{(1+g)}{(1+r)} = \frac{K(1+g)}{(1+r)^2} + \frac{K(1+g)^2}{(1+r)^3} + \frac{K(1+g)^3}{(1+r)^4} - \dots - \dots$$
(9)

Subtracting equation (9) from (8) we get,

$$PV - \frac{PV(1+g)}{1+r} = \frac{K}{1+r}$$

On solving we get the Present value of a growing perpetuity.

Using Laplace transform equation: For an exponential or geometric cash flow the Present discounted value of a stream growing at rate g, is given by:

$$L[C(t)] = K L[e^{g t}] = \frac{K}{r-g} \quad if \ r > g \tag{10}$$

This is the geometric growth stream or Present value of growing perpetuity having cash flow after the first period divided by the difference between the discount rate and the growth rate and the growth rate must be less than the interest rate.

For example: A company is expected to pay Rs.2 of dividend per share that wills increases 5% forever. If investors require 10% return on the company's stocks, how much should investors pay for the stocks? The cash flows are as follows:

$$PVG = \frac{K}{r-g} = \frac{2}{0.10 - 0.05} = Rs.40$$
(11)

For an arithmetic cash flow the Present discounted value of a stream at rate r, is given by:

$$L[C(t)] = \mathbf{K} L[t] = \frac{K}{r^2}$$
(12)

This shows that an arithmetic growth stream is equivalent to receiving one consol per period in perpetuity. This rule is widely used in finance for solving Preset value.

The above rules are commonly used transforms but more useful are the general properties of the Laplace transforms in an algebraic fashion .Let us look at some of the main properties.

Property 1: Linearity: The Laplace Transform is a linear operator. Hence if the Laplace Transforms of the cash flows f(t) and g(t) both exists then we have for any arbitrary constants (a,b) that:

$$L\left\{a f(t) + b g(t)\right\} = a L\left\{f(t)\right\} + b L\left\{g(t)\right\}$$
(13)

This property allows us to deduce more complex transforms to simple transforms. Property 2: Geometric scaling:

$$L\left\{e^{\alpha t}c(t)\right\} = V(r-\alpha) \quad \text{for } \alpha < r \tag{14}$$

This property shows that the scaling a cash flow by geometric term is equivalent to corresponding reduction in the rate of discount. Property 3: Multiplication by t:

 $L\left\{t C(t)\right\} = -V'(r) \tag{15}$ 

We can confirm this property by using the derivative of exponential function. Property 4: Time shifting:

$$\left. \begin{array}{l} L\left\{ C(a+bt) \right\} \text{ for } t \ge a/b \\ 0 \quad \text{ for } t < a/b \end{array} \right\} = e^{r a/b} \left(\frac{1}{b}\right) P(r/b)$$
(16)

This property applies the change of variable theorem of integral calculus and helpful for finding cash flows with altered time schedules.

Property 5: Time derivative:

$$L\{C'(t)\} = r L\{C(t)\} - C(0)$$
(17)

This property identifies a fundamental linear relationship between Laplace transform for cash flows and their time derivatives. For the confirmation we use integration by parts:

Notes

$$\int u dv = uv - \int v du$$

When we evaluate the integral over relevant range 0 to  $\infty$  for the Laplace transform and impose a standard assumption in present value problems that the marginal present value of the cash flow vanishes as t gets large.

All present value rules of section second can be derived from this time derivative property of Laplace transform and hence having particular significance in finance. For the confirmation we rewrite the time-derivative property by using notation

$$(PV)_{r} = L[C(t)], \text{ as:}$$
$$L[C(t)] = \frac{C(0)}{r} + \frac{L[C'(t)]}{r}$$
(18)

Apply the property, for some cash flows.

Ex: For S (t) =K  $\Rightarrow$  S (0) =K & S'(t) =0, we get the consol rule by using property 5. Alternatively, each asset is valued as if its cash flow were projected at a constant level equal to the current rate plus the present value of the time derivative of the cash flow.

For geometric cash flow (2.I)

$$S(t) = e^{\alpha t} \Rightarrow S(0) = 1 \& S'(t) = \alpha e^{\alpha t}, \text{ we get}$$
$$L[e^{\alpha t}] = \frac{1}{\theta} + \frac{\alpha L\left[e^{\alpha t}\right]}{\theta}$$
(19)

Alternatively, we could combine the consol rule with property 2 to establish the rule for geometric growth.

Similarly we can derive the rule for arithmetic growth by using equation (19) or combining the consol rule and property 3.

#### IV. CONCLUSION

In this article we have presented the close relationship between present discounted value in finance and Laplace transform. We can solve the present discounted value examples within a few minutes by using Laplace equation method. The result seems to be new & to have a potential to increase the practical utility of Laplace transform especially in finance. However it is important to notice that frequency domain is possible appreciate also in the real world & applied in the areas like economics or finance. But the Laplace transform is the big source for present discounted value function to illustrate the enhanced problems.

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# Formation of a Summation Formula Enmeshed with Hypergeometric Function

By Salahuddin

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*Abstract* - The main aim of the present paper is to form a summation formula attached with contiguous relation and recurrence relation.

Keywords : Gaussian Hypergeometric function , Contiguous function, Recurrence relation, Bailey summation theorem and Legendre duplication formula.

GJSFR-F Classification : MSC 2010: 65B10, 33D60

## FORMATION OF A SUMMATION FORMULA ENMESHED WITH HYPERGEOMETRIC FUNCTION

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# Formation of a Summation Formula Enmeshed with Hypergeometric Function

#### Salahuddin

Abstract - The main aim of the present paper is to form a summation formula attached with contiguous relation and recurrence relation.

*Keywords* : Gaussian Hypergeometric function , Contiguous function, Recurrence relation, Bailey summation theorem and Legendre duplication formula.

I. INTRODUCTION

#### Generalized Gaussian hypergeometric function of one variable is defined by

$${}_{A}F_{B}\left[\begin{array}{cc}a_{1},a_{2},\cdots,a_{A} ;\\ b_{1},b_{2},\cdots,b_{B} ;\end{array}\right] = \sum_{k=0}^{\infty} \frac{(a_{1})_{k}(a_{2})_{k}\cdots(a_{A})_{k}z^{k}}{(b_{1})_{k}(b_{2})_{k}\cdots(b_{B})_{k}k!}$$

or

$${}_{A}F_{B}\begin{bmatrix} (a_{A}) & ; \\ & & z \\ (b_{B}) & ; \end{bmatrix} \equiv {}_{A}F_{B}\begin{bmatrix} (a_{j})_{j=1}^{A} & ; \\ & & z \\ (b_{j})_{j=1}^{B} & ; \end{bmatrix} = \sum_{k=0}^{\infty} \frac{((a_{A}))_{k}z^{k}}{((b_{B}))_{k}k!}$$
(1)

where the parameters  $b_1, b_2, \dots, b_B$  are neither zero nor negative integers and A, B are non-negative integers.

Contiguous Relation[E. D. p.51(10), Andrews p.363(9.16)] is defined as follows

$$(a-b) {}_{2}F_{1} \begin{bmatrix} a, b; \\ c; \end{bmatrix} = a {}_{2}F_{1} \begin{bmatrix} a+1, b; \\ c; \end{bmatrix} = b {}_{2}F_{1} \begin{bmatrix} a, b+1; \\ c; \end{bmatrix}$$
(2)

Recurrence relation of gamma function is defined as follows

$$\Gamma(z+1) = z \ \Gamma(z) \tag{3}$$

Legendre duplication formula [Bells & Wong p.26(2.3.1)] is defined as follows

$$\sqrt{\pi} \ \Gamma(2z) = 2^{(2z-1)} \ \Gamma(z) \ \Gamma\left(z + \frac{1}{2}\right)$$
(4)

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$$\Gamma\left(\frac{1}{2}\right) = \sqrt{\pi} = \frac{2^{(b-1)} \Gamma\left(\frac{b}{2}\right) \Gamma\left(\frac{b+1}{2}\right)}{\Gamma(b)} \tag{5}$$

$$=\frac{2^{(a-1)} \Gamma(\frac{a}{2}) \Gamma(\frac{a+1}{2})}{\Gamma(a)} \tag{6}$$

Bailey summation theorem [Prud, p.491(7.3.7.8)] is defined as follows

$${}_{2}F_{1}\begin{bmatrix} a, 1-a & ; \\ c & ; \end{bmatrix} = \frac{\Gamma(\frac{c}{2}) \ \Gamma(\frac{c+1}{2})}{\Gamma(\frac{c+1}{2}) \ \Gamma(\frac{c+1-a}{2})} = \frac{\sqrt{\pi} \ \Gamma(c)}{2^{c-1} \ \Gamma(\frac{c+a}{2}) \ \Gamma(\frac{c+1-a}{2})}$$
(7)

II. MAIN RESULT OF SUMMATION FORMULA

$$\label{eq:relation} \begin{split} _2F_1\left[\begin{array}{c}a \ , \ -a-48 \ ; \ \frac{1}{2}\right] \\ &= \frac{\sqrt{\pi}\ \Gamma(c)}{2^{c+48}}\left[\frac{-3638347904750543085030062414561280000a}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{4230534459144635193233439012777984000a^2}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{4230534459144635193233439012777984000a^2}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-1773530111269024379361184888978329600a^3}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-26072127788223783027931526767525632a^5 - 140082855115327355120120725082688a^6}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-26072127788223783027931526767525632a^5 - 140082855115327355120120725082688a^6}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-249488180140450905945277350672a^9 + 1896611354738752958221477012a^{10}}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-221961189928545392626392a^{13} - 4488938418788950118258a^{14}}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{26237742565110055980a^{15} + 1726308193141046911a^{16} + 16724033867495328a^{17}}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{-67838656895768a^{18} - 2424088437540a^{19} - 16239228929a^{20} - 12952632a^{21} + 295702a^{22}}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ &+ \frac{1140a^{23} + a^{24} + 3638347904750568937046801299537920000c}{\Gamma(\frac{c-a+1}{2})\ \Gamma(\frac{c+a+48}{2})} + \\ \end{array}$$

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$+\frac{3425646083934616768512a^{10}c^7 - 50038536300856097280a^{11}c^7 - 974138332318255104a^{12}c^7 + 97616a^{12}c^7 + 9$	
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$+\frac{-2184451291486464a^{13}c^{7}+45506452992000a^{14}c^{7}+291087413760a^{15}c^{7}+283345920a^{16}c^{7}}{\Gamma(c^{-a+1})\Gamma(c^{+a+48})}+$	
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$+ \frac{\Gamma(c-a+1)}{\Gamma(\frac{c-a+1}{2})} \frac{\Gamma(\frac{c-a+48}{2})}{\Gamma(\frac{c-a+2}{2})} + \frac{\Gamma(c-a+1)}{\Gamma(\frac{c-a+2}{2})} \Gamma(\frac{c-a+28}{2})$	
$37986129070713604063172198400a^5c^8 + 389769280200184576457945088a^6c^8$	
$+ \frac{\Gamma(\frac{c-a+1}{2}) \Gamma(\frac{c+a+48}{2})}{\Gamma(\frac{c+a+48}{2})} +$	

$$+ \frac{-31372314252824265838755840a^7c^6 - 411109175500644611480064a^8c^8}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{9366308406942489722880a^9c^8 + 187215352352351810114316a^{10}c^8 - 146424613495493020a^{11}c^8}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} \Gamma(\frac{c-g+1}{2})} + \frac{+263608406942489722880a^9c^8 + 123540894597120a^{13}c^8 + 173781104640a^{14}c^8}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+2503987200a^{15}c^8 + 3294720a^4b^c^8 + 662317910051181926669156716904448c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+24540011579607153295876545141640c^9 + 28153238255209821490041472417792a^2c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+24540011579607153295876545141640c^9 + 28153238255209821490041472417792a^2c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+264545276012502462741086208a^3c^9 - 42641895620379018617550274560a^4c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+61235197372524416472088570a^5c^9 + 39662648103197518265810944a^6c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+61235197372524416472088570a^5c^9 - 39662648103197518265810944a^6c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+6074374451907338804193681997824c^{10} - 12573345020a^{14}c^9 + 24692042573406208a^{11}c^9}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+6074374451907338804193681997824c^{10} - 18518348550706651821965710458880ac^{10}}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+6531008891784526824937372828352a^2c^{10} - 21740721608271376090456843776a^3c^{10}}{\Gamma(\frac{c-g+1}{2})\Gamma(\frac{c-g+1}{2})} + \frac{+6008133294619037943037296644c^{10} + 4280261880435796873871360a^5c^{10}}{\Gamma(\frac{c-g+1}{2})} + \frac{+20582519609430501472a^6c^{10} - 227533252a^5c^{10} - 21740721608271376090456843776a^5c^{10}}{\Gamma(\frac{c-g+1}{2})} + \frac{+20582519509603424633946112c^{11} - 1133943949129335145013892087808ac^{11}}{\Gamma(\frac{c-g+1}{2})}) + \frac{+26858259609430500472a^6a^{10} - 2275393266568713360a^9c^{10} + 83354346743635968a^{11}c^{10}}{\Gamma(\frac{c-g+1}{2})})\Gamma(\frac{c-g+1}{2})} + \frac{+66743744451967335246633920a^6c^{10} - 124638918560435796873871360a^5c^{10}}{\Gamma(\frac{c-g+1}{2})})\Gamma(\frac{c-g+1}{2})} + \frac{+667437444519673358246633920a^6c^{10}}{\Gamma(\frac{c-g+1}{2})})\Gamma(\frac{c-g+1}{2})} + \frac{+6674542545784a^{11}c^{10} - 22009818$$



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$$\begin{split} + & \frac{-90493747200a^{9}c^{14} - 190513152a^{10}c^{14} + 20067778097297440376881152c^{15}}{\Gamma(\frac{c=\pm1}{2})} \Gamma(\frac{c\pm\pm8}{2}) \\ + & \frac{-2063368899940734008997248aa^{15} + 23616227634398246207488a^{2}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-102213608275968a^{6}c^{15} + 31611720302592a^{7}c^{15} + 91954348032a^{8}c^{15} - 127008768a^{9}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-102213608275968a^{6}c^{15} + 31611720302592a^{7}c^{15} + 91954348032a^{8}c^{15} - 127008768a^{9}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-102213608275968a^{6}c^{15} + 31611720302592a^{7}c^{15} + 91954348032a^{8}c^{15} - 127008768a^{9}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-102213608275968a^{6}c^{15} + 31611720302592a^{7}c^{15} + 91954348032a^{8}c^{15} - 127008768a^{9}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-102213608275968a^{6}c^{15} + 31611720302592a^{7}c^{15} + 91954348032a^{8}c^{15} - 127008768a^{9}c^{15}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-4728686302986240a^{5}c^{15} - 14549489418240a^{6}c^{16} + 120658329600a^{7}c^{16} + 317521920a^{8}c^{16}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-4728686302986240a^{5}c^{15} - 14549489418240a^{6}c^{16} + 120658329600a^{7}c^{16} + 317521920a^{8}c^{16}}{\Gamma(\frac{c=\pm1}{2})} \Gamma(\frac{c\pm\pm8}{2}) \\ + & \frac{-4728686302986240a^{5}c^{15} - 14549489418240a^{6}c^{16} + 120658329600a^{7}c^{16} + 317521920a^{8}c^{16}}{\Gamma(\frac{c=\pm1}{2})} \Gamma(\frac{c\pm\pm8}{2}) \\ + & \frac{-2697012025875234816a^{2}c^{17} + 340925659342700544a^{3}c^{17} + 1206869439283200a^{4}c^{17}}{\Gamma(\frac{c=\pm1}{2})} \Gamma(\frac{c\pm\pm8}{2}) \\ + & \frac{-2697012025875234816a^{2}c^{17} + 340925659342700544a^{3}c^{17} + 149422080a^{7}c^{47}}{\Gamma(\frac{c=\pm1}{2})} + \\ + & \frac{-2697012025875234816a^{2}c^{17} + 212376683320a^{6}c^{17} + 149422080a^{7}c^{47}}{\Gamma(\frac{c=\pm1}{2})} \\ + & \frac{259068608527627976704c^{18} - 1024506164252847680a^{18} - 86103626336960512a^{2}c^{18}}{\Gamma(\frac{c=\pm1}{2})} \Gamma(\frac{c\pm\pm4}{2}) \\ + & \frac{289500352849920a^{3}c^{18} + 16701453762560a^{4}c^{18} - 9305668320a^{6}c^{18} - 348651520a^{6}c^{18}}{\Gamma(\frac{c=\pm1}{2})} \\ + & \frac{289500352849920a^{3}c^{18} + 16701453762560a^{4}c^{18} - 9305668320a^{6}c^{18} - 348651520a^{6}c^{18}}{\Gamma(\frac{c=\pm1}{2})} \\ + & \frac{396305513145292c^{2}}$$

















Derivation of result (8):

Substituting  $b = -a - 48, z = \frac{1}{2}$  in given result (2), we get

$$(2a+48) {}_{2}F_{1} \begin{bmatrix} a & , & -a-48 & ; \\ c & & ; \\ \end{bmatrix}$$

$$= a {}_{2}F_{1} \begin{bmatrix} a+1 & , & -a-48 & ; & \\ c & & & ; \\ c & & & ; \\ \end{bmatrix} + (a+48) {}_{2}F_{1} \begin{bmatrix} a & , & -a-47 & ; \\ c & & & ; \\ \end{bmatrix}$$

Now applying same parallel method which is used in Ref[6], we can prove the main formula.

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### Orbit - Orbit Resonance of Pluto and Neptune

By M. A. Sharaf & L. A. Alaqal

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*Abstract* - In the present paper, an algorithm for the planar restricted circular threebody problem in rotating symbolic system is developed to determine orbit-orbit resonance of Pluto and Neptune.

*Keywords* : Celestial Mechanics-Planetary close encounters-Pluto- Neptune- solar system dynamics

GJSFR-F Classification : MSC 2010: 70M20

### ORBIT -DRBIT RESONANCE OF PLUTO AND NEPTUNE

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# Orbit - Orbit Resonance of Pluto and Neptune

M. A. Sharaf<sup> a</sup> & L. A. Alaqal<sup> o</sup>

*Abstract* - In the present paper, an algorithm for the planar restricted circular threebody problem in rotating symbolic system is developed to determine orbit-orbit resonance of Pluto and Neptune. *Keywords : Celestial Mechanics-Planetary close encounters-Pluto- Neptune- solar system dynamics* 

#### I. INTRODUCTION

Because of Pluto is locked into a 3:2 resonance with Neptune, Pluto completes 2 orbits every 3 orbits of the Sun completed by Neptune. Although, the ratio is not exactly 3:2, sometimes Pluto's period is slightly faster than its average value or slower. It is the possibility to indefinitely close approach if the perihelion and nod of Pluto are unrestricted, where, the radius of perihelion of Pluto is less than the radius of Neptune's orbit. This is the most important case of orbit - orbit resonance in the solar system. It is well known that the orbit of Pluto has a large eccentricity of e = 0.247, which brings the planet at a certain moment inside the orbit of Neptune. The two planets are trapped in an orbitorbit resonance. The period of Pluto is 3:2 times the period of Neptune.

#### II. Equations of Motion

We consider the planar restricted circular three-body problem in rotating synodic system (e.g. Szebehely 1967) in which the two primaries are the Sun and Neptune while the third body is Pluto. The equations of motion to be solved are

$$\dot{\mathbf{x}} = \mathbf{u}, \tag{1.1}$$

$$\dot{\mathbf{y}} = \mathbf{v} \,, \tag{1.2}$$

$$\dot{u} = -(1-\mu)\frac{x-\mu}{R_1^3} - \mu\frac{x+1-\mu}{R_2^3} + x + 2v, \qquad (1.3)$$

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$$\dot{\mathbf{v}} = -(1-\mu)\frac{\mathbf{y}}{\mathbf{R}_1^3} - \mu \frac{\mathbf{y}}{\mathbf{R}_2^3} + \mathbf{y} + 2\mathbf{u},$$
 (1.4)

with

$$R_1 = \sqrt{(x - \mu)^2 + y^2}$$
(2.1)

and

$$R_2 = \sqrt{(x+1-\mu)^2 + y^2} , \qquad (2.2)$$

Notes

where dot denotes differentiation with respect to the time t, (x, y) are the coordinates of the third body ,  $\mu$  denotes the mass of the smaller primary when the total mass of the primaries has been normalized to unity.

In these equations, the unit of length is the distance between the primaries, the unit of mass is the sum of the masses of the primaries. The unit of time is 1/n. (n is the mean motion).Normally, n is expressed in a number of radians per second, hence in 1/sec. Its inverse 1/n is therefore expressed in seconds and may be interpreted as a unit of time.

#### III. Orbit Determination of Pluto and Neptune

All the numerical values of the following are taken from the reference (Hellings,1994) *a)* Orbital elements

Neptune:

$$e = 0$$
  
P = 165.62  
a = 30.1584

**Pluto:** 

$$e = 0.247$$
  
 $P = 248.43$   
 $a = 39.5187$ 

and µ: 0.0000525

Amplitude of the libration is known to  $be 38^{\circ}$ .

b) Initial conditions

The Initial conditions are

 $x_0 = -0.6073955952; y_0 = -0.7774968265; u_0 = 0.1083342234; v_0 = -0.0863997159.$ 

#### c) The results

It should be noted that ,all the computations are performed using *Mathematica* **7**. For clear illustrations of our analysis, the results are displayed graphically in the following manner











#### IV. Conclusion

In this paper, general computational algorithm for the planar restricted circular threebody problem in rotating synodic system is developed in Section 2. This algorithm is applied to determinate orbit-orbit resonance of Pluto and Neptune. Finally the results are illustrate graphically in Section 3 which could be summarized as :

**1**-Figure 1 shows the basic part of the orbit of Pluto relative to the Sun and Neptune. This part represents two revolutions of Pluto around the Sun.

2- Pluto reaches two times a distance closer to the sun than Neptune.

**3**-The next two revolutions have the same shape, but the figure is rotated a little bit counter clockwise as the two perihelia approach the y- axis. This phenomenon increases until the whole figure is rotated over  $76^{\circ}$ .

**4-** A total libration, shown in Fig. 5, illustrates that Pluto will never collide with Neptune since its distance to Neptune is always larger than about 17 A.U.

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### Notes



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## New Representations in Terms of q-product Identities for Ramanujan's Results IV

By M.P. Chaudhary, Upendra Kumar Pandit & Ashish Arora

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*Abstract* - In this paper author has established seven q-product identities, which are presumably new, and not available in the literature.

Keywords : Theta functions, functions, triple product identities.

GJSFR-F Classification : AMS Subject Classifications: Primary 05A17, 05A15; Secondary 11P83

### NEW REPRESENTATIONS IN TERMS OF Q-PRODUCT IDENTITIES FOR RAMANUJANS RESULTS IN

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### New Representations in Terms of q-product Identities for Ramanujan's Results IV

M.P. Chaudhary  $^{\alpha}$ , Upendra Kumar Pandit  $^{\sigma}$  & Ashish Arora  $^{\rho}$ 

Abstract - In this paper author has established seven q-product identities, which are presumably new, and not available in the literature.

Keywords : Theta functions, functions, triple product identities.

#### I. INTRODUCTION

For |q| < 1,

$$(a;q)_{\infty} = \prod_{n=0}^{\infty} (1 - aq^n)$$
(1.1)

$$(a;q)_{\infty} = \prod_{n=1}^{\infty} (1 - aq^{(n-1)})$$
(1.2)

$$(a_1, a_2, a_3, \dots, a_k; q)_{\infty} = (a_1; q)_{\infty} (a_2; q)_{\infty} (a_3; q)_{\infty} \dots (a_k; q)_{\infty}$$
(1.3)

Ramanujan has defined general theta function, as

$$f(a,b) = \sum_{-\infty}^{\infty} a^{\frac{n(n+1)}{2}} b^{\frac{n(n-1)}{2}} ; \ |ab| < 1,$$
(1.4)

Jacobi's triple product identity [9,p.35] is given, as

$$f(a,b) = (-a;ab)_{\infty}(-b;ab)_{\infty}(ab;ab)_{\infty}$$
(1.5)

Special cases of Jacobi's triple products identity are given, as

$$\Phi(q) = \sum_{n=-\infty}^{\infty} q^{n^2} = (-q; q^2)^2_{\infty} (q^2; q^2)_{\infty}$$
(1.6)

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$$\Psi(q) = \sum_{n=0}^{\infty} q^{\frac{n(n+1)}{2}} = \frac{(q^2; q^2)_{\infty}}{(q; q^2)_{\infty}}$$
(1.7)

$$f(-q) = \sum_{n=-\infty}^{\infty} (-1)^n q^{\frac{n(3n-1)}{2}} = (q;q)_{\infty}$$
(1.8)

Equation (1.8) is known as Euler's pentagonal number theorem. Euler's another well known identity is as

$$(q;q^2)_{\infty}^{-1} = (-q;q)_{\infty}$$
(1.9)

Ref.

6.

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Roger-Ramanujan identities [6, p.578] are given as

$$G(q) = \sum_{n=0}^{\infty} \frac{q^{n^2}}{(q;q)_n} = \frac{1}{(q;q^5)_{\infty}(q^4;q^5)_{\infty}} = \frac{(q^2;q^5)_{\infty}(q^3;q^5)_{\infty}(q^5;q^5)_{\infty}}{(q;q)_{\infty}}$$
(1.10)

$$H(q) = \sum_{n=0}^{\infty} \frac{q^{n(n+1)}}{(q;q)_n} = \frac{1}{(q^2;q^5)_{\infty}(q^3;q^5)_{\infty}} = \frac{(q;q^5)_{\infty}(q^4;q^5)_{\infty}(q^5;q^5)_{\infty}}{(q;q)_{\infty}}$$
(1.11)

Roger-Ramanujan function is given by

$$R(q) = q^{\frac{1}{5}} \frac{H(q)}{G(q)} = q^{\frac{1}{5}} \frac{(q; q^5)_{\infty} (q^4; q^5)_{\infty}}{(q^2; q^5)_{\infty} (q^3; q^5)_{\infty}}$$
(1.12)

Throughout this paper we use the following representations

$$(q^{a};q^{n})_{\infty}(q^{b};q^{n})_{\infty}(q^{c};q^{n})_{\infty}\cdots(q^{t};q^{n})_{\infty} = (q^{a},q^{b},q^{c}\cdots q^{t};q^{n})_{\infty}$$
(1.13)

$$(q^{a};q^{n})_{\infty}(q^{a};q^{n})_{\infty}(q^{c};q^{n})_{\infty}\cdots(q^{t};q^{n})_{\infty} = (q^{a},q^{a},q^{c}\cdots q^{t};q^{n})_{\infty}$$
(1.14)

Now we can have following q-products identities, as

$$(q^2; q^2)_{\infty} = \prod_{n=0}^{\infty} (1 - q^{2n+2})$$

$$=\prod_{n=0}^{\infty} (1-q^{2(4n)+2}) \times \prod_{n=0}^{\infty} (1-q^{2(4n+1)+2}) \times \prod_{n=0}^{\infty} (1-q^{2(4n+2)+2}) \times \prod_{n=0}^{\infty} (1-q^{2(4n+3)+2})$$
$$=\prod_{n=0}^{\infty} (1-q^{8n+2}) \times \prod_{n=0}^{\infty} (1-q^{8n+4}) \times \prod_{n=0}^{\infty} (1-q^{8n+6}) \times \prod_{n=0}^{\infty} (1-q^{8n+8})$$
$$= (q^2; q^8)_{\infty} (q^4; q^8)_{\infty} (q^6; q^8)_{\infty} (q^8; q^8)_{\infty} = (q^2, q^4, q^6, q^8; q^8)_{\infty}$$
(1.15)

$$\begin{aligned} (q^4;q^4)_{\infty} &= \prod_{n=0}^{\infty} (1-q^{4n+4}) \\ &= \prod_{n=0}^{\infty} (1-q^{4(3n)+4}) \times \prod_{n=0}^{\infty} (1-q^{4(3n+1)+4}) \times \prod_{n=0}^{\infty} (1-q^{4(3n+2)+4}) \\ &= \prod_{n=0}^{\infty} (1-q^{12n+4}) \times \prod_{n=0}^{\infty} (1-q^{12n+8}) \times \prod_{n=0}^{\infty} (1-q^{12n+12}) \\ &= (q^4;q^{12})_{\infty} (q^8;q^{12})_{\infty} (q^{12};q^{12})_{\infty} = (q^4,q^8,q^{12};q^{12})_{\infty} \qquad (1.16) \\ (q^4;q^{12})_{\infty} &= \prod_{n=0}^{\infty} (1-q^{12n+4}) = \prod_{n=0}^{\infty} (1-q^{12(5n)+4}) \times \prod_{n=0}^{\infty} (1-q^{12(5n+1)+4}) \times \\ &\times \prod_{n=0}^{\infty} (1-q^{12(5n+2)+4}) \times \prod_{n=0}^{\infty} (1-q^{12(5n+3)+4}) \times \prod_{n=0}^{\infty} (1-q^{12(5n+4)+4}) \\ &= \prod_{n=0}^{\infty} (1-q^{60n+4}) \times \prod_{n=0}^{\infty} (1-q^{60n+16}) \times \prod_{n=0}^{\infty} (1-q^{60n+28}) \times \prod_{n=0}^{\infty} (1-q^{60n+40}) \times \prod_{n=0}^{\infty} (1-q^{60n+52}) \\ &= (q^4;q^{60})_{\infty} (q^{16};q^{60})_{\infty} (q^{28};q^{60})_{\infty} (q^{40};q^{60})_{\infty} (q^{52};q^{60})_{\infty} = (q^4,q^{16},q^{28},q^{40},q^{52};q^{60})_{\infty} \end{aligned}$$

Similarly we can compute following as

$$(q^4; q^{12})_{\infty} = (q^4; q^{60})_{\infty} (q^{16}; q^{60})_{\infty} (q^{28}; q^{60})_{\infty} (q^{40}; q^{60})_{\infty} (q^{52}; q^{60})_{\infty}$$
$$= (q^4, q^{16}, q^{28}, q^{40}, q^{52}; q^{60})_{\infty}$$
(1.18)

$$(q^6; q^6)_{\infty} = (q^6; q^{24})_{\infty} (q^{12}; q^{24})_{\infty} (q^{18}; q^{24})_{\infty} (q^{24}; q^{24})_{\infty} = (q^6, q^{12}, q^{18}, q^{24}; q^{24})_{\infty}$$
(1.19)

$$(q^{6};q^{12})_{\infty} = (q^{6};q^{60})_{\infty}(q^{18};q^{60})_{\infty}(q^{30};q^{60})_{\infty}(q^{42};q^{60})_{\infty}(q^{54};q^{60})_{\infty}$$
$$= (q^{6},q^{18},q^{30},q^{42},q^{54};q^{60})_{\infty}$$
(1.20)

$$\begin{aligned} (q^8;q^8)_{\infty} &= (q^8;q^{48})_{\infty} (q^{16};q^{48})_{\infty} (q^{24};q^{48})_{\infty} (q^{32};q^{48})_{\infty} (q^{40};q^{48})_{\infty} (q^{48};q^{48})_{\infty} \\ &= (q^8,q^{16},q^{24},q^{32},q^{40},q^{48};q^{48})_{\infty} \end{aligned}$$
(1.21)

$$(q^{8};q^{12})_{\infty} = (q^{8};q^{60})_{\infty}(q^{20};q^{60})_{\infty}(q^{32};q^{60})_{\infty}(q^{44};q^{60})_{\infty}(q^{56};q^{60})_{\infty}$$
$$= (q^{8},q^{20},q^{32},q^{44},q^{56};q^{60})_{\infty}$$
(1.22)

$$(q^8; q^{16})_{\infty} = (q^8; q^{48})_{\infty} (q^{24}; q^{48})_{\infty} (q^{40}; q^{48})_{\infty} = (q^8, q^{24}, q^{40}; q^{48})_{\infty}$$
(1.23)

$$(q^{10}; q^{20})_{\infty} = (q^{10}; q^{60})_{\infty} (q^{30}; q^{60})_{\infty} (q^{50}; q^{60})_{\infty} = (q^{10}, q^{30}, q^{50}; q^{60})_{\infty}$$
(1.24)

$$(q^{12}; q^{12})_{\infty} = (q^{12}; q^{60})_{\infty} (q^{24}; q^{60})_{\infty} (q^{36}; q^{60})_{\infty} (q^{48}; q^{60})_{\infty} (q^{60}; q^{60})_{\infty}$$
  
=  $(q^{12}, q^{24}, q^{36}, q^{48}, q^{60}; q^{60})_{\infty}$  (1.25)

 $N_{\rm otes}$ 

$$(q^{16}; q^{16})_{\infty} = (q^{16}; q^{48})_{\infty} (q^{32}; q^{48})_{\infty} (q^{48}; q^{48})_{\infty} = (q^{16}, q^{32}, q^{48}; q^{48})_{\infty}$$
(1.26)

$$(q^{20}; q^{20})_{\infty} = (q^{20}; q^{60})_{\infty} (q^{40}; q^{60})_{\infty} (q^{60}; q^{60})_{\infty} = (q^{20}, q^{40}, q^{60}; q^{60})_{\infty}$$
(1.27)

The outline of this paper is as follows. In sections 2, we have recorded some well known results, those are useful to the rest of the paper. In section 3, we state and prove seven new q-product identities, which are not available in the literature of special functions.

#### II. Preliminaries

Let us recall the definition of cubic theta functions A(q), B(q) and C(q) due to Borwein et al.[4], as

$$A(q) = \sum_{m,n=-\infty}^{\infty} q^{m^2 + mn + n^2}$$
(2.1)

$$B(q) = \sum_{m,n=-\infty}^{\infty} \omega^{m-n} q^{m^2 + mn + n^2}; \quad \omega = exp\left(\frac{2\pi i}{3}\right)$$
(2.2)

$$C(q) = \sum_{m,n=-\infty}^{\infty} q^{m^2 + mn + n^2 + m + n}$$
(2.3)

Borwein et al.[4] established the following relations

$$A(q) = A(q^3) + 2qC(q^3)$$
(2.4)

$$B(q) = A(q^3) - qC(q^3)$$
(2.5)

$$C(q) = \frac{3(q^3; q^3)_{\infty}^3}{(q; q)_{\infty}}$$
(2.6)

$$A(q)A(q^{2}) = B(q)B(q^{2}) + qC(q)C(q^{2})$$
(2.7)

Entry-2, in Ramanujan's first note book [8, p.230], [10, p.356] is stated as

$$\Psi(q)\Psi(q^3) - \Psi(-q)\Psi(-q^3) = 2q\Phi(q^2)\Psi(q^{12})$$
(2.8)

Entry-4(iv), in the chapter 20 of Ramanujan's second note book [8], [9, p.359] is stated as

$$\Phi(q)\Phi(q^{27}) - \Phi(-q)\Phi(-q^{27}) = 4qf(-q^6)f(-q^{18}) + 4q^7\Psi(q^2)\Psi(q^{54})$$
(2.9)

Entry-9(i), in the chapter 20 of Ramanujan's second note book [8], [9, p.277] is stated as

$$\Psi(q^3)\Psi(q^5) - \Psi(-q^3)\Psi(-q^5) = 2q^3\Psi(q^2)\Psi(q^{30})$$
(2.10)

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Borwein, P.B. Borwein and F.G.Garvan; Some cubic modular identities of Ra-

Entry-9(iii), in the chapter 20 of Ramanujan's second note book [8], [9, p.377] is stated as

$$\Phi(q^3)\Phi(q^5) = \Phi(-q^2)\Phi(-Q^2) + 2q^2\Psi(q)\Psi(Q); \quad where \ Q = q^{15}$$
(2.11)

Entry-9(iv), in the chapter 20 of Ramanujan's second note book [8], [9, p.377] is stated as

$$\Psi(q)\Psi(q^{15}) + \Psi(-q)\Psi(-q^{15}) = 2\Psi(q^6)\Psi(q^{10})$$
(2.12)

Entry-25, in Ramanujan's note book [9, p.39] is stated as

$$\Phi(q) + \Phi(-q) = 2\Phi(q^4)$$
(2.13)

$$\Phi(q) - \Phi(-q) = 4q\Psi(q^8)$$
(2.14)

$$\Phi(q)\Phi(-q) = \Phi(-q^2) \tag{2.15}$$

#### III. MAIN RESULTS

We have establish following

Notes

$$(q^2, q^4, q^6; q^8)_{\infty} [(-q; q^2)_{\infty}^2 + (q; q^2)_{\infty}^2] = 2(-q^4; q^8)_{\infty}^2$$
(3.1)

$$(q^2, q^4, q^6, q^8; q^8)_{\infty} [(-q; q^2)_{\infty}^2 - (q; q^2)_{\infty}^2] = 4q \frac{(q^{16}, q^{32}, q^{48}; q^{48})_{\infty}}{(q^8, q^{24}, q^{40}; q^{48})_{\infty}}$$
(3.2)

$$\frac{(-q;q^2)_{\infty}^2 + (q;q^2)_{\infty}^2}{(-q;q^2)_{\infty}^2 - (q;q^2)_{\infty}^2} = \frac{(-q^4;q^8)_{\infty}^2(q^8,q^8,q^{24},q^{24},q^{40},q^{40};q^{48})_{\infty}}{2q}$$
(3.3)

$$(-q;q^2)^2_{\infty}(q;q^2)^2_{\infty}(q^2;q^2)^2_{\infty} = (q^2,q^2,q^4;q^4)_{\infty}$$
(3.4)

$$\frac{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty} - (q;q^2)_{\infty}(q^3;q^6)_{\infty}}{(-q;q^2)_{\infty} \times (-q^3;q^6)_{\infty} \times (q;q^2)_{\infty} \times (q^3;q^6)_{\infty}} = \frac{2q(-q^2;q^4)_{\infty}^2(q^4,q^8,q^{16},q^{20},q^{24};q^{24})_{\infty}}{(q^2,q^4,q^6,q^8;q^8)_{\infty}(q^6,q^{12},q^{18};q^{24})_{\infty}}$$

$$\frac{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty} - (q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}}{(-q^3;q^6)_{\infty} \times (-q^5;q^{10})_{\infty} \times (q^3;q^6)_{\infty} \times (q^5;q^{10})_{\infty}} = \frac{(q^4,q^8,q^{12};q^{12})_{\infty}}{(q^6,q^{12},q^{18},q^{24};q^{24})_{\infty}} \times$$

$$\times \frac{2q^3}{(q^2,q^6,q^{10};q^{12})_{\infty}(q^{10},q^{20},q^{30},q^{30},q^{40},q^{50};q^{60})_{\infty}}$$

$$(3.6)$$

$$\frac{[(q;q^2)_{\infty}(q^{15};q^{30})_{\infty}] + [(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty}]}{[(q;q^2)_{\infty}(q^{15};q^{30})_{\infty}][(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty}]} = \frac{(q^{12},q^{20},q^{24},q^{36},q^{40},q^{48},q^{60},q^{60};q^{60})_{\infty}}{(q^{10},q^{30},q^{30},q^{50},q^{60};q^{60})_{\infty}} \times \frac{2}{(q^2,q^4,q^6,q^8,q^8;q^8)_{\infty}(q^6,q^{18},q^{30},q^{42},q^{54};q^{60})_{\infty}}$$
(3.7)

**Proof of (3.1):** Employing equation (1.6) in equation (2.13), we have

 $(-q;q^2)^2_{\infty}(q^2;q^2)_{\infty} + (q;q^2)^2_{\infty}(q^2;q^2)_{\infty} = 2(-q^4;q^8)^2_{\infty}(q^8;q^8)_{\infty}$ 

$$\begin{aligned} (q^2;q^2)_{\infty}[(-q;q^2)^2_{\infty} + (q;q^2)^2_{\infty}] &= 2(-q^4;q^8)^2_{\infty}(q^8;q^8)_{\infty} \\ (q^2;q^8)_{\infty}(q^4;q^8)_{\infty}(q^6;q^8)_{\infty}(q^8;q^8)_{\infty}[(-q;q^2)^2_{\infty} + (q;q^2)^2_{\infty}] &= 2(-q^4;q^8)^2_{\infty}(q^8;q^8)_{\infty} \\ (q^2;q^8)_{\infty}(q^4;q^8)_{\infty}(q^6;q^8)_{\infty}[(-q;q^2)^2_{\infty} + (q;q^2)^2_{\infty}] &= 2(-q^4;q^8)^2_{\infty} \\ (q^2,q^4,q^6;q^8)_{\infty}[(-q;q^2)^2_{\infty} + (q;q^2)^2_{\infty}] &= 2(-q^4;q^8)^2_{\infty} \end{aligned}$$

which establish the result (3.1).

**Proof of (3.2):** Employing equations (1.6) and (1.7) in equation (2.14), we have

$$(-q;q^2)^2_{\infty}(q^2;q^2)_{\infty} - (q;q^2)^2_{\infty}(q^2;q^2)_{\infty} = \frac{4q(q^{16};q^{16})_{\infty}}{(q^8;q^{16})_{\infty}}$$
$$(q^2;q^2)_{\infty}[(-q;q^2)^2_{\infty} - (q;q^2)^2_{\infty}] = 4q\frac{(q^{16},q^{32},q^{48};q^{48})_{\infty}}{(q^8,q^{24},q^{40};q^{48})_{\infty}}$$
$$(q^2,q^4,q^6,q^8;q^8)_{\infty}[(-q;q^2)^2_{\infty} - (q;q^2)^2_{\infty}] = 4q\frac{(q^{16},q^{32},q^{48};q^{48})_{\infty}}{(q^8,q^{24},q^{40};q^{48})_{\infty}}$$

which establish the result (3.2).

**Proof of (3.3):** Dividing equation (3.1) by (3.2), we get equation (3.3). **Proof of (3.4):** Employing equation (1.6) in equation (2.15), we have

$$(-q;q^2)^2_{\infty}(q^2;q^2)_{\infty}(q;q^2)^2_{\infty}(q^2;q^2)_{\infty} = (q^2;q^4)^2_{\infty}(q^4;q^4)_{\infty}$$
$$(-q;q^2)^2_{\infty}(q;q^2)^2_{\infty}(q^2;q^2)^2_{\infty} = (q^2;q^4)^2_{\infty}(q^4;q^4)_{\infty}$$
$$(-q;q^2)^2_{\infty}(q;q^2)^2_{\infty}(q^2;q^2)^2_{\infty} = (q^2;q^4)_{\infty}(q^2;q^4)_{\infty}(q^4;q^4)_{\infty}$$
$$(-q;q^2)^2_{\infty}(q;q^2)^2_{\infty}(q^2;q^2)^2_{\infty} = (q^2,q^2,q^4;q^4)_{\infty}$$

which establish the result (3.4).

**Proof of (3.5):** Employing equations (1.6) and (1.7) in equation (2.8), we get.

$$\frac{(q^2;q^2)_{\infty}(q^6;q^6)_{\infty}}{(q;q^2)_{\infty}(q^3;q^6)_{\infty}} - \frac{(q^2;q^2)_{\infty}(q^6;q^6)_{\infty}}{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty}} = \frac{2q(-q^2;q^4)_{\infty}^2(q^4;q^4)_{\infty}(q^{24};q^{24})_{\infty}}{(q^{12};q^{24})_{\infty}}$$

$$\frac{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty} - (q;q^2)_{\infty}(q^3;q^6)_{\infty}}{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty}(q;q^2)_{\infty}(q^3;q^6)_{\infty}} = \frac{2q(-q^2;q^4)_{\infty}^2(q^4;q^4)_{\infty}(q^{24};q^{24})_{\infty}}{(q^{12};q^{24})_{\infty}(q^2;q^2)_{\infty}(q^6;q^6)_{\infty}}$$

$$\frac{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty} - (q;q^2)_{\infty}(q^3;q^6)_{\infty}}{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty}(q;q^2)_{\infty}(q^3;q^6)_{\infty}} = \frac{2q(-q^2;q^4)_{\infty}^2(q^4,q^8,q^{16},q^{20},q^{24};q^{24})_{\infty}}{(q^2;q^2)_{\infty}(q^6,q^{12},q^{18};q^{24})_{\infty}}$$

$$\frac{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty} - (q;q^2)_{\infty}(q^3;q^6)_{\infty}}{(-q;q^2)_{\infty}(-q^3;q^6)_{\infty}(q;q^2)_{\infty}(q^3;q^6)_{\infty}} = \frac{2q(-q^2;q^4)_{\infty}^2(q^4,q^8,q^{16},q^{20},q^{24};q^{24})_{\infty}}{(q^2;q^2)_{\infty}(q^6,q^{12},q^{18};q^{24})_{\infty}}$$

which establish the result (3.5). **Proof of (3.6):**Employing equation (1.7) in equation (2.10), we get.

$$\frac{(q^6;q^6)_{\infty}(q^{10};q^{10})_{\infty}}{(q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}} - \frac{(q^6;q^6)_{\infty}(q^{10};q^{10})_{\infty}}{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty}} = \frac{2q^3(q^4;q^4)_{\infty}(q^{60};q^{60})_{\infty}}{(q^2;q^4)_{\infty}(q^{30};q^{60})_{\infty}}$$

Notes

$$\begin{aligned} \frac{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty}-(q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}}{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty}(q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}} &= \frac{2q^3(q^4;q^4)_{\infty}(q^{60};q^{60})_{\infty}}{(q^2;q^4)_{\infty}(q^6;q^6)_{\infty}(q^{10};q^{10})_{\infty}(q^{30};q^{60})_{\infty}} \\ & \frac{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty}-(q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}}{(-q^3;q^6)_{\infty}(-q^5;q^{10})_{\infty}(q^3;q^6)_{\infty}(q^5;q^{10})_{\infty}} &= \frac{(q^4,q^8,q^{12};q^{12})_{\infty}}{(q^6,q^{12},q^{18},q^{24};q^{24})_{\infty}} \times \\ & \times \frac{2q^3}{(q^2,q^6,q^{10};q^{12})_{\infty}(q^{10},q^{20},q^{30},q^{30},q^{40},q^{50};q^{60})_{\infty}} \end{aligned}$$

which establish the result (3.6).

Notes

**Proof of (3.7):** Employing equation (1.7) in equation (2.12), we get.

$$\begin{aligned} \frac{(q^2;q^2)_{\infty}(q^{30};q^{30})_{\infty}}{(q;q^2)_{\infty}(q^{15};q^{30})_{\infty}} + \frac{(q^2;q^2)_{\infty}(q^{30};q^{30})_{\infty}}{(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty}} &= \frac{2(q^{12};q^{12})_{\infty}(q^{20};q^{20})_{\infty}}{(q^6;q^{12})_{\infty}(q^{10};q^{20})_{\infty}} \\ \frac{(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty} + (q;q^2)_{\infty}(q^{15};q^{30})_{\infty}}{(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty} + (q;q^2)_{\infty}(q^{15};q^{30})_{\infty}} &= \frac{2(q^{12};q^{12})_{\infty}(q^{20};q^{20})_{\infty}}{(q^2;q^2)_{\infty}(q^{10};q^{20})_{\infty}(q^{30};q^{30})_{\infty}} \\ \frac{(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty} + (q;q^2)_{\infty}(q^{15};q^{30})_{\infty}}{(-q;q^2)_{\infty}(-q^{15};q^{30})_{\infty}(q;q^2)_{\infty}(q^{15};q^{30})_{\infty}} &= \frac{2(q^{12},q^{20},q^{24},q^{36},q^{40},q^{48},q^{60},q^{60};q^{60})_{\infty}}{(q^2;q^2)_{\infty}(-q^{15};q^{30})_{\infty}(q;q^2)_{\infty}(q^{15};q^{30})_{\infty}} &= \frac{(q^{12},q^{20},q^{24},q^{36},q^{40},q^{48},q^{60},q^{60};q^{60})_{\infty}}{(q^{10},q^{30},q^{30},q^{50},q^{60};q^{60})_{\infty}} \times \\ &\times \frac{2}{(q^2,q^4,q^6,q^8,q^8;q^8)_{\infty}(q^6,q^{18},q^{30},q^{42},q^{54};q^{60})_{\infty}} \end{aligned}$$

which establish the result (3.7).

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### Note Oncertain Field of Fractions

### By S. Usaini & S. M. Tudunkaya

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*Abstract* - The set of some real rhotrices of the same dimension  $D^*$  was defined in [2] to be an integral domain. An example of a finite field  $M[R_3]$  was given in [4] based on this definition also and on the construction of finite fields presented in [3]. It was discovered that the finite sub collection of the elements of  $M[R_3]$  as contained in  $D^*$  is not closed under rhotrix addition and hence not an integral domain. More generally,  $D^*$  is not an integral domain as it is not closed under rhotrix addition. This problem affects the field of fractions constructed in [8]. A solution to this problem is provided in this article and the construction method of such fields is reviewed. This reviewed version gives the generalization of such construction as the n-dimensional rhotrices are used.

Keywords : n-dimensional rhotrix; Quotient rhotrix; Integral domain; Field of fraction. GJSFR-F Classification : MSC 2010: 83A05



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Ref.

### Note Oncertain Field of Fractions

S. Usaini<sup>a</sup> & S. M. Tudunkaya<sup>o</sup>

Abstract - The set of some real rhotrices of the same dimension  $D^*$  was defined in [2] to be an integral domain. An example of a finite field  $M[R_3]$  was given in [4] based on this definition also and on the construction of finite fields presented in [3]. It was discovered that the finite sub collection of the elements of  $M[R_3]$  as contained in  $D^*$  is not closed under rhotrix addition and hence not an integral domain. More generally,  $D^*$  is not an integral domain as it is not closed under rhotrix addition. This problem affects the field of fractions constructed in [8]. A solution to this problem is provided in this article and the construction method of such fields is reviewed. This reviewed version gives the generalization of such construction as the n-dimensional rhotrices are used.

Keywords : n-dimensional rhotrix; Quotient rhotrix; Integral domain; Field of fraction

#### I. INTRODUCTION

The idea of classifying the set of all rhotrices of dimension 3 as abstract structures was presented in [1] and [2].In [2] the set of some 3-dimensional real rhotrices

$$D^* = \langle (R - ZD), +, \circ \rangle \tag{1.1}$$

was defined to be an integral domain under rhotrix addition and multiplication, where R is the set of all real rhotrices of dimension 3 as defined in [6] by

$$R = \left\{ \left\langle \begin{array}{c} a \\ b & c \\ e \end{array} \right\rangle : a, b, c, d, e \in \Re \right\},$$
$$ZD = \left\{ \left\langle \begin{array}{c} a \\ b & 0 \\ e \end{array} \right\rangle : a, b, d, e, 0 \in \Re \text{ and at least one of } a, b, d, e \neq 0 \right\}.$$

Recall that an integral domain is a commutative ring with out zero divisors. However,  $D^*$  is not even a ring because the additive closure is not there. This can be seen as follows: Let  $R, Q \in D^*$  such that h(R) = c and h(Q) = -c. If R + Q = S then h(S) = 0and at least one of  $a, b, d, e \neq 0$  which implies that  $S \notin D^*$ . Global Journal of Science Frontier Research (F) Volume XII Issue XII Version I

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A method of constructing finite fields through the use of rhotrices was presented in [3]. The cardinalities of such fields were also provided. In [4] an example of a particular finite field  $M[R_3]$  whose cardinality is  $|M[R_3]| = 3^5 = 243$  was given. This field gave the clear picture of the problem in  $D^*$ .

In [1] a hearty rhotrix of dimension 3 was defined to be a rhotrix S having all its entries (except the heart) as zero. Thus, an integer hearty rhotrix of dimension 3 is of the

form  $\begin{pmatrix} 0 & c \\ 0 & c & 0 \\ 0 & - \end{pmatrix}$ ,  $c \neq 0 \in \mathbb{Z}$ . Therefore we may define the set of all integer hearty rhotrices

of the same dimension as

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$$H = \left\{ \begin{pmatrix} 0 \\ 0 & c & 0 \\ 0 & 0 \end{pmatrix} : c \neq 0 \in \mathbb{Z} \right\}$$
(1.2)

For any two base rhotrices R, S the quotient  $\frac{R}{S}$  is defined in [5] to be the quotient rhotrix as follows:

$$\frac{R}{S} = R \circ S^{-1} \text{, provided } h(S) \neq 0.$$
(1.3)

The concept of n-dimensional heart-oriented rhotrix multiplicationwas introduced in [7]. A rhotrix  $R_n$  of dimension n have  $|R_n|$  entries where  $|R_n| = \frac{1}{2}(n^2 + 1)$  as indicated in [6]. Thus any given rhotrix  $R_n$  with entries  $a_1, a_2, \ldots, a_{\frac{1}{2}(n^2+1)}$ , is generally represented as



The method of constructing field of fractions through the use of base rhotrices based on definitions (1.1) and (1.3) was presented in [8]. To take care of the problem that affects this construction as pointed out earlier; this article aims at reviewing and generalizing the construction method using definitions (1.2) and (1.3).

Ref.

#### II. A Particular Field of Fraction of an Integral Domain

#### Theorem 2.1

Let  $H_n$  be the set of all n-dimensional integer hearty rhotrices. If  $H_n^* = H_n \cup \{O_n\}$  then  $H_n^*$  is an integral domain, where  $O_n$  is an n-dimensional zero rhotrix.

#### Proof

Notes

It suffices to show that  $H_n^*$  is isomorphic to an integral domain  $\mathbb{Z}$ . That is  $H_n^* \cong \mathbb{Z}$ .

Define a mapping  $\tau : \mathbb{Z} \to H_n^*$  by  $\tau(c) = C_n$ .

For homomorphism, let  $c, d \in \mathbb{Z}$ , then

(i)  $\tau(c+d) = C_n + D_n = \tau(c) + \tau(d)$  (ii)  $\tau(cd) = C_n \circ D_n = \tau(c)\tau(d)$ 

Therefore  $\tau$  is a homomorphism

Since  $\forall \tau(c) \in H_n^*$  there exists  $c \in \mathbb{Z}$  such that  $\tau(c) = C_n$  then  $\tau$  is onto.

Now let  $\tau(c), \tau(d) \in H_n^*$  such that  $\tau(c) = \tau(d)$ .

 $\tau(c) = \tau(d) \Longrightarrow C_n = D_n \Longrightarrow c = d$ .

Thus  $\tau$  is one to one.

Hence  $H_n^* \cong \mathbb{Z}$ .

#### Definition 2.1

Let  $H_n^*$  and  $H_n$  be as in Theorem 2.1 above. Then a relation ~ on  $H_n^* \ge H_n$  defined by cross multiplication as  $(C_{n1}, D_{n1}) \sim (C_{n2}, D_{n2})$  if  $C_{n1} \circ D_{n2} = C_{n2} \circ D_{n1}$ ,  $\ni C_{n1}, C_{n2} \in H_n^*$ ;  $D_{n1}, D_{n2} \in H_n$ .

#### Proposition 2.1

The relation  $\sim$  as defined in Definition (2.1) is an equivalence relation.

#### Proof

Reflexivity and Symmetry of the relation are obvious.

For transitivity, let  $C_{n1} \circ D_{n2} = C_{n2} \circ D_{n1}$  and  $C_{n2} \circ D_{n3} = C_{n3} \circ D_{n2}$ . To show that  $C_{n1} \circ D_{n3} = C_{n3} \circ D_{n1}$  we have

$$(C_{n1} \circ D_{n3}) \circ D_{n2} = (C_{n1} \circ D_{n2}) \circ D_{n3}$$
  
=  $(C_{n2} \circ D_{n1}) \circ D_{n3}$   
=  $(C_{n2} \circ D_{n3}) \circ D_{n1}$   
=  $(C_{n3} \circ D_{n2}) \circ D_{n1}$   
=  $(C_{n3} \circ D_{n1}) \circ D_{n2}$   
 $\therefore (C_{n1} \circ D_{n3}) = (C_{n3} \circ D_{n1})$  by cancellation law.

We denote by  $\frac{C_n}{D_n}$  the equivalence class of  $(C_n, D_n)$  in  $H_n^* \ge H_n$  and define  $H_n^* [H_n^{-1}]$  to

be the set of all the equivalence classes  $\frac{C_n}{D_n}$ , where  $C_n \in H_n^*$  and  $D_n \in H_n$ .

For all  $\frac{C_{n1}}{D_{n1}}, \frac{C_{n2}}{D_{n2}} \in H_n^*[H_n^{-1}]$  we define addition and multiplication on  $H_n^*[H_n^{-1}]$  as

Notes

follows:  $\frac{C_{n1}}{D_{n1}} + \frac{C_{n2}}{D_{n2}} = \frac{C_{n1} \circ D_{n2} + C_{n2} \circ D_{n1}}{D_{n1} \circ D_{n2}}$  and  $\frac{C_{n1}}{D_{n1}} \circ \frac{C_{n2}}{D_{n2}} = \frac{C_{n1} \circ C_{n2}}{D_{n1} \circ D_{n2}}$ 

#### Proposition2.2

The operations (+'),  $(\circ')$  as defined above are well-defined.

#### Proof

Suppose  $\frac{C'_{n1}}{D'_{n1}} = \frac{C_{n1}}{D_{n1}}$  and  $\frac{C'_{n2}}{D'_{n2}} = \frac{C_{n2}}{D_{n2}}$ ; then  $C'_{n1} \circ D_{n1} = D'_{n1} \circ C_{n1}$  and  $C'_{n2} \circ D_{n2} = D'_{n2} \circ C_{n2}$ , so that  $(C'_{n1} \circ D'_{n2} + C'_{n2} \circ D'_{n1})D_{n1}D_{n2} = C'_{n1} \circ D_{n1} \circ D'_{n2} \circ D_{n2} + C'_{n2} \circ D_{n2} \circ D'_{n1} \circ D_{n1}$   $= C_{n1} \circ D'_{n1} \circ D'_{n2} \circ D_{n2} + C_{n2} \circ D'_{n2} \circ D'_{n1} \circ D_{n1}$   $= (C_{n1} \circ D_{n2} + C_{n2} \circ D_{n1})D'_{n1} \circ D'_{n2}$ implying that  $\frac{C'_{n1}}{D'_{n1}} + \frac{C'_{n2}}{D'_{n2}} = \frac{C_{n1}}{D_{n1}} + \frac{C_{n2}}{D_{n2}}$ . Similarly  $(C'_{n1} \circ C'_{n2})D_{n1} \circ D_{n2} = (C_{n1} \circ C_{n2})D'_{n1} \circ D'_{n2}$  implies that  $\frac{C'_{n1}}{D'_{n1}} \circ \frac{C'_{n2}}{D'_{n2}} = \frac{C_{n1} \circ C_{n2}}{D_{n1} \circ D_{n2}}$ . By definition (1.3) the equivalence class  $\frac{C_n}{D_n} = C_n \circ D_n^{-1}$  since  $D_n \neq 0_n \in H_n$ . Therefore, for all  $D_n \in H_n$ ,  $0_n \in H_n^*$ ,  $\frac{0_n}{D_n} = 0_n \circ D_n^{-1} = 0_n = 0_n \circ I_n = \frac{0_n}{I_n}$ . Thus  $\frac{0_n}{I_n} = \frac{0_n}{D_n}$  is the additive inverse. Similarly,  $\frac{I_n}{I_n} = \frac{D_n}{D_n}$  is the multiplicative identity.

#### Theorem 2.2

With the above definitions and the definitions of the operations (+') and  $(\circ')$ , the set of the equivalence classes  $H_n^*[H_n^{-1}]$  is a commutative ring.

#### Proof

One should check that the properties of a ring are fulfilled. But the proof follows from the fact that addition and multiplication are the regular addition and multiplication of fractions.

#### Proposition 2.3

The function  $\psi: H_n^* \to H_n^*[H_n^{-1}]$  defined by  $\psi(C_n) = \frac{C_n}{I_n}$  is a ring homomorphism whose kernel is  $\{C_n \in H_n^*: C_n \circ' D_n = 0 \text{ for some } D_n \in H_n^*[H_n^{-1}]\}$ .

#### Proof

Ref.

Mohammed (2007a). Enrichment exercises through extension to rhotrices. Int. Math. Educ. Sci. Technol.38(2007b), 131-136.

Let  $C_{n1}, C_{n2} \in H_n^*$ , then

$$\psi(C_{n1} + C_{n2}) = \frac{C_{n1} + C_{n2}}{I_n} = (C_{n1} + C_{n2}) \circ I_n = C_{n1} \circ I_n + C_{n2} \circ I_n = \frac{C_{n1}}{I_n} + \frac{C_{n2}}{I_n} = \psi(C_{n1}) + \psi(C_{n2})$$

$$\psi(C_{n1} \circ' C_{n2}) = \frac{C_{n1} \circ' C_{n2}}{I_n} = (C_{n1} \circ' C_{n2}) \circ I_n = C_{n1} \circ I_n \circ' C_{n2} \circ I_n = \frac{C_{n1}}{I_n} \circ' \frac{C_{n2}}{I_n} = \psi(C_{n1}) \circ' \psi(C_{n2})$$
$$\psi(I_n) = \frac{I_n}{I_n}.$$

Now  $C_n \in \ker \psi$  if and only if  $\frac{C_n}{I_n} = \frac{0_n}{I_n}$ , if and only if  $C_n \circ I_n = 0_n \circ I_n = 0_n$ , which imply that  $\ker \psi = \{0_n\}$ .

Recall from [1] that, the set  $M = \{nI : n \in \mathbb{Z}\}$  where I is the unity element of the commutative ring of 3-dimensional rhotrices R is a subring and submonoid of R under multiplication ( $\circ$ ). Thus the set  $M_n = \{nI_n : n \in \mathbb{Z}\}$  is a subring and submonoid of the commutative ring  $R_n^*$  of n-dimensional rhotrices. Therefore any submonoid,  $H_n$  of  $R_n^*$  with property that for all  $Q_n \neq 0 \in R_n^*$  and  $S_n \in H_n$ ,  $Q_n \circ S_n \neq 0$  can serve in the above construction for the generalization of proposition 2.3 as stated in the following proposition.

#### Proposition 2.4

 $R_n^*[H_n^{-1}]$  as constructed above is a ring, and there is a homomorphism  $\psi: R_n^* \to R_n^*[H_n^{-1}]$  given by  $\psi(Q_n) = \frac{Q_n}{I_n}$ .

#### Proof

The proof follows from propositions 2.2 and 2.3.

As defined in [1], a diagonal rhotrix of dimension 3 is a rhotrix whose two nondiagonal entries are all zero. Let D be the set of all n-dimensional diagonal rhotrices then it is easy for someone to verify that  $W = D \cup \{O_n, I_n\}$ , where  $O_n$  is the n-dimensional additive identity;  $I_n$  is the n-dimensional multiplicative identity is a group and is normal in  $R_n^*$  under multiplication.

#### Proposition 2.5

Let  $R_n^*$  be a commutative ring of n-dimensional rhotrices, and let  $H_n$  be a submonoid of  $R_n^*$  such that  $Q_n \circ S_n \neq 0_n$  for every  $Q_n \neq 0_n \in R_n^*$  and  $S_n \in H_n$ . Then every ideal of  $R_n^*[H_n^{-1}]$  has the form  $W[H_n^{-1}]$ , for suitable W normal in  $R_n^*$ .

#### Proof

Since all the elements of  $W[H_n^{-1}]$  are also elements of  $R_n^*[H_n^{-1}]$  and  $I_n \in H_n$  then obviously  $W[H_n^{-1}]$  is an additive subgroup of  $R_n^*[H_n^{-1}]$ .

For all 
$$\frac{C_n}{D_n} \in R_n^*[H_n^{-1}]$$
;  $\frac{W_n}{D'_n} \in W[H_n^{-1}]$ ;  $\frac{C_n}{D_n} \circ' \frac{W_n}{D'_n} = \frac{C_n \circ W_n}{D_n \circ D'_n} \in W[H_n^{-1}]$  since  $C_n \circ W_n \in W, D_n \circ D'_n \in H_n$ .  
*W* is normal in  $R_n^*$  implies that  $\frac{W_n}{D'_n} \circ \frac{C_n}{D_n} \in W[H_n^{-1}]$ .  
*Proposition 2.6*  
 $H_n^*[H_n^{-1}]$  is an integral domain.  
*Proof*  
Suppose  $\frac{C_{n1}}{D_{n1}} \circ' \frac{C_{n2}}{D_{n2}} = 0_n \in H_n^*[H_n^{-1}]$ , that is  $\frac{C_{n1} \circ C_{n2}}{D_{n1} \circ D_{n2}} = \frac{0_n}{I_n}$   
 $\Rightarrow (C_{n1} \circ C_{n2}, D_{n1} \circ D_{n2}) \tilde{(0_n, I_n)}$  and  $C_{n1} \circ C_{n2} \circ D_n = 0$  for some  $D_n \in H_n$ .  
 $C_{n1} \circ C_{n2} \circ D_n = 0_n \in H_n^*$ , which is an integral domain, and  $D_n \neq 0_n$ , thus  $C_{n1} \circ C_{n2} = 0_n$ .  
So either  $C_{n1}$  or  $C_{n2}$  is  $0_n$  and consequently either  $\frac{C_{n1}}{D_{n1}}$  or  $\frac{C_{n2}}{D_{n2}}$  is  $0_n$ .

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#### Theorem 2.3

The set  $H_n^*[H_n^{-1}]$  of all equivalence classes  $\frac{C_n}{D_n}$  is a field.

#### Proof

From Theorem 2.2,  $H_n^*[H_n^{-1}]$  is a commutative ring with unity  $\frac{I_n}{I_n}$ . So we just need to show that every non zero element of  $H_n^*[H_n^{-1}]$  has multiplicative inverse.

$$\begin{split} & \text{Suppose } \frac{C_n}{D_n} \neq \frac{O_n}{I_n}, \text{ then } C_n \neq O_n, \text{ so } C_n \in H_n \text{ which implies that } \frac{C_n}{D_n} \in H_n^*[H_n^{-1}]. \\ & \text{Clearly, } \frac{C_n}{D_n} \circ' \frac{D_n}{C_n} = \frac{C_n \circ D_n}{D_n \circ C_n} = \frac{I_n}{I_n} \text{ . Thus } \frac{D_n}{C_n} \text{ is the multiplicative inverse of } \frac{C_n}{D_n}. \end{split}$$

#### III. Conclusion

In this short note, amendment concerning some definitions in [2] and [8] with their generalizations were provided. The steps observed in the construction of field of fractions illustrated in [8] were also amended respectively.

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Notes



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## Bianchi Type- $VI_0$ Dark Energy Cosmological Models in General Relativity

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*Abstract* - Bianchi type-VI<sub>0</sub> cosmological models of the universe filled with dark energy with constant and time-dependent equation of state parameters are investigated in general relativity. We obtain exact solutions of Einstein's field equations using the condition that the shear scalar is proportional to the expansion scalar, which represent singular and non-singular cosmological models of the universe. The physical behavior of the models are discussed. We conclude that the universe models do not approach isotropy through the evolution of the universe.

Keywords : Bianchi type-VI. Dark energy. Cosmological models.

GJSFR-F Classification : MSC 2010: 83A05



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### R<sub>ef.</sub> Bianchi Type-Vl<sub>o</sub> Dark Energy Cosmological Models in General Relativity

Priyanka, S. Chandel, M.K. Singh & Shri Ram

*Abstract* - Bianchi type-VI<sub>0</sub> cosmological models of the universe filled with dark energy with constant and timedependent equation of state parameters are investigated in general relativity. We obtain exact solutions of Einstein's field equations using the condition that the shear scalar is proportional to the expansion scalar, which represent singular and non-singular cosmological models of the universe. The physical behavior of the models are discussed. We conclude that the universe models do not approach isotropy through the evolution of the universe.

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#### I. INTRODUCTION

Recent observations on expansion history of the universe indicate that the universe is currently experiencing a phase of accelerated expansion. This was first observed from high red shift supernova Ia (Reiss et al. [1-2], Perlmutter et al. [3], Astier et al. [4], Spergel et al.[5] etc.) and confirmed later by cross checks from the cosmic microwave background radiation (Bennett et al. [6], Abazajian et al.[7-9], Hawkins et al. [10] etc.). The current accelerating expansion of the universe attributed to the fact that our universe is dominated by an unknown dark energy DE an exotic energy with negative pressure.

The simplest dark energy candidate is the vacuum energy density which is mathematically equivalent to the cosmological constant  $\Lambda$ . As per Copeland et al. [11] "fine tuning" and the cosmic "coincidence" are the two well known difficulties of the cosmological constant problems. There are several alternative theories for the dynamical DE scenario which have been proposed by scientists to interpret the accelerating universe. Wang and Tegmark [12] have shown that the universe is actually undergoing an acceleration with repulsive gravity of some strange energy-form i.e. DE at work. Dark energy is a mysterious substance with negative pressure and accounts for nearly 70% of total matter-energy of universe, but has no clear explanation. Karami et al. [13] introduced a polytropic gas model of DE as an alternative model to explain the accelerated expansion of the universe. Gupta and Pradhan [14] proposed a new candidate known as cosmological nuclear-energy as a possible candidate for the dark energy. Year 2012

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Bianchi types I-IX cosmological models are important in the sense that these are homogeneous and anisotropic, from which the process of isotropization of the universe is studied through the passage of time. Moreover, from the theoretical point of view anisotropic universe have a greater generality than FRW isotropic models. The simplicity of the field equations made Bianchi space-times useful in constructing models of spatially homogeneous and anisotropic cosmologies. Considerable works have been done in obtaining various Bianchi type cosmological models and their inhomogeneous generalization. Bianchi type-VI<sub>0</sub> space-time is of special interest in anisotropic cosmology. Barrow [15] pointed out that Bianchi type-VI<sub>0</sub> models of the universe give a better explanation of some of the cosmological problems like primordial helium abundance and they also isotropize in a special sense. Looking to the importance of Bianchi type- $VI_0$  universes, many authors [16-20] have studied it in different context. Shri Ram[21, 22] has presented Bianchi type- $VI_0$  cosmological models filled with dust and perfect fluid in modified Brans-Dicke theory respectively.

Adhav et al. [23] studied Bianchi type-VI<sub>0</sub> cosmological models with anisotropic dark energy. Abdussattar and Prajapati [24] obtained a class of bouncing non-singular FRW models by constraining the deceleration parameter (DP) in the presence of an interacting dark energy represented by a time-varying cosmological constant. They have also discussed the role of deceleration parameter and interacting dark energy in singularity avoidance. Bisabr [25] has shown that an accelerating expansion is possible in a spatially flat universe for large values of the Brans-Dicke parameter consistent with the local gravity experiments. Yadav and Saha [26] studied DE models with variable equation of state (EoS) parameter. Recently, Saha and Yadav [27] presented a general relativistic cosmological model with time-dependent DP in LRS Bianchitype-II space-time which can be described by isotopic and variable EoS parameter. In this paper, We present general relativistic cosmological models with constant and time-dependent DP in Bianchi type-VI<sub>0</sub> space-time which can be described by isotropic constant and variable EoS parameters. This paper is organized as follows: We present the metric and field equations in Sect.2. In Sect.3, we obtain the solutions of the field equations representing Bianchi type-VI<sub>0</sub> cosmological models with perfect fluid by imposing the condition that the shear scalar is proportional to expansion scalar. We also discuss the physical behaviors of the cosmological models with dark energy. Concluding remarks are given in Sect.4.

#### II. THE METRIC AND FIELD EQUATIONS

We consider the spatially homogeneous and anisotropic Bianchi type-VI\_0 space-time in the form

$$ds^{2} = -dt^{2} + A^{2}(t)dx^{2} + B^{2}(t)e^{-2mx}dy^{2} + C^{2}(t)e^{2mx}dz^{2}$$
(1)

where A, B and C are functions of the cosmic time t and m is a constant The Einstein's field equations, in natural limits  $(8\pi G = c = 1)$  are

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -T_{\mu\nu}$$
 (2)

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where  $R_{\mu\nu}$  is the Ricci tensor, R is the Ricci scalar curvature and  $T_{\mu\nu}$  is the energy-momentum tensor of matter. For a perfect fluid distribution, the tensor  $T_{\mu\nu}$  is given by

$$T_{\mu\nu} = (\rho + p)u_{\mu}u_{\nu} + pg_{\mu\nu}$$
(3)

where  $\rho$  is the energy density of the cosmic matter p is the isotropic pressure and  $u^{\mu}$  is the four-velocity vector. In comoving coordinate system  $u^{\mu} =$ (0,0,0,1), the Einstein's field equation (2) together with (3), for the metric (1), yield

$$\frac{\ddot{B}}{B} + \frac{\ddot{C}}{C} + \frac{\dot{B}\dot{C}}{BC} + \frac{m^2}{A^2} = -\omega\rho, \qquad (4)$$

$$\frac{\ddot{A}}{A} + \frac{\ddot{C}}{C} + \frac{\dot{A}\dot{C}}{AC} - \frac{m^2}{A^2} = -\omega\rho,$$
(5)

$$\frac{\ddot{A}}{A} + \frac{\ddot{B}}{B} + \frac{\dot{A}\dot{B}}{AB} - \frac{m^2}{A^2} = -\omega\rho, \qquad (6)$$

$$\frac{\dot{A}\dot{B}}{AB} + \frac{\dot{A}\dot{C}}{AC} + \frac{\dot{B}\dot{C}}{BC} - \frac{m^2}{A^2} = \rho, \tag{7}$$

$$\left(\frac{\dot{B}}{B} - \frac{\dot{C}}{C}\right) = 0 \tag{8}$$

where  $\omega$  is the EoS parameter given by

$$p = \omega \rho \tag{9}$$

and a dot denotes ordinary differentiation with respect to t.

The average scalar factor a and volume scalar V are given by

$$a^3 = V = ABC. \tag{10}$$

The generalized mean Hubble parameter H is defined by

$$H = \frac{\dot{a}}{a} = \frac{1}{3}(H_1 + H_2 + H_3) \tag{11}$$

where the directional Hubble parameters  $H_1$ ,  $H_2$  and  $H_3$  are given by

$$H_1 = \frac{\dot{A}}{A}, H_2 = \frac{\dot{B}}{B}, H_3 = \frac{\dot{C}}{C}.$$
 (12)

The expansion scalar  $\theta$  and shear scalar  $\sigma$  are given by

$$\theta = \frac{\dot{A}}{A} + \frac{\dot{B}}{B} + \frac{\dot{C}}{C},\tag{13}$$

$$\sigma^2 = \frac{1}{2} \left[ \frac{\dot{A}^2}{A^2} + \frac{\dot{B}^2}{B^2} + \frac{\dot{C}^2}{C^2} \right] - \frac{1}{6} \theta^2.$$
(14)

The deceleration parameter q is defined by

$$q = -1 + \frac{d}{dt}(H). \tag{15}$$

Notes

The sign of q indicates whether the model inflates or not. A positive sign of q corresponds to the standard decelerating model whereas the negative sign of q indicates inflation. The recent observations of SN Ia (Reiss et al.[1], Perlmutter et al.[3]) reveal that the present universe is accelerating and the value of DP lies somewhere in the range -1 < q < 0.

#### III. SOLUTION OF FIELD EQUATIONS

Equation (8), on integration, gives

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$$B = C \tag{16}$$

where the constant of integration is absorbed in B or C. Using (16), equations (4) - (7) reduce to

$$\frac{2\ddot{B}}{B} + \frac{\dot{B}^2}{B^2} + \frac{m^2}{A^2} = -\omega\rho,$$
(17)

$$\frac{\ddot{A}}{A} + \frac{\ddot{B}}{B} + \frac{\dot{A}\dot{B}}{AB} - \frac{m^2}{A^2} = -\omega\rho, \qquad (18)$$

$$\frac{2\dot{A}\dot{B}}{AB} + \frac{\dot{B}^2}{B^2} - \frac{m^2}{A^2} = \rho.$$
(19)

These are three equations connecting four unknown functions A, B,  $\rho$  and  $\omega$ . In order to solve the above equations we use the physical condition that expansions scalar is proportional to shear scalar, which in our case leads to

$$A = B^n \tag{20}$$

where n is a constant. Roy and Banerjee [28], Bali and Singh [29] have proposed this condition to find exact solutions of cosmological models.

Here we use the procedure of Saha and Yadav [27] to find exact solutions of (17) - (19) combining (10) and (20), we obtain

$$A = V^{\frac{n}{n+1}}, \qquad B = V^{\frac{1}{n+1}}.$$
 (21)

Subtraction of (18) from (17) gives

$$\frac{\ddot{B}}{B} - \frac{\ddot{A}}{A} + \frac{\dot{B}^2}{B^2} - \frac{\dot{A}\dot{B}}{AB} + \frac{2m^2}{A^2} = 0.$$
 (22)

Substituting (21) into (22), we obtain

$$\ddot{V} = \frac{2m^2(n+2)}{n-1}V^{\frac{2-n}{n+2}}.$$
(23)

The first integral of (23) is

$$\int \frac{dV}{V^{\frac{4}{n+2}+C}} = \frac{m(n+2)t}{\sqrt{n-1}}$$
(24)

 $R_{\rm ef.}$ 

where C is an arbitrary constant. Clearly (24) imposes some restriction on the choice of n namely, n > 1. It is not possible to solve equation (24) in general. So, in order to solve the problem completely, we have to choose either C or n in such a way that (24) be integrable. Therefore we consider the following cases.

Case 3.1 When C=0

In this case the solution of (24) is

$$V = \left(\frac{mn}{\sqrt{n-1}}\right)^{\frac{n+2}{n}} (t+k_1) \tag{25}$$

where  $k_1$  is an arbitrary constant. From (21) and (25) we obtain the scale factor as

$$A = \frac{mn}{\sqrt{n-1}}(t+k),\tag{26}$$

$$B = \left(\frac{mn}{\sqrt{n-1}}\right)^{\frac{1}{n}} (t+k)^{\frac{1}{n}}.$$
 (27)

With these scale factors, the metric (1) can be written in form

$$ds^{2} = -dT^{2} + \left(\frac{mn}{\sqrt{n-1}}\right)^{2} dx^{2} + \left(\frac{mn}{\sqrt{n-1}}\right)^{\frac{2}{n}} T^{\frac{2}{n}} \left(e^{-2mx} dy^{2} + e^{2mx} dz^{2}\right)$$
(28)

where T=t+k.

The expressions for the energy density  $\rho$  and the EOS  $\omega$  for the model (28) are obtained as

$$\rho = \frac{1+n}{n^2 T^2},\tag{29}$$

$$\omega = \frac{n-2}{n+1}.\tag{30}$$

The other physical and kinematical parameters are given by

$$nH_1 = H_2 = H_3 = \frac{1}{T}, (31)$$

$$\theta = 3H = \frac{n+2}{nT},\tag{32}$$

$$\sigma = \frac{1}{\sqrt{3}} \frac{n-1}{nT},\tag{33}$$

$$q = -\frac{2}{n+2}.\tag{34}$$

### Notes

The deceleration parameter q is always negative. The EoS parameter is positive when n > 2 and is negative if 1 < n < 2. Thus, the metric (28) represents as ever power-law accelerated expansion universe filled with a perfect fluid. If 1 < n < 2,  $\omega < 0$ , we obtain DE cosmological model of Bianchi type-VI<sub>0</sub>.

The spatial volume V is zero and all physical parameters diverge at T = 0. Therefore, the model has a point-type singularity at T = 0. For  $0 < T < \infty$ , the spatial volume is an increasing function of time. The physical parameters are monotonically decreasing function of time and ultimately tend to zero for large T. The anisotropy in the model is maintained throughout the passage of time. For the physical reality of the model we will have to choose n, greater than 1, in such a way that  $\left|\frac{n-2}{n+2}\right| \leq 1$ . It deserves mention that we are unable to find n for which  $\omega = \pm 1$ 

#### Case 3.2 When $C \neq 0$

When  $C \neq o$  equation (24) is not integrable for general values of n. However, for n = 2, it becomes

$$\int \frac{dV}{\sqrt{V+C}} = 4mt \tag{35}$$

which, after integration, yields

$$V = 4m^2t^2 + 2\beta t + \gamma \tag{36}$$

where  $\beta$  and  $\gamma$  are arbitrary constants. The constant C is absorbed in  $\gamma$ . From (21) and (36), we obtain the scale factors as

$$A = (4m^2t^2 + 2\beta t + \gamma)^{\frac{1}{2}}, \tag{37}$$

$$B = (4m^2t^2 + 2\beta t + \gamma)^{\frac{1}{4}}.$$
(38)

Therefore, the metric (1) of our solutions can be written in the form

$$ds^{2} = -dt^{2} + (4m^{2}t^{2} + 2\beta t + \gamma)dx^{2} + (4m^{2}t^{2} + 2\beta t + \gamma)^{\frac{1}{2}}(e^{-2mx}dy^{2} + e^{2mx}dz^{2})$$
(39)

The expressions for  $(H_1, H_2, H_3)$ , H,  $\rho$ ,  $\theta$  and  $\sigma$  are obtained as

$$H_1 = \frac{4m^2t + \beta}{4m^2t^2 + 2\beta t + \gamma},$$
(40)

$$H_2 = H_3 = \frac{1}{2} \left( \frac{4m^2t + \beta}{4m^2t^2 + 2\beta t + \gamma} \right), \tag{41}$$

$$H = \frac{2}{3} \left( \frac{4m^2 t + \beta}{4m^2 t^2 + 2\beta t + \gamma} \right), \tag{42}$$

$$\theta = 2\left(\frac{4m^2t + \beta}{4m^2t^2 + 2\beta t + \gamma}\right),\tag{43}$$

$$\sigma = \frac{1}{\sqrt{3}} \left( \frac{4m^2 t + \beta}{4m^2 t^2 + 2\beta t + \gamma} \right).$$
(44)

The energy density, DP and  $\omega$  are obtained as

$$\rho = \frac{(8m^2t + 2\beta)^2 - (4m^2\gamma - \beta^2)}{4(4m^2t^2 + 2\beta t + \gamma)^2},\tag{45}$$

$$\omega = -\frac{5(4m^2\gamma - \beta^2)}{(8m^2t + 2\beta)^2 - (4m^2\gamma - \beta^2)},\tag{46}$$

$$q = -\frac{2m^2(4m^2t^2 + 2\beta t + \gamma)}{(4m^2t + \beta)^2}.$$
(47)

The value of DP is always negative since V is never negative. The EoS parameter  $\omega$  is negative if  $\gamma > \frac{\beta^2}{4m^2}$ . If this condition holds, the model (39) corresponds to a Bianchi type-VI<sub>0</sub> energy cosmological model with variable q and  $\omega$ .

If  $\gamma > \frac{\beta^2}{4m^2}$ , the model (39) has no finite singularity. The physical and kinematical parameters are all decreasing function of time and ultimately tend to zero for large time. The model essentially gives an empty space-time for large time. The anisotropy in the model never dies out.

#### IV. CONCLUSION

In this paper, we have presented exact solutions of Einstein's field equations for a Bianchi-type VI<sub>0</sub> space-time filled with perfect fluid satisfying the barotropic equation of state under the assumption that the expansion scalar is proportional to shear scalar. Under some specific choice of problem parameters, the present consideration yields singular and non-singular models of the accelerated expansion universe filled with perfect fluid and dark energy. Models with negative EoS parameter  $\omega$  may be attributed to the current accelerated expansion of universe. The physical and kinematical parameters are all decreasing function of time and ultimately tend to zero for large time. The universe models do not approach to isotropy. The models presented in this paper can be potential tools to describe the present universe as well as the early universe.

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#### INFORMAL GUIDELINES OF RESEARCH PAPER WRITING

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- Submit all work in its final form.
- Write your paper in the form, which is presented in the guidelines using the template.
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A purpose of organizing a research paper is to let people to interpret your effort selectively. The journal requires the following sections, submitted in the order listed, each section to start on a new page.

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· Adhere to recommended page limits

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٠

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- Fundamental goal
- To the point depiction of the research
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- Present a justification. Status your particular theory (es) or aim(s), and describe the logic that led you to choose them.
- Very for a short time explain the tentative propose and how it skilled the declared objectives.

#### Approach:

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#### Approach:

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The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.

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- Sum up your conclusion in text and demonstrate them, if suitable, with figures and tables.
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#### Approach

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- Give details all of your remarks as much as possible, focus on mechanisms.
- Make a decision if the tentative design sufficiently addressed the theory, and whether or not it was correctly restricted.
- Try to present substitute explanations if sensible alternatives be present.
- One research will not counter an overall question, so maintain the large picture in mind, where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.

Approach:

- When you refer to information, differentiate data generated by your own studies from available information
- Submit to work done by specific persons (including you) in past tense.
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Introduction	Containing all background details with clear goal and appropriate details, flow specification, no grammar and spelling mistake, well organized sentence and paragraph, reference cited	Unclear and confusing data, appropriate format, grammar and spelling errors with unorganized matter	Out of place depth and content, hazy format
Methods and Procedures	Clear and to the point with well arranged paragraph, precision and accuracy of facts and figures, well organized subheads	Difficult to comprehend with embarrassed text, too much explanation but completed	Incorrect and unorganized structure with hazy meaning
Result	Well organized, Clear and specific, Correct units with precision, correct data, well structuring of paragraph, no grammar and spelling mistake	Complete and embarrassed text, difficult to comprehend	Irregular format with wrong facts and figures
Discussion	Well organized, meaningful specification, sound conclusion, logical and concise explanation, highly structured paragraph reference cited	Wordy, unclear conclusion, spurious	Conclusion is not cited, unorganized, difficult to comprehend
References	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring

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