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A New Approximation to Standard Normal Distribution Function

By Malki Abderrahmane & Boukhetala Kamel

E.P.S.T School of Algiers

Abstract- This paper, presents three news-improved approximations to the Cumulative Distribution Function (C.D.F.). The first approximation improves the accuracy of approximation given by Polya (1945). In this first new approximation, we reduce the maximum absolute error (M.A.E.) from, 0.00314 to 0.00103. For this first new approximation, K. M. Aludaat and M. T. Alodat (2008) was reduce the (M.A.E.) from, 0.00314 to 0.001972. The second new approximation improve Tocher's approximation, we reduce the (M.A.E.) from, 0.166 to 0.00577. For the third new approximation, we combined the two previous approximations. Hence, this combined approximation is more accurate and its inverse is hard to calculate. This third approximation reduce the (M.A.E.) to be less than $2.232e - 004$. The two improved previous approximations are less accurate, but his inverse is easy to calculate. Finally, we give an application to the third approximation for pricing a European Call using Black-Scholes Model.

Keywords: *cumulative distribution function, normal distribution, maximum absolute error.*

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A New Approximation to Standard Normal Distribution Function

Malki Abderrahmane ^α & Boukhetala Kamel ^σ

Abstract- This paper, presents three news-improved approximations to the Cumulative Distribution Function (C.D.F.). The first approximation improves the accuracy of approximation given by Polya (1945). In this first new approximation, we reduce the maximum absolute error (M.A.E.) from, 0.00314 to 0.00103. For this first new approximation, K. M. Aludaat and M. T. Alodat (2008) was reduce the (M.A.E.) from, 0.00314 to 0.001972. The second new approximation improve Tocher's approximation, we reduce the (M.A.E.) from, 0.166 to 0.00577. For the third new approximation, we combined the two previous approximations. Hence, this combined approximation is more accurate and its inverse is hard to calculate. This third approximation reduce the (M.A.E.) to be less than $2.232e - 004$. The two improved previous approximations are less accurate, but his inverse is easy to calculate. Finally, we give an application to the third approximation for pricing a European Call using Black-Scholes Model.

Keywords: cumulative distribution function, normal distribution, maximum absolute error.

I. INTRODUCTION

The cumulative distribution function (CDF) play an important role in financial mathematics and especially in pricing options with Black-Scholes Model. The European option pricing call given by Black-Scholes Model is

$$C(S, K, T, r, \sigma) = S\Phi(d) - Ke^{-rT}\Phi(d - \sigma\sqrt{T}) \quad (1)$$

Where

$$d = \frac{\ln\left(\frac{S}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T}{\sigma\sqrt{T}} \quad (2)$$

S , the current price, K the exercise price, r interest rate, T time option and σ volatility. The cumulative distribution function (C.D.F.) is

$$\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{t^2}{2}} dt \quad (3)$$

The (C.D.F) have not a closed form. His evaluation is an expensive task. For evaluate the (CDF) at a point z we need compute the integral under the probability density function (PDF) given by $\varphi(t) = e^{-0.5t^2} / \sqrt{2\pi}$.

In much research, we find approximations, with closed forms, for the area under the standard normal curve. Otherwise, we need consulting Tables of cumulative standard normal probabilities. Hence, in the literature, we find several approximations to this function from polya (1945) to Yerukala (2015). For this raison; we use some approximations to this C.D.F. (Polya's approximation and Tocher's approximation).

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II. IMPROVING POLYA'S APPROXIMATION

We consider the case of, $z \geq 0$. (For $z < 0, \Phi(z) = 1 - \Phi(-z)$).

The original Polya's approximation given by:

$$\Phi_{Polya}(z) \approx \frac{1}{2} \left\{ 1 + \sqrt{1 - e^{-az^2}} \right\}, \text{ where } a = \frac{2}{\pi}. \quad (2.1)$$

The Maximum Absolute Error (M.A.E.)

$$M.A.E._{Polya} = \max_z |\Phi_{Polya}(z) - N(z)| = 0.003138181653387. \quad (2.2)$$

K.M.Aludaat and M.T.Alodat (2008) proposed the same formula with $a = \sqrt{\frac{\pi}{8}}$ instead of $a = \frac{2}{\pi}$. They have

$$M.A.E._{Aludaat} = \max_z |\Phi_{Aludaat}(z) - \Phi(z)| = 0.001971820656170.$$

In this paper, we write the formula (2.1) and (2.2) as

$$\Phi_{Malki}(z) \approx a + b\sqrt{1 - e^{-cz^2}} \quad (2.3)$$

Hence, we search the parameters a, b and c that

$$M.A.E._{Malki} = \max_z |\Phi_{Malki}(z) - \Phi(z)| \quad (2.4)$$

Was the smallest possible using the following algorithm?

- 1) $h = 0.00001; H = 20h; Er = 0.00314;$
- 2) $a_0 = 0.5, b_0 = 0.5, c_0 = \frac{2}{\pi},$
- 3) for $a = a_0 - H: h: a_0 + H$ for $b = b_0 - H: h: b_0 + H$
- 4) for $c = c_0 - H: h: c_0 + H; M = a + b\sqrt{1 - e^{-cz^2}},$
- 5) $e = \max_z |M - N(z)|; \text{ if } (Er > e) Er = e; A = a; B = b; C = c; \text{ end};$
- 6) $a_0 = A, b_0 = B, c_0 = C.$
- 7) Repeat 3) to 6) until convergence

Using our algorithm, we find the best parameters

$$a^* = 0.50103; b^* = 0.49794; c^* = 0.62632 \quad (2.4)$$

Hence the best formula is

$$\Phi_{Malki1}(z) = 0.50102976 + 0.49794047\sqrt{1 - e^{-0.626317743 z^2}}, \quad (2.5)$$

Note that the absolute error as function of z variable noted by

$$E(z) = |\Phi_{Malki1}(z) - \Phi(z)| = 0.001029767666887 \quad (2.6)$$

Figure one, shows the graph of Absolute Error for Polya, Aludaat and Malki1 as function of $-5 \leq z \leq 5$.

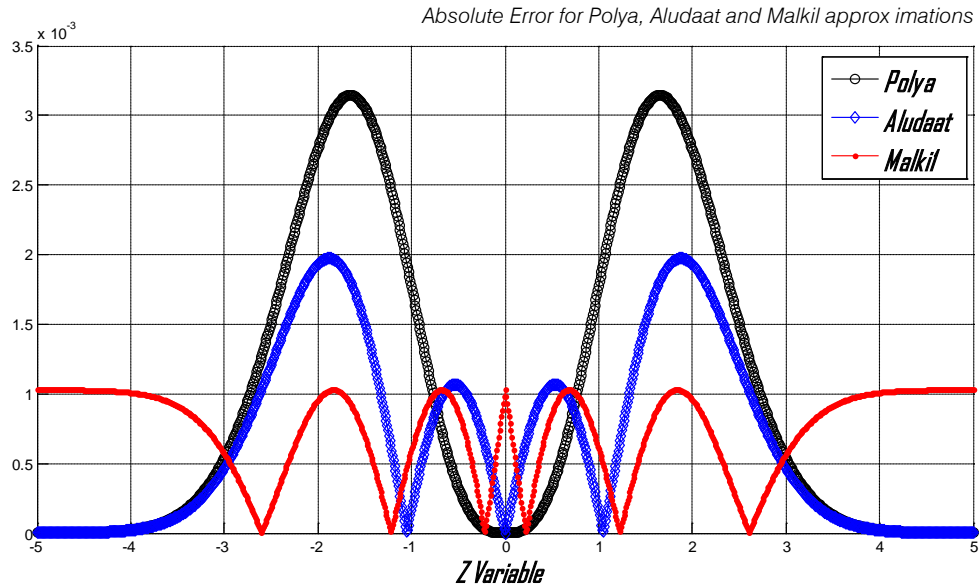
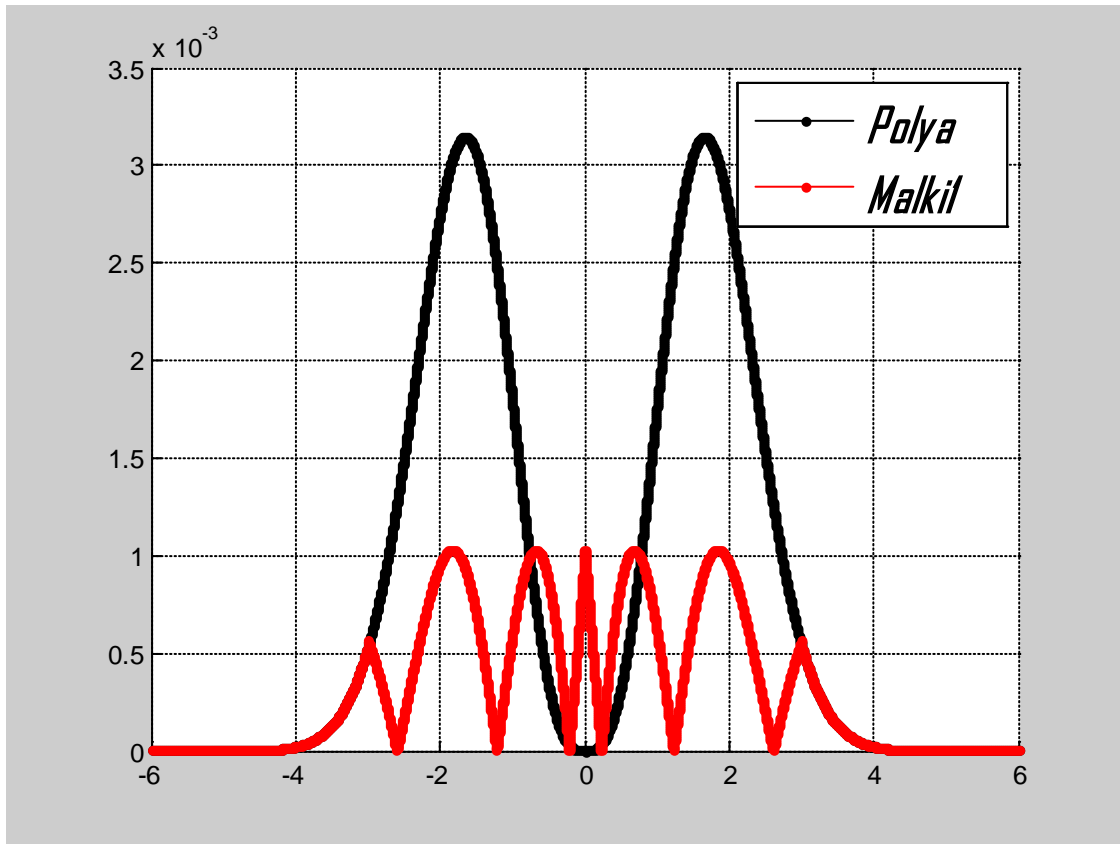


Figure 1: Comparison of absolute error for Polyá, Aludaat and Malkil

III. IMPROVING TOCHER'S APPROXIMATION

The Original Tocher's approximation is $\Phi_{Tocher}(z) = 1/(1 + e^{-\sqrt{\frac{2}{\pi}}z})$ with

$$\max_z |\Phi_{Tocher}(z) - \Phi(z)| = 0.165811983691380 \approx 0.166. \tag{3.1}$$

This approximation have the form:

$$\Phi_{Malki2}(z) = \frac{a}{b+e^{-cz}} \tag{3.2}$$

Hence, we search the parameters a, b and c that

$$M. A. E_{Malki2} = \max_z |N_{Malki2}(z) - N(z)| \tag{3.3}$$

Was the smallest possible using the following algorithm?

- 1) $h = 0.00001; H = 20h; Er = 0.166;$
- 2) $a_0 = 1, b_0 = 1, c_0 = \sqrt{\frac{2}{\pi}};$
- 3) for $a = a_0 - H:h:a_0 + H$ for $b = b_0 - H:h:b_0 + H$
- 4) for $c = c_0 - H:h:c_0 + H; M = \frac{a}{b+e^{-cz}};$
- 5) $e = \max_z |M - \Phi(z)|;$ if $(Er > e) Er = e; A = a; B = b; C = c;$ end;
- 6) $a_0 = A, b_0 = B, c_0 = C.$
- 7) Repeat 3) to 6) until convergence

Using our algorithm, we find the best parameters

$$a^* = 0.97186; b^* = 0.96628; c^* = 1.69075 \tag{3.4}$$

Hence the best-improved formula for Tocher's approximation is

$$\Phi_{Malki2}(z) = \frac{0.97186}{0.96628 + e^{-1.69075z}} \tag{3.5}$$

$$\max_z |\Phi_{Malki2}(z) - N(z)| = 0.005774676414954 \tag{3.6}$$

Figure 2 gives the curves of original absolute error and the new absolute error

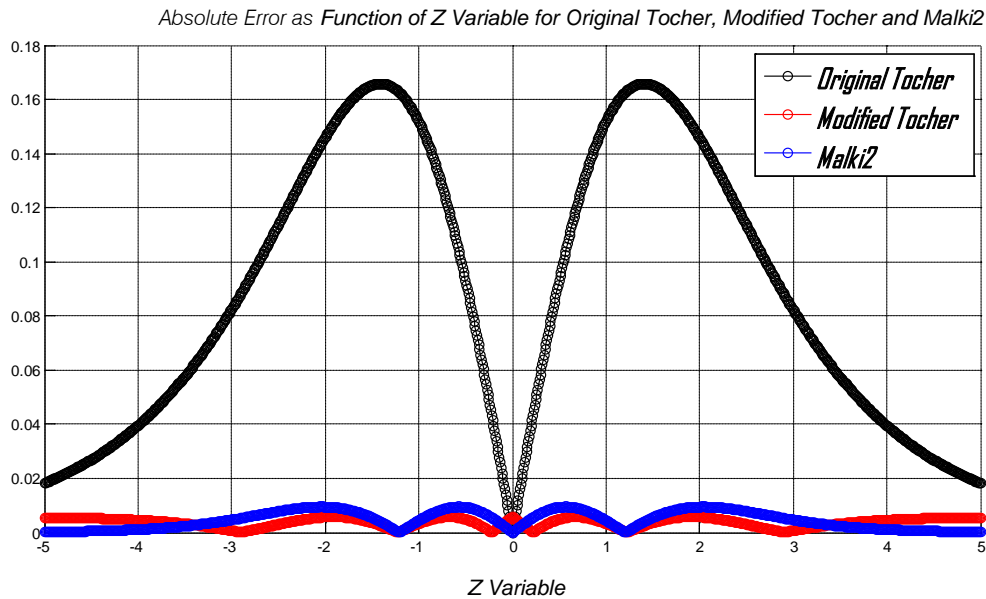


Figure 2: Comparison of Absolute Error for Original Tocher, Modified Tocher and Malki2 as function of z variable ($-5 \leq z \leq 5$)

IV. COMBINED FORMULA

As the third new approximation formula, we consider the two previous formula

$$\Phi_{Malki\ 1}(z) = 0.50103 + 0.49794\sqrt{1 - e^{-0.62632 z^2}},$$

and,
$$\Phi_{Malki\ 2}(z) = \frac{0.97186}{0.96628 + e^{-1.69075 z}}.$$

Hence, we consider the third new formula as

$$\Phi_{Malki\ 3}(z) = \omega\Phi_{Malki\ 1}(z) + (1 - \omega)\Phi_{Malki\ 2}(z), \text{ for, } (0 \leq \omega \leq 1) \tag{4.1}$$

We search the optimum parameter ω that the

$$M.A.E_{Malki\ 3} = \max_z |\Phi_{Malki\ 3}(z) - \Phi(z)|$$

Was the smallest possible. We find optimum parameter $\omega^* = 0.16$

The new third approximation is

$$\Phi_{Malki\ 3}(z) = 0.16\Phi_{Malki\ 1}(z) + 0.84\Phi_{Malki\ 2}(z) \tag{4.2}$$

The adjusted formula is

$$\Phi_{Malki\ 3}(z) = \frac{0.1544976}{0.96568 + e^{-1.68975 z}} + 0.4212652 + 0.4189696\sqrt{1 - e^{-0.62642 z^2}} \tag{4.3}$$

For, this approximation we have:

$$\max_z |\Phi_{Malki\ 3}(z) - \Phi(z)| = 2.231943559627414e - 004 \tag{4.4}$$

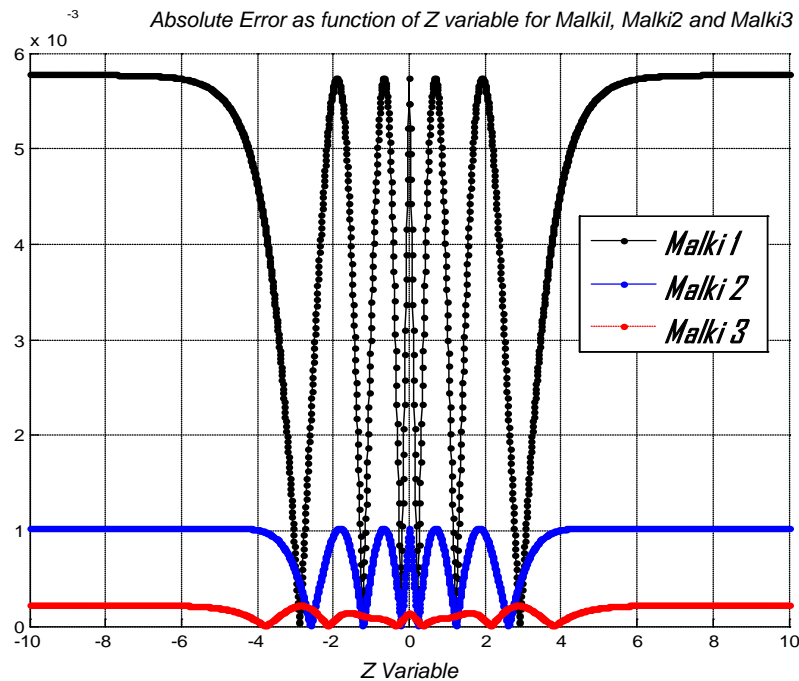


Figure 3

V. APPLICATION WITH BLACK-SCHOLES MODEL

For

$$S = 35; K = 30; r = 0.065; T = 1.2; \sigma = 0.35; \tag{5.1}$$

To calculate a Call European option we compute

$$d = \frac{\ln\left(\frac{S}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T}{\sigma\sqrt{T}} = 0.797198914562755 \quad (5.2)$$

$$\text{And} \quad d - \sigma\sqrt{T} = 0.413793124309139 \quad (5.3)$$

Hence

$$C = S\Phi(d) - Ke^{-rT}\Phi(d - \sigma\sqrt{T}) = 9.228813813962439 \quad (5.4)$$

Using, Φ_{Malki3} we have

$$C_3 = S\Phi_{Malki3}(d) - Ke^{-rT}\Phi_{Malki3}(d - \sigma\sqrt{T}) = 9.231095739041432 \quad (5.5)$$

The absolute error is $|C - C_3| \leq 0.0023$ (5.6).

VI. CONCLUSION

We have proposed three approximations to the cumulative distribution function of the standard normal distribution. The first approximation improve the Polya's formula in accuracy. The second new approximation improve the accuracy of Tocher's formula. The third formula is a combination of the two previous formula. The M.A.E. for the first approximation is 0.00103. The M.A.E. for the second approximation is 0.00577. For the third approximation the M.A.E. is less than $2.232e - 004$. Finally, we insert an application to option pricing of a Call European option based on Black-Scholes formula.

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1. Ivanova E.P., Grant I. 1998 Oscillator strength anomalies in the neon isoelectronic sequence with applications to x-ray laser modeling. *J. of Phys. B: At. Mol. Opt. Phys.* **31**, 2871-2883

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I. INTRODUCTION

Effect of oscillator strength transfer in the neon isoelectronic sequence with application to X-ray laser modeling was considered by us in [1]. This study suggests that Z points at which interacting levels are close to each other may be important for modeling emission spectra of dense plasma. Later the authors of [2] where the level crossing in the Ni-like sequence and associated irregularities in the functions of energies and probabilities of radiative transitions in the range $Z = 74-84$ were studied arrived at the same conclusion. From this, the conclusion about the possible incorrect identification of levels in their crossing regions follows. Here we review the experiments on the study of self-photo pumped X-ray laser in Ni- like ions in order to determine possible irregularities in the sequences of working levels. Another challenge is to detect misidentifications in the working levels energies.

Self-photo pumped (SPP) x-ray lasers (XRL) in Ni-like ions were presented in 1996 [3] as an alternative approach to the standard radiative collisional scheme for inversion creation. We use the term SPP following the name given in literature. This is really collisionally pumped laser assisted by radiation trapping. Both schemes for Ni-like ions are shown in Figure1. This new class of SPP in Ni-like XRL was first investigated theoretically in [4] where high gain was predicted for the $4f^1P_1 - 4d^1P_1$ transition in Mo^{14+} at 22.0 nm. It was supposed that preplasma was created by a nanosecond pulse

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followed by a picosecond pulse to control the temperature and density in plasma and to achieve high gain. This wavelength was calculated using the multiconfiguration Dirac-Fock atomic physics code by Grant and co-workers in the extended average level mode [5]. In the experiment [6] the Ni-like SPP XRL on the $4f^1P_1 - 4d^1P_1$ transition was demonstrated in Ni-like Zr, Nb, and Mo, and the measured wavelengths for these ions were presented. For Mo^{14+} a gain of 13 cm^{-1} was measured at 22.6 nm for a target up to 1 cm long [6]. The wavelengths of this transition for ions from $Z = 36$ to 54 were predicted in [6] using the experimental data of this work to provide small corrections to their calculations. In the experiment [7], the progress in the optimization and understanding of the collisional pumping of X-ray lasers using an ultrashort subpicosecond heating pulse was reported. Time integrated and time resolved lasing signals at the standard $4d^1S_0 - 4p^1P_1$ XRL line in Ni-like Ag was studied in detail. Under specific irradiation conditions, strong lasing was obtained on the SPP $4f^1P_1 - 4d^1P_1$ transition at 16.1 nm . The strong lasing on the SPP transition in Mo^{14+} was also observed with very modest (less than 1 J) pump energy at high repetition rate [8]. Recently lasing on the SPP $3d^1P_1 - 3p^1P_1$ laser line has been observed for Ne-like V, Cr, Fe, and Co, as well as for Ni-like Ru, Pd, and Ag [9]. A strong dependence on delay between the main and second prepulses was found: the optimum delay shifts towards smaller delays with increasing atomic number Z . Accurate wavelength measurements and calculations are shown to be in excellent agreement. The experiment [9] has demonstrated that the list of elements that lase on the SPP transitions can be extended much further than originally known.

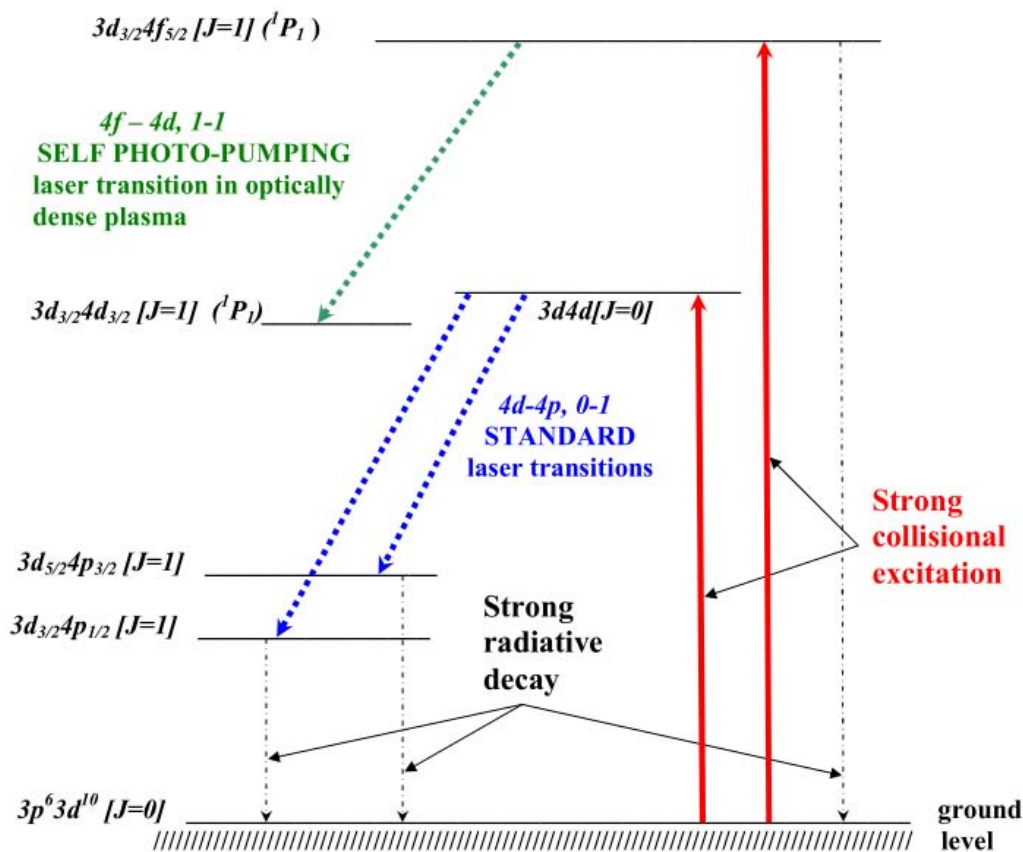


Fig. 1: The diagram of three XRL transitions in Ni-like ions

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6. Nilsen J., Dunn J., Osterheld A.L., Li Yu 1999 Lasing on the self-photopumped nickel-like $4f^1P_1 - 4d^1P_1$ x-ray transition. *Phys. Rev. A* **60** R2677-80

Many authors have investigated the spectra of Ni-like ions using vacuum spark, laser produced plasma and electron beam ion trap as light sources [10-16]. The $3d^94d$ and $3d^94f$ configurations have been analyzed in the Rb X – Mo XV sequence [12-13]. In [12-13], these configurations were investigated using parameter extrapolations within the Generalized-Least-Squares (GLS) method. This method was used in [14,15] to predict for $3d^94d$, $3d^94f$ configuration energy levels in Cd XXI and Ag XX. GLS predictions of $3d^94d$, $3d^94f$ energy levels in the Zr XIII – Pd XIX sequence are tabulated in [16].

Note that lasing wavelength (λ_{las}) in Mo¹⁴⁺ was determined theoretically [4] and in the experiment [6] using one and the same atomic physics code [5], but results for λ_{las} were somewhat different (by 4Å). The $3d_{3/2}4f_{5/2} [J=1]$ upper working level has the largest oscillator strength and RTP to the $3d^{10}$ ground level. This fact allows it to achieve high precision in this level energy measurement along the Ni-like sequence up to high $Z \sim 84$; in some ions, the energy of the transition to the ground state was accurate up to the fourth significant digit. The wavelengths of resonant radiative transitions in heavy Ni-like ions were calculated by us to $Z = 83$ in [17]. Moreover, in [17] the wavelengths (for Z within 79 –82) were predicted with the same accuracy, although they have not yet been measured experimentally.

In the present paper, we analyze the smoothness of the working energy levels of SPP XRL along the Ni-like sequence. We have found some irregularities in Ni- like sequence energies in the region $Z=42$ (Mo¹⁴⁺) and in the region $Z = 49$ (In²¹⁺) for the upper $3d_{3/2}4f_{5/2} [J=1]$ working level. The causes of irregularities are studied.

The principle purpose of this paper is to predict the wavelengths of SPP XRL lines in Ni-like ions with $Z \leq 79$. The calculations are performed by the Relativistic Perturbation Theory with Model zero approximation Potential (RPTMP). The fundamental principles of the RPTMP approach are given in [18] where energy levels of the $3p^63d^04l$, $3p^53d^14l$, ($l=0,1$) configurations and radiative transition rates to the $3p^63d^0$ ground state in the Kr IX ion are calculated. The stability of calculations on the approximation used was discussed in [18]. Energy levels of the odd and even states with $J=1$ of the Ni- like ions with $Z = 36-51$ are given in Tables 1 and 2.

Table 1: Energy levels (in 1000 cm⁻¹) of the odd states with $J=1$ of the Ni- like ions with $Z = 36-51$

level	36	37	38	39	40	41	42	43
$3d_{5/2}4p_{3/2}$	855.9	1005.5	1175.7	1366.2	1557.8	1758.9	1971.7	2.210.0+
$3d_{3/2}4p_{1/2}$	869.6	1020.4	1191.7	1383.1	1575.7	1777.7	1991.5	2189.2+
$3d_{3/2}4p_{3/2}$	875.3	1027.6	1200.7	1394.4	1589.5	1794.4	2011.5	2233.8
$3d_{5/2}4f_{5/2}$	1310.8	1516.9	1743.8	1990.5	2238.1	2495.1	2771.8	3033.7
$3d_{5/2}4f_{7/2}$	1318.7	1526.3	1755.4	2004.5	2254.7	2514.3	2793.5	3060.0
$3d_{3/2}4f_{5/2}$	1332.2	1.545.2	1779.7	2034.9	2292.0	2559.1	2843.9	3121.3
$3p_{3/2}4s_{1/2}$	1650.9	1868.7	2077.8	2309.0	2541.3	2782.4	3035.0	3292.3
$3p_{1/2}4s_{1/2}$	1712.0	1939.7	2159.6	2403.5	2649.6	2905.8	3175.3	3451.0
$3p_{3/2}4d_{3/2}$	2044.8	2305.1	2256.9	2831.1	3106.7	3391.7	3688.7	3990.8
$3p_{3/2}4d_{5/2}$	2055.4	2317.2	2570.4	2846.0	3122.9	3409.4	3707.8	4011.6
$3p_{1/2}4d_{3/2}$	2116.3	2387.8	2651.6	2939.6	3230.2	3531.3	3846.2	4167.8

level	44	45	46	47	48	49	50	51
$3d_{5/2}4p_{3/2}$	2440.9	2682.8	2937.5	3205.2	3480.4	3.767.1	4064.5	4372.8
$3d_{3/2}4p_{1/2}$	2419.1	2659.7	2913.1	3179.1	3452.4	3737.0	4031.8	4337.2
$3d_{3/2}4p_{3/2}$	2468.9	2715.4	2975.2	3248.6	3530.0	3823.4	4128.1	4444.3
$3d_{5/2}4f_{5/2}$	3321.4	3617.3	3924.2	4247.3	4576.1	4916.4	5267.1	5627.2
$3d_{5/2}4f_{7/2}$	3350.0	3649.4	3960.0	4286.7	4619.5	4964.0	5319.1	5683.8
$3d_{3/2}4f_{5/2}$	3419.9	3728.2	4048.4	4383.3	4723.1	5094.1+	5454.3	5828.8
$3p_{3/2}4s_{1/2}$	3561.8	3842.3	4135.8	4442.1	4757.8	5065.3+	5404.8	5751.8
$3p_{1/2}4s_{1/2}$	3740.8	4043.4	4360.9	4692.7	5034.2	5389.3	5757.3	6139.8
$3p_{3/2}4d_{3/2}$	4305.9	4632.5	4972.3	5325.9	5687.3	6060.8	6445.5	6842.3
$3p_{3/2}4d_{5/2}$	4328.3	4656.6	4998.2	5353.7	5717.2	6092.9	6480.1	6879.4
$3p_{1/2}4d_{3/2}$	4504.2	4854.0	5219.2	5600.1	5991.3	6397.0	6816.4	7250.9

Table 2: Energy levels (in 1000 cm^{-1}) of the even states with $J=1$ of the Ni- like ions with $Z = 36-51$

level	36	37	38	39	40	41	42	43
$3d_{3/2}4s_{1/2}$	706.2	840.9	995.9	1171.0	1347.3	1532.7	1729.8	1931.4
$3d_{5/2}4d_{3/2}$	1088.4	1263.0	1458.1	1673.1	1889.4	2115.1	2352.6	2594.8
$3d_{5/2}4d_{5/2}$	1098.9	1275.3	1472.1	1688.8	1906.8	2134.3	2373.4	2617.4
$3d_{3/2}4d_{5/2}$	1106.4	1284.2	1482.7	1701.4	1921.6	2151.6	2400.8+	2648.7
$3d_{3/2}4d_{3/2}$	1110.1	1288.5	1487.5	1706.7	1927.6	2158.2	2393.6+	2640.6
$3p_{3/2}4p_{1/2}$	1793.6	2.025.4	2248.6	2494.2	2740.6	2996.2	3263.4	3535.2
$3p_{3/2}4p_{3/2}$	1811.0	2045.6	2271.6	2520.6	2770.7	3030.5	3302.4	3579.5
$3p_{1/2}4p_{1/2}$	1862.1	2104.2	2338.5	2597.0	2857.6	3128.4	3412.6	3703.1
$3p_{1/2}4p_{3/2}$	1.874.4	2119.3	2356.7	2618.9	2883.5	3159.0	3448.2	3744.5
$3p_{3/2}4f_{5/2}$	2258.9	2.549.8	2832.0	3136.7	3442.4	3757.5	4092.6	4413.0
$3d_{3/2}4s_{1/2}$	2145.1	2369.7	2607.0	2856.4	3113.3	3381.3	3659.5	3948.6
$3d_{5/2}4d_{3/2}$	2849.6	3115.3	3393.8	3685.5	3984.6	4295.3	4616.5	4948.6
$3d_{5/2}4d_{5/2}$	2873.9	3141.5	3421.8	3715.5	4016.7	4329.5	4653.1	4987.6
$3d_{3/2}4d_{5/2}$	2909.5	3181.8	3467.4	3766.8	4074.3	4394.0	4725.1	5067.6
$3d_{3/2}4d_{3/2}$	2900.6	3172.0	3456.5	3754.8	4060.9	4379.1	4708.5	5049.2
$3p_{3/2}4p_{1/2}$	3819.4	4114.3	4422.2	4742.5	5070.2	5409.0	5758.3	6118.8
$3p_{3/2}4p_{3/2}$	3869.5	4171.0	4486.0	4814.4	5150.9	5499.4	5859.3	6231.3
$3p_{1/2}4p_{1/2}$	4007.8	4325.1	4657.5	5.004.5	5361.2	5731.5	6114.8	6512.4
$3p_{1/2}4p_{3/2}$	4055.5	4379.9	4719.8	5075.4	5441.4	5821.8	6216.2	6625.7
$3p_{3/2}4f_{5/2}$	4760.5	5116.2	5483.5	5867.5	6257.7	6660.0	7073.3	7497.2

II. FEATURES OF LOWER AND UPPER WORKING LEVELS OF SPP XRL ALONG THE Ni- LIKE SEQUENCE

The schematic diagram of three strong XRL transitions is shown in Fig. 1: two of them are standard $3d4d [J=0] - 3d_{5/2}4p_{3/2} [J=1]$ and $3d4d [J=0] - 3d_{3/2}4p_{1/2}[J=1]$ transitions. The classifications of lower working levels in Fig. 1 are valid for $Z > 42$. The $3d_{5/2}4p_{3/2} [J=1]$ level is the lower working level of an XRL for the entire nickel isoelectronic sequence, the $3d_{3/2}4p_{1/2}[J=1]$ level is the lower working level for heavy ions starting with $Z = 62$. The third $3d_{3/2}4p_{3/2}[J=1]$ level decays to the ground state significantly weaker than two mentioned above, and does not provide a significant gain. In our recent work [19], the energies of standard XRL transitions in ions of the Ni-like sequence with $Z \leq 79$ are refined by RPTMP calculations. The calculated energies of

the two standard $4d-4p$, $J=0-1$ XRL transitions are corrected by extrapolation of the experimental differentials of XRL transition energies $dE_Z^{las} = E_Z^{las} - E_{Z-1}^{las}$; i.e., the differences between transition energies of neighboring ions, which weakly depend on Z (especially, in the region $Z \leq 50$). It is proven that the accuracy for the final results for large Z is within the experimental error.

The $3d_{3/2}4f_{5/2} [J=1] - 3d_{3/2}4d_{3/2} [J=1]$ transition is optically self-photopumped XRL in all Ni-like ions, the positions of working levels vary with respect to other levels along the sequence. Based on our previous studies of XRL [20-22], it can be argued that there are at least four principal differences between standard and self photo-pumped mechanisms:

- (i) In the standard scheme, the upper working level is populated by strong monopole electron collisions; in the SPP scheme it is populated by strong dipole electron collisions, which means large oscillator strength and effective photoabsorption.
- (ii) Effective SPP XRL is possible only in optically thick plasma (large electron density n_e and diameter d), while the standard XRL is possible both in optically thick and in optically thin plasma over a wide range of n_e and d .
- (iii) In the SPP, the upper working level is quickly emptied due to the large radiative decay rate. Therefore, in this scheme, a laser effect is short-lived; maximum XRL duration may be a few tens of picoseconds. A standard XRL can operate in quasi-continuous mode (under certain conditions).
- (iv) In the SPP, the lower and upper working levels does not change their classification along the Ni-like sequence, in the standard scheme the upper working level changes its classification: the $3d_{5/2}4d_{5/2} [J=0]$ state is dominant in the classification of the upper working level at $Z \leq 51$, and the $3d_{3/2}4d_{3/2} [J=0]$ state is dominant for $Z > 51$ [19].

Below we demonstrate the irregularities in the sequence of both the lower and the upper working levels of SPP XRL. Crossing of each working level with another level causes the irregularities. Level crossing is accompanied by a strong interaction at certain Z points. Fig. 2a shows the scaled energies along Z of the $3d_{3/2}4d_{3/2} [J=1]$ lower working level and $3d_{3/2}4d_{5/2} [J=1]$ level close to it. In addition to the energy levels calculated here, Fig. 2a also shows the corresponding experimental values [16]. Reference [16] does not indicate classification of $3d4d [J=1]$ levels, their classification was made earlier in [13]. Note that theoretical and experimental classifications are identical. There are some differences between theoretical and experimental energies, typically few units in the 4th-5th digits. These differences are conditioned by the shift of the theoretical list of energy levels as a whole, but this shift does not affect the accuracy of λ_{las} . The energy levels in Fig.2a are scaled by dividing by $(Z-23)^2$, so that the behavior of the third and fourth significant digits can be observed. At the beginning of the sequence, the $3d_{3/2}4d_{3/2} [J=1]$ level is above the $3d_{3/2}4d_{5/2} [J=1]$ level. The crossing of these levels is in the range $41 < Z < 42$ (shown by arrows). The crossing of the corresponding experimental energy levels occurs at exactly the same Z value. At $Z = 42$, one can observe the “repulsion” of levels caused by their interaction; the “repulsion” is a feature of theoretical and experimental data. Note, that repulsion can be seen due to energy scaling; in fact, the repulsion value is about few thousand of cm^{-1} , i.e. few units in the fourth digit for the $3d_{3/2}4d_{5/2} [J=1]$ level.

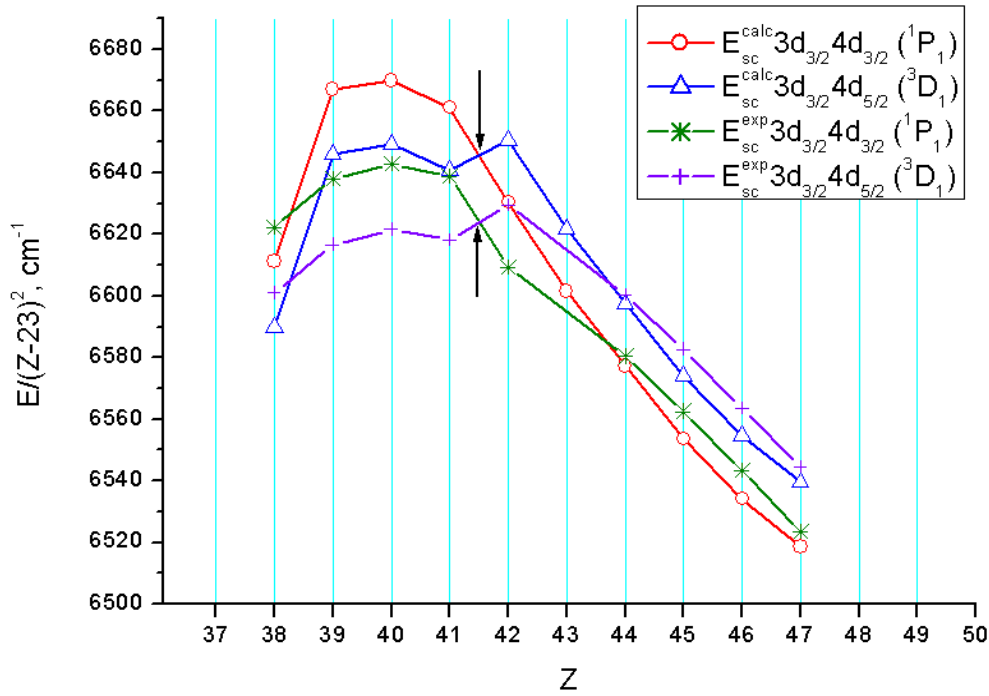


Fig. 2a: The crossing of low working $3d_{3/2}4d_{3/2} [J=1]$ energy level with $3d_{3/2}4d_{5/2} [J=1]$ energy level in Ni-like sequence, shown for the theoretical and experimental scaled energies along Z

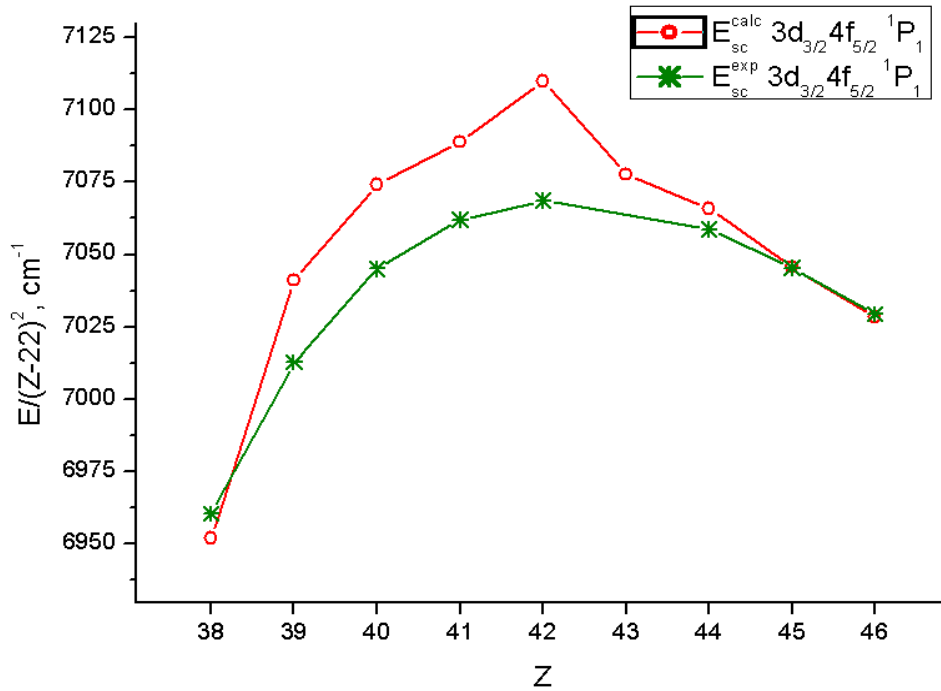


Fig. 2b: Features of theoretical upper working level $3d_{3/2}4f_{5/2} [J=1]$, shown by scaled energy along Z in comparison with correspondent experimental data

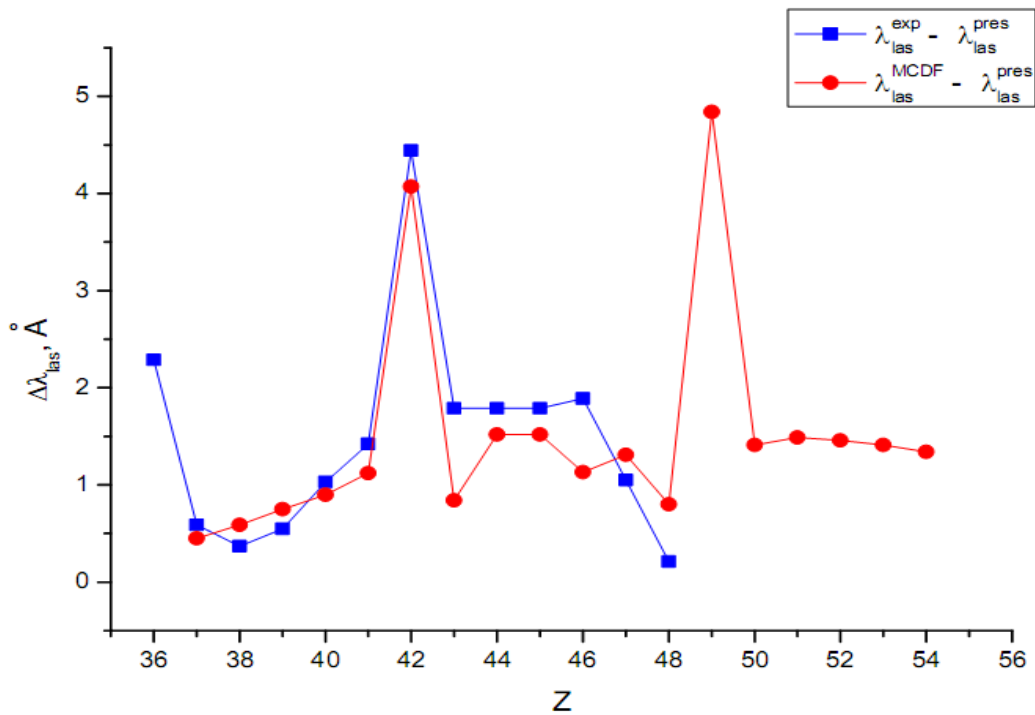


Fig. 3: Difference between experimental, predicted from [6] and calculated here, λ_{las} of SPP XRL transition in Ni-like ions

In Fig. 2b, we can see hard to explain behavior of the $3d_{3/2}4f_{5/2} [J=1]$ upper working level in the region of $Z = 42$. The features of this level will be considered below in more detail; however, it is important to note here that the energy structure of odd states in the range $Z = 40-49$ exhibits extremely high instability caused by the interaction of levels with each other, which rapidly changes with Z . (Note, that the calculation in simpler approximations without accounting for $3p_{1/2}$, $3p_{3/2}$ orbital's, in principle, confirms the results shown in Figures 2a, 2b). In this case at hand, we understand the instability as the ambiguity of the calculation of eigenvectors and eigenenergies. As a result, the calculation in the same approximation leads to different energies of a certain level. The deviation from the smooth curve in Fig. 2a $\sim 10000 \text{ cm}^{-1}$; however, such a value leads to a sufficiently large deviation from the corresponding experimental values of λ_{las} at $Z = 42$, shown in Fig. 3.

At the point $Z = 42$, λ_{las} calculated here is $\sim 222 \text{ \AA}$ that is smaller than the experimental and theoretical values of [4] by 4 \AA . In the recent experiment [9], the delay time between preliminary and main pump pulses was optimized to achieve the maximum yield of the X-ray laser. In fact, the electron density was optimized in [9]. X-ray lasing occurs in the Ni-like ion ionization mode, so that the lasing times on both transitions were restricted to the ionization time of Ni-like ion to the Co-like state. Time resolved measurements in [9] allowed high-accuracy wavelength measurements of the SPP and standard X-ray laser lines. Thus, the calculations of the previous work [6] were confirmed: $\lambda_{las} \approx 22.61 \text{ nm}$ in Ni-like molybdenum (Mo^{14+} , $Z=42$). Our calculations are performed for an isolated atom. Based on the studies performed, it can be argued that the interaction of levels at the point $Z = 42$ is so strong that the energy levels $3d_{3/2}4d_{3/2} [J=1]$, $3d_{3/2}4d_{5/2} [J=1]$ in dense hot plasma can differ significantly from the corresponding energy levels in an isolated atom.

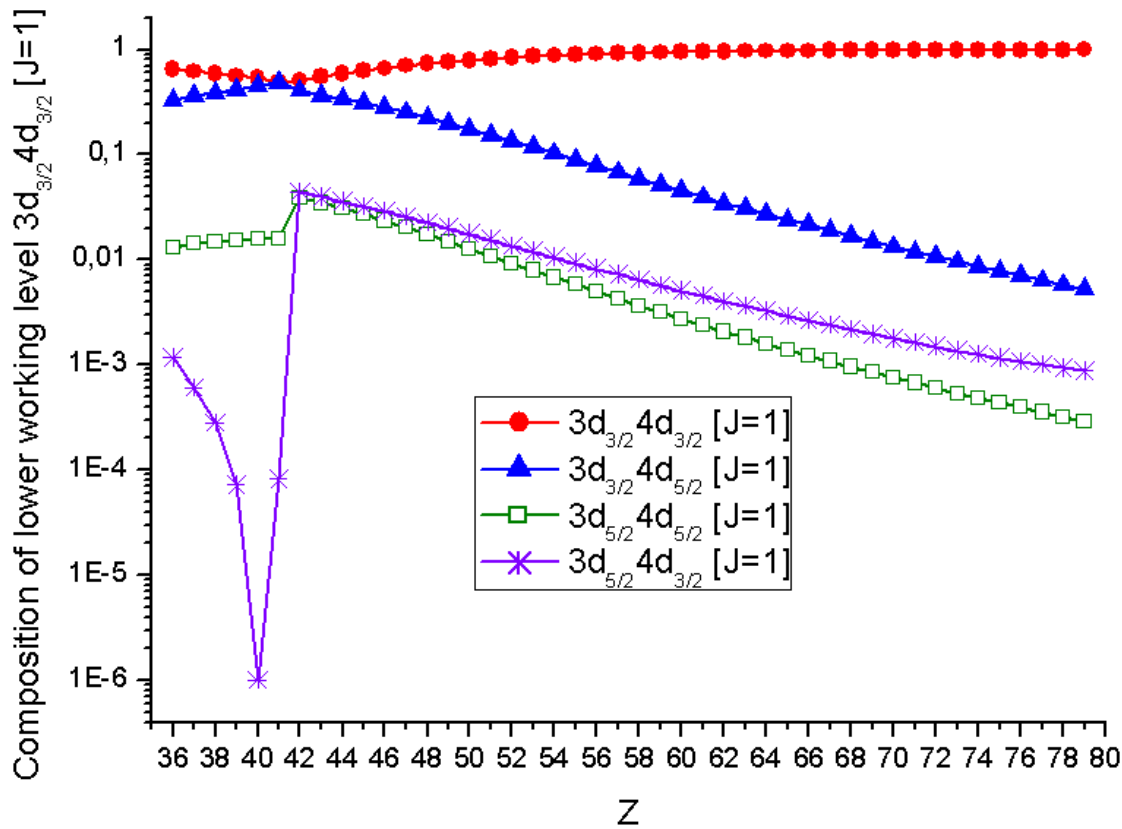


Fig. 4: Composition of low working level $3d_{3/2}4d_{3/2} [J=1]$ along Ni-like sequence on a logarithmic scale

The problem is related to the composition of the $3d_{3/2}4d_{3/2} [J=1]$ working level, which indicates the strength of level interaction. It is shown in Fig. 4 for all $3d4d [J=1]$ levels in Ni-like ions with $Z = 36 - 79$. Figure 4 shows that contributions of the $3d_{3/2}4d_{3/2} [J=1]$ and $3d_{3/2}4d_{5/2} [J=1]$ levels are almost equal at $Z = 42$, which could lead to levels' misidentification. Theoretical energies of these levels at $Z = 42$ are 2393554 cm^{-1} and 2400846 cm^{-1} (51% and 41%, respectively, are the contributions to the $3d_{3/2}4d_{3/2} [J=1]$ low working level). The contributions of these levels in [13] are 45% and 34%, and the energies are 2385902 cm^{-1} and 2393229 cm^{-1} respectively. (We note that the theoretical list of energies of Ni-like ions in the range of small Z is shifted as a whole by $5000-8000 \text{ cm}^{-1}$). Fig. 4 demonstrates the rapid restructuring of lower working level compositions: so that the $3d_{5/2}4d_{3/2} [J=1]$ level contribution increases by five orders of magnitude in the range $Z = 40 - 42$.

Ref

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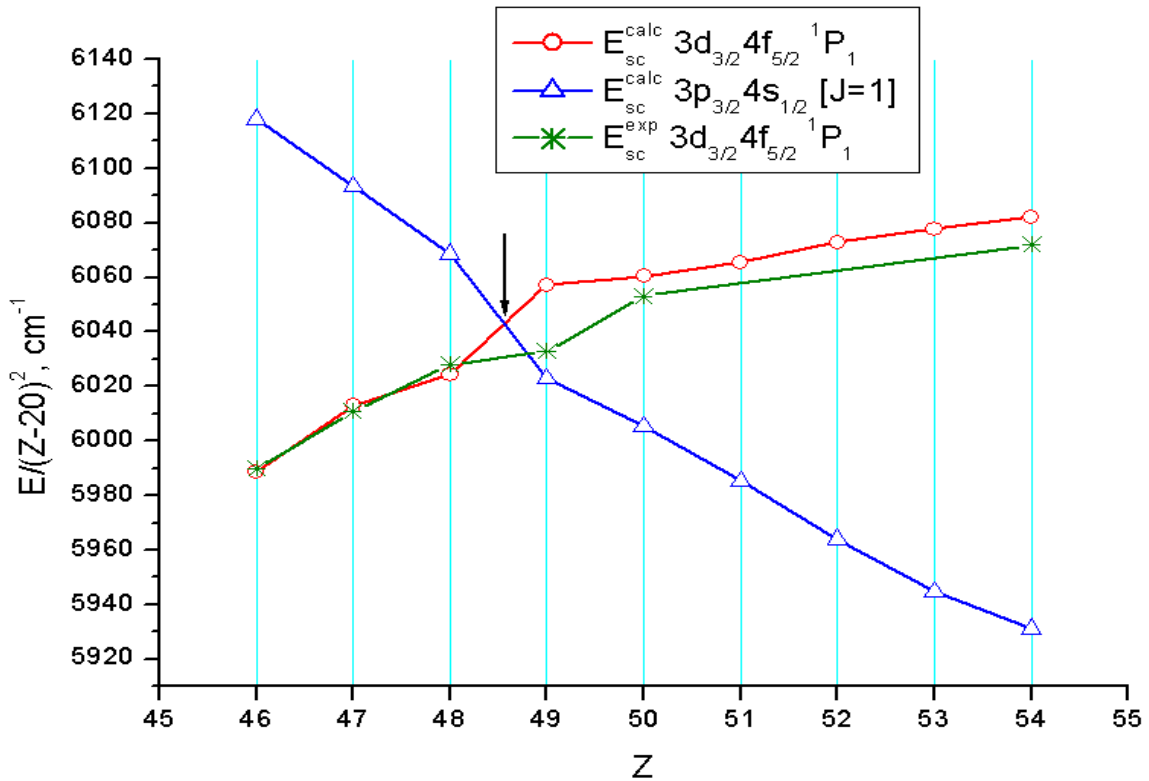


Fig. 5: Crossing of upper working $3d_{3/2}4f_{5/2} [J=1]$ energy level with $3p_{3/2}4s_{1/2} [J=1]$ energy level in Ni-like sequence, shown by scaled energy values along Z . The corresponding experimental values for $3d_{3/2}4f_{5/2} [J=1]$ energies are also shown

Figure 5 shows the scaled energies along Z of the $3d_{3/2}4f_{5/2} [J=1]$ upper working level and the close $3p_{3/2}4s_{1/2} [J=1]$ level. Crossing of these levels occurs in the range $48 < Z < 49$. At $Z = 49$ one can see the “repulsion” of levels caused by their interaction; the “repulsion” is a feature of theoretical data. In Fig.5, the corresponding experimental energies for the $3d_{3/2}4f_{5/2} [J=1]$ level are shown [16]. Unfortunately, we have no available data on the experimental $3p_{3/2}4s_{1/2} [J=1]$ levels in the Z region under consideration. The value $Z = 49$ is the point of an abrupt jump (irregularity) in spectroscopic constants of the $3d_{3/2}4f_{5/2} [J=1]$ upper working level and the $3p_{3/2}4s_{1/2} [J=1]$ level crossing it, caused by the strong interaction of these levels at this value of Z . This interaction is shown in Fig. 6, where we can see the $3d_{3/2}4f_{5/2} [J=1]$ level composition. The interaction of levels at the point $Z = 49$ leads to the so-called effect of oscillator strength transfer we considered in [1] for the Ne-like sequence. At this point, the rate of radiative processes abruptly changes: the probabilities of the transition from the $3d_{3/2}4f_{5/2} [J=1]$ level to the ground state and to the state of the lower working level slightly decrease. At the same time, these probabilities for the $3p_{3/2}4s_{1/2} [J=1]$ level increase by an order of magnitude and become almost equal in magnitude to the corresponding values of the $3d_{3/2}4f_{5/2} [J=1]$ level. These effects are clearly expressed in figures 7a, 7b showing the RTP to the ground state from $3d_{3/2}4f_{5/2} [J=1]$ and $3p_{3/2}4s_{1/2} [J=1]$ levels. Thus, it can be assumed that there was incorrect identification at the point $Z = 49$ when extrapolating the upper working level in [6], and the $3p_{3/2}4s_{1/2} [J=1]$ level which is close to the $3d_{3/2}4f_{5/2} [J=1]$ level in energy was used as the upper working level (see Figure 5). If this assumption is correct, $\lambda_{las} \sim 144.7 \text{ \AA}$ for $Z = 49$, which is identical to [6]. When using our value for $3d_{3/2}4f_{5/2} [J=1]$, $\lambda_{las} \sim 140.0 \text{ \AA}$ (here the energy jump shown in Fig. 5 is taken into

account). Another argument in favor of the incorrect identification in [6], are large jumps of the differential $d\lambda_{las}(Z) = \lambda_{las}(Z) - \lambda_{las}(Z-1)$ in the range $Z = 47-50$.

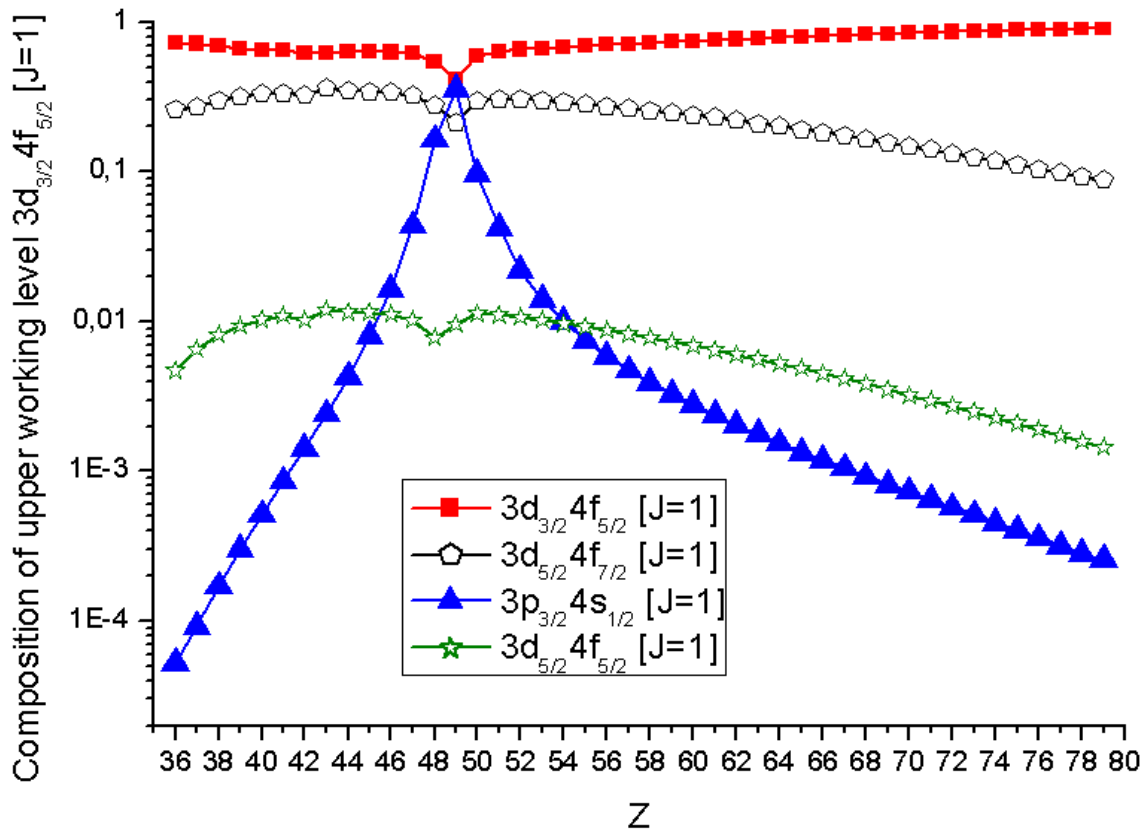


Fig. 6: Composition of upper working level $3d_{3/2}4f_{5/2} [J=1]$ along Ni-like sequence on a logarithmic scale

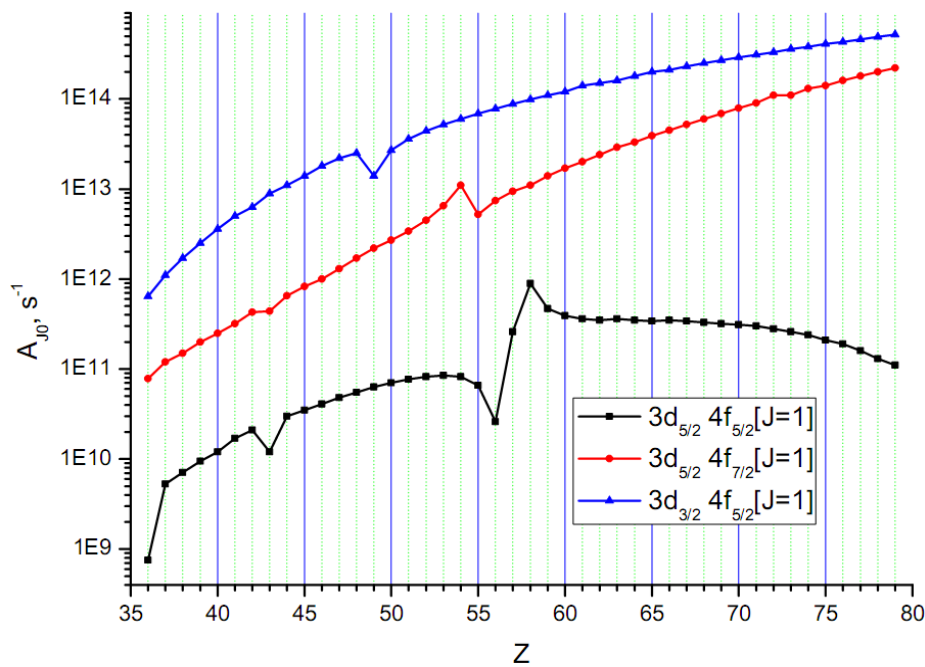


Fig. 7a: Radiative transition probability from the upper working level $3d_{3/2}4f_{5/2} [J=1]$ and the levels $3d_{5/2}4f_{5/2} [J=1]$, $3d_{5/2}4f_{7/2} [J=1]$ to the ground level 1S_0 .

Ref

6. Nilsen J., Dunn J., Osterheld A.L., Li Yu 1999 Lasing on the self-photopumped nickel-like $4f^1P_1 - 4d^1P_1$ x-ray transition. *Phys. Rev. A* **60** R2677-80

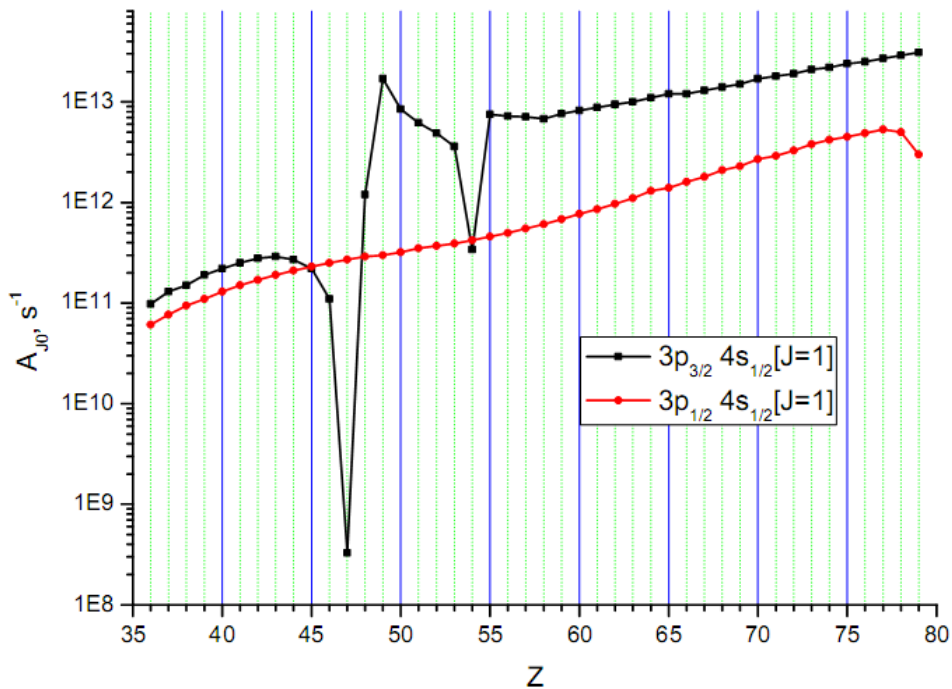


Fig. 7b: Radiative transition probability from the levels $3p_{3/2}4s_{1/2} [J=1]$ and $3p_{1/2}4s_{1/2} [J=1]$ to the ground level 1S_0

III. WAVELENGTHS OF THE SELF-PHOTOPUMPED NICKEL-LIKE $4F^1P_1 \rightarrow 4D^1P_1$ X-RAY LASER TRANSITIONS

A comparison of the wavelengths of the self-photopumped nickel-like $4f^1P_1 \rightarrow 4d^1P_1$ X-ray laser transitions, we calculated by the RPTMP method with corresponding experimental values, shown in Figure 3, exhibits a deviation of $\leq 1\%$ in the range $Z = 37-46$. For $Z \geq 48$ Å, our results are identical to experimental data with an accuracy of several units in the fourth significant digit.

Table 3: Energy levels (10^3 cm^{-1}) of W XLVII. Comparison of present calculations with experimental data [23, 24] and with calculations by GRASP92 [25]

Configuration	Term	Experiment	Present Work	GRASP92
$3p^63d^{10}$	1S_0	0.0	0.0	0.0
$3p^63d^94s$	$(5/2,1/2)$	12601.5	12600.1	
		12616.44	12615.2	12591.1
$3p^63d^94s$	$(3/2,1/2)$	13138.66	13137.8	13110.8
		13148.2	13147.4	13120.7
$3p^63d^94p$	$(5/2,1/2)$	13379.05	13357.5	
		13388.20	13366.3	
$3p^63d^94p$	$(3/2,1/2)$	13916.27	13894.8	
		13940.6	13922.4	13930.6
$3p^63d^94p$	$(5/2,3/2)$	14229.0	14234.9	14221.0
$3p^63d^94p$	$(3/2,3/2)$	14751.0	14756.2	14741.1
$3p^63d^94d$	$(3/2,3/2)$		15935.9	15924.2
$3p^63d^94d$	$(5/2,5/2)$	15556.1	15561.3	15550.2
		15610.2	15614.9	15605.0

$3p^53d^{10}4s$	(3/2,1/2)		16247.0	16258.9	
$3p^53d^94d$	(3/2,3/2)		16256.2	16284.7	16282.9
$3p^53d^94f$	(5/2,7/2)		17045.9	17042.2	17030.6
$3p^53d^94f$	(3/2,5/2)		17574.7 17580.3*	17586.5	17585.6
$3p^53d^{10}4s$	(1/2,1/2)		[18727]	18726.4	18724.4
$3p^53d^{10}4d$	(3/2,3/2)		19044.4	19041.8	19057.5
$3p^53d^{10}4d$	(3/2,5/2)		19244.5	19234.8	19244.1
$3p^53d^{10}4f$	(3/2,7/2)		20589.0	20600.1	20613.8
$3p^53d^{10}4d$	(1/2,3/2)		21561.0	21547.0	21614.6

Data from [24]

Two values of Z are exceptions: (i) the calculation instability point at $Z = 42$ and (ii) the point $Z = 49$ where the $3d_{3/2}4f_{5/2}$ [$J=1$] and $3p_{3/2}4s_{1/2}$ [$J=1$] states are probably incorrectly identified in the calculation by the MCDF method in [6].

Table 4: Wavelengths (λ_{las} , Å) of the $3d_{3/2}4f_{5/2}$ (1P_1) – $3d_{3/2}4d_{3/2}$ (1P_1) SPP laser transitions in Ni-like sequence calculated by RPTMP

Z	λ_{las}
50	134.08
51	128.12
52	122.54
53	117.39
54	112.66
55	108.36
56	104.295
57	100.51
58	96.98
59	93.68
60	90.57
61	87.65
62	84.89
63	82.28
64	79.81
65	77.47
66	75.23
67	73.08
68	71.06
69	69.11
70	67.25
71	65.47
72	63.75
73	62.10
74	60.51
75	58.97
76	57.48
77	56.04
78	54.64
79	53.23

Ref

6. Nilsen J., Dunn J., Osterheld A.L., Li Yu 1999 Lasing on the self-photopumped nickel-like $4f^1P_1 - 4d^1P_1$ x-ray transition. *Phys. Rev. A* **60** R2677-80

We estimated the accuracy of the calculation of the energies of the upper and lower working states for high Z using experimental measurements of various studies. As an example, we compare the experimental energies for $Z = 74$ (W^{46+}) obtained using the Super EBIT (electron beam ion trap) [23-24], presented in Table 1. There are also listed the theoretical results calculated using the MCDF method called the Grasp92 [25]. Here we do not present earlier calculations of other authors. We also note the impossible comparison to the other calculations [26] in view of the level identification entanglement in this paper.

Good agreement between experimental and theoretical results for the energy levels in Table 3 may be noted: the maximum deviation is two units in the fourth significant digit. For the problem under study, it is important to ascertain the high accuracy of the calculation of the upper and lower working levels. For the experimental energy of the $3d_{3/2}4f_{5/2}$ [$J=1$] level, Table 3 gives two values: one obtained in the experiments [23] and the other later [24], respectively. The difference with our calculation is 6 units in the fifth significant digit. We did not find the experimental energy of the $3d_{3/2}4d_{3/2}$ [$J=1$] lower working level for high Z in the literature. The energies of two other states of the $3d4d$ configuration with $J = 1, 2$, given in Table 1 also agree with high accuracy, which indirectly confirms the calculation reliability.

Wavelengths of the $3d_{3/2}4f_{5/2}$ (1P_1) – $3d_{3/2}4d_{3/2}$ (1P_1) SPP laser transitions in Ni-like sequence calculated by RPTMP are listed in Table 4. The data on λ_{las} (see Table 4) are obtained *a priori*, no fittings were used. The error can be several units in the fourth significant digit. The precision wavelengths of laser transitions are necessary, in particular, to determine ions in which intense laser emission is possible at wavelength for which multilayer mirrors (MM) with high reflectance are developed.

IV. CONCLUSION

It is generally accepted that the energy levels of atomic system/multicharged ion are identified unambiguously. It means that atomic energy values are practically independent on plasma sources. Present studies of the irregularities in energy sequences led to a theoretical observation of an extraordinary phenomenon; it could be called “instability of the multicharged ion state”. The calculations directly indicates the ion Mo^{14+} (Ni-like state of Mo) in which the $3d_{3/2}4d_{3/2}$ [$J=1$] level energy defined in typical laboratory source might significantly differs from that defined in a source of very small ion density. The ultra high vacuum is maintained in EBITs (electron beam ion trap) apparatus. Thereby EBITs are used to investigate the fundamental properties of highly charged ions.

The crossing region of each working level with another level is characterized by their strong effect on each other, which can cause strong instability of the energy structure in the crossing region. In such regions, jumps in functions of energy levels and probabilities of radiative transition on Z are possible (see Figures 7a and 7b). From this, the conclusion about the possible incorrect identification of levels in their crossing regions follows.

The SPP XRL can be very sensitive to external fields. It is implied that even an insignificant change in the plasma density can affect the emission spectrum. An indirect confirmation of this can be the remarkable phenomenon (see Fig. 4) where a rapid increase in the contribution of the $3d_{5/2}4d_{3/2}$ [$J=1$] level to the composition of the lower working level is demonstrated. In the interval $Z = 40-42$, the contribution of this level increases by five orders of magnitude. A similar pattern is observed in Fig. 6 where the contribution of $3p_{3/2}4s_{1/2}$ [$J=1$] also rapidly increases to $Z = 49$, where this level strongly

interacts with the upper working level. In this case, the oscillator strength is transferred from the upper working level to the $3p_{3/2}4s_{1/2} [J=1]$ level.

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On The Applications of Transmuted Inverted Weibull Distribution

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Keywords: moments, bathtub failure rate, shape parameters.

GJSFR-F Classification: MSC 2010: 97K80



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I. INTRODUCTION

The inverted Weibull distribution is one of the most popular probability distribution to analyze the life time data with some monotone failure rates. Ref. [11] explained the flexibility of the three parameters inverted Weibull distribution and its interested properties. Ref. [1] studied the properties of the inverted Weibull distribution and its application to failure data. Ref. [2] introduced the exponentiated Weibull distribution as generalization of the standard Weibull distribution and applied the new distribution as a suitable model to the bus-motor failure time data. Ref. [3] reviewed the exponentiated Weibull distribution with new measures. Ref. [4] studied the properties of transmuted Weibull distribution. Ref. [6] proposed and studied the various structural properties of the transmuted Rayleigh distribution. Ref. [7] introduced the transmuted modified Weibull distribution. Transmuted Lomax distribution is presented by Ref. [8]. Ref. [9] introduces transmuted Pareto distribution. Transmuted Generalized Linear Exponential Distribution introduced by Ref. [10].

In this article we use transmutation map approach suggested by Shaw *et al.* [5] to define a new model which generalizes the inverted Weibull model. We will call the generalized distribution as the transmuted inverted Weibull distribution. According to the Quadratic Rank Transmutation Map (QRTM), approach the cumulative distribution function(cdf) satisfy the relationship

$$F(x) = (1 + \lambda)G(x) - \lambda[G(x)]^2 | \lambda | \leq 1 \tag{1}$$

The probability density function (*PDF*) is given by

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$$f(x) = \frac{dF}{dx} = [(1 + \lambda) - 2\lambda G(x)]g(x) \tag{2}$$

Where $g(x)$ is the *pdf* of the base line distribution.

II. TRANSMUTED INVERTED WEIBULL DISTRIBUTION (TIWD)

We say that the random variable X has a standard inverted Weibull distribution (IWD) if its distribution function takes the following form:

$$G(x) = e^{-x^{-\beta}} \quad x > 0, \beta > 0 \tag{3}$$

The pdf of Inverted Weibull distribution is given by

$$g(x) = \beta x^{-\beta} e^{-x^{-\beta}} \tag{4}$$

Now using (3) and (4) we have the cdf of a (TIWD) given by

$$F(x) = e^{-x^{-\beta}} [(1 + \lambda) - \lambda e^{-x^{-\beta}}] \tag{5}$$

Where $|\lambda| \leq 1$ is simply the transmutation parameter of the distribution function of the standard inverted Weibull distribution (IWD). Here λ and β are the shape parameters. Therefore, the probability density function is:

$$f(x) = \beta x^{-(\beta+1)} e^{-x^{-\beta}} [1 + \lambda - 2\lambda e^{-x^{-\beta}}] \tag{6}$$

Note that for $\lambda = 0$, we have the pdf of a standard inverted Weibull distribution. Figure 1 illustrates some of the possible shapes of the density function of (TIWD) for selected parameters.

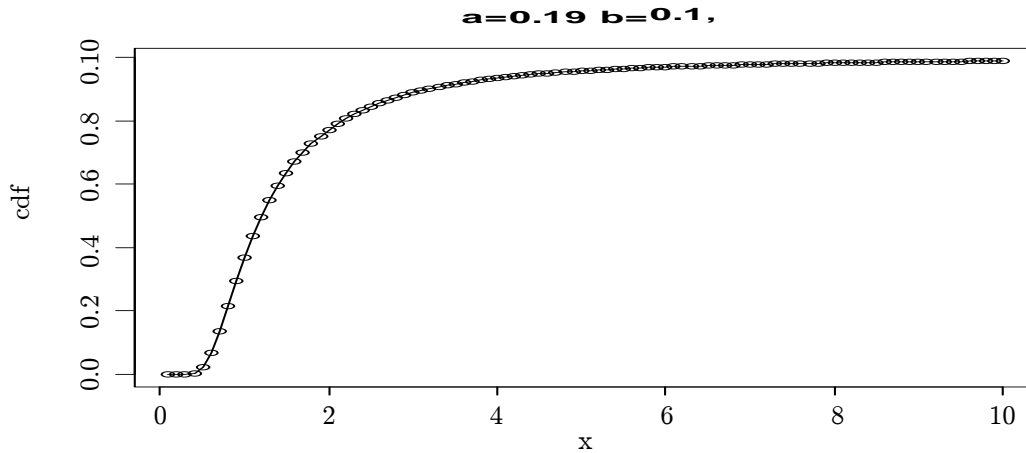


Fig. 1: The graph of the cdf of TIWD

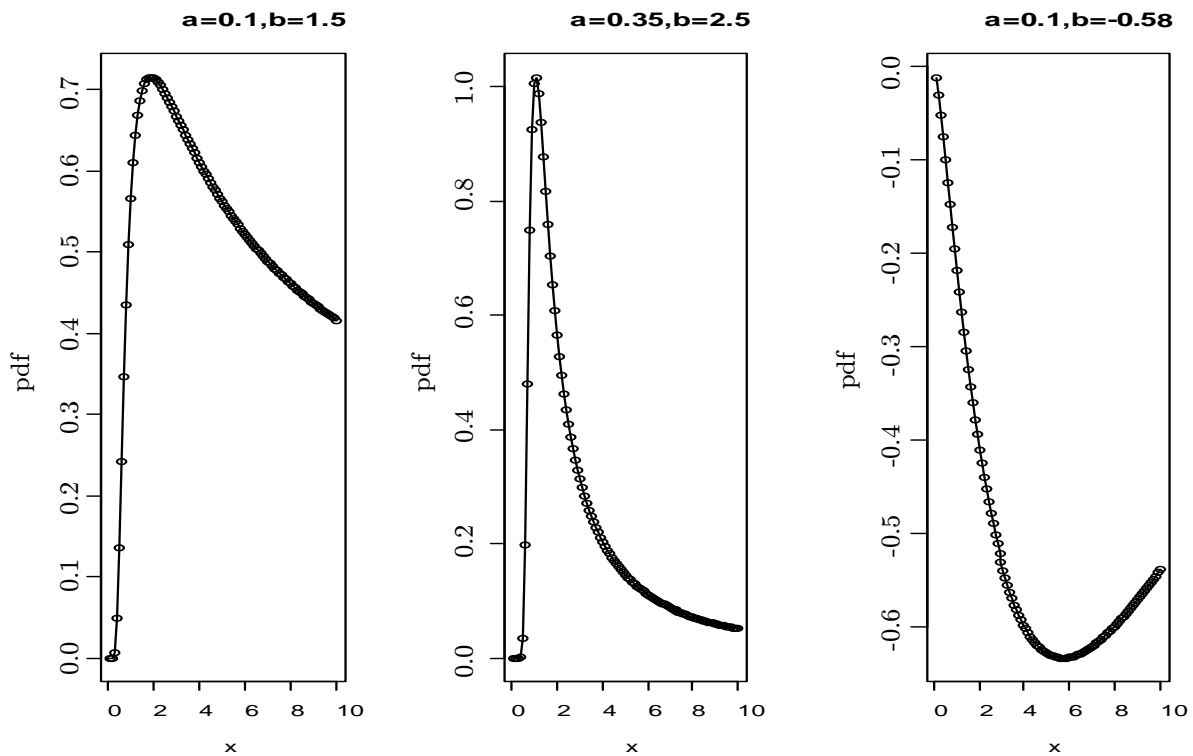


Fig. 2: The graph of the pdf of TIWD

III. MOMENTS, MEAN, VARIANCE, MEDIAN AND QUANTILE OF (TIWD)

In this section we shall present the moments and quantiles for the (TIWD). The k^{th} order moments, for $< \beta$, of (TIWD) can be obtained as follows for a random variable X ,

$$E(X)^k = \int_{-\infty}^{\infty} x^k f(x) dx \tag{7}$$

Putting eq. (6) in eq. (7), we have

$$E(X)^k = \beta \int_{-\infty}^{\infty} x^k x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] dx \tag{8}$$

Expanding eq. (8) and splitting it into three, we obtain

$$P_1 = \beta \int_{-\infty}^{\infty} x^k x^{-(\beta+1)} e^{-x^{-\beta}} dx \tag{9}$$

$$P_2 = \lambda \beta \int_{-\infty}^{\infty} x^k x^{-(\beta+1)} e^{-x^{-\beta}} dx \tag{10}$$

$$P_3 = -2\lambda \beta \int_{-\infty}^{\infty} x^k x^{-(\beta+1)} e^{-2x^{-\beta}} dx \tag{11}$$

If we let $u = x^{-\beta}$ in eq. (9) and eq. (10) and also let $u = 2x^{-\beta}$ in eq. (11), then we have

$$P_1 = -\Gamma\left(1 - \frac{k}{\beta}\right) \tag{12}$$

$$P_2 = -\lambda\Gamma\left(1 - \frac{k}{\beta}\right) \tag{13}$$

$$P_3 = \left(\frac{1}{2}\right)^{\frac{k}{\beta}} \lambda\Gamma\left(1 - \frac{k}{\beta}\right) \tag{14}$$

It should be noted that $\beta < k$

Then combining eq.(12), eq.(13) and eq.(14) we obtain the k^{th} moment of (TIWD), we have

$$\mu_k = E(X)^k = \left(1 - \frac{k}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{k}{\beta}} - 1 \right] - 1 \right\} \tag{15}$$

Using eq. (15), we obtain the 1st, 2nd, 3rd, and 4th moment for $k = 1, 2, 3, 4$

$$\mu_1 = \Gamma\left(1 - \frac{1}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{1}{\beta}} - 1 \right] - 1 \right\} \tag{16}$$

$$\mu_2 = \Gamma\left(1 - \frac{2}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{2}{\beta}} - 1 \right] - 1 \right\} \tag{17}$$

$$\mu_3 = \Gamma\left(1 - \frac{3}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{3}{\beta}} - 1 \right] - 1 \right\} \tag{18}$$

$$\mu_4 = \Gamma\left(1 - \frac{4}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{4}{\beta}} - 1 \right] - 1 \right\} \tag{19}$$

The mean of (TIWD) is the first moment about the origin (μ_1) which corresponds to eq. (16)

And the variance of (TIWD) can be obtained using the relation

$$V(X) = \mu_2 - (\mu_1)^2 \tag{20}$$

Inserting eq. (16) and eq. (17) in eq. (20) we have

$$V(X) = \Gamma\left(1 - \frac{2}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{2}{\beta}} - 1 \right] - 1 \right\} - \left[\Gamma\left(1 - \frac{1}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{1}{\beta}} - 1 \right] - 1 \right\} \right]^2 \tag{21}$$

The quantile function for the (TIWD) is given as,

$$x_q = \left[-\ln \frac{\lambda - \sqrt{\lambda(\lambda + 4q)}}{2\lambda} \right]^{\frac{1}{\beta}} \tag{22}$$

The lower quartile, median and the upper quartile of the (TIWD) can be obtained by letting $q = 0.25, q = 0.5$ and $q = 0.75$ respectively in eq. (22).

Table 1: Moments based values for TIWD

β	λ	$\hat{\mu}_1$	$\hat{\mu}_2$	$\hat{\mu}_3$	$\hat{\mu}_4$
-1.0	-3.0	0.50	2.50	9.75	43.50
-1.0	-3.5	0.75	3.25	12.30	54.75
-1.0	-4.0	1.00	4.00	15.00	66.00
-1.0	-4.5	1.25	4.75	17.63	386.25

Table 2: Moments based measures of the TIWD

β	λ	Mean	Variance	CV	CS	CK
-1.0	-3.0	0.50	2.25	3.17	2.47	6.96
-1.0	-3.5	0.75	2.69	2.19	2.10	5.18
-1.0	-4.0	1.00	3.00	1.73	1.89	4.12
-1.0	-4.5	1.25	3.19	1.43	1.70	17.12

IV. RELIABILITY ANALYSIS

The survival function, also known as the reliability function in engineering, is the characteristic of an explanatory variable that maps a set of events, usually associated with mortality or failure of some certain mechanical wearing system with time. It is the conditional probability that the system will survive beyond a specified time. The (TIWD) can be a useful model to characterize failure time of a given system because of the analytical structure. The reliability function $R(t)$, which is the probability of an item not failing prior to time t , is defined by $R(t) = 1 - F(t)$. The reliability function of a (TIWD) is given by

The reliability function define as, $R(x) = 1 - F(x)$, for (TIWD) is given by:

$$R(x) = 1 - e^{-x^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x^{-\beta}} \right] \quad (23)$$

The other characteristic of interest of a random variable is the hazard rate function also known as instantaneous failure rate defined by

$$h(x) = \frac{f(x)}{1-F(x)} \quad (24)$$

Is an important quantity characterizing life phenomenon. It can be loosely interpreted as the conditional probability of failure, given it has survived to the time t : The hazard rate function for a (TIWD) is given by

$$h(x) = \frac{\beta x^{-(\beta+1)} e^{-x^{-\beta}} [1 + \lambda - 2\lambda e^{-x^{-\beta}}]}{1 - e^{-x^{-\beta}} [(1 + \lambda) - \lambda e^{-x^{-\beta}}]} \quad (25)$$

For $\lambda = 0$, it represents the hazard of the standard inverted Weibull distribution. The graph (fig.3) drawn below depict the graph of the hazard rate function for TIWD for various values of the parameters.

Recently, it is observed that the reversed hazard function plays an important role in the reliability analysis; see Gupta and Gupta (2007). The reversed hazard function of the (TIWD) is given as

$$R(x) = \beta x^{-(\beta+1)} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \quad (26)$$

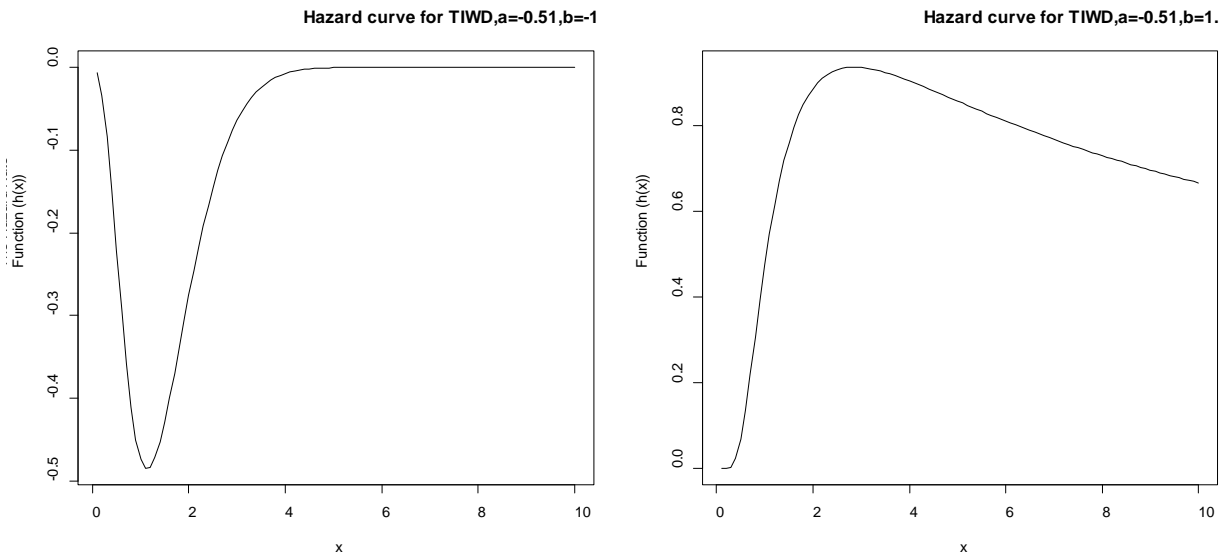


Fig. 3: The graph of hazard rate function for TIWD

V. MOMENT GENERATING FUNCTION OF (TIWD)

The moment generating function of a random variable x is defined by

$$M_t(x) = \int_{-\infty}^{\infty} e^{tx} f(x) dx \tag{27}$$

The above expression can further be simplify as

$$M_t(x) = \sum_{k=0}^{\infty} \frac{t^k}{k!} \int_{-\infty}^{\infty} x^k f(x) dx \tag{28}$$

Since,

$$e^{tx} = \sum_{r=0}^{\infty} \frac{t^k x^k}{k!} \tag{29}$$

Inserting eq. (15) in eq. (28) we have

$$M_t(x) = \sum_{k=0}^{\infty} \frac{t^k}{k!} \left(1 - \frac{k}{\beta}\right) \left\{ \lambda \left[\left(\frac{1}{2}\right)^{\frac{k}{\beta}} - 1 \right] - 1 \right\} \tag{30}$$

The above expression is the moment generating function of (TIWD).

VI. ORDER STATISTICS

Order statistics make their appearance in many areas of statistical theory and practice. We know that if $X_{(1)}, X_{(2)}, \dots, X_{(n)}$ denotes the order statistics of a random sample X_1, X_2, \dots, X_n from a continuous population with cdf $F_X(X)$ and pdf $f_X(x)$.

Then the pdf of $X_{(j)}$ is given by

$$f_{X_{(j)}} = \frac{n!}{(j-1)!(n-j)!} f_X(x) [F_X(x)]^{j-1} [1 - F_X(x)]^{n-j} \tag{31}$$

For $j = 1, 2, 3, \dots, n$

We have from (5) and (6) the pdf of the j^{th} order inverted Weibull random variable X_j given by

$$f_{X(j)} = \frac{n!}{(j-1)!(n-j)!} \beta x^{-\beta} e^{-x^{-\beta}} \left[e^{-x^{-\beta}} \right]^{j-1} \left[1 - e^{-x^{-\beta}} \right]^{n-j} \quad (32)$$

If we consider the series expansion,

$$(1 - z)^m = \sum_{j=0}^{\infty} (-1)^i \binom{m}{i} z^i \quad (33)$$

Applying eq. (33) in eq. (31) will yield

$$f_{X(j)} = \frac{n!}{(j-1)!(n-j)!} \beta x^{-\beta} \sum_{i=0}^{\infty} (-1)^i \binom{n-j}{i} \left[e^{-x^{-\beta}} \right]^{i+j} \quad (34)$$

Therefore, the pdf of the n^{th} order inverted Weibull random variable X_n is given by

$$f_{X(n)} = n! \beta x^{-\beta} \left[e^{-x^{-\beta}} \right]^n \quad (35)$$

Now we provide the distribution of the order statistics for transmuted inverted Weibull random variable. The pdf of the j^{th} order statistic for the transmuted inverted Weibull random variable is given by

$$f_{X(j)} = \frac{n!}{(j-1)!(n-j)!} \beta x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \left[e^{-x^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x^{-\beta}} \right] \right]^{j-1} \left[1 - e^{-x^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x^{-\beta}} \right] \right]^{n-j}$$

Using the relation in eq. (32) the above expression can be simplified as

$$f_{X(j)} = \frac{n!}{(j-1)!(n-j)!} \beta x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \sum_{j=0}^{\infty} (-1)^i \binom{n-j}{i} \left[e^{-x^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x^{-\beta}} \right] \right]^{i+j-1} \quad (36)$$

Therefore the pdf of the largest order statistic $X_{(n)}$ for the transmuted inverted Weibull random variable is given by

$$f_{X(n)} = n! \beta x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \left[e^{-x^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x^{-\beta}} \right] \right]^{n-1} \quad (37)$$

And for the first order we have

$$f_{X(1)} = \beta x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \quad (38)$$

VII. ENTROPY

The entropy of a random variable X with probability density $f(x)$ is a measure of variation of the uncertainty. A large value of entropy indicates the greater uncertainty in the data. The Renyi, A. (1961) introduced the Renyi entropy defined as

$$I_R(\delta) = \frac{1}{1-\delta} \log \left\{ \int_0^\infty f(x)^\delta dx \right\} \tag{39}$$

Where $\delta > 0$ and $\delta \neq 1$. the integral in $I_R(\delta)$ of the TIWD($x; \lambda, \beta$) can be define as

$$\int_0^\infty f(x)^\delta dx = \int_0^\infty \left\{ x^{-(\beta+1)} e^{-x^{-\beta}} [1 + \lambda - 2\lambda e^{-x^{-\beta}}] \right\}^\delta dx \tag{40}$$

This can be simplify as

$$\begin{aligned} \beta^\delta \int_0^\infty x^{-\delta(\beta+1)} e^{-\delta x^{-\beta}} [1 - \lambda(2e^{-x^{-\beta}} - 1)]^\delta dx \\ = \beta^\delta \sum_{k=1}^\infty (-1)^k \binom{\delta}{k} \lambda^k \int_0^\infty x^{-\delta(\beta+1)} e^{-\delta x^{-\beta}} (2e^{-x^{-\beta}} - 1)^k dx \end{aligned} \tag{41}$$

But $(2e^{-x^{-\beta}} - 1)^k = (-1)^k (1 - 2e^{-x^{-\beta}})^k$, therefore the RHS equation (41) can be simplify as

$$\beta^\delta \sum_{k=1}^\infty \sum_{l=1}^k (-1)^{2k} (-1)^l \binom{\delta}{k} \lambda^k \binom{k}{l} 2^l \int_0^\infty x^{-\delta(\beta+1)} e^{-(\delta+l)x^{-\beta}} dx \tag{42}$$

Letting $P = x^{-\beta(\delta+l)}$, then $x = \frac{-1}{P^{\frac{1}{\beta(\delta+l)}}}$ and $dx = -\frac{P^{-\frac{1}{\beta(\delta+l)}-1}}{\beta(\delta+l)} dP$

Then substituting in the above integral function we have

$$-\frac{1}{\beta(\delta+l)} \int_0^\infty P^{\frac{\delta-1-\beta l}{\beta(\delta+l)}} e^{-P} dP = -\frac{1}{\beta(\delta+l)} \Gamma\left(\frac{\delta-1-\beta l}{\beta(\delta+l)} + 1\right) \tag{43}$$

Then substituting equation (43), (42) in (39), we have the entropy of TIWD as

$$I_R(\delta) = \frac{-1}{1-\delta} \log \left\{ \beta^\delta \sum_{k=1}^\infty \sum_{l=1}^k (-1)^{2k} (-1)^l \binom{\delta}{k} \lambda^k \binom{k}{l} 2^l \frac{1}{\beta(\delta+l)} \Gamma\left(\frac{\delta-1-\beta l}{\beta(\delta+l)} + 1\right) \right\} \tag{44}$$

VIII. PARAMETERS ESTIMATION

In this section, we discuss the maximum likelihood estimators of the two-parameter transmuted inverted Weibull distribution and their fisher information matrix as well as asymptotic confidence intervals.

a) Maximum likelihood estimators and fisher information matrix

If x_1, x_2, \dots, x_n is a random sample from transmuted inverted Weibull distribution given by (6), then the Likelihood function (L) becomes:

$$L = \prod_{i=1}^n f(x_i, \lambda, \beta) \tag{45}$$

By substituting from equation (6) into Equation (39), we get

$$L = \prod_{i=1}^n \beta x^{-(\beta+1)} e^{-x^{-\beta}} \left[1 + \lambda - 2\lambda e^{-x^{-\beta}} \right] \tag{46}$$

Then the log – likelihood function becomes

$$l = \ln(\beta) - (\beta + 1) \sum_{i=1}^n \ln(x_i) - \sum_{i=1}^n x_i^{-\beta} + \sum_{i=1}^n \ln(1 + \lambda - 2\lambda e^{-x_i^{-\beta}}) \tag{47}$$

And the score vector is given as

$$\frac{dl}{d\beta} = \frac{n}{\beta} - \sum_{i=1}^n \ln(x_i) + \sum_{i=1}^n x_i^{-\beta} \ln(x_i) + 2\lambda \sum_{i=1}^n \frac{x_i^{-\beta} e^{-x_i^{-\beta}}}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})} \tag{48}$$

$$\frac{dl}{d\lambda} = \sum_{i=1}^n \frac{(1 - 2e^{-x_i^{-\beta}})}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})} \tag{49}$$

Therefore, the MLEs of λ and β which maximize equation (47) must satisfy the nonlinear normal equations given by:

$$\frac{dl}{d\beta} = \frac{n}{\beta} - \sum_{i=1}^n \ln(x_i) + \sum_{i=1}^n x_i^{-\beta} \ln(x_i) + 2\lambda \sum_{i=1}^n \frac{x_i^{-\beta} e^{-x_i^{-\beta}}}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})} = 0 \tag{50}$$

$$\frac{dl}{d\lambda} = \sum_{i=1}^n \frac{(1 - 2e^{-x_i^{-\beta}})}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})} = 0 \tag{51}$$

The maximum likelihood estimator $\hat{\theta} = (\hat{\lambda}, \hat{\beta})'$ of $\theta = (\lambda, \beta)'$ is obtained by setting the score vector to zero and solving the nonlinear system of equations. It is usually more convenient to use nonlinear optimization algorithms such as quasi-Newton algorithm to numerically maximize the log-likelihood function given in (47).

b) Least square Estimates

Let $x_{(1)}, x_{(2)}, \dots, x_{(n)}$ be the ordered sample of size n from TIWD. Then the expectation of the empirical cumulative distribution function is defined as

$$E[F(X_{(i)})] = \frac{i}{n+1}; \quad i = 1, 2, 3, \dots, n \tag{52}$$

Then the least square estimates of $\hat{\lambda}_{LS}$ and $\hat{\beta}_{LS}$ of λ and β are obtained by minimizing Z giving as

$$Z(\lambda, \beta) = \sum_{i=1}^n \left(e^{-x_i^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x_i^{-\beta}} \right] - \frac{i}{n + 1} \right)^2 \tag{53}$$

Therefore the $\hat{\lambda}_{LS}$ and $\hat{\beta}_{LS}$ of λ and β can be obtained as the solution of the following equations

$$\frac{\delta Z(\lambda, \beta)}{\delta \lambda} = \sum_{i=1}^n - \left\{ e^{-x_i^{-\beta}} \right\}^2 \left(e^{-x_i^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x_i^{-\beta}} \right] - \frac{i}{n + 1} \right) = 0 \tag{54}$$

$$\frac{\delta Z(\lambda, \beta)}{\delta \beta} = \sum_{i=1}^n \left\{ \beta x_i^{-(\beta+1)} e^{-x_i^{-\beta}} (1 + \lambda) \right\} \left(e^{-x_i^{-\beta}} \left[(1 + \lambda) - \lambda e^{-x_i^{-\beta}} \right] - \frac{i}{n + 1} \right) = 0 \tag{55}$$

IX. ASYMPTOTIC CONFIDENCE BOUNDS

In this section, we derive the asymptotic confidence intervals of these parameters when $\lambda > 0$ and $\beta > 0$ and as the MLEs of the unknown parameters λ and β cannot be obtained in closed forms, by using variance covariance matrix I_0^{-1} see Lawless(2003), where I_0^{-1} is the inverse of the observed information matrix

$$I_0^{-1} = \begin{bmatrix} \frac{\partial^2 l}{\partial \lambda^2} & \frac{\partial^2 l}{\partial \lambda \partial \beta} \\ \frac{\partial^2 l}{\partial \lambda \partial \beta} & \frac{\partial^2 l}{\partial \beta^2} \end{bmatrix} \tag{56}$$

Thus

$$I_0^{-1} = \begin{bmatrix} var \hat{\lambda} & cov(\hat{\lambda}, \hat{\beta}) \\ cov(\hat{\lambda}, \hat{\beta}) & var \hat{\beta} \end{bmatrix} \tag{57}$$

The derivatives in I_0^{-1} are given as follows:

$$\frac{d^2 l}{d \lambda^2} = - \sum_{i=1}^n \left(\frac{1 - 2e^{-x_i^{-\beta}}}{1 + \lambda - 2\lambda e^{-x_i^{-\beta}}} \right)^2 \tag{58}$$

$$\frac{d^2 l}{d \beta^2} = - \frac{n}{\beta} - \sum_{i=1}^n x_i^{-\beta} (\ln x)^2 + \sum_{i=1}^n \frac{x_i^{-\beta} \ln x e^{-x_i^{-\beta}} [(x_i^{-\beta} - 1) - 2x_i^{-\beta} e^{-x_i^{-\beta}}]}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})^2} \tag{59}$$

$$\frac{d^2 l}{d \lambda d \beta} = \sum_{i=1}^n \frac{2x_i^{-\beta} \ln x e^{-x_i^{-\beta}} [(1 + \lambda - 2\lambda e^{-x_i^{-\beta}}) - \lambda (1 - 2e^{-x_i^{-\beta}})]}{(1 + \lambda - 2\lambda e^{-x_i^{-\beta}})^2} \tag{60}$$

We can derive the $(1 - \delta)100\%$ confidence intervals of the parameters λ and β by using variance covariance matrix as in the following forms

$$\hat{\lambda} \pm Z_{\frac{\delta}{2}} \sqrt{var \hat{\lambda}} \quad , \quad \hat{\beta} \pm Z_{\frac{\delta}{2}} \sqrt{var \hat{\beta}}$$

Where $Z_{\frac{\delta}{2}}$ is the upper $\left(\frac{\delta}{2}\right)^{th}$ percentile of the standard normal distribution.

X. APPLICATIONS

In this section, we use two real data sets to show that the TIWD can be a better model than one based on the IWD and the exponentiated inverted Weibull distribution (EIWD). In the first application, we consider a data set of the tensile strength of 100 observation of carbon fibers, the data was obtained from see Ref.[12]. These data are: 3.7, 2.74, 2.73, 2.5, 3.6, 3.11, 3.27, 2.87, 1.47, 3.11,4.42, 2.41, 3.19, 3.22, 1.69, 3.28, 3.09, 1.87, 3.15, 4.9, 3.75, 2.43, 2.95, 2.97, 3.39, 2.96, 2.53,2.67, 2.93, 3.22, 3.39, 2.81, 4.2, 3.33, 2.55, 3.31, 3.31, 2.85, 2.56, 3.56, 3.15, 2.35, 2.55, 2.59,2.38, 2.81, 2.77, 2.17, 2.83, 1.92, 1.41, 3.68, 2.97, 1.36, 0.98, 2.76, 4.91, 3.68, 1.84, 1.59,3.19,1.57, 0.81, 5.56, 1.73, 1.59, 2, 1.22, 1.12, 1.71, 2.17, 1.17, 5.08, 2.48, 1.18, 3.51, 2.17, 1.69,1.25, 4.38, 1.84, 0.39, 3.68, 2.48, 0.85, 1.61, 2.79, 4.7, 2.03, 1.8, 1.57, 1.08, 2.03, 1.61, 2.12,1.89, 2.88,

Ref

12. Andrews, D. F. & Herzberg, A. M. (1985), Data: A Collection of Problems from Many Fields for the Student and Research Worker, Springer Series in Statistics, New York.

2.82, 2.05, 3.65. Table 3.0 and Table 6.0 gives the exploratory data analysis of the data considered, Table 4.0 and Table 7.0 gives the maximum likelihood estimates of the parameters with their standard error in parenthesis and Table 5.0 and Table 8.0 gives the criteria for comparison. Fig. 4 and fig. 5 represents the empirical density and the cumulative density of the data considered.

Table 3: Descriptive Statistics on Breaking stress of Carbon fibres

Min	Lower quartile	Median	Upper quartile	Mean	Max.	Skewness	Kurtosis	Range
0.390	1.840	2.700	3.220	2.640	5.560	0.37378	0.17287	5.17

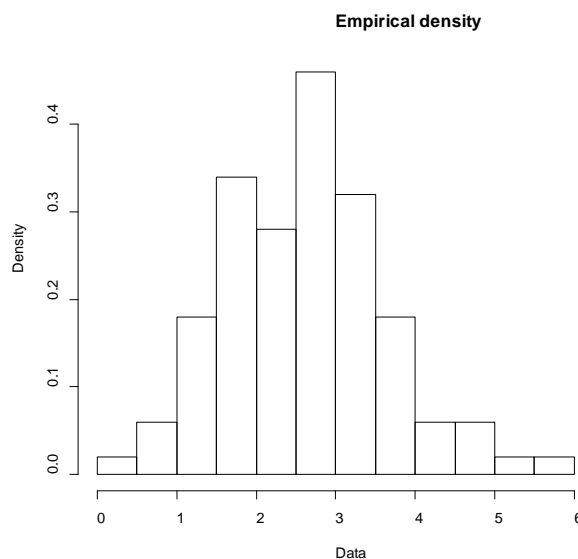


Fig. 4: The graph of the Empirical density and the cumulative distribution function of the carbon data

Table 4: Estimated parameters of the TIWD, EIWD and IWD

Mode I	Estimates		$l(\hat{\theta})$
TIWD (λ, β)	-0.8965 (0.0908)	3.1175 (0.2668)	-44.571
EIWD (θ, β)	0.2485 (1.9685)	0.2344 (2.8876)	-46.853
IWD (β)	- (-)	2.806 (2.723)	-58.482

Table 5: Measures of Goodness of Fit

Mode I	$K - S$	AD	W	AIC	BIC	HQIC	CAIC
TIWD	0.4591	6.3175	1.1915	93.142	97.428	94.827	93.827
EIWD	0.5173	5.7414	1.0727	97.907	101.993	99.392	97.907
IWD	0.4359	6.0615	1.1388	118.963	121.107	119.806	119.029

Also, we consider a data set of the life of fatigue fracture of Kevlar 373/epoxy that are subject to constant pressure at the 90% stress level until all had failed, so we have complete data with the exact times of failure. This data are:

0.0251, 0.0886, 0.0891, 0.2501, 0.3113, 0.3451, 0.4763, 0.5650, 0.5671, 0.6566, 0.6748, 0.6751, 0.6753, 0.7696, 0.8375, 0.8391, 0.8425, 0.8645, 0.8851, 0.9113, 0.9120, 0.9836, 1.0483, 1.0596, 1.0773, 1.1733, 1.2570, 1.2766, 1.2985, 1.3211, 1.3503, 1.3551, 1.4595, 1.4880, 1.5728, 1.5733, 1.7083, 1.7263, 1.7460, 1.7630, 1.7746, 1.8275, 1.8375, 1.8503, 1.8808, 1.8878, 1.8881, 1.9316, 1.9558, 2.0048, 2.0408, 2.0903, 2.1093, 2.1330, 2.2100, 2.2460, 2.2878, 2.3203, 2.3470, 2.3513, 2.4951, 2.5260, 2.9911, 3.0256, 3.2678, 3.4045, 3.4846, 3.7433, 3.7455, 3.9143, 4.8073, 5.4005, 5.4435, 5.5295, 6.5541, 9.0960. For previous studies with these data sets see Andrews and Herzberg [12]

Table 6: Summary of data on fatigue fracture of Kevlar 373/epoxy at 90 % stress level

Min	Lower quartile	Median	Upper quartile	Mean	Max.	Variance	Skewness	Kurtosis	Range
0.0251	0.09048	1.7361	2.2960	1.9590	9.0960	2.4774	1.9406	8.1608	9.0709

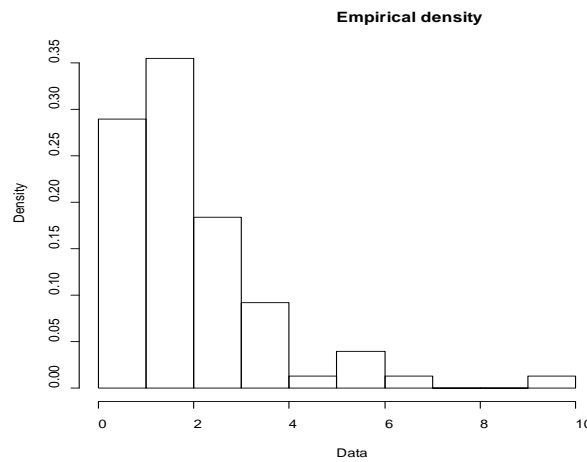


Fig. 7: The graph of the Empirical density and the cumulative distribution function of the Kevlar 373/epoxy data

Table 7: Estimated parameters of the TIWD, EIWD and IWD

Mode I	Estimates		$l(\hat{\theta})$
TIWD (λ, β)	0.7074 (0.3994)	0.6903 (0.0575)	-152.483
EIWD (θ, β)	0.8608 (0.1088)	0.7588 (0.0541)	-153.539
IWD (β)	- (-)	0.7322 (0.0474)	-154.278

Table 8: Measures of Goodness of Fit

Mode I	$K - S$	AD	W	AIC	BIC	$HQIC$	$CAIC$
TIWD	0.2440	4.9831	0.8506	308.967	313.128	310.829	308.967
EIWD	0.2290	5.9661	1.0351	311.078	315.740	312.941	311.243
IWD	0.2291	5.2691	0.9036	310.556	312.887	311.487	310.610

We employ the statistical tools for model comparison such as Kolmogorov-Smirnov (K-S) statistics, Anderson Darling statistic (AD), crammer von misses statistic

(W), Akaike information criterion (AIC), Consistent Akaike information criterion (CAIC), Hannan Quinine information criterion (HQIC) and Bayesian information criterion to choose the best possible model for the data sets among the competitive models. The selection criterion is that the lowest AIC, CAIC, BIC and HQIC correspond to the best fit model.

XI. CONCLUSION

Among the models considered the best model is the transmuted inverted Weibull distribution for the two data sets.

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A Little Note on the Twisted/Warped Product Metrics and the Hopf Conjecture

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GJSFR-F Classification: *MSC 2010: F3C20, F3C50*



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A Little Note on the Twisted/Warped Product Metrics and the Hopf Conjecture

Adama Thiandoum ^α, Athoumane Niang ^σ & Abdoulaye Sarr ^ρ

Abstract- This work defines some notions on the twisted, warped product metric on the manifold $\mathbb{S}^2 \times \mathbb{S}^2$ before proving that Hopf conjecture is true in the class of this metrics.

Keywords: twisted, warped product metrics, sectional curvature, hopf conjecture.

I. INTRODUCTION

Let g_0 be the riemannian metric induced by \mathbb{R}^6 on $M = \mathbb{S}^2 \times \mathbb{S}^2$ and let $T_p M$ denoted the tangent vector space of M at p . For any 2-plane $\sigma \subset T_p M$ spanned by two tangent vector fields, we define a function $K(\sigma)$ called the sectional curvature of σ . We will say that the riemannian manifold M has positive sectional curvature if for every point $p \in M$ the sectional curvature $K(\sigma)$ of every 2-plane $\sigma \subset T_p M$ is positive. An example of such manifolds are the n dimensional spheres \mathbb{S}^n with the metric induced by \mathbb{R}^{n+1} . In this case its sectional curvature is equal to 1 for any 2-plane $\sigma \subset T_p M$. In general the question of deciding if a given manifold admits a riemannian metric with positive sectional curvature is a difficult one. One of the Hopf conjecture can be stated as follows: The product manifold $\mathbb{S}^2 \times \mathbb{S}^2$ does not admit any riemannian metrics with strictly positive sectional curvature. For the relevance of this problem, we refer to the [4], [5] and [6].

A direct computation shows that when we endowed $\mathbb{S}^2 \times \mathbb{S}^2$ with the riemannian metric g_0 , then for any $(a, b) \in \mathbb{S}^2 \times \mathbb{S}^2$ the sectional curvature of a plane spanned by a vector of the form $(v, 0) \in T_{(a,b)}(\mathbb{S}^2 \times \mathbb{S}^2)$ and a vector of the form $(0, w) \in T_{(a,b)}(\mathbb{S}^2 \times \mathbb{S}^2)$, with $v, w \in \mathbb{R}^3$, is zero, we also found out that the sectional curvature for the planes $T_{(a,b)}\mathbb{S}^2 \times \mathbb{S}^2 \cap \mathbb{R}^3 \times \{0\}$ and $T_{(a,b)}\mathbb{S}^2 \times \mathbb{S}^2 \cap \{0\} \times \mathbb{R}^3$ is 1, for any other plane the sectional curvature is a number between 0 and 1 ([4]).

The notion of warped product manifolds was introduced by Bishop and O'Neil [7] for constructing manifolds of negative curvature. Later this notion has been extended to be twisted product manifolds [[9], [8]].

More precisely, let (M_1, g_1) and (M_2, g_2) be two-riemannian manifolds of dimension m_1 and m_2 (respectively) and let $\pi_1 : M_1 \times M_2 \mapsto M_1$ and $\pi_2 : M_1 \times M_2 \mapsto M_2$ be the canonical projections. Also let $f : M_1 \times M_2 \mapsto \mathbb{R}^+$ be a smooth function. Then the twisted product $M = M_1 \times_f M_2$ of the manifolds (M_1, g_1) and (M_2, g_2) with twisting

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function f , is defined to be the product manifold $M = M_1 \times M_2$ with the riemannian tensor $g = g_1 \oplus f^2 g_2$ given by $g = \pi_1^* g_1 + f^2 \pi_2^* g_2$. Moreover, if the function f only depends on the points of M_1 , that is $f : M_1 \mapsto \mathbb{R}^+$, then $M = M_1 \times_f M_2$ is called the warped product manifold of (M_1, g_1) and (M_2, g_2) with warping function f . In particular, if $f = 1$, then $M = M_1 \times_1 M_2$ is the product manifold of (M_1, g_1) and (M_2, g_2) with the product metric defined by $g = \pi_1^* g_1 + \pi_2^* g_2$.

Now, let $(\mathbb{S}^2 \times_f \mathbb{S}^2, g)$ be a twisted product manifold with twisting function f and let $h = \log(f)$. In this paper, we prove the following mains results.

Theorem 1.1. For any smooth function $h : \mathbb{S}^2 \times \mathbb{S}^2 \mapsto \mathbb{R}$, the twisted product manifold $(\mathbb{S}^2 \times \mathbb{S}^2, g)$ has no positive sectional curvature.

Corollary 1.1. For any smooth function $h : \mathbb{S}^2 \mapsto \mathbb{R}$, the warped product manifold $(\mathbb{S}^2 \times \mathbb{S}^2, g)$ has no positive sectional curvature.

II. PRELIMINARIES

Let M_1 and M_2 be two riemannian manifolds, and let $f > 0$ be smooth function on M_1 , the warped product $M = M_1 \times_f M_2$ is the product manifold $M_1 \times M_2$ furnished with the riemannian metric

$$g = \pi_1^* g_1 + (f \circ \pi_1)^2 \pi_2^* g_2, \tag{1}$$

where π_1 and π_2 are canonical projections of $M_1 \times M_2$ onto M_1 and M_2 , respectively. This notion has been extended to several forms. Let (M, g_1) and (M_2, g_2) be riemannian manifolds, $h : M_1 \times M_2 \mapsto \mathbb{R}$ a positive and smooth function, g a riemannian metric on the manifold $M = M_1 \times M_2$ and assume that the canonical foliation L_1 and L_2 intersects perpendicularly everywhere. Then g is the metric tensor of

- (1) a twisted product $M_1 \times_h M_2$ if only if L_1 is a totally geodesic foliation and L_2 is a totally umbilic foliation,
- (2) a warped product $M_1 \times_h M_2$ if only if L_1 is a totally geodesic foliation and L_2 is a spheric foliation,
- (3) a usual product of riemannian manifolds if only if L_1 and L_2 are totally geodesic foliations.

let (M, g_1) and (M_2, g_2) be riemannian manifolds with the Levi-Civita connections ∇^1 and ∇^2 , respectively, and let ∇ denote the Levi-Civita connection of the twisted product manifold $M_1 \times_f M_2$ of (M_1, g_1) and (M_2, g_2) with twisting function f . Also, let $h = \log(f)$ and let $\mathcal{L}(M_1)$ and $\mathcal{L}(M_2)$ be the sets of lifts of vector fields on M_1 and M_2 to $M_1 \times M_2$, respectively.

We have the following proposition for a twisted product manifold.

Proposition 2.1. ([7], [9], [8]) Let $M = M_1 \times_f M_2$ be a twisted product manifold with the metric $g = g_1 \oplus f^2 g_2$ and let $X, Y \in \mathcal{L}(M_1)$ and $V, W \in \mathcal{L}(M_2)$. Then

- 1) $\nabla_X Y = \nabla_X^1 Y$,
- 2) $\nabla_X V = \nabla_V X = X(h)V$,
- 3) $\nabla_V W = \nabla_V^2 W + V(h)W + W(h)V - g(V, W)\nabla h$,

where $h = \log(f)$ and ∇h is the gradient of the function h .

We define the hessian $Hess_1h(X, Y) = XY(h) - (\nabla_X^1 Y)(h)$, for $X, Y \in \mathcal{L}(M_1)$. If $X, Y \in \mathcal{L}(M_1)$ and $V \in \mathcal{L}(M_2)$, we have $XV(h) = VX(h)$ and the hessian $hessh$ of h on the manifold $M = M_1 \times_f M_2$ satisfies

$$Hessh(X, V) = XV(h) - X(h)V(h), \tag{2}$$

$$Hessh(X, Y) = Hess_1h(X, Y). \tag{3}$$

We have the following proposition for the riemannian curvature tensor of a twisted product manifold.

Proposition 2.2. ([7], [9], [8]) *Let $M = M_1 \times_f M_2$ be a twisted product manifold and let $X, Y, Z \in \mathcal{L}(M_1)$, $V, W, U \in \mathcal{L}(M_2)$. Then, we have*

- 1) $R(X, Y)Z = R^1(X, Y)Z$,
- 2) $R(X, Y)V = 0$,
- 3) $R(V, W)U = R^2(V, W)U - |\nabla h|^2[g_2(V, U)W - g_2(W, U)V]$,
- 4) $R(X, W)V = [X(h)V(h) + Hessh(X, Y)]W - g(W, V)[X(h)\nabla h + H^h(X)]$,

where H^h is the hessian tensor of h on $M_1 \times_f M_2$, that is $Hessh(X, Y) = g(H^h(X), Y)$.

Lemma 2.1. *Let $M = M_1 \times_f M_2$ be a twisted product manifold. Then, for orthonormal vectors X and V , where $X \in \mathcal{L}(M_1)$, $V \in \mathcal{L}(M_2)$. The mixed sectional curvature is given by*

$$K(X, V) = g(R(X, V)V, X) = -[g(\nabla h, X)^2 + Hessh(X, X)], \tag{4}$$

where $h = \log(f)$ and f positive smooth function.

Proof of the Lemma. Using the formula in 4) of the Proposition 2.2 with the definition of the sectional curvature in orthonormal mixed coordinate systems $\{X, V\}$, we obtain the result (4) of the lemma. \square

III. PROOF OF THE THEOREM AND THE COROLLARY

In this section we prove the theorem and the corollary. The proof of the corollary is strongly related to that of the theorem, it is the same proof.

Proof of the Theorem. we will assume that the sectional curvature of the manifold (M, g) is everywhere positive.

We consider the case where M_1 and M_2 are the standard unit sphere \mathbb{S}^2 , and the twisted product manifold $\mathbb{S}^2 \times_f \mathbb{S}^2$ with the twisting function f and $h = \log(f)$. Let X and Y be orthonormal vectors, tangents to the left sphere \mathbb{S}^2 , and V and W orthonormal vectors, tangents to the right sphere \mathbb{S}^2 . Then, it readily follows from 1) and 3) of the Proposition 2.2 that the sectional curvatures $K(X, Y) = g(R(X, Y)Y, X)$ and $K(V, W) = g(R(V, W)W, V)$ are strictly positive, or still if for every unit tangent vector X one have

$$g(\nabla h, X)^2 + hessh(X, X) < 0. \tag{5}$$

Finally, Since M is a compact manifold, the smooth function $h : \mathbb{S}^2 \times \mathbb{S}^2 \rightarrow \mathbb{R}$ has a minimum $m = (m_1, m_2) \in \mathbb{S}^2 \times \mathbb{S}^2$. It is sufficient to show that at critical point m of h , we have $g(\nabla h, X) = 0$ and the mixed sectional curvature in (4) becomes

$$K(X, V) = -XXh. \quad (6)$$

Since the critical point m of h is a minimum then, at m we have that $XXh \geq 0$. And in this case, the sectional curvature $K(X, V)$ is not positive. This leads to a contradiction.

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Bounds on Vertex Zagreb Indices of Graphs

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Abstract- The vertex version of first and second Zagreb indices were introduced by Tavakoli et al. [2] are defined as $\overline{M}_1^*(G) = \sum_{\{u,v\} \subseteq V(G)} (d_G(u) + d_G(v))$ and $\overline{M}_2^*(G) = \sum_{\{u,v\} \subseteq V(G)} d_G(u)d_G(v)$. In this paper, we obtained the relation between the first and second vertex Zagreb indices of graphs using some well-known results.

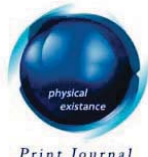
Keywords: *degree, zagreb index, topological index.*

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Bounds on Vertex Zagreb Indices of Graphs

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Keywords: degree, zagreb index, topological index.

I. INTRODUCTION

A graph can be recognized by a numeric number, a polynomial, a sequence of numbers or a matrix which represents the whole graph, and these representations are aimed to be uniquely defined for that graph. A topological index is a numeric quantity associated with a graph which characterize the topology of graph and is invariant under graph automorphism. There are some major classes of topological indices such as distance based topological indices, degree based topological indices and counting related polynomials and indices of graphs. Among these classes degree based topological indices are y and particularly in chemistry. In more precise way, a topological index $Top(G)$ of a graph G , is a number with the property that for every graph H isomorphic to G , $Top(G) = Top(H)$. The topological indices are graph invariants which has been used for examine quantitative structure-property relationships (QSPR) and quantitative structure-activity relationships (QSAR) extensively in which the biological activity or other properties of molecules are correlated with their chemical structures, see [4].

For a (molecular) graph G , The *first Zagreb index* $M_1(G)$ is the equal to the sum of the squares of the degrees of the vertices, and the *second Zagreb index* $M_2(G)$ is the equal to the sum of the products of the degrees of pairs of adjacent vertices, that is, $M_1(G) = \sum_{u \in V(G)} d_G^2(u) = \sum_{uv \in E(G)} (d_G(u) + d_G(v))$, $M_2(G) = \sum_{uv \in E(G)} d_G(u)d_G(v)$, where $d_G(v)$ is a degree of a vertex v in G . There are various study of different versions of Zagreb indices. One of the modified versions of classical Zagreb indices, the vertex version of first and second Zagreb indices were introduced by Tavakoli et al. [2] are defined as $\overline{M}_1^*(G) = \sum_{\{u,v\} \subseteq V(G)} (d_G(u) + d_G(v))$ and $\overline{M}_2^*(G) = \sum_{\{u,v\} \subseteq V(G)} d_G(u)d_G(v)$.

Another topological index, defined as sum of cubes of degrees of all the vertices was also introduced in the same paper, where the first and second Zagreb indices were introduced [14]. Furtula and Gutman in [13] recently investigated this index and named this index as *forgotten topological index* (or) *F-index* and showed that the predictive ability of this index is almost similar to that of first Zagreb index and for the entropy and acetic factor, both of them yield correlation coefficients greater than 0.95. The *F-index* of a graph G is defined as $F = F(G) = \sum_{u \in V(G)} d_G^3(u) = \sum_{uv \in E(G)} (d_G^2(u) + d_G^2(v))$.

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For the survey on theory and application of Zagreb indices, see [11]. Feng et al.[10] have given a sharp bounds for the Zagreb indices of graphs with a given matching number. Khalifeh et al. [3] have obtained the Zagreb indices of the Cartesian product, composition, join, disjunction and symmetric difference of graphs. Ashrafi et al. [9] determined the extremal values of Zagreb coindices over some special class of graphs. Hua and Zhang [12] have given some relations between Zagreb coindices and some other topological indices. In [2], the vertex version of Zagreb indices for the generalized hierarchical product of two connected graphs are computed. The vertex Zagreb indices of different types of operations of graphs are computed by De [1]. In this sequence, we have obtained the relation between the first and second vertex Zagreb indices of graphs.

II. MAIN RESULTS

In this section, we present the relation between the first and second vertex Zagreb indices of graph. The *inverse degree* of a graph G is the sum of reciprocal of the vertex degrees, that is,

$$ID(G) = \sum_{u \in V(G)} \frac{1}{d_G(u)}.$$

Lemma 2.1. [15] Let $\vec{x} = (x_1, x_2, \dots, x_N)$ and $\vec{y} = (y_1, y_2, \dots, y_N)$ be sequences of real numbers $\vec{z} = (z_1, z_2, \dots, z_N)$ and $\vec{w} = (w_1, w_2, \dots, w_N)$ be nonnegative sequences, then

$$\sum_{i=1}^N w_i \sum_{i=1}^N z_i x_i^2 + \sum_{i=1}^N z_i \sum_{i=1}^N w_i y_i^2 \geq 2 \sum_{i=1}^N z_i x_i \sum_{i=1}^N w_i y_i. \tag{2.1}$$

In particular, if z_i and w_i are positive, then the equality holds in (2.1) if and only if $\vec{x} = \vec{y} = \vec{k}$, where $\vec{k} = (k, k, \dots, k)$ is a constant sequence. ■

Theorem 2.2. Let G be a connected graph with n vertices and m edges. Then

$$2\overline{M}_1^*(G)\overline{M}_2^*(G) \leq (n-1)ID(G) + \frac{(n-1)\delta\Delta}{\delta + \Delta} + \frac{(n-1)(n-2)\Delta}{4} + 2mM_1(G) - F(G) \tag{2.2}$$

with equality if and only if G is regular.

Proof. Note that each i in Lemma 2.1 corresponds a vertex pair $\{u_i, u_j\}$ such that $N = \frac{n(n-1)}{2}$, setting $z_i = w_i = \frac{1}{x_i y_i}$ and each x_i is replaced by $\frac{1}{d_G(u_i)d_G(u_j)}$ and each y_i is replaced by $\frac{1}{d_G(u_i)+d_G(u_j)}$, then we obtain

$$\begin{aligned} \sum_{\{u_i, u_j\} \subseteq V(G)} d_G(u_i)d_G(u_j)(d_G(u_i) + d_G(u_j)) \sum_{\{u_i, u_j\} \subseteq V(G)} \left(\frac{d_G(u_i) + d_G(u_j)}{d_G(u_i)d_G(u_j)} + \frac{d_G(u_i)d_G(u_j)}{d_G(u_i) + d_G(u_j)} \right) \\ \geq 2 \sum_{\{u_i, u_j\} \subseteq V(G)} (d_G(u_i) + d_G(u_j)) \sum_{\{u_i, u_j\} \subseteq V(G)} d_G(u_i)d_G(u_j). \end{aligned} \tag{2.3}$$

One can observe that $\frac{2}{\Delta} \leq \frac{1}{d_G(u_i)} + \frac{1}{d_G(u_j)} \leq \frac{2}{\delta}$, it immediately follows that $\frac{d_G(u_i)d_G(u_j)}{d_G(u_i)+d_G(u_j)} \leq \frac{\Delta}{2}$. Also $\frac{1}{\delta} + \frac{1}{\Delta} \leq \frac{1}{d_G(u_i)} + \frac{1}{\delta}$, we have $\frac{d_G(u_i)\delta}{d_G(u_i)+\delta} \leq \frac{\delta\Delta}{\delta+\Delta}$. Let v_k be the minimum degree vertex in G . Then

$$\begin{aligned} \sum_{\{u_i, u_j\} \subseteq V(G)} \left(\frac{d_G(u_i) + d_G(u_j)}{d_G(u_i)d_G(u_j)} + \frac{d_G(u_i)d_G(u_j)}{d_G(u_i) + d_G(u_j)} \right) &= \sum_{\{u_i, u_j\} \subseteq V(G)} \frac{d_G(u_i) + d_G(u_j)}{d_G(u_i)d_G(u_j)} + \sum_{\{u_i, u_j\} \subseteq V(G)} \frac{d_G(u_i)d_G(u_j)}{d_G(u_i) + d_G(u_j)} \\ &= \sum_{\{u_i, u_j\} \subseteq V(G)} \left(\frac{1}{d_G(u_i)} + \frac{1}{d_G(u_j)} \right) + \sum_{\{u_i, u_k\} \subseteq V(G)} \frac{d_G(u_i)\delta}{d_G(u_i) + \delta} \end{aligned}$$



$$\begin{aligned}
 & + \sum_{\substack{\{u_i, u_j\} \subseteq V(G) \\ u_j \neq u_k}} \frac{d_G(u_i)d_G(u_j)}{d_G(u_i) + d_G(u_j)} \\
 & \leq \sum_{u_i \in V(G)} \frac{n-1}{d_G(u_i)} + \frac{(n-1)\delta\Delta}{\delta + \Delta} + \left(\frac{n(n-1)}{2} - (n-1)\right)\frac{\Delta}{2} \\
 & = (n-1)ID(G) + \frac{(n-1)\delta\Delta}{\delta + \Delta} + \frac{(n-1)(n-2)\Delta}{4}, \quad (2.4)
 \end{aligned}$$

where $ID(G)$ is the inverse degree index of G .

Since $\sum_{u_i \in V(G)} d_G(u_i) = 2m$, then we have

$$\sum_{\{u_i, u_j\} \subseteq V(G)} d_G(u_i)d_G(u_j)(d_G(u_i) + d_G(u_j)) \leq \sum_{u_i \in V(G)} d_G(u_i)^2(2m - d_G(u_i)).$$

From the definitions of first Zagreb index and F -index of G , we obtain

$$\sum_{\{u_i, u_j\} \subseteq V(G)} d_G(u_i)d_G(u_j)(d_G(u_i) + d_G(u_j)) \leq 2mM_1(G) - F(G). \quad (2.5)$$

Using (2.4) and (2.5) in (2.3), we obtain the required result in (2.2).

By Lemma 2.1, the equality in (2.2) holds if $\frac{1}{d_G(u_i)d_G(u_j)} = \frac{1}{d_G(u_i)d_G(u_k)} = \frac{1}{d_G(u_i)+d_G(u_j)} + \frac{1}{d_G(u_i)+d_G(u_k)}$ for any three vertices u_i, u_j and u_k in G . This implies G is regular. ■

Proposition 2.3. Let p be the number of pendent vertices in G . Then $F(G) \geq \delta M_1(G) + p(1 - \delta)$.

Proof. Since p is the number of pendent vertices in G ,

$$\begin{aligned}
 F(G) & = \sum_{u_i \in V(G)} d_G(u_i)^3 = p + \sum_{\substack{u_i \in V(G) \\ d_G(u_i) \neq 1}} d_G(u_i)^3 \geq p + \delta \sum_{\substack{u_i \in V(G) \\ d_G(u_i) \neq 1}} d_G(u_i)^2 \\
 & = p + \delta(M_1(G) - p).
 \end{aligned}$$

Using Proposition 2.3 in Theorem 2.2, we obtain the following corollary.

Corollary 2.4. Let G be a connected graph with n vertices and m edges. If p is the number of pendent vertices in G , then

$$2\overline{M}_1^*(G)\overline{M}_2^*(G) \leq (n-1)ID(G) + \frac{(n-1)\delta\Delta}{\delta + \Delta} + \frac{(n-1)(n-2)\Delta}{4} + (2m - \delta)M_1(G) + p(\delta - 1)$$

with equality if and only if G is regular. ■

Lemma 2.5.(Radon's inequality) For real numbers $p > 0, a_1, a_2, \dots, a_N \geq 0$ and $b_1, b_2, \dots, b_N > 0$, the following inequality holds:

$$\sum_{i=1}^N \frac{a_i^{p+1}}{b_i^p} \geq \frac{\left(\sum_{i=1}^N a_i\right)^{p+1}}{\left(\sum_{i=1}^N b_i\right)^p}.$$

Next we obtain the another relation between the first and second vertex Zagreb indices of graphs.

Theorem 2.6. Let G be a connected graph with n vertices and m edges. Then $\frac{(M_1(G))^2}{M_2(G)} \leq \frac{n(n-1)(\delta+\Delta)^2}{2\delta\Delta}$ with equality if and only if G is regular.

Proof. For each i in Lemma 2.5 corresponds a vertex (u_i, u_j) with $N = \frac{n(n-1)}{2}$ and $p = 1$, setting each $a_i = d_G(u_i) + d_G(u_j)$ and $b_i = d_G(u_i)d_G(u_j)$, it follows that

$$\sum_{(u_i, u_j) \subseteq V(G)} \frac{(d_G(u_i) + d_G(u_j))^2}{d_G(u_i)d_G(u_j)} \geq \frac{\left(\sum_{(u_i, u_j) \subseteq V(G)} d_G(u_i) + d_G(u_j)\right)^2}{\sum_{(u_i, u_j) \subseteq V(G)} d_G(u_i)d_G(u_j)}. \quad (2.6)$$

The equation (2.6) is equivalent to

$$\sum_{(u_i, u_j) \subseteq V(G)} \left(\sqrt{\frac{d_G(u_i)}{d_G(u_j)}} + \sqrt{\frac{d_G(u_j)}{d_G(u_i)}}\right)^2 \geq \frac{(\overline{M}_1^*(G))^2}{\overline{M}_2^*(G)}.$$

It has been proved in [15] that

$$\left(\sqrt{\frac{d_G(u_i)}{d_G(u_j)}} + \sqrt{\frac{d_G(u_j)}{d_G(u_i)}}\right)^2 \leq \frac{(\delta + \Delta)^2}{\delta\Delta}.$$

Hence

$$\frac{(M_1(G))^2}{M_2(G)} \leq \sum_{(u_i, u_j) \subseteq V(G)} \frac{(\delta + \Delta)^2}{\delta\Delta} = \frac{n(n-1)(\delta + \Delta)^2}{2\delta\Delta}. \quad (2.7)$$

Equality in (2.7) holds if and only if G is regular. ■

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A Reliable Technique for Solving Gas Dynamic Equation using Natural Homotopy Perturbation Method

By Adesina. K. Adio

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Abstract- In this paper, a new analytical technique called Natural transform homotopy perturbation method has been successfully applied to obtain exact solution of nonlinear gas dynamic equation.

Application of the method to three test modelling problems from mathematical physics lead to sequence which tends to the exact solution of the problems.

The solution procedure shows the reliability of the method and is high accuracy evident.

Keywords: *gas dynamic equation, homotopy perturbation method, natural transform method.*

GJSFR-F Classification: *MSC 2010: 26E70*



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Abstract- In this paper, a new analytical technique called Natural transform homotopy perturbation method has been successfully applied to obtain exact solution of nonlinear gas dynamic equation.

Application of the method to three test modelling problems from mathematical physics lead to sequence which tends to the exact solution of the problems.

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I. INTRODUCTION

Gas dynamics is a science in the branch of fluid dynamics concerned with studying the motion of gases and its effects on physical systems, based on the principles of fluid mechanics and thermodynamics.

The science arises from the studies of gas flows, often around or within physical bodies. Examples of these studies include but not limited to choked flows in nozzles and valves, shock waves around jets, aerodynamic heating on atmospheric reentry vehicles and flow of gas fuel within a jet engine.

The equations of gas dynamics (Aminikah & Jamalain, 2013) are mathematical expressions based on the physical laws of conservation, namely, the laws of conservation of mass, conservation of momentum, conservation of energy and so forth.

The nonlinear equations of ideal gas dynamics are applicable for three types of nonlinear waves like shock fronts, rare factions and contact discontinuities.

Different types of gas dynamics equations in physics have been solved using Fourier transform A domian decomposition method (Ramezanpour, et al, 2013), homotopy analysis method (Jafari, et al, 2009), finite difference scheme (Rasulov & Karaguler, 2003), Reduced differential transform method (Keskin & Oturanc, 2010), Reconstruction of Variational Iteration method (Nikkar, 2012), Homotopy perturbation method (Jafari, et al, 2008), Variational iterative method (Jafari, et al, 2008), El-zaki transform homotopy perturbation method (Bhadane & Pradhan, 2013), Natural decomposition method (Maitama & Sabuwa, 2014), Variational homotopy perturbation method (Matinfar & Raeisi, 2011), Differential transform method, Modified homotopy perturbation method (Mohiuddin, 2015), Homotopy perturbation transform method (Singh, et al, 2012) and so on.

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In this study, we construct solution of gas dynamic equation by using a combination of Natural transform and homotopy perturbation methods (NHPM).

In one spatial dimension, the inviscid equations of gas dynamics can be written in the conservative form (Keskin & Oturanc, 2010) as:

$$v_t(x,t) - v(x,t) + \frac{1}{2} v_x^2(x,t) + v^2(x,t) = f(x,t); \quad 0 \leq x \leq 1, \quad t > 0 \tag{1.1}$$

$$v(x,0) = g(x) \tag{1.2}$$

II. ANALYSIS OF THE METHOD

For the purpose of illustration of the methodology of the proposed method, we write the gas dynamic equation in the standard operator form:

$$Dv(x,t) + Rv(x,t) + Nv(x,t) = f(x,t) \tag{2.1}$$

With the following initial conditions:

$$v(x,0) = g(x); \quad v_t(x,0) = h(x) \tag{2.2}$$

Where $D(v(x,t)) = v_t(x,t)$ is a linear operator which has partial derivatives; $R(v(x,t)) = v(x,t)$; $N(v(x,t)) = \frac{1}{2} v_x^2(x,t) + v^2(x,t)$ is a nonlinear term and $g(x)$ is an in homogenous term.

Applying the Natural transform to equation (2.1) subject to the given initial condition, we have

$$N^+[Dv(x,t)] + N^+[Rv(x,t)] + N^+[Nv(x,t)] = N^+[f(x,t)] \tag{2.3}$$

using differentiation property of Natural transform and above initial conditions, we have

$$V(x,s,v) = \frac{1}{s} g(x) + \frac{v}{s^2} h(x) - \frac{v^2}{s^2} N^+[RV(x,t)] - \frac{v^2}{s^2} N^+[NV(x,t)] + \frac{v^2}{s^2} N^+[f(x,t)] \tag{2.4}$$

Operating with the inverse Natural transform on both sides of equation (2.3), we have

$$v(x,t) = F(x,t) - N^{-1} \left[\frac{v^2}{s^2} N^+[Rv(x,t) + Nv(x,t)] \right] \tag{2.5}$$

where $F(x,t)$ represents the term arising from the source term and the prescribed initial condition.

Now, applying the homotopy perturbation method (HPM)

$$v(x,t) = \sum_{n=0}^{\infty} P^n v_n(x,t) \tag{2.6}$$

and the nonlinear term can be decomposed as

$$Nv(x,t) = \sum_{n=0}^{\infty} P^n H_n(v) \tag{2.7}$$

where $H_n(v)$ are He's polynomials and can be evaluated using the following formula:

$$H_n(v_1, v_2, \dots, v_n) = \frac{1}{n!} \frac{\partial^n}{\partial P^n} \left[N \sum_{j=0}^n P^j V_j \right]_{p=0}; \quad n = 0, 1, 2, \dots \tag{2.8}$$

Substituting equations (2.6) and (2.7) in (2.5); we have

$$\sum_{n=0}^{\infty} P^n v_n(x, t) = F(x, t) - P \left(N^{-1} \left[\frac{v^2}{s^2} N^+ \left[R \sum_{n=0}^{\infty} P^n v_n(x, t) + \sum_{n=0}^{\infty} P^n H_n(v) \right] \right] \right) \tag{2.9}$$

which is the coupling of the Natural transform and the homotopy perturbation method using

He's polynomials.

Comparing the coefficient of same powers of P , we obtain the following approximations:

$$\begin{aligned} P^0 : v_0(x, t) &= F(x, t) \\ P^1 : v_1(x, t) &= -N^{-1} \left[\frac{v^2}{s^2} N^+ [Rv_0(x, t) + H_0(v)] \right] \\ P^2 : v_2(x, t) &= -N^{-1} \left[\frac{v^2}{s^2} N^+ [Rv_1(x, t) + H_1(v)] \right] \\ P^3 : v_3(x, t) &= -N^{-1} \left[\frac{v^2}{s^2} N^+ [Rv_2(x, t) + H_2(v)] \right] \end{aligned} \tag{2.10}$$

and so on.

Thus, the series solution of equation (2.1) is

$$v(x, t) = \lim_{k \rightarrow \infty} \sum_{n=0}^k v_n(x, t) \tag{2.11}$$

III. EXPERIMENTAL EVALUATION

In this section; we consider the following nonlinear homogenous and nonhomogenous gas dynamics equations:

Example 3.1: Consider the nonlinear homogenous gas dynamic equation [3-7]:

$$v_t(x, t) + \frac{1}{2} v^2_x(x, t) - v(x, t) + v^2(x, t) = 0 \tag{3.1}$$

with initial condition $v(x, 0) = g(x) = e^{-x}$ (3.2)

applying the natural transform on both sides of equation (3.1) subject to the initial condition (3.2), we have

$$v(x, s) = \frac{e^{-x}}{s} + \frac{v}{s} N^+ \left[v(1-v) - \frac{1}{2} (v^2)_x \right] \tag{3.3}$$

The inverse of natural transform implies that

$$v(x, t) = e^{-x} + N^{-1} \left[\frac{v}{s} N^+ \left[v(1-v) - \frac{1}{2} (v^2)_x \right] \right] \tag{3.4}$$

Now, we apply the homotopy perturbation method to get

$$\sum_{n=0}^{\infty} P^n v_n(x, t) = e^{-x} + P \left(N^{-1} \left[\frac{v}{s} N^+ \left[\sum_{n=0}^{\infty} P^n v_n(x, t) \left(1 - \sum_{n=0}^{\infty} P^n v_n(x, t) \right) - \frac{1}{2} \left(\sum_{n=0}^{\infty} P^n v_n(x, t) \right)^2 \right] \right] \right) \tag{3.5}$$

Comparing the coefficients of like powers of P in eqn (3.5); we obtain the following approximations.

$$\begin{aligned} P^0 : \quad & v_0(x, t) = e^{-x} \\ P^1 : \quad & v_1(x, t) = N^{-1} \left[\frac{v}{s} N^+ \left[v_0(1-v_0) - \frac{1}{2} (v_0^2)_x \right] \right] = e^{-x} t \\ P^2 : \quad & v_2(x, t) = N^{-1} \left[\frac{v}{s} N^+ \left[v_1(1-v_1) - \frac{1}{2} (v_1^2)_x \right] \right] = e^{-x} \frac{t^2}{2!} \\ P^3 : \quad & v_3(x, t) = N^{-1} \left[\frac{v}{s} N^+ \left[v_2(1-v_2) - \frac{1}{2} (v_2^2)_x \right] \right] = e^{-x} \frac{t^3}{3!} \end{aligned}$$

and so on.

Therefore, the solution $v(x, t)$ is given by

$$v(x, t) = e^{-x} \left(1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \frac{t^4}{4!} + \dots \right) = e^{t-x} \tag{3.6}$$

Obtained upon using the Taylor expansion for e^t . Higher number of iterations lead to convergence to the exact solution e^{t-x} . This result is similar to what obtained using HPTM [16], RDTM [7], VIM [5], RVIM [7], ADM [13], ETHPM [2], HPM [4], VHPM [10], MHPM [11] and NDM[9].

Example 3.2: Consider the nonlinear, nonhomogenous gas dynamic equation [2,12,13]

$$v_t(x, t) + \frac{1}{2} v_x^2(x, t) - v(x, t) + v^2(x, t) = -e^{t-x} \tag{3.7}$$

with initial condition $v(x, 0) = g(x) = 1 - e^{-x}$ (3.8)

Applying the natural transform on both sides of equation (3.7) subject to the initial condition(3.8), we have

$$v(x, s) = \frac{1 - e^{-x}}{s} - \frac{v e^{-x}}{s(s-v)} + \frac{v}{s} \left[N^+ \left[v(1-v) - \frac{1}{2} (v^2)_x \right] \right] \tag{3.9}$$

The inverse of Natural transform implies that:

Ref

4. Jafari, H., Zabih, M., Saïdy, M., 2008. Application of homotopy perturbation method for solving gas dynamic equation. Applied Mathematical Sciences. 2, 2393-2396.

$$v(x, t) = (1 - e^{-t-x}) + N^{-1} \left[\frac{v}{s} N^+ \left[v(1-v) - \frac{1}{2} (v^2)_x \right] \right] \tag{3.10}$$

Since
$$N^{-1} \left[\frac{ve^{-x}}{s(s-v)} \right] = e^{-x} N^{-1} \left[\frac{v}{s(s-v)} \right] = e^{-x} (e^t - 1)$$

Now, we apply the homotopy perturbation method to get:

$$\sum_{n=0}^{\infty} P^n v_n(x, t) = (1 - e^{-t-x}) + P \left(N^{-1} \left[\frac{v}{s} N^+ \left[\sum_{n=0}^{\infty} P^n v_n(x, t) \left(1 - \sum_{n=0}^{\infty} P^n v_n(x, t) \right) - \frac{1}{2} \left(\sum_{n=0}^{\infty} P^n v_n(x, t) \right)^2 \right] \right] \right) \tag{3.11}$$

Comparing the coefficients of like powers of P in eqn (3.11), we obtain the following approximations:

$$\begin{aligned} P^0 : v_0(x, t) &= 1 - e^{-t-x} \\ P^1 : v_1(x, t) &= N^{-1} \left[\frac{v}{s} N^+ \left[v_0(1-v_0) - \frac{1}{2} (v_0^2)_x \right] \right] = 0 \\ P^2 : v_2(x, t) &= N^{-1} \left[\frac{v}{s} N^+ \left[v_1(1-v_1) - \frac{1}{2} (v_1^2)_x \right] \right] = 0 \\ P^3 : v_3(x, t) &= N^{-1} \left[\frac{v}{s} N^+ \left[v_2(1-v_2) - \frac{1}{2} (v_2^2)_x \right] \right] = 0 \end{aligned}$$

and so on.

Therefore, the solution $v(x, t)$ is given by

$$v(x, t) = 1 - e^{-t-x} \tag{3.12}$$

Similar to results obtained using VIM [5], RVIM [12], ADM [13], ETHPM [2], VHPM [10] and NDM [9].

Example 3.3: Consider the non-homogenous, nonlinear gas dynamic equation [1,3]

$$v_t(x, t) + v(x, t)v_x(x, t) - v(x, t) + v^2(x, t) = -e^{-t-x} \tag{3.13}$$

with initial condition
$$v(x, 0) = 1 - e^{-x} \tag{3.14}$$

Applying the natural transform on both sides of eqn(3.13) subject to the initial condition (3.14) we have

$$v(x, s) = \frac{1 - e^{-x}}{s} - \frac{ve^{-x}}{s(s-v)} + \frac{v}{s} N^+ [v(1-v) - vv_x] \tag{3.15}$$

The inverse of Natural transform implies that

$$v(x, t) = 1 - e^{-t-x} + N^{-1} \left[\frac{v}{s} N^+ [v(1-v) - vv_x] \right] \tag{3.16}$$

Ref

12. Nikkar, A., 2012. A new approach for solving gas dynamic equation. Acta Technica Corviniensis Bulletin of Engineering. 4, 113-116.

Now, we apply the homotopy perturbation method to get:

$$\sum_{n=0}^{\infty} P^n v_n(x,t) = 1 - e^{t-x} + P \left(N^{-1} \left[\frac{v}{s} N^+ \left[\sum_{n=0}^{\infty} P^n v_n(x,t) \left(1 - \sum_{n=0}^{\infty} P^n v_n(x,t) \right) - \sum_{n=0}^{\infty} P^n v_n(x,t) \left(\sum_{n=0}^{\infty} P^n v_n(x,t) \right)_x \right] \right] \right) \tag{3.17}$$

Comparing the coefficients of like powers of P in eqn (3.17), we obtain the following approximations

$$\begin{aligned} P^0 : v_0(x,t) &= 1 - e^{t-x} \\ P^1 : v_1(x,t) &= N^{-1} \left[\frac{v}{s} N^+ [v_0(1-v_0) - v_0 v_{0x}] \right] = 0 \\ P^2 : v_2(x,t) &= N^{-1} \left[\frac{v}{s} N^+ [v_1(1-v_1) - v_1 v_{1x}] \right] = 0 \\ P^3 : v_3(x,t) &= N^{-1} \left[\frac{v}{s} N^+ [v_2(1-v_2) - v_2 v_{2x}] \right] = 0 \end{aligned}$$

and so on.

Therefore, the solution $v(x,t)$ is given by

$$v(x,t) = 1 - e^{t-x} \tag{3.18}$$

Which is the exact solution of the problem.

IV. CONCLUSION

In the present work, we proposed a combination of Natural transform and Homotopy perturbation methods and successfully applied it to study the homogenous and non-homogenous cases of nonlinear gas dynamics equation.

The method gave closed form solution of the equations, with high accuracy, using the initial conditions and can be considered as a reliable refinement of existing techniques.

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Asymptotic Solutions of Second Order Equations with Holomorphic Coefficients with Degeneracies and Laplace's Equations on A Manifold with A Cuspidal Singularity

By M. V. Korovina

Abstract- In this paper, we construct the asymptotics for second order linear differential equations with higher-order singularity for the case where the principle symbol has multiple roots. In addition, we solve the problem of constructing asymptotic solutions of Laplace's equation on a manifold with a second order cuspidal singularity.

Keywords: differential equations with cuspidal, singularitus, laplas-borel transformation, resurgent function, laplace's equation.

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1. Kondratev V.A. Boundary Value Problems for Elliptic Equations in Domains with Conical or Angular Points, Tr. Mosk. Mat. Obs., 1967, vol.16, pp 209-292.

Asymptotic Solutions of Second Order Equations with Holomorphic Coefficients with Degeneracies and Laplace's Equations on a Manifold with a Cuspidal Singularity

M. V. Korovina

Abstract- In this paper, we construct the asymptotics for second order linear differential equations with higher-order singularity for the case where the principle symbol has multiple roots. In addition, we solve the problem of constructing asymptotic solutions of Laplace's equation on a manifold with a second order cuspidal singularity.

Keywords: differential equations with cuspidal, singularitus, laplas-borel transformation, resurgent function, laplace's equation.

I. INTRODUCTION

This paper is devoted to asymptotic expansions for solutions to equations with higher-order degeneracies, namely, to equations of the form

$$H\left(r, -\frac{1}{k}r^{k+1}\frac{d}{dr}, x, -i\frac{\partial}{\partial x}\right)u=0 \tag{1}$$

where

$$H\left(r, r^{k+1}\frac{d}{dr}, x, -i\frac{\partial}{\partial x}\right) = \sum_{j=0}^2 \sum_{l=1}^2 a_{jl}(x, r) \left(-i\frac{\partial}{\partial x}\right)^j \left(r^{k+1}\frac{d}{dr}\right)^l$$

k – integer non-negative number, $a_{jl}(x, r)$ holomorphic coefficients in the neighbourhood of zero in variable r . Here $r \in \mathbb{C}$ and x belongs to a compact manifold without edge. Such equations are referred to as equations with cuspidal singularitus of order $k+1$, for $k=0$, such singularitus are said to be conical. The case of conical singularitus was studied dy Kondratev in [1]. Here we consider the case of cuspidal singularitus. Note that any linear differential equations of second order with holomorphic coefficients with singularitus in one of the variables is representable in the form (1). Laplace's equation on a manifold with cuspidal singularity is a typical example of such an equation.

In the first part of the article we construct asymptotic solutions of ordinary differential equations of second order with coefficients $a_i(r), i=0,1,2$ which is holomorphic in some neighborhood of the point $r=0$

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$$a_2(r)\left(\frac{d}{dr}\right)^2 u(r) + a_1(r)\left(\frac{d}{dr}\right)u(r) + a_0(r)u(r) = 0. \tag{2}$$

$a_i(r), i = 0, 1, 2$ are holomorphic in some neighborhood of the point $r = 0$

In paper [5] received asymptotic solutions of equation

$$H\left(r, -r^2 \frac{d}{dr}\right)u = 0, \tag{3}$$

where $H(r, p) = \sum_{i=0}^n a_i(r)p^i$, with the roots of principle operator symbol $H_0(p) = H(0, p)$ being simple. The asymptotic solutions of the above equation have the form

$$u = \sum_{i=1}^n e^{\alpha_i/r} r^{\sigma_i} \sum_{k=0}^{\infty} a_i^k r^k \tag{4}$$

where $\alpha_i, i = 1, \dots, n$ are the roots of $H(0, p)$ and σ_i and a_i^k are some complex numbers. However, if the asymptotic expansion has at least two terms corresponding to values α_1 and α_2 with distinct real parts (to be definite, we assume that $\text{Re} \alpha_1 > \text{Re} \alpha_2$), then it becomes quite difficult to interpret the right hand part of (4). The point is that all terms of the first element corresponding to the value α_1 (the dominant component) have a higher order as $r \rightarrow 0$ than any term of the second (the recessive element). If the argument r moves in the complex plane, then the role of the components can be changed. Therefore, to interpret the expansion (4), one should sum the (not necessarily convergent) series (3), the analysis of asymptotic expansions of solutions of equations (1) requires the introduction of regular summation method for divergent series for the construction of uniform asymptotic expansions of solutions with respect to the variable r .

In paper [2] and [5] author examined the conditions of infinite continuation for Laplace-Borel k -transforms of solutions to these equations and proved their continuability along any path on the Riemann surface not passing through a certain discrete set of points depending on the function, the exact definition of resurgent function is given in below.

Based on the concept of resurgent function first introduced by J. Ecalle [3], apparatus for summing expressions of the form (4), based on the Borel-Laplace transformation is called resurgent analysis. The fundamentals of resurgent analysis and of the Borel-Laplace transform are based on can be found in [4].

In articles [7], [8] asymptotic solutions of equations

$$\left(\frac{d}{dx}\right)^2 u(x) + a_1(x)\left(\frac{d}{dx}\right)u(x) + a_0(x)u(x) = 0$$

are constructed in the neighborhood of infinity, provided that the coefficients $a_i(x)$ are holomorphic in the neighborhood of infinity. This equation is reduced to the second order equations with cuspidal singularity in the neighborhood of the point $r = 0$, by substituting $x = \frac{1}{r}$, which is a private case of tasks which are considering in that paper, that is equations of any order singularity.

In the second part of the paper we consider partial differential equations with cuspidal singularities. As an example we construct asymptotic solutions of Laplace's equation on a manifold with a second order cuspidal singularity.

The paper continues the research into asymptotic behaviour of solutions to equations with singularity carried out in a series of articles [2], [5], [6] and so on.

In [5], asymptotic expansions for solutions to equations of type (1) are constructed for $k=1$, and, in [6], they are constructed for $k > 1$ if the roots of the principle operator symbol are simple. The problem of asymptotic solutions in the case of multiple roots is much more complicated and is still an open problem. This paper proposes a method for obtaining asymptotic solutions of second order equations with higher-order singularity in the case of multiple roots. The method is also applicable to some types of higher-order ordinary or partial differential equations.

a) *Basic definitions*

In this section we introduce some notions of resurgent analysis for further use.

Let $S_{R,\varepsilon}$ denote the sector $S_{R,\varepsilon} = \{r | -\varepsilon < \arg r < \varepsilon, |r| < R\}$. We say that the function f analytic at $S_{R,\varepsilon}$ has at most k -exponential growth if there exist nonnegative constants C and α such that the inequality

$$|f| < Ce^{\frac{\alpha}{|r|^k}}$$

holds in the sector $S_{R,\varepsilon}$.

Let $E_k(S_{R,\varepsilon})$ denote the space of holomorphic functions of k -exponential growth, and let $E(\tilde{\Omega}_{R,\varepsilon})$ denote the space of holomorphic functions of exponential growth in $\tilde{\Omega}_{R,\varepsilon}$. The domain $\tilde{\Omega}_{R,\varepsilon}$ is shown in Fig1. $E(C)$ will denote the space of entire functions of exponential growth.

The Laplace-Borel k -transform of the function $f(r) \in E_k(S_{R,\varepsilon})$ is given by

$$B_k f = \int_0^{r_0} e^{-p/r^k} f(r) \frac{dr}{r^{k+1}}.$$

We can show that $B_k : E_k(S_{R,\varepsilon}) \rightarrow E(\tilde{\Omega}_{R,\varepsilon})/E(C)$. The inverse -transform is defined by

$$B_k^{-1} \tilde{f} = \frac{k}{2\pi i} \int_{\tilde{\gamma}} e^{p/r^k} \tilde{f}(p) dp.$$

where $\tilde{\gamma}$ is shown in Fig. 1.

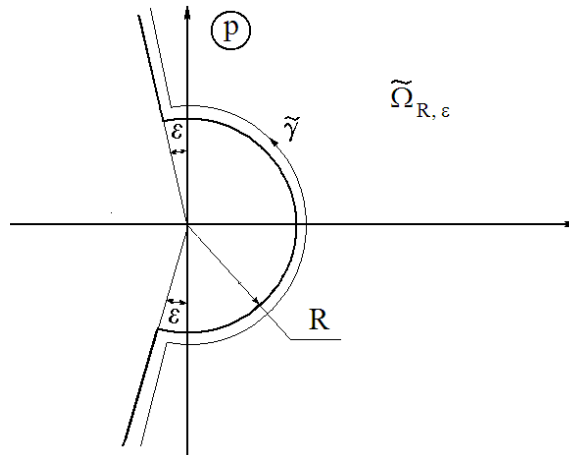


Fig. 1: The Laplace-Borel transform domain of holomorphy and the reverse transform calculation

We can now give the definition of a k -resurgent function.

Definition 1. The function \tilde{f} is called k -endlessly continuable, if for any R there exists a discrete set of points Z_R in \mathbb{C} such that the function \tilde{f} can be analytically continued from the initial domain along any path of length $< R$ not passing through Z_R .

Definition 2. The element f of the space $E_k(S_{R,\epsilon})$ is called a k -resurgent function, if its Borel k -transform $\tilde{f} = B_k f$ is endlessly continuable.

II. ASYMPTOTIC SOLUTIONS OF ORDINARY DIFFERENTIAL EQUATIONS

In this section we consider second-order homogeneous ordinary differential equations with cuspidal singularity, that is the equations of the form

$$H\left(r, \frac{1}{n} r^{n+1} \frac{d}{dr}\right) = 0,$$

where the symbol $H(r, p)$ is second-order polynomial in p with holomorphic coefficients. In [2] it is proved that solutions of these equations are resurgent functions as formulated in Definition 2. Here we assume that the principle symbol $H_0(p) = H(0, p)$ has a multiple root. In the case of simple roots of a principle symbol such equations are discussed in [6]. In other words, we consider the equations of the form

$$\left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right)^2 u + a_1(r) \left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right) u + a_0(r) u + r v(r) \left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right)^2 u = 0, \quad (5)$$

where $a_i(r)$ are holomorphic coefficients.

$$a_1(r) = br^k + r^{k+1} b_1(r),$$

$$a_0(r) = cr^p + r^{p+1} c_1(r)$$

Here $b_1(r), c_1(r)$ are holomorphic functions, with non-zero c and b .

Thus we rewrite equation (5) as



$$\left(\frac{1}{n}r^{n+1}\frac{d}{dr}\right)^2u + br^k\left(\frac{1}{n}r^{n+1}\frac{d}{dr}\right)u + cr^p u + r^{k+1}b_1(r)\left(\frac{1}{n}r^{n+1}\frac{d}{dr}\right)u + r^{p+1}c_1(r)u + rv(r)\left(\frac{1}{n}r^{n+1}\frac{d}{dr}\right)u = 0. \tag{6}$$

Since for any $m : 0 < m < n + 1$ the relation

$$\left(r^{n+1}\frac{d}{dr}\right)^2 = mr^{n+m}\left(r^{n-m+1}\frac{d}{dr}\right) + r^{2m}\left(r^{n-m+1}\frac{d}{dr}\right)^2,$$

holds, then equation (6) can be rewritten in the form

$$r^{2m}\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)^2u + \frac{m}{n}r^{n+m}\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)u + br^{k+m}\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)u + cr^p u + r^{k+1+m}b_1(r)\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)u + r^{p+1}c_1(r)u + r^{2m+1}v(r)\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)^2u + \frac{m}{n}r^{m+n+1}v(r)\left(\frac{1}{n}r^{n-m+1}\frac{d}{dr}\right)u = 0 \tag{7}$$

The following two cases are considered.

1. $\frac{p}{2} \geq n$ and $k \geq n$.

This is the simplest case. We set $m = n$, then equation (7) has the form

$$r^{2n}\left(\frac{1}{n}r\frac{d}{dr}\right)^2u + r^{2n}\left(\frac{1}{n}r\frac{d}{dr}\right)u + br^{k+n}\left(\frac{1}{n}r\frac{d}{dr}\right)u + cr^p u + r^{k+n+1}b_1(r)\left(\frac{1}{n}r\frac{d}{dr}\right)u + r^{p+1}c_1(r)u + r^{2n+1}v(r)\left(\frac{1}{n}r\frac{d}{dr}\right)^2u + r^{2n+1}v(r)\left(\frac{1}{n}r\frac{d}{dr}\right)u = 0 \tag{8}$$

Dividing (8) by r^{2n} , we obtain the equation

$$\left(\frac{1}{n}r\frac{d}{dr}\right)^2u + \left(\frac{1}{n}r\frac{d}{dr}\right)u + br^{k-n}\left(\frac{1}{n}r\frac{d}{dr}\right)u + cr^{p-2n}u + r^{k-n+1}b_1(r)\left(\frac{1}{n}r\frac{d}{dr}\right)u + r^{p-2n+1}c_1(r)u + rv(r)\left(\frac{1}{n}r\frac{d}{dr}\right)^2u + rv(r)\left(\frac{1}{n}r\frac{d}{dr}\right)u = 0$$

This is an equation with a conic singularity. In other words, it is not the case of a cuspidal singularity. This case is have been studied extensively (e.g. [1]). It is reasonable to search for the solutions of these equations in weighted Sobolev spaces $H^{k,\sigma}(0, \infty)$. For nonhomogeneous equations a solution can be represented in the form of conormal asymptotics. For homogeneous equations, it is identically equal to zero.

2. Let $\frac{p}{2} < n$ or $k < n$, and if $k < \frac{p}{2}$, then, similarly to the conic case, we set $m = k$ in (7). Divide the equation (7) by r^{2k} and multiplying by $\left(\frac{n}{n-k}\right)^2$ we obtain the equation



$$\begin{aligned} & \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right)^2 u + \frac{n}{n-k} r^{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + b \frac{n}{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + c \frac{n^2}{(n-k)^2} r^{p-2k} u + \\ & + r b_1(r) \frac{n}{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + r^{p+1-2k} \left(\frac{n}{n-k}\right)^2 c_1(r) u + \\ & + r v(r) \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right)^2 u + \frac{n}{n-k} r v(r) \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u = 0 \end{aligned}$$

The principle symbol in this case is equal to $H_0(p) = p^2 + b \frac{n}{n-k} p$, and has simple roots. In [6], the solution of this equation is shown to belong to the space $E_{n-k}(S_{R,\varepsilon})$. Asymptotic solutions for this equation has the form

$$r^{\sigma_0} v_0(r) \exp\left(\sum_{i=1}^{n-k-1} \frac{\alpha_{n-k-1}^0}{r^{n-k-i}}\right) + r^{\sigma_1} v_1(r) \exp\left(-\frac{bn}{(n-k)r^{n-k}} + \sum_{i=1}^{n-k-1} \frac{\alpha_{k-i}^1}{r^{n-k-i}}\right).$$

In this case $v_i(r), i = 0,1$ denotes, in general, divergent series

$$v_i(r) = \sum_{j=1}^{\infty} v_j^i r^j, i = 0,1$$

and $\sigma_i(r), i = 0,1$ and α^j_i denote corresponding numbers. The method to calculate them is outlined in [6].

Now assume that $\frac{p}{2} < k$ then, we set $m = \frac{p}{2}$, in equation (7) and divide it by r^p , thus obtain the equation

$$\begin{aligned} & \left(\frac{1}{n} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right)^2 u + \frac{p}{2n} r^{\frac{n-p}{2}} \left(\frac{1}{n} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right) u + b r^{\frac{k-p}{2}} \left(\frac{1}{n} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right) u + c u + \\ & + r^{\frac{k+1-p}{2}} b_1(r) \left(\frac{1}{n} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right) u + r c_1(r) u + r v(r) \left(\frac{1}{n} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right)^2 u + \frac{p}{2n} r^{n+1-q} v(r) \left(\frac{1}{n-q} r^{\frac{n-p}{2}+1} \frac{d}{dr}\right) u = 0 \end{aligned} \tag{9}$$

If $p = 2q$ is an even number, then the equation takes the form

$$\begin{aligned} & \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right)^2 u + \frac{q}{n-q} r^{n-q} \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right) u + \\ & + b r^{k-q} \frac{n}{n-q} \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right) u + c \left(\frac{n}{n-q}\right)^2 u + \\ & + r^{k+1-q} b_1(r) \frac{n}{n-q} \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right) u + r \left(\frac{n}{n-q}\right)^2 c_1(r) u + \\ & + r v(r) \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right)^2 u + \frac{q}{n-q} r^{n-q+1} v(r) \left(\frac{1}{n-q} r^{n-q+1} \frac{d}{dr}\right) u = 0 \end{aligned}$$

Then the symbol is equal to $H_0(p) = p^2 + \left(\frac{n}{n-q}\right)^2 c$. Its roots are simple. The solution of this equation belongs to the space $E_{n-q}(S_{R,\varepsilon})$. In this case, as shown in the article [6], the asymptotics has the form

$$r^{\sigma_1} v_1(r) \exp\left(-\frac{i \frac{n}{n-q} \sqrt{c}}{r^{n-q}} + \sum_{i=1}^{n-q-1} \frac{\alpha^1_{n-q-i}}{r^{n-q-i}}\right) + r^{\sigma_2} v_0(r) \exp\left(\frac{i \frac{n}{n-q} \sqrt{c}}{r^{n-q}} + \sum_{i=1}^{n-q-1} \frac{\alpha^2_{n-q-i}}{r^{n-q-i}}\right).$$

If p is odd, we make the change (of) $x = r^{\frac{1}{2}}$ and by substituting

$$r^{\frac{n-p}{2}+1} \frac{d}{dr} = \frac{1}{2} \left(x^{2n-p+1} \frac{du}{dx} \right)$$

into equation (9) we obtain

$$\begin{aligned} & \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right)^2 u + \frac{p}{2n-p} x^{2n-p} \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right) u + b x^{2k-p} \frac{2n}{2n-p} \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right) u + \\ & + \left(\frac{2n}{2n-p}\right)^2 c u + x^{2k+2-p} b_1(x^2) \frac{2n}{2n-p} \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right) u + \\ & + x^2 \left(\frac{2n}{2n-p}\right)^2 c_1(x^2) u + x^2 v(x^2) \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right)^2 u + \frac{2p}{2n-p} x^{2n+2-p} v(x^2) \left(\frac{1}{2n-p} x^{2n+1-p} \frac{d}{dx}\right)^2 u = 0 \end{aligned}$$

In this case the principle symbol is equal to $H_0(p) = p^2 + \left(\frac{2n}{2n-p}\right)^2 c$. The asymptotic solution of the last equation has the form

$$\begin{aligned} & \exp\left(-\frac{2\pi i \sqrt{c}}{(2n-p)x^{2n-p}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^1_i}{x^{2n-p-i}}\right) x^{\sigma_1} v_0(x) + \exp\left(\frac{2\pi i \sqrt{c}}{(2n-p)x^{2n-p}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^2_{ii}}{x^{2n-p-i}}\right) x^{\sigma_2} v_1(x) = \\ & = \exp\left(-\frac{2\pi i \sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^1_i}{r^{\frac{n-p}{2} \frac{i}{2}}}\right) r^{\frac{\sigma_1}{2}} v_0\left(r^{\frac{1}{2}}\right) + \exp\left(\frac{2\pi i \sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^2_i}{r^{\frac{n-p}{2} \frac{i}{2}}}\right) r^{\frac{\sigma_2}{2}} v_1\left(r^{\frac{1}{2}}\right) \end{aligned}$$

Since

$$v_1\left(r^{\frac{1}{2}}\right) = \sum_{i=1}^{\infty} v_i^1 r^{\frac{i}{2}} = \sum_{i=1}^{\infty} v_{2i}^1 r^i + \sum_{i=0}^{\infty} v_{2i+1}^1 r^{i+\frac{1}{2}} = \sum_{i=1}^{\infty} v_{2i}^1 r^i + r^{\frac{1}{2}} \sum_{i=0}^{\infty} v_{2i+1}^1 r^i,$$

then the asymptotic solution can be rewritten in the form

$$\exp\left(-\frac{2\pi i\sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^1_i}{r^{\frac{n-p-i}{2}}}\right) r^{\frac{\sigma_1}{2}} \left(\tilde{v}_1^1(r) + r^{\frac{1}{2}}\tilde{v}_1^2(r)\right) +$$

$$+ \exp\left(\frac{2\pi i\sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^2_i}{r^{\frac{n-p-i}{2}}}\right) r^{\frac{\sigma_2}{2}} \left(\tilde{v}_2^1(r) + r^{\frac{1}{2}}\tilde{v}_2^2(r)\right).$$

Here $\tilde{v}_j^1 = \sum_{i=1}^{\infty} v_{2i}^j r^i, \tilde{v}_j^2 = \sum_{i=1}^{\infty} v_{2i+1}^j r^i, j=1,2$. In this case we have obtained a new asymptotic type, namely the asymptotics with nonintegral degrees r in their exponents.

Let us consider the last case. Suppose $k = \frac{p}{2} < n$. We set $m = k = \frac{p}{2}$ and dividing by r^{2m} we obtain and multiplying on $\left(\frac{n}{n-k}\right)^2$ then

$$\left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right)^2 u + \frac{n}{n-k} r^{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + b \frac{n}{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + \left(\frac{n}{n-k}\right)^2 cu +$$

$$+ rb_1(r) \frac{n}{n-k} \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u + r \left(\frac{n}{n-k}\right)^2 c_1(r) u +$$

$$+ rv(r) \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right)^2 u + \frac{n}{n-k} r^{n-k+1} v(r) \left(\frac{1}{n-k} r^{n-k+1} \frac{d}{dr}\right) u = 0$$

The principle symbol in this case has the form $H_0(p) = p^2 + b \frac{n}{n-k} p + c \left(\frac{n}{n-k}\right)^2$.

If $b \neq 2\sqrt{c}$, then the polynomial $p^2 + b \frac{n}{n-k} p + c \left(\frac{n}{n-k}\right)^2$ has two roots c_1, c_2 and the asymptotics has the form

$$r^{\sigma_0} v_0(r) \exp\left(\frac{c_1}{r^{n-k}} + \sum_{i=1}^{n-k-1} \frac{\alpha^0_i}{r^{n-k-i}}\right) + r^{\sigma_1} v_1(r) \exp\left(\frac{c_2}{r^{n-k}} + \sum_{i=1}^{n-k-1} \frac{\alpha^1_i}{r^{n-k-i}}\right)$$

If $b = 2\sqrt{c}$, namely $p^2 + b \frac{n}{n-k} p + c \left(\frac{n}{n-k}\right)^2$, then by replacing $\tilde{u} = e^{\frac{n\sqrt{c}}{n-k} r} u$ we obtain the equation with a multiple root at zero. The asymptotic solution of this equation is constructed in the same way as is shown above and depends on the degrees of degeneracy of the functions $b_1(r), c_1(r)$.

Thus we have cuspidal degeneracies in the case where $\frac{p}{2} < n$ or $k < n$. The obtained results are written in the table

Theorem 1. Let $\frac{p}{2} < n$ or $k < n$ then

Table 1

Conditions	Space	Asymptotics
$k < \frac{p}{2}$	$u \in E_{n-k}(S_{R,\varepsilon})$	$r^{\sigma_0} v_0(r) \exp\left(\sum_{i=1}^{n-k-1} \frac{\alpha^0_{n-k-i}}{r^{n-k-i}}\right) +$ $+ r^{\sigma_1} v_1(r) \exp\left(-\frac{bn}{r^{n-k}(n-k)} + \sum_{i=1}^{n-k-1} \frac{\alpha^1_{k-i}}{r^{n-k-i}}\right)$
$k > \frac{p}{2},$ $p = 2q, q \in \mathbb{N}$	$u \in E_{n-q}(S_{R,\varepsilon})$	$r^{\sigma_1} v_0(r) \exp\left(-\frac{i \frac{n}{n-q} \sqrt{c}}{r^{n-q}} + \sum_{i=1}^{n-q-1} \frac{\alpha^1_{n-q-i}}{r^{n-q-i}}\right) +$ $+ r^{\sigma_2} v_1(r) \exp\left(\frac{i \frac{n}{n-q} \sqrt{c}}{r^{n-q}} + \sum_{i=1}^{n-q-1} \frac{\alpha^2_{n-q-i}}{r^{n-q-i}}\right)$
$k > \frac{p}{2},$ p is odd	$u \in E_{\frac{n-p-1}{2}}(S_{R,\varepsilon})$	$\exp\left(-\frac{2\pi i \sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^1_i}{r^{\frac{n-p-i}{2}}}\right) r^{\frac{\sigma_1}{2}} \left(\mathfrak{V}_1^1(r) + r^{\frac{1}{2}} \mathfrak{V}_1^2(r)\right) +$ $+ \exp\left(\frac{2\pi i \sqrt{c}}{(2n-p)r^{\frac{n-p}{2}}} + \sum_{i=1}^{2n-p-1} \frac{\alpha^2_i}{r^{\frac{n-p-i}{2}}}\right) r^{\frac{\sigma_2}{2}} \left(\mathfrak{V}_2^1(r) + r^{\frac{1}{2}} \mathfrak{V}_2^2(r)\right)$
$k = \frac{p}{2}$ and $b \neq 2\sqrt{c}$	$u \in E_{n-k-1}(S_{R,\varepsilon})$	$r^{\sigma_0} v_0(r) \exp\left(\frac{c_1}{r^{n-k}} + \sum_{i=0}^{n-k-1} \frac{\alpha^0_{n-k-i}}{r^{n-k-i}}\right) +$ $+ r^{\sigma_1} v_1(r) \exp\left(\frac{c_2}{r^{n-k}} + \sum_{i=2}^{n-k-1} \frac{\alpha^1_{k-i}}{r^{n-k-i}}\right)$

Now we proceed to examine the higher-order equations

$$\left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right)^k u + b_{k-1}(r) \left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right)^{k-1} u + \dots + b_1(r) \left(\frac{1}{n} r^{n+1} \frac{d}{dr}\right) u + b_0(r) u = 0$$

where $b_i(r) = \sum_{j=m_i}^{\infty} c_i^j r^j, i = 0, \dots, k-1$ are entire functions. We assume that $c_i^{m_i} \neq 0$. The number m_i will be called a degree of degeneracy of the coefficient $b_i(r)$. Suppose that zero is the root of this equation principle symbol and the degree of degeneracy of the coefficients $b_1(r)$ or $b_0(r)$ is no more than the degree of degeneracy for any of the coefficients $b_i(r), i = 2, \dots, k-1$. The above method is also applicable to this case. Specifically, the equation is to be divided by r^p , where $p = \min(m_0, m_1)$, then we have

the equation with a symbol of the form $H\left(r, r^{\frac{n-p}{k}} \frac{d}{dr}\right)$, which is solved similarly to the previous one.

III. PARTIAL DIFFERENTIAL EQUATIONS

We consider a second-order partial differential equation with holomorphic coefficients. It can be represented in the form

$$H\left(r, -\frac{1}{k} r^{k+1} \frac{d}{dr}, x, -i \frac{\partial}{\partial x}\right) u = 0,$$

where x varies on some compact manifold without boundary. These equations can be interpreted as equations with respect to the functions with values in Banach spaces, namely

$$\hat{H}\left(r, -\frac{1}{k} r^{k+1} \frac{d}{dr}\right) u = 0, \tag{10}$$

where $\hat{H} : E_k(S_{R,\varepsilon}, B_1) \rightarrow E_k(S_{R,\varepsilon}, B_2)$. Here $B_i, i=1,2$ denote some Banach spaces (e.g. the space $H^s(\Omega)$). The degree k of the function u grows exponentially for $r \rightarrow 0$, for fixed r and p

$$\hat{H}(r, p) : B_1 \rightarrow B_2$$

is a bounded operator acting in Banach spaces which is polynomial dependent on p and holomorphic in the neighbourhood of zero.

In what follows, we will assume that the operator family $\hat{H}_0(p) = \hat{H}(0, p)$ is a *Fredholm* family. This implies that the operator $\hat{H}_0(p)$ is a Fredholm operator for each fixed p , and there exists $p_0 \in C$ such that the operator $\hat{H}_0(p_0)$ is invertible.

In addition to the requirement of the Fredholm property for the family $\hat{H}_0(p)$ we assume that there exists a cone in C containing the imaginary axis and does not contain the points of the spectrum of $\hat{H}_0(p)$ for a sufficiently large $|p|$. The spectrum of a Fredholm family is a set of points $p \in C$ such that $\hat{H}_0(p)$ is irreversible.

Suppose that the point $p_1 \in \text{spec} \hat{H}_0(p)$ is such that the following conditions hold:

1. The operator-valued function $\hat{H}_0^{-1}(p)$ has the second-order pole at the point p_1 .
2. The dimensionality of the $\ker \hat{H}_0(p_1)$ is equal to one.

In this case theorem 1 is also true. The proof is analogous to that of Theorem 9 in [5] In this case the coefficients of the series $\sum_{j=1}^{\infty} v_j^i r^j$ are the elements of the space B_1 .

IV. LAPLACE'S EQUATION ON A MANIFOLD WITH A CASPIDAL SINGULARITY

We consider the Laplace equation $\Delta u = 0$ on the 2D-Riemannian manifold with a second order caspidal singularity. The Riemannian metric induced from R^3 with the help of embedding which is defined as the surface by the rotational of the parabolic branch $y = r^2$ around axis $0r$. in R^3 . We choose local coordinates r, φ on the manifold in the neighbourhood of zero. The metrics on this manifold is given by

$$ds^2 = dr^2 + 4r^2 dr^2 + r^4 d\varphi^2 = (1 + 4r^2)dr^2 + r^4 d\varphi^2,$$

hence

$$gradu = (A_1, A_2) = \left(\frac{1}{\sqrt{4r^2 + 1}} \frac{\partial u}{\partial r}, \frac{1}{r^2} \frac{\partial u}{\partial \varphi} \right).$$

and

$$divu = \frac{1}{h_1 h_2} \left(\frac{\partial}{\partial r} (h_2 A_1) + \frac{\partial}{\partial \varphi} (h_1 A_2) \right) = \frac{1}{r^2 \sqrt{4r^2 + 1}} \frac{\partial}{\partial r} (r^2 A_1) + \frac{1}{r^2} \frac{\partial}{\partial \varphi} A_2.$$

Finally, for the Laplace operator we obtain

$$\Delta u = divgradu = \frac{1}{r^2 \sqrt{4r^2 + 1}} \frac{\partial}{\partial r} \left(r^2 \frac{1}{\sqrt{4r^2 + 1}} \frac{\partial u}{\partial r} \right) + \frac{1}{r^4} \left(\frac{\partial}{\partial \varphi} \right)^2 u.$$

Thus Laplace's equation on a manifold has the form

$$\hat{H}u = \frac{1}{4r^2 + 1} \frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{2r^2 + 1}{(4r^2 + 1)^2} \frac{\partial u}{\partial r} + \frac{1}{r^4} \frac{\partial^2 u}{\partial \varphi^2} = 0. \tag{11}$$

In other words

$$\hat{H} : E_k(S_{R,\varepsilon}, H^s(S_1)) \rightarrow E_k(S_{R,\varepsilon}, H^{s-2}(S_1)),$$

We rewrite equation (11) in the form

$$\left(r^2 \frac{d}{dr} \right)^2 u + \frac{\partial^2 u}{\partial \varphi^2} = -4r^2 \frac{\partial^2 u}{\partial \varphi^2} + \frac{4r^3}{(4r^2 + 1)} \left(r^2 \frac{\partial u}{\partial r} \right) \tag{12}$$

Obviously this case does not satisfy condition 2 who formulated in part 3, (see of the paper) Therefore, the results formulated there is not applicable. We perform the Laplace-Borel transform

$$p^2 \tilde{u} + \left(\frac{\partial}{\partial \varphi} \right)^2 \tilde{u} = -Br^3 a_1(r) \left(r^2 \frac{\partial}{\partial r} \right) \tilde{u} - 4 \frac{\partial^2}{\partial \varphi^2} Br^2 \tilde{u} + \tilde{f}(p, \varphi), \tag{13}$$

where $a_1(r) = \frac{r}{(4r^2 + 1)}$, and $\tilde{f}(p, \varphi)$ denotes a holomorphic function.

The principle symbol of this operator is equal $H(o, p) = p^2 + \left(\frac{\partial}{\partial \varphi}\right)^2$. Therefore the corresponding operator family $\hat{H}_0(p)$ is a Fredholm one. The existence of resurgent solution of this equation follows from the results of [2], [3]. We denote $\hat{r}^n = Br^n B^{-1}$, as was done in [5]. If $a(r)$ is holomorphic in the neighbourhood of $r = 0$, vanishing at the origin, and

$$a(r) = \sum_{k=1}^{\infty} a_k r^k \tag{14}$$

is its Taylor expansion, then the function

$$\tilde{a}(p) = \sum_{k=1}^{\infty} (-1)^k a_k \frac{p^{k-1}}{(k-1)!} \tag{15}$$

is called a *formal Laplace-Borel transform* of (14), then as shown in the article [5] the equation

$$B \circ a(r) \circ B^{-1} \tilde{f} = \int_{p_0}^p \tilde{a}(p-p') \tilde{f}(p') dp' \tag{16}$$

Equality (16) implies that the right-hand part of equation (13) can be transformed

$$\begin{aligned} & -Br^2 B^{-1} Bra_1(r) \left(r^2 \frac{\partial}{\partial r} \right) \tilde{u} - 4 \frac{\partial^2}{\partial \varphi^2} Br^2 \tilde{u} + \tilde{f}(p, \varphi) = \\ & = -\hat{r}^2 \int_{p_0}^p \tilde{a}(p-p') p' \tilde{u}(p', \varphi) dp' - 4 \frac{\partial^2}{\partial \varphi^2} \hat{r}^2 \tilde{u}(p, \varphi) + \tilde{f}(p, \varphi) \end{aligned}$$

Equation (13) is ultimately transformed into following

$$p^2 \tilde{u} + \left(\frac{\partial}{\partial \varphi}\right)^2 \tilde{u} = -\hat{r}^2 \int_{p_0}^p \tilde{a}(p-p') p' \tilde{u}(p', \varphi) dp' - 4 \hat{r}^2 \frac{\partial^2}{\partial \varphi^2} \tilde{u}(p, \varphi) + \tilde{f}(p, \varphi) \tag{17}$$

Decompose functions \tilde{u} and \tilde{f} into a series on eigen function of operator $\frac{\partial^2}{\partial \varphi^2}$

$$\begin{aligned} \tilde{u}(p, \varphi) &= \sum_{k=-\infty}^{\infty} A_k(p) e^{ik\varphi} \\ \tilde{f}(p, \varphi) &= \sum_{k=1}^{\infty} a_k(p) e^{ik\varphi} \end{aligned} \tag{18}$$

Substituting (18) into equation, (17) we obtain

$$\begin{aligned} & p^2 \sum_{k=-\infty}^{\infty} A_k(p) e^{ik\varphi} - \sum_{k=1}^{\infty} k^2 A_k(p) e^{ik\varphi} = \\ & = -\hat{r}^2 \int_{p_0}^p \tilde{a}(p-p') \sum_{k=-\infty}^{\infty} A_k(p') e^{ik\varphi} dp' + 4 \hat{r}^2 \sum_{k=-\infty}^{\infty} k^2 A_k(p) e^{ik\varphi} + \sum_{k=1}^{\infty} a_k(p) e^{ik\varphi} \end{aligned}$$

This equality is equivalent to the system of equations

$$(p^2 - k^2)A_k(p) = -\hat{r}^2 \int_{p_0}^p \tilde{a}(p - p')p'A_k(p')dp' + 4\hat{r}^2k^2A_k(p) + a_k(p),$$

Here k is an integer. The cases $k = 0$ and $k \neq 0$ should be considered separately. In the first case the singular point of the function $A_0(p)$ is $p = 0$, being a pole of second order. We solve this equation by the method of successive approximations.

$$A_0(p) = -\frac{2}{p^2} \hat{r}^2 \int_{p_0}^p \tilde{a}(p - p')p' \frac{A_0(p')}{2} dp' + \frac{1}{p^2} a_0(p) \tag{19}$$

Substitute $A_0(p) = \frac{1}{p^2} a_0(p)$ into the integral in right-hand part side of (19).

Applying successive approximation method. Obtain the equality

$$\frac{1}{p^2} \hat{r}^2 \int_{p_0}^p \tilde{a}(p - p') \frac{1}{p'} a_0(p') dp' = \frac{1}{p^2} \hat{r}^2 \int_{p_0}^p \frac{G(p, p')}{p'} dp'$$

where $G(p, p') = \tilde{a}(p - p')a_0(p')$. We represent this function as the series

$G(p, p') = \sum_{i=0}^{\infty} l_i(p)p'^i$, then similarly to [5] we obtain

$$\begin{aligned} \frac{1}{p^2} \hat{r}^2 \int_{p_0}^p \frac{\sum_{i=0}^{\infty} l_i(p)p'^i}{p'} dp' &= \frac{1}{p^2} \int_0^{p_2} \int_{p_0}^{p_2} (b_1(p_1) \ln p_1 + n(p_1)) dp_1 dp_2 = \\ &= C_{-1} \frac{1}{p} + C_0 \ln p + \sum_{i=1}^{\infty} C_i p^i \ln p + g(p) \end{aligned}$$

where $g(p)$ denotes the function holomorphic in the zero neighbourhood, and C_i denotes corresponding constants. The proof of convergence of the successive approximation method is the same as analogous to the proof in [6]. Thus we obtain that the function $A_0(p)$ with an accuracy of a holomorphic summand in the neighbourhood of the point $p = 0$ has the form

$$A_0(p) = \frac{M_{-2}}{p^2} + \frac{M_{-1}^0}{p} + \sum_{i=0}^{\infty} M_i^0 p^i \ln p$$

Here by M_i^0 we denote corresponding constants.

Now we consider the second case $k \neq 0$. In this case the points $p = k$ and $p = -k$ are first-order poles of the function $A_k(p)$. Here we have the equation

$$A_k(p) = -\frac{1}{p^2 - k^2} \hat{r}^2 \int_{p_0}^p \tilde{a}(p - p')p'A_k(p')dp' + \frac{1}{p^2 - k^2} 4\hat{r}^2k^2A_k(p) + \frac{a_k(p)}{p^2 - k^2}$$

Equations of this form have been studied in [5]. The asymptotics of the function $A_k(p)$ in the neighbourhood of the singular point $p = k$, with an accuracy of a holomorphic function, will take the form

$$A_k(p) = \frac{M_{-1}^k}{p-k} + \sum_{j=0}^{\infty} M_j^k (p-k)^j \ln(p-k)$$

Here by M_i^k we denote corresponding constants. Thus we have demonstrated that, with an accuracy of a holomorphic function, the solution of equation (17) has the form

$$\tilde{u}(p, \varphi) = \sum_{k=-\infty}^{\infty} A_k(p) e^{ik\varphi} = \frac{M_{-2}}{p^2} + \sum_{k=-\infty}^{\infty} \left(\frac{M_{-1}^k}{p-k} + \sum_{j=0}^{\infty} M_j^k (p-k)^j \ln(p-k) \right) e^{ik\varphi}$$

Hence it follows that singular points of the function $\tilde{u}(p, \varphi)$ lie in any half-plane $\text{Re } p > A > 0$. In order to construct the solution of problem (17) we represent the function $\tilde{u}(p, \varphi)$ as a sum of two functions $\tilde{u}_-(p, \varphi)$ and $\tilde{u}_+(p, \varphi)$ such that the singularities of the first one lie to the left of the line $\text{Re } p > A$, and the singularities of the second one lie to the right of this line $\text{Re } p > A$, where $\text{Re } A \notin Z$. Then the solution can be constructed as the inverse transformation of the function $\tilde{u}_-(p, \varphi)$ (see [5]). To put it differently the equality

$$u(r, \varphi) = B^{-1} \tilde{u}_-(p, \varphi) = B^{-1} \left(\frac{M_{-2}}{p^2} + \sum_{k=-\infty}^N \left(\frac{M_{-1}^k}{p-k} + \sum_{j=0}^{\infty} M_j^k (p-k)^j \ln(p-k) \right) e^{i\varphi k} \right)$$

holds with an accuracy of an entire function.

Hence it follows that the asymptotic solution of Laplace's equation (13) has the form

$$u(r, \varphi) = \frac{C_{-1}}{r} + \sum_{k=-\infty}^N e^{\frac{k}{r}} e^{i\varphi k} \sum_{i=0}^{\infty} M_i^k r^i$$

We should note that the solution depends on the representation $\tilde{u}(p, \varphi) = \tilde{u}_-(p, \varphi) + \tilde{u}_+(p, \varphi)$. One solution differs from the other solutions by an operator kernel. Thus we have proved

Assertion. Any solution of equation of exponential growth (12) can be represented as

$$u(r, \varphi) = \frac{C_{-1}}{r} + \sum_j u_j(r, \varphi) + O\left(e^{-\frac{A}{r}}\right),$$

where A is an arbitrary positive number, and the sum contains a finite number of summands, each of which corresponding to a point $p = k$ located in the half-plane

$\text{Re } p > -A$, and $u_j(r)$ have asymptotic expansions

$$u_j(r, \varphi) = e^{\frac{j}{r}} e^{i\varphi j} \sum_{l=0}^{\infty} M_l^k r^l,$$

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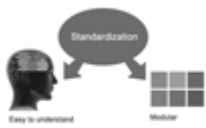
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- Line Spacing of 1 pt
- Large Images must be in One Column
- Numbering of First Main Headings (Heading 1) must be in Roman Letters, Capital Letter, and Font Size of 10.
- Numbering of Second Main Headings (Heading 2) must be in Alphabets, Italic, and Font Size of 10.

You can use your own standard format also.

Author Guidelines:

1. General,
2. Ethical Guidelines,
3. Submission of Manuscripts,
4. Manuscript's Category,
5. Structure and Format of Manuscript,
6. After Acceptance.

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(b) A brief Summary, "Abstract" (less than 150 words) containing the major results and conclusions.

(c) Up to ten keywords, that precisely identifies the paper's subject, purpose, and focus.

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(e) Resources and techniques with sufficient complete experimental details (wherever possible by reference) to permit repetition; sources of information must be given and numerical methods must be specified by reference, unless non-standard.

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- Describe the method entirely
- To be succinct, present methods under headings dedicated to specific dealings or groups of measures
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- If well known procedures were used, account the procedure by name, possibly with reference, and that's all.

Approach:

- It is embarrassed or not possible to use vigorous voice when documenting methods with no using first person, which would focus the reviewer's interest on the researcher rather than the job. As a result when script up the methods most authors use third person passive voice.
- Use standard style in this and in every other part of the paper - avoid familiar lists, and use full sentences.

What to keep away from

- Resources and methods are not a set of information.
- Skip all descriptive information and surroundings - save it for the argument.
- Leave out information that is immaterial to a third party.

Results:

The principle of a results segment is to present and demonstrate your conclusion. Create this part a entirely objective details of the outcome, and save all understanding for the discussion.

The page length of this segment is set by the sum and types of data to be reported. Carry on to be to the point, by means of statistics and tables, if suitable, to present consequences most efficiently. You must obviously differentiate material that would usually be incorporated in a study editorial from any unprocessed data or additional appendix matter that would not be available. In fact, such matter should not be submitted at all except requested by the instructor.



Content

- Sum up your conclusion in text and demonstrate them, if suitable, with figures and tables.
- In manuscript, explain each of your consequences, point the reader to remarks that are most appropriate.
- Present a background, such as by describing the question that was addressed by creation an exacting study.
- Explain results of control experiments and comprise remarks that are not accessible in a prescribed figure or table, if appropriate.
- Examine your data, then prepare the analyzed (transformed) data in the form of a figure (graph), table, or in manuscript form.

What to stay away from

- Do not discuss or infer your outcome, report surroundings information, or try to explain anything.
- Not at all, take in raw data or intermediate calculations in a research manuscript.
- Do not present the similar data more than once.
- Manuscript should complement any figures or tables, not duplicate the identical information.
- Never confuse figures with tables - there is a difference.

Approach

- As forever, use past tense when you submit to your results, and put the whole thing in a reasonable order.
- Put figures and tables, appropriately numbered, in order at the end of the report
- If you desire, you may place your figures and tables properly within the text of your results part.

Figures and tables

- If you put figures and tables at the end of the details, make certain that they are visibly distinguished from any attach appendix materials, such as raw facts
- Despite of position, each figure must be numbered one after the other and complete with subtitle
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Discussion:

The Discussion is expected the trickiest segment to write and describe. A lot of papers submitted for journal are discarded based on problems with the Discussion. There is no head of state for how long a argument should be. Position your understanding of the outcome visibly to lead the reviewer through your conclusions, and then finish the paper with a summing up of the implication of the study. The purpose here is to offer an understanding of your results and hold up for all of your conclusions, using facts from your research and generally accepted information, if suitable. The implication of result should be visibly described. Infer your data in the conversation in suitable depth. This means that when you clarify an observable fact you must explain mechanisms that may account for the observation. If your results vary from your prospect, make clear why that may have happened. If your results agree, then explain the theory that the proof supported. It is never suitable to just state that the data approved with prospect, and let it drop at that.

- Make a decision if each premise is supported, discarded, or if you cannot make a conclusion with assurance. Do not just dismiss a study or part of a study as "uncertain."
- Research papers are not acknowledged if the work is imperfect. Draw what conclusions you can based upon the results that you have, and take care of the study as a finished work
- You may propose future guidelines, such as how the experiment might be personalized to accomplish a new idea.
- Give details all of your remarks as much as possible, focus on mechanisms.
- Make a decision if the tentative design sufficiently addressed the theory, and whether or not it was correctly restricted.
- Try to present substitute explanations if sensible alternatives be present.
- One research will not counter an overall question, so maintain the large picture in mind, where do you go next? The best studies unlock new avenues of study. What questions remain?
- Recommendations for detailed papers will offer supplementary suggestions.

Approach:

- When you refer to information, differentiate data generated by your own studies from available information
- Submit to work done by specific persons (including you) in past tense.
- Submit to generally acknowledged facts and main beliefs in present tense.



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<i>References</i>	Complete and correct format, well organized	Beside the point, Incomplete	Wrong format and structuring



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